

# Advanced Programming Techniques (AdvPT)

Winter Term 2015/16

Sebastian Kuckuk and Martin Bauer  
Chair for System Simulation



FRIEDRICH-ALEXANDER  
UNIVERSITÄT  
ERLANGEN-NÜRNBERG

TECHNISCHE FAKULTÄT



# Assignment 2

November 2, 2015 – November 17, 2015

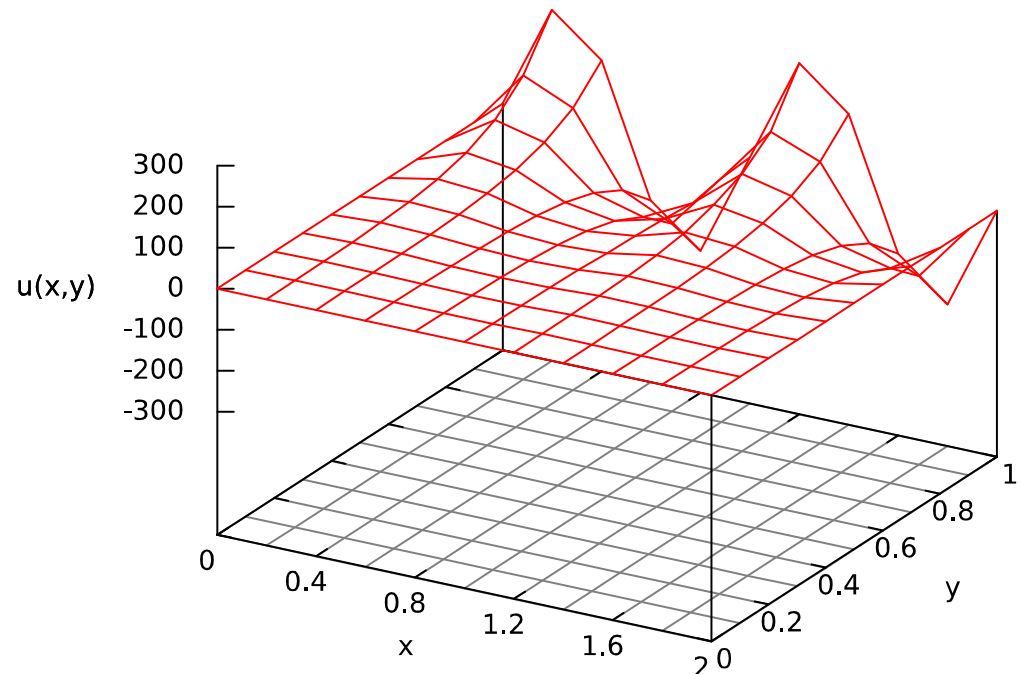


FRIEDRICH-ALEXANDER  
UNIVERSITÄT  
ERLANGEN-NÜRNBERG

TECHNISCHE FAKULTÄT

$$\Delta u(x, y) + k^2 u(x, y) = f(x, y)$$

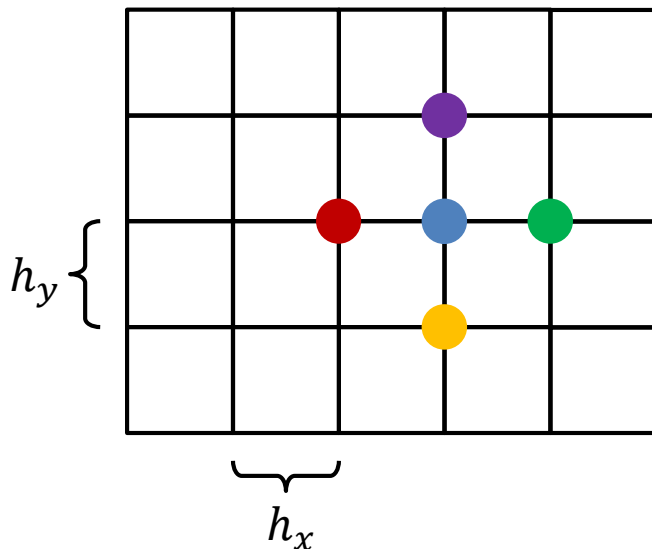
$$\left( \frac{\partial^2 u(x, y)}{\partial x^2} + \frac{\partial^2 u(x, y)}{\partial y^2} \right) + k^2 u(x, y) = f(x, y)$$



- Discretization using the differential quotient for  $\Delta u(x, y)$ :

$$\frac{1}{h_x^2} [u(x + h_x, y) - 2u(x, y) + u(x - h_x, y)] + \frac{1}{h_y^2} [u(x, y + h_y) - 2u(x, y) + u(x, y - h_y)] + k^2 u(x, y) = f(x, y)$$

- We are solving the given PDE on a **discretized domain**  $\Omega$ :



$u(x, y) / f(x, y)$

$u(x - h_x, y)$

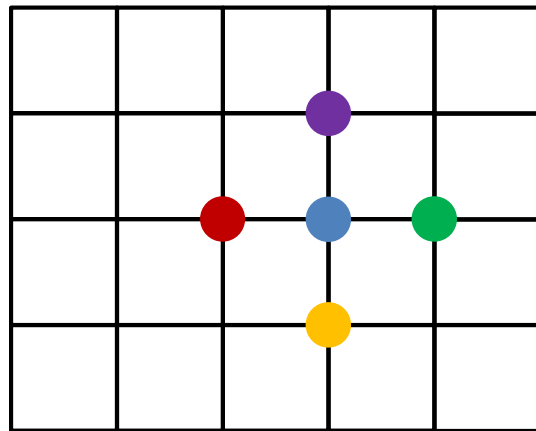
$u(x + h_x, y)$

$u(x, y - h_y)$

$u(x, y + h_y)$

- For every point  $u_{x,y}$  on the grid, we can formulate a linear equation:

$$\frac{1}{h_x^2} [u_{x-1,y} + u_{x+1,y}] + \frac{1}{h_y^2} [u_{x,y-1} + u_{x,y+1}] + \left( -\frac{2}{h_x^2} - \frac{2}{h_y^2} + k^2 \right) u_{x,y} = f_{x,y}$$



$u_{x,y} / f_{x,y}$

$u_{x-1,y}$

$u_{x+1,y}$

$u_{x,y-1}$

$u_{x,y+1}$

- Formulating this equation for every point of the grid leads to a linear system of equations (LSE):  $A\vec{u} = \vec{f}$

- The Jacobi method **iteratively** solves the LSE ( $k$  represents the number of the iteration) according to the following formula:

$$u^{k+1} = D^{-1}(f - (A - D)u^k)$$

- Or, for each line:

$$u_i^{k+1} = \frac{1}{a_{ii}} \left( f_i - \sum_{j \neq i} a_{ij} u_j^k \right)$$

⇒ This corresponds to solving the  $i$ -th equation of the LSE using the unknowns from the **previous** iteration.

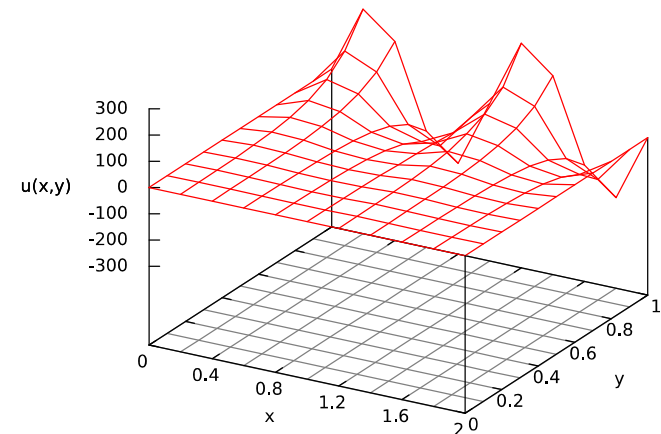
- In order to solve the elliptic partial differential equation ...

$$\Delta u(x, y) + k^2 u(x, y) = f(x, y)$$

... no Matrix  $A$  must be assembled.

- We just need to know the “stencil”:

$$\begin{bmatrix} & & \frac{1}{h_y^2} & & \\ & \frac{1}{h_x^2} & -\frac{2}{h_x^2} - \frac{2}{h_y^2} + k^2 & \frac{1}{h_x^2} & \\ & & \frac{1}{h_y^2} & & \end{bmatrix}$$



A solution of the PDE

- Every grid point  $u_{x,y}$  can be computed as follows:

$$u_{x,y} = \frac{1}{\left(\frac{-2}{h_x^2} + \frac{-2}{h_y^2} + k^2\right)} \left( f_{x,y} - \frac{1}{h_x^2} [u_{x-1,y} + u_{x+1,y}] - \frac{1}{h_y^2} [u_{x,y-1} + u_{x,y+1}] \right)$$

# THE END QUESTIONS ?



FRIEDRICH-ALEXANDER  
UNIVERSITÄT  
ERLANGEN-NÜRNBERG

TECHNISCHE FAKULTÄT