Problem Set 4

Problem 1. Mechanical and electrical energy Consider the unforced mass-spring system

$$m\ddot{x} + b\dot{x} + kx = 0, \quad t > 0.$$

We define the total mechanical energy of this system to be the function

$$E(t) = \frac{1}{2}m(\dot{x}(t))^2 + \frac{1}{2}k(x(t))^2,$$

which you might recognize as the sum of kinetic energy and spring potential energy.

- (a) Show that $\dot{E}(t) = 0$ in an undamped system. This shows that E(t) is constant over time (this is an instance of the *law of conservation of mechanical energy*.
- (b) On the other hand, if there is damping in this system, give a mathematical argument as to why $\dot{E}(t) < 0$ (so that total mechanical energy is *not* conserved over time).
- (c) Recall the forced (non-homogeneous) mass-spring system

$$m\ddot{x} + b\dot{x} + kx = q(t),$$

where g(t) is the forcing function. We define the change in total mechanical energy to be the function

$$(\Delta E)(t) = E(t) - E(0) = \int_0^t \dot{E}(s) \, ds.$$

Show that $(\Delta E)(t)$ can be explicitly written as

$$(\Delta E)(t) = \int_0^t \dot{x}(s)g(s) - b(\dot{x}(s))^2 ds.$$

(d) Recall the RLC-circuit governed by the equation

$$L\ddot{Q} + R\dot{Q} + \frac{1}{C}Q = V(t).$$

Given the discussion above, what should we define as the total electrical energy of the circuit? Interpret the two terms in your definition in terms of the charge Q on the capacitor and the current $I = \dot{Q}$ running through it.

Problem 2. Wait... you can do that?!

(a) Be sure to look at problems 30 and 31 of the suggested problems. Show that you've read through them by explaining how we can use the *Gamma function* $\Gamma(t)$ to compute $\left(\frac{1}{2}\right)!$; that is, the factorial of $\frac{1}{2}$.

[Hint: You may find the u-substitution $u = \sqrt{x}$ helpful in your explanation.]

(b) The only stumbling block in computing $(\frac{1}{2})!$ is that we might not know how to compute

$$G = \int_0^\infty e^{-x^2} \, dx.$$

We will show this below, but first use the comparison test to show that G converges.

(c) Using polar coordinates $x = r \cos \theta$ and $y = r \sin \theta$, show that

$$(2G)^2 = 2\pi \int_0^\infty re^{-r^2} dr.$$

[Hint: Write $(\int e^{-x^2} dx)^2$ as $(\int e^{-x^2} dx)(\int e^{-y^2} dy)$ and remember that constants can be brought inside integrals.]

(d) Evaluate the improper integral above to show that $G = \frac{1}{2}\sqrt{\pi}$. Explain how this means that

$$\left(\frac{1}{2}\right)! = \sqrt{\pi}.$$