Extra credit problem

Let T be the Calculus I antiderivative:

$$T(f) = \int_0^x f(t) dt.$$

The goal of this exercise is to solve

$$T(f) = g, (1)$$

where the right-hand side g is given on the interval [0, 1]; by solving Equation (1) we mean finding f on the interval [0, 1].

From the point of view of Calculus, Equation (1) is solved simply by differentiation:

$$f = T^{-1}(g) = \frac{dg}{dx}.$$

Clearly, the symbolic differentiation will work only if g is specified by a symbolic expression. More likely, however, is the scenario where we are given a sample of values of g and asked for a sample of values of f. Furthermore, it is very likely that the values of g will not be exact due to noise and round-off errors.

Part 1 (25 Points)

Divide the interval [0,1] into N equal subintervals; denote the subdivision points by \mathbf{x} . To simplify notation, let us abbreviate

$$\mathbf{g} = g(\mathbf{x}), \quad \mathbf{f} = f(\mathbf{x}).$$

Denote by A the matrix representation of T corresponding to the left endpoint rule of integration ¹. Now, to solve the discretized problem

$$A\mathbf{f} = \mathbf{g},$$

form the normal equations

$$A^T A \mathbf{f} = A^T \mathbf{g},$$

 $^{^{1}}$ There are many ways to discretize T and the left end-point rule is by no means ideal, yet it will suffice for our purposes.

and consider the eigenvalue decomposition $[V, \Lambda]$ of $A^T A$. Henceforth we assume, and this is important, that the eigenvalues of $A^T A$ are sorted in decreasing order; the eigenvectors \mathbf{v}_n must be sorted accordingly. In class we derived the following formula

$$\mathbf{f} = \sum_{j=1}^{N} \frac{\mathbf{v}_{j}^{T} A^{T} \mathbf{g}}{\lambda_{j}} \mathbf{v}_{j}.$$

This formula works well if λ_n are bounded away from zero. If $\lambda_n \to 0$ we can pick n < N and approximate:

$$\mathbf{f} \approx \sum_{j=1}^{n} \frac{\mathbf{v}_{j}^{T} A^{T} \mathbf{g}}{\lambda_{j}} \mathbf{v}_{j}. \tag{2}$$

Perform the following investigation in Matlab or its equivalent:

- 1. Set N=100. Form the matrix A and compute the eigen-decomposition $[V,\Lambda]$ of A^TA . Use the **sort** command to rearrange the eigen-decomposition so that the eigenvalues form a *decreasing* sequence: $\lambda_1 > \lambda_2 > \dots$
- 2. Produce plots of the first nine eigenvectors of V (corresponding to the largest eigenvalues). Indicate the eigenvalues in the titles of the plots. You can arrange the plots on one figure using the subplot command. If the plots looks highly oscillatory, you may have forgotten to sort the decomposition.
- 3. Plot the sorted eigenvalues in logarithmic coordinates (loglog command). How fast are the eigenvalues decreasing? Make a conjecture.
- 4. Generate \mathbf{x} using linspace command and set $\mathbf{g} = \mathbf{x}$. Notice that $\mathbf{g} = \mathbf{x}$ corresponds to $\mathbf{f} = \mathbf{1}$.
- 5. Use Equation (2) to find \mathbf{f} : first, set n = N = 100 and see if it works. Plot on the same figure \mathbf{f} (against \mathbf{x}) in red and $\mathbf{1}$ in blue; title the plot "Full reconstruction without noise".
- 6. Add a little bit of noise: g = x + .01*rand(size(x)). Plot noisy g against x; title the plot "Noisy data".

- 7. Attempt to recover \mathbf{f} from noisy \mathbf{g} using all eigenvectors (Equation (2) with n = N = 100); Plot the result and the vector of ones on the same figure and title the plot "Full reconstruction with noise".
- 8. Use Equation (2) with n = 9 to compute an approximation of \mathbf{f} ; Plot the result and the vector of ones on the same figure and title the plot "Reconstruction with 9 eigenvectors".

Submit your work in the following format:

- 1. Explain how you discretize T; Write the matrix A for N=4.
- 2. Present all of the plots in the order that they were generated. Make sure the plots are titled appropriately.
- 3. Attach Matlab script.

If you wish to submit the problem electronically you must e-mail one PDF file containing explanations, code, and plots before the final exam.

Part 2 (25 Points)

As $N \to \infty$ the eigenvalues and eigenvectors of $A^T A$ approach the eigenvalues and eigenfunctions of $T^* T$ (the star superscript is the continuous analogue of transposition). It so happens that the eigenvalues and eigenfunctions of $T^* T$ can be found exactly: doing that will double your score.