

1           **Restratification at a California Current Upwelling Front, Part 1:**

2           **Observations**

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## ABSTRACT

16 A coordinated survey between a subsurface Lagrangian float and a ship  
17 towed Triaxus profiler obtained detailed measurements of a restratifying sur-  
18 face intensified front (above 30 m) within the California Current System. The  
19 survey began as down-front winds incited mixing in the boundary layer. As  
20 winds relaxed and mixing subsided, the system entered a different dynamical  
21 regime as the front developed an overturning circulation with large vertical  
22 velocities that tilted isopycnals and stratified the upper ocean within a day.  
23 The horizontal buoyancy gradient was  $1.5 \times 10^{-6} \text{ s}^{-2}$  and associated with  
24 vorticity, divergence and strain that approached the Coriolis frequency. Es-  
25 timates of vertical velocity from the Lagrangian float reached  $1.2 \times 10^{-3} \text{ m}$   
26  $\text{s}^{-1}$ . These horizontal gradients and vertical velocities were consistent with  
27 submesoscale dynamics that are distinct from the classic quasi-geostrophic  
28 framework used to describe larger-scale flows. Vertical and horizontal gradi-  
29 ents of velocity and buoyancy in the vicinity of the float revealed that sheared  
30 currents differentially advected the horizontal buoyancy gradient to increase  
31 vertical stratification. This was supported by analyses of temperature and  
32 salinity gradients that comprised the horizontal and vertical stratification. Po-  
33 tential vorticity was conserved during restratification at 16 m, consistent with  
34 adiabatic processes. Conversely, potential vorticity near the surface (8 m)  
35 increased, highlighting the role of friction in modulating near surface strat-  
36 ification. The observed increase in stratification due to these submesoscale  
37 processes was equivalent to a heat flux of  $2000 \text{ W m}^{-2}$ , an order of magni-  
38 tude larger than the average observed surface heat flux of  $100 \text{ W m}^{-2}$ .

<sup>39</sup> **1. Introduction**

<sup>40</sup> The upper ocean contains rich variations in temperature ( $T$ ), salinity ( $S$ ), and therefore density  
<sup>41</sup> ( $\rho$ ) that change over mesoscale (100 km) and submesoscale (0.1–10 km) distances. Features  
<sup>42</sup> associated with submesoscale density gradients can contain large horizontal velocity shears that  
<sup>43</sup> induce vorticity,  $\zeta$ , divergence,  $\delta$ , and strain,  $\alpha$  which are as large as the Coriolis parameter,  $f$   
<sup>44</sup> (Shcherbina et al. 2013). This implies Rossby numbers,  $\text{Ro} = \zeta/f \sim 1$ , and dynamics that separate  
<sup>45</sup> submesoscale flows from the quasi-geostrophic (QG) framework used to describe mesoscale and  
<sup>46</sup> large-scale flows. Submesoscale features in the upper ocean have small length-scales yet strong  
<sup>47</sup> horizontal gradients in the presence of low stratification, and therefore can undergo instabilities  
<sup>48</sup> or interact with inertia-gravity waves (IGW) and boundary layer turbulence on timescales that  
<sup>49</sup> are faster than mesoscale flows (Boccaletti et al. 2007; Thomas 2012, 2005; McWilliams et al.  
<sup>50</sup> 2015). Many of the dynamics associated with submesoscale flows withdraw available potential  
<sup>51</sup> energy stored at the front and induce large ageostrophic velocities that convert horizontal buoy-  
<sup>52</sup> ancy gradients into vertical gradients, increasing vertical stratification on timescales that compete  
<sup>53</sup> with surface radiative forcing, pointing to the importance of submesoscale fronts on upper ocean  
<sup>54</sup> stratification. As such, the effects of subgrid scale submesoscale frontal restratification has been  
<sup>55</sup> parameterized for course resolution models (Fox-Kemper et al. 2011), though a full understand-  
<sup>56</sup> ing of these phenomena is incomplete due to the challenges in obtaining observations that capture  
<sup>57</sup> frontal slumping.

<sup>58</sup> Studies have identified an abundance of submesoscale features in influencing the upper ocean  
<sup>59</sup> buoyancy budget (e.g. Rudnick (1999); Mahadevan et al. (2012); Hosegood et al. (2006)). Ob-  
<sup>60</sup> taining detailed observations of submesoscale processes is inherently difficult due to the need for  
<sup>61</sup> high-resolution scalar and velocity fields (0.1–1 km) over a large spatial domain (10–100 km)

62 within short (superinertial, i.e. less than the inertial period,  $T_i = 2\pi/f$ ) timescales. Additionally,  
63 submesoscale flows have spatial and temporal scales comparable to unbalanced IGW, such that  
64 surveys designed to focus on submesoscale temporal and spatial scales alias wave motions. Larger  
65 mesoscale surveys of fronts are particularly designed to smooth out aliased IGW (i.e., Rudnick  
66 (1996)) and not resolve submesoscale variability. As such, a common approach is to evaluate  
67 regions with many sharp gradients within a small domain in a statistical sense (Shcherbina et al.  
68 2013; Mahadevan et al. 2012; Thompson et al. 2016; Buckingham et al. 2016). This manuscript  
69 presents data from a Lagrangian survey that captured the evolution of a single submesoscale sur-  
70 face intensified front as strong ageostrophic flows, with large vertical shears and vertical velocities,  
71 tilt the front over and stratify the mixed layer (ML) within one day.

## 72 **2. Data Collection**

73 The data were collected in the California Current System (CCS) 4 – 5 August 2006, yearday  
74 (yd) 216–217, as part of the ONR Assessing the Effects of Submesoscale Ocean Parameteriza-  
75 tions (AESOP) program. On 30 July 2006 (yd 212), northerly wind stress increased off the coast  
76 near Monterey Bay from near zero to  $0.5 \text{ N m}^{-2}$  over the course of two days. The along shore  
77 winds set up an Ekman transport offshore with an associated upwelling index of 150 (typical  
78 values range 100-200 during upwelling, <https://www.pfeg.noaa.gov/products/las.html>),  
79 and sea surface temperature (SST) that revealed cold water upwelling from the deep along the  
80 coast (Fig. 1).

81 An energized mesoscale field associated with the southward California Current stirred the up-  
82 welled waters with the warmer fresher surface waters offshore to create multiple smaller fronts  
83 and filaments. The front sitting at the edge of upwelled waters became the target of coordinated  
84 surveys that captured different phases of the frontal evolution. The first phase was 1–3 August

85 2006 (yd 213–215) as northerly winds aligned down-front continuously homogenized the upper  
86 30 m (not discussed here). The second phase, 4–5 August 2006 (yd 216–217), occurred as winds  
87 decreased rapidly and the upper 30 m stratified. This restratification phase is the focus of this  
88 study.

89 During each phase, the front was surveyed by two ships simultaneously. *R/V Wecoma* performed  
90 a mesoscale survey of zonal transects set 11 km apart while towing a SeaSoar profiling vehicle  
91 (i.e., mesoscale survey, Fig. 1). Details of the mesoscale survey can be found at Pallàs-Sanz et al.  
92 (2010a,b) and Johnston et al. (2011), which characterize the vertical velocity and turbulence of  
93 the front on scales of 10–40 km. Starting 30 hr later, *R/V Melville* surveyed around a drifting  
94 Lagrangian float (D’Asaro 2003) using a Triaxus profiler, conducting a Lagrangian survey on a  
95 scale of 5 km. The mesoscale structure of the upwelling region evolved considerably between the  
96 two phases, with the front changing from a north-south orientation in phase one that developed  
97 cyclonic curvature in phase two. This was coincident with several mesoscale eddies in the sur-  
98 rounding regions of phase two that acted to squeeze the front together (Pallàs-Sanz et al. 2010b).

99 The Lagrangian float was equipped with two Seabird sensors 1.4 m apart on the top and bottom  
100 of the hull that collected measurements of pressure ( $P$ ), temperature ( $T$ ), and salinity ( $S$ ) every 30 s  
101 which allowed for an estimation of density ( $\rho$ ) and buoyancy,  $b = -g\rho/\rho_o$ , where  $g$  is gravitational  
102 acceleration and  $\rho_o$  is a reference density of  $1024 \text{ kg m}^{-3}$ . When neutrally buoyant, the float was  
103 designed to follow the average three-dimensional motion of the water immediately surrounding it.

104 The flow-through system on *R/V Melville* collected  $T$  and  $S$  at  $\sim 5 \text{ m}$  depth every 30 s providing  
105 a horizontal resolution of roughly 100 m. Shipboard meteorological measurements were used to  
106 estimate air-sea fluxes based on the COARE 3.5 bulk formula.

107 Triaxus was equipped with temperature and conductivity sensors, chlorophyll fluorometer, trans-  
108 missometer, dissolved oxygen sensor, as well as 300 kHz (down-looking) and 1200 kHz (up-

<sup>109</sup> looking) RDI ADCPs. Triaxus profiled between 4 and 140 m depth with a vertical speed of 1 m  
<sup>110</sup> s<sup>-1</sup> and horizontal speed of roughly 3 m s<sup>-1</sup>, providing horizontal resolution of 800 m near the top  
<sup>111</sup> and bottom of the profiles and 400 m in the middle of the profiles. Shear from Triaxus ADCP was  
<sup>112</sup> estimated using a technique similar to the inverse method for processing measurements collected  
<sup>113</sup> with lowered ADCPs (Visbeck 2002).

<sup>114</sup> Satellite SST was used to locate the front followed by an initial Triaxus transect that identified  
<sup>115</sup> the cross-frontal structure in depth. The Lagrangian float was placed in the center of the front tar-  
<sup>116</sup> geting the 23.8 kg m<sup>-3</sup> isopycnal. The float's position was tracked acoustically as it was advected  
<sup>117</sup> downstream by the frontal flow using a TrackPoint II USB system operating at 15 kHz, allowing  
<sup>118</sup> the ship to survey around the float while towing the Triaxus profiler. The survey lasted 30 hr as the  
<sup>119</sup> float traveled roughly 50 km along the front. During this time, the ship circled the float 31 times,  
<sup>120</sup> taking about one hour to complete loops 3–5 km in diameter (Fig. 1).

<sup>121</sup> The circular sampling pattern was well suited for calculating means and first derivatives (but not  
<sup>122</sup> higher) of tracers and vector fields. The objective of the data processing was to project the frontal  
<sup>123</sup> structure from Triaxus onto a transect traced by the float trajectory. Tracer and velocity data were  
<sup>124</sup> averaged into 4 m vertical bins. Cross-frontal sections were defined by density extrema at 4 m (e.g.  
<sup>125</sup> density maximum sets an eastern edge and density minimum sets the western edge) for a total of  
<sup>126</sup> 62 cross-front transects. Loops were defined by two consecutive sections, and each section was  
<sup>127</sup> included in two loops for a total of 61 loops, therefore reducing bias that may result from choice  
<sup>128</sup> in loop definition (Fig. 2). Data in each loop and each vertical level were applied to a plane-fit,  
<sup>129</sup>  $\mathbf{y} = \mathbf{Ax}_1 + \mathbf{Bx}_2 + C$  using a least squares estimate (Deep 2005)

$$\mathbf{F} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} \quad (1)$$

130 where  $\mathbf{X} = (\mathbf{x}_1, \mathbf{x}_2)$ , denotes geographic position with  $\mathbf{x}_1$  and  $\mathbf{x}_2$  being the meridional and zonal  
 131 distances, respectively. The variable to be fit is  $\mathbf{y}$  and  $\mathbf{F}$  contains the gradients ( $A, B$ ) and averages  
 132 ( $C$ ). A 95% confidence interval ( $\varepsilon$ ) associated with the least squares estimation is

$$\varepsilon = c \sqrt{(\mathbf{X}^T \mathbf{X})^{-1} \left( \frac{1}{m} \sum_{i=1}^m (\mathbf{y} - \mathbf{xF})_i^2 \right)} \quad (2)$$

133 where  $m$  is the number of data points in each loop to be fit and  $c$  is the t-test critical value for  $m$ .  
 134 This provides an estimate of error for  $A$  and  $B$  (i.e. gradients). An example (Fig. 2b) shows a  
 135 clear slope in the density field that was captured by the least squares plane fit. The results were  
 136 smoothed further by averaging gradients and means for three consecutive loops ( $n-1, n, n+1$ ),  
 137 that spanned two hours of data. (Fig. 2 a).

138 Gradients were used to calculate vorticity,  $\zeta = \partial v / \partial x - \partial u / \partial y$ , divergence,  $\delta = \partial u / \partial x + \partial v / \partial y$ ,  
 139 and strain  $\alpha = \sqrt{(\partial u / \partial x - \partial v / \partial y)^2 + (\partial v / \partial x + \partial u / \partial y)^2}$  (along with propagated errors), which  
 140 were essential for characterizing the submesoscale. This provided a depth vs. time (or along-front  
 141 distance) view of the water surrounding the float as it was advected by the frontal flow. At times,  
 142 it is more convenient to present results referenced to the frontal orientation. In this case, gradients  
 143 and velocities were rotated in the direction of  $\nabla_h b$  at 4 m, where positive cross-front ( $xf$ ) implies  
 144 down gradient and positive along-front ( $af$ ) is along the direction of geostrophic shear.

145 Objective maps of tracer distributions were produced from the Traixus survey (Le Traon 1990;  
 146 Bretherton et al. 1976) using a Gaussian covariance. Traditionally, anisotropic length-scales are  
 147 chosen for mapping frontal systems. This approach was not adopted here, instead correlation  
 148 length-scales were set to the approximate loop size ( $L_x = L_y = 5$  km) to minimize along front  
 149 changes due to temporal evolution. For example, as the wind stops and the float turns eastward,  
 150 a 5 km swath may contain several loops and up to five hours of data, highlighting the poten-  
 151 tial influence of time-space aliasing inherent in spatially smoothing such rapidly evolving fronts.

152 Nonetheless, objective maps reveal essential qualitative information about the frontal structure.

153 Results presented here use the loop method outlined above, unless noted otherwise.

154 The float-following reference frame allow for a Lagrangian analysis of the front, where measured rates of change can be interpreted as Lagrangian rates of change. This assumption was evaluated by estimating the change in density due to advection as  $\Delta\rho_{ADV} = \int_{t_o}^{t_i} (u - u_{tri}) (\partial\rho/\partial x) + (v - v_{tri}) (\partial\rho/\partial y) dt$ , where  $t_o$  is the beginning of the survey (yd 216.0),  $u_{tri}$  and  $v_{tri}$  are velocities of the survey calculated from the mean location and time of each loop, and  $u$  and  $v$  are the measured velocities of the flow at 4 m. During the survey,  $\Delta\rho_{ADV}$  oscillated between  $\pm 0.1$  kg m $^{-3}$ , with an average  $\Delta\rho_{ADV} = 0.04$  kg m $^{-3}$ . This can be compared to the  $\Delta\rho$  spanned in each loop of 0.5 kg m $^{-3}$ . Oscillations in  $\Delta\rho_{ADV}$  could be attributed to the position of loop relative to a Lagrangian parcel, but on average this does not contribute significantly to the material derivative.

163 The assumption of Lagrangian rates of change verified above is true only in layers that move in the advective frame of the float, an assumption that may not be valid in depth as the front evolves. The ability to assume Lagrangian rates of change at different depths was assessed by integrating shear in depth and time at each vertical bin, such that  $d^{xf} = \int_{t_o}^{t_i} \int_{z_b}^{z_t} (\partial u^{xf}/\partial z) dz dt$ , where  $t_o$  is the beginning of the survey (yd 216.0),  $z_t$  is the upper bin of Triaxus data (4 m), and  $z_b$  is the depth to be considered (Fig. 3). Therefore,  $d^{xf}$  is the distance a parcel of water at depth ( $z_b$ ) traveled relative to 4 m, the closest resolved depth to the float during the time of frontal evolution (see section 4) and is a test of whether the deformation of the initially-surveyed volume is beyond the subsequent survey. For example, at yd = 216.7, a parcel of water at 20 m cannot be approximated by Lagrangian rates of change, and advective terms cannot be ignored. Similarly,  $d_{af}$  can be estimated from along-front shear (not shown), and is less than  $d^{xf}$  (consistent with section 4b). Flows near the surface (i.e., above 12 m) were approximated as Lagrangian rates of change throughout the survey.

<sup>176</sup> **3. Scale Resolution**

<sup>177</sup> Submesoscale motions are energized near the surface (Callies and Ferrari 2013; Shcherbina  
<sup>178</sup> et al. 2013; Thompson et al. 2016) and characterized by small, sharp gradients of buoyancy and  
<sup>179</sup> velocity with typical length scales of 0.1–10 km and  $\zeta \approx f$  that evolve on inertial timescales ( $T_i$   
<sup>180</sup> =  $2\pi/f = 20.3$  hr). Resolving these space and time scales present an observational challenge,  
<sup>181</sup> yet are essential for characterizing the structure of the upper ocean. The influence of observa-  
<sup>182</sup> tion resolution can be readily seen by comparing tracers, velocities, and their respective gradients  
<sup>183</sup> resolved by AVISO (Archiving, Validation and Interpretation of Satellite Oceanographic Data,  
<sup>184</sup> <http://www.marine.copernicus.eu>; >100 km), the mesoscale survey (12 km) and the La-  
<sup>185</sup> grangian survey (5 km) (Table 1).

<sup>186</sup> Objective maps of surface density from the mesoscale and Lagrangian surveys exhibit differ-  
<sup>187</sup> ences in intensity, structure, and position of the same front observed within 30 hours of each other  
<sup>188</sup> (Fig. 4). The surveys aligned initially, yet deviate later as contours of the front between the two  
<sup>189</sup> surveys diverged and wavelike features (here referred to as meanders) resolved by the Lagrangian  
<sup>190</sup> survey were smoothed by the mesoscale survey. The ~10 km wavelength meanders in the objec-  
<sup>191</sup> tive maps were also apparent in the raw data (not shown), and resolved in less than 10 hr by the  
<sup>192</sup> Lagrangian survey, faster than the local inertial period,  $T_i = 20.3$  hr. This suggests the meanders  
<sup>193</sup> were either small scale physical features or superinertial motions and not associated with aliased  
<sup>194</sup> tides or inertial motions. Additionally, the spatial scale of along-front variability was smaller  
<sup>195</sup> than the objective map correlation length scales (10 - 50 km) often used for mesoscale surveys  
<sup>196</sup> (Pallàs-Sanz et al. 2010a; Rudnick 1996).

<sup>197</sup> Tracer and velocity gradients increased with higher spatial resolution (Table 1). This is seen  
<sup>198</sup> qualitatively as isopycnals in the Lagrangian survey squeezed together (Fig. 4) compared with the

mesoscale survey, consistent with a factor of two difference in  $\nabla_h b$  between the surveys (Table 1). The sharper front in the Lagrangian survey was consistent with larger  $\zeta$ ,  $\delta$ , and  $\alpha$ , of  $O(f)$  (Table 1). The fields observed by AVISO and the mesoscale survey catalog a larger-scale flow described by classic QG. This framework predicts a rapid decay in energy and vorticity in the submesoscale, associated with a velocity spectral slope of  $k^{-3}$ . The increase in gradients at smaller scales observed by the Lagrangian survey is more consistent with strong stirring and frontogenesis that sharpens lateral buoyancy gradients near the surface. This results in a shallower velocity spectral slope of  $k^{-2}$ , as previously theorized (Blumen 1978; Klein et al. 2008; Kunze 2019) and observed (Shcherbina et al. 2013; Callies and Ferrari 2013). As such, lower estimates of  $\zeta$ ,  $\delta$ ,  $\alpha$  at larger spatial scales are not simply a result of the smoothed submesoscale field, but are ultimately associated with different dynamics. For example, strain estimated from AVISO were purely geostrophic and resulted from the mesoscale eddy field that acted to stir gradients at the surface and squeeze this front together, an essential ingredient for the submesoscale. On top of this background flow was a submesoscale  $\alpha$  implying local processes acting to strain the front (see section 4b).

Finally, the deviation between the two surveys illustrates time space aliasing challenges of observing rapidly evolving submesoscale features and need to be considered when interpreting such data. Here, the Lagrangian survey clearly illustrates the importance of resolving small scales as the sharp gradients observed here are an important feature of submesoscale flows.

218 **4. Frontal Evolution**

219 *a. Three stages of evolution*

220 The initial Triaxus transect revealed the vertical structure of the surface intensified submesoscale  
221 front above a pycnocline of 30 m (Fig. 5). The entire front was broad with horizontal changes  
222 in density of  $0.9 \text{ kg m}^{-3}$  over 20 km, with evidence of sloping isopycnals deep into the interior  
223 down to 150 m. Embedded in the broad buoyancy gradient was a sharper front with a poten-  
224 tial density anomaly difference  $\Delta\sigma$  of  $0.44 \text{ kg m}^{-3}$  over 4 km between the  $24-24.4 \text{ kg m}^{-3}$   $\sigma$   
225 isopycnals with a  $|\nabla_h b| = 1 \times 10^{-6} \text{ s}^{-2}$ . This sharper portion of the front became the target of the  
226 Lagrangian survey. The entire frontal extent was not captured by the 3–5 km loop sampling pat-  
227 tern aimed to focus on the sharpest part of the front. The evolution of stratification can be divided  
228 into three stages. Stage 1: down-front winds, turbulent mixing, and a homogeneous boundary  
229 layer (BL). Stage 2: Low winds, diurnal warming, frontal slumping and increased stratification.  
230 Stage 3: Night-time surface cooling, increased winds, rapid near surface restratification, and float  
231 subduction (Fig. 6).

232 Stage 1 (yd 216–216.3): Northerly winds that began five days prior had peaked at  $0.5 \text{ N m}^{-2}$   
233 18 hr before the start of the survey. Stage 1 began with a  $0.23 \text{ N m}^{-2}$  down front wind stress that  
234 decreased to  $0.04 \text{ N m}^{-2}$  within 6 hr. The float was placed slightly dense (east) of the front at  
235 the  $24.3 \text{ kg m}^{-3}$  isopycnal and began traveling west towards the light side of the front. During  
236 this time, the sharpest part of the front was only partially resolved. Isopycnals in the upper 30  
237 m were steep as the upper ocean was vertically homogeneous with strong horizontal gradients of  
238 buoyancy (Fig. 7a). For simplicity, the region above 30 m will be referred to as the mixed layer  
239 (ML), though this region was not well mixed throughout the survey.

240 Stage 2 (yd 216.3–216.8): The heat flux changed from cooling to warming and the wind re-  
241 mained less than  $0.02 \text{ N m}^{-2}$ . The float was trapped between 1–2 m such that the float’s antennae  
242 was just below the surface, suggesting a decrease of turbulent mixing (Fig. 6 a, b). The float trajec-  
243 tory slowed down and began to veer shore-ward (east, Fig. 4). At this time, and for the remainder  
244 of the survey, the shipboard survey resolved the sharpest part of the front between 24–24.2 kg  
245  $\text{m}^{-3}$ . During this stage, the frontal flow increased and the vertical isopycnals that defined the front  
246 squeezed closer together (Fig. 4) and began to tilt, stratifying the waters above the pycnocline  
247 (Fig. 6 b, Fig. 7, Fig. 8).

248 Stage 3 (yd 216.8–217.3): The heat flux changed from net warming to cooling, and the wind  
249 stress increased to  $0.09 \text{ N m}^{-2}$  and rotated to an upfront orientation (Fig. 6 c). Along-front  
250 wavelike meanders appeared in the survey and the float downwelled along isopycnals. In the  
251 classic 1-D view, night-time cooling and winds would erode the day-time stratification (e.g. Price  
252 et al. (1986)). Here, stratification in the near surface layer strengthened as warm fresh water slid  
253 over the cold salty side of the front (Fig. 7). The remainder of this manuscript aims to detail the  
254 frontal evolution. It is shown that ageostrophic circulation, associated with strong vertical shear  
255 and large vertical velocity, contributes to ML stratification.

256 *b. Horizontal buoyancy gradient and ageostrophic shear*

257 Horizontal buoyancy gradient was estimated using the loop method outlined in section 2 (Fig. 2)  
258 as well as using the ship underway system assuming  $|\nabla b_s| = |\Delta b / \Delta s|$ , where  $\Delta b$  and  $\Delta s$  are changes  
259 along the ship-track (Fig. 10). Lateral buoyancy gradients,  $|\nabla b_s|$ , were larger in magnitude than  
260 estimated by loop method using Triaxus at 4 m by a factor of 1.7, as gradients revealed by the flow  
261 through system ( $\Delta s \sim 100 \text{ m}$ ) were not fully resolved by Triaxus with  $\sim 800 \text{ m}$  resolution. Lateral  
262 gradients of buoyancy from Triaxus were strongest at the surface, decreased with depth and were

almost non-existent below the pycnocline (100-140 m), consistent with an increasingly surface intensified front (Fig. 9). Never throughout the survey did the front become sub-resolution (i.e., smaller than 100 m), and generally maintained a frontal width of 600 m, smaller than the mixed layer Rossby radius of deformation  $L_D = NH/|f|$  of 5 km, assuming  $H = 30$  m and  $N^2$  averaged over stages 2–3.

Thermal wind balance was evaluated by separating the vertical shear into geostrophic  $\partial \mathbf{u}^g / \partial z = \hat{\mathbf{z}} \times (f^{-1} \nabla_h b)$  and ageostrophic ( $\partial \mathbf{u}^a / \partial z = \partial \mathbf{u} / \partial z - \partial \mathbf{u}^g / \partial z$ ) components (Fig. 11). Here, vertical shear was rotated to the along-front ( $af$ ) and across-front ( $xf$ ) direction (referenced at 4 m, see section 2).

The front was only partially resolved during stage 1, yet was completely resolved by the start of stage 2. After this time, the front continued to strengthen by a factor of 2, with  $|\nabla b_s|$  exceeding  $2 \times 10^{-6} \text{ s}^{-2}$  at the surface (underway along track) within 12 hr. Throughout stages 2 and 3, the frontal structure resolved by the ship flow-through fluctuated from tight and organized to broad, and sometimes fragmented with multiple jumps in buoyancy gradient (Fig. 10). The increase in horizontal buoyancy gradient at the surface was not coincident with an increase in shear as along-front shear at 8 m remained close to zero until stage 3, when it began to approach geostrophic balance. This inhibition of total shear implies strong ageostrophic shear in the near surface that acted to oppose the frontal flow. Along-front shear at 16 m fluctuated with geostrophic shear, as ageostrophic shear, of about  $0.005 \text{ s}^{-1}$ , acted to oppose along-frontal flow. Cross-frontal shear at 16 m and 8 m behaved similarly, increasing before the onset of stage 2 and decreasing towards the end of the survey. It will be shown that this ageostrophic shear was responsible for increasing stratification at the front.

285 *c. Stratification*

286 Stratification in the near surface layer began to increase as turbulent mixing ceased and was co-  
287 incident with day-time warming (see section 4a). Yet the evolution and distribution of stratification  
288 throughout the mixed layer points to the importance of lateral processes through frontal slumping.  
289 This is seen in the different cross-frontal structures of salinity between the beginning and end of  
290 the survey (Fig. 7) and the horizontal spreading of the 24.4 isopycnal at different depths as the  
291 front tilted over (Fig. 8). The distribution of the stratification was not uniform as deeper layers  
292 began to stratify earlier than the surface layers (Fig. 6 b, Fig. 8 a).

293 The lateral slumping of isopycnals was imprinted on the  $T$  and  $S$  structure of the stratification.  
294 Contributions of horizontal (frontal slumping) and vertical (i.e, turbulent mixing, vertical advec-  
295 tion) to stratification changes can be decomposed into vertical and horizontal contributions of  $T$   
296 and  $S$  assuming a linear equation of state,  $\rho = \rho_o + \rho_o(-\alpha_T(T - T_o) + \beta(S - S_o))$ , such that

$$\Delta N^2 \approx g \left[ \alpha_T \frac{\partial T^v}{\partial z} + \alpha_T \frac{\partial T^h}{\partial z} - \beta \frac{\partial S^v}{\partial z} - \beta \frac{\partial S^h}{\partial z} \right], \quad (3)$$

297 where  $\alpha_T = 2.0 \times 10^{-4} \text{ K}^{-1}$  is the thermal expansion coefficient for seawater and  $\beta = 7.5 \times 10^{-4}$   
298  $\text{psu}^{-1}$  is the haline contraction coefficient for seawater. Here,  $\partial T^v/\partial z$ ,  $\partial S^v/\partial z$  are the contribu-  
299 tions from vertical processes, and  $\partial T^h/\partial z$ ,  $\partial S^h/\partial z$  are the vertical gradients due to horizontal  
300 advection. The contribution from  $\partial S/\partial z$  on  $N^2$  was assumed to be from horizontal advection en-  
301 tirely (precipitation and evaporation were negligible), and therefore  $\partial S^v/\partial z = 0$ . Estimating the  
302 contribution from  $\partial T^v/\partial z$  due to vertical processes and heat flux requires knowledge of small scale  
303 turbulence and vertical velocity, and is difficult to calculate here. Yet  $\partial T^h/\partial z$  can be estimated  
304 using knowledge of the horizontal density structure through the density ratio ( $R$ ),

$$R = \frac{\alpha_T \Delta T}{\beta \Delta S}. \quad (4)$$

305 During adiabatic slumping of isopycnals, horizontal changes in  $T$  and  $S$  are converted into vertical  
 306 ones (Johnson et al. 2016). Assuming that the gradients of  $T$  and  $S$  are aligned (as in this case), that  
 307 vertical changes in  $S$  are a result of horizontal advection (therefore  $\partial S^h / \partial z$  is observed entirely),  
 308 and  $R$  is conserved during this process, then

$$\frac{\partial T^h}{\partial z} = \frac{\beta}{\alpha_T} R^h \frac{\partial S^h}{\partial z} \quad (5)$$

309 where  $R^h = \alpha_T \nabla_h T / \beta \nabla_h S$  (Fig. 8b). At 8 m, 80% of the vertical changes in  $T$  can be explained  
 310 by  $\partial T_h / \partial z$  and therefore tilted horizontal gradients, while the remaining 20% can be attributed to  
 311 a combination of day-time solar warming during stage 2, vertical advection and turbulent mixing.  
 312 Using  $\partial T^h / \partial z$  and  $\partial S^h / \partial z$  (but omitting  $\partial T^v / \partial z$ ) in (3) provides an estimate of stratification,  
 313  $N^{2h}$ , that agrees with observed  $N^2$  (Fig. 8 a) and support the conversion of horizontal gradients  
 314 into vertical ones through frontal slumping.

315 Furthermore, changes in the vertical gradients of tracers as a result of differential advection by  
 316 vertical shear can be quantified as

$$\frac{DC_z^{ADV}}{Dt} = -\frac{\partial C}{\partial x} \frac{\partial u}{\partial z} - \frac{\partial C}{\partial y} \frac{\partial v}{\partial z} \quad (6)$$

317 for  $C$  representing tracers  $T, S, b$ . The float provided a Lagrangian reference frame for the Triaxus  
 318 data such that estimates of (6) were made with the advective terms contained within the mate-  
 319 rial derivative (see section 2). Vertical gradients resulting from horizontal advection,  $\partial T^{ADV} / \partial z$ ,  
 320  $\partial S^{ADV} / \partial z$  and  $N^{2ADV}$  were calculated using (6) at 8 m, where the survey was considered La-  
 321 grangian and where shear could be estimated by centered-finite-difference (Fig. 8). The ability  
 322 of (6) to predict the increase in vertical gradients signifies that most changes in  $N^2$ ,  $\partial T / \partial z$ , and  
 323  $\partial S / \partial z$  were due to horizontally sheared currents advecting tracers across the front. The contri-  
 324 bution from vertical advection,  $(\partial C / \partial z)(\partial w / \partial z)$  (calculated assuming continuity), added a 10%  
 325 increase in stratification to (6). This value is within error of  $N^{2ADV}$  and associated with increased

uncertainty such that it was not included in (6). It is concluded that  $N^2$  estimated from (6) and (3) in conjunction with positive cross-front ageostrophic shear present throughout the survey (Fig. 11) support the role of lateral advection of horizontal gradients for increasing stratification and is a major result of this study.

The increase in vertical stratification was used to estimate an equivalent vertical flux of buoyancy,

$$\mathcal{B}_{eq} = \frac{d}{dt} \int_{-H}^0 \int_{-H}^0 N^2 dz dz \quad (7)$$

Integrating total observed  $N^2$  from  $H = 30$  m gives  $\mathcal{B}_{eq} = 9.58 \times 10^{-7} \text{ m}^2 \text{ s}^{-3}$  and a heat flux equivalent,  $Q_{eq} = c_p \rho_o \mathcal{B}_{eq} / g \alpha_T$ , of  $Q_{eq} \sim 2000 \text{ W m}^{-2}$ , where  $c_p$  is the heat capacity of seawater. This was an order of magnitude larger than the average heat fluxed onto the ocean surface during the stratification phases (2 and 3) of  $Q_{avg} \sim 100 \text{ W m}^{-2}$ .

#### *d. Vorticity, divergence and strain*

Vorticity, divergence, and strain were surface intensified and fluctuated throughout the survey (Fig. 9). All approached values of  $O(f)$  near the surface, several times greater than values deeper below the pycnocline (100 - 140 m). In the ocean interior, inertia-gravity waves (IGW) dominate fluctuations in vorticity and divergence such that

$$\frac{D\zeta}{Dt} \approx -(f + \zeta) \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right). \quad (8)$$

This relationship has also been shown to exist along meanders within larger frontal systems (Bower and Rossby 1989; Thomas 2008). To assess the relationship in (8),  $\zeta$  and  $\delta$  were averaged at the surface (4–20 m) and depth (100–140 m) and the right hand side was integrated in time to compare with  $\zeta$  assuming a lagrangian reference frame. Below the ML, where horizontal buoyancy gradient was much less than at the surface (Fig. 9), these terms oscillated with a correlation of

346 0.60. This oscillatory pattern at depth was decoupled from the surface (Fig. 9), where the corre-  
 347 lation at 4–20 m decreased to 0.17. The lack of correlation near the surface indicates that terms  
 348 in the vorticity equation omitted in (8) were non-negligible in the observed flow. This can include  
 349 tilting of horizontal vorticity or frictional torques, and suggest a complicated relationship between  
 350 the sharp front, IGW and boundary layer dynamics.

351 A background strain field estimated from the mesoscale survey to be  $0.3f$  (Pallàs-Sanz et al.  
 352 (2010b)) was attributed to eddies in the surrounding mesoscale field. On top of this background  
 353 strain,  $O(f)$  strain was resolved by the Lagrangian survey (Table 1) that was particular to the  
 354 local dynamics around the front, and was not captured by the mesoscale survey or AVISO. The  
 355 influence of this strain field on  $\nabla b_h$  is captured by the frontogenetic tendency equation associated  
 356 with horizontal advection (Hoskins 1982)

$$F_{hadv} = \frac{1}{2} \frac{\mathrm{D}|\nabla_h b|^2}{\mathrm{D}t} \Big|_{hadv} = \left( -\frac{\partial b}{\partial x} \nabla_h u - \frac{\partial b}{\partial y} \nabla_h v \right) \cdot \nabla_h b \quad (9)$$

357 that includes both the geostrophic and ageostrophic component of the flow (Fig. 12).  $F_{hadv}$  was  
 358 near zero during stage one. After wind forcing ceased,  $F_{hadv}$  fluctuated between frontogenetic  
 359 and frontolytic between yd 216.2–216.6. During this time,  $\nabla_h b$  steadily increased (Fig. 9). The  
 360 largest values of  $F_{hadv}$  at the end of stage 2 and beginning of stage 3 were simultaneous with strong  
 361  $\nabla_h b$ . Although there was consistency between positive frontogenetic tendency and an increase in  
 362 frontal strength, the tendency of  $\nabla_h b$  cannot be explained by integrating (9) in time, including the  
 363 increase at the beginning of stage 2 or the deterioration  $\nabla_h b$  after yd 217. Large errors in  $F_{hadv}$  are  
 364 expected with the multiple derivatives needed to compute (9), and may not represent the true  $F_{hadv}$   
 365 of the front. Additionally, turbulence and vertical velocity may induce a frontal response (Gula  
 366 et al. 2014), that are not resolved here and can be frontolytic and counteract  $F_{hadv}$ .

367 The classic frontogenesis problem of Hoskins and Bretherton (1972) assumes the advection of  
368 momentum by the ageostrophic flow is negligible following the semigeostrophic approximation.  
369 Here, frontogenesis and frontal sharpening occurred in the presence of strong divergence as well as  
370 large ageostrophic, cross front shears. Departures from classic frontogenesis have been explored  
371 in context of submesoscale fronts by Shakespeare and Taylor (2013) and Barkan et al. (2019),  
372 suggesting a regime of submesoscale frontogenesis in addition to that induced by external strain.  
373 In particular, Barkan et al. (2019) explored frontogenesis in the presence of large convergence  
374 and found cross frontal flows to have a reinforcing role on the frontogenetic sharpening rate.  
375 A complete discussion of this observed front in context of different frontogenetic frameworks  
376 would require isolating the relative contributions of the geostrophic and ageostrophic flows in  
377 the frontogenetic function, which cannot be done in this data set (see section 4b). Nonetheless,  
378 the ageostrophic cross front shears along with the increase in strain and divergence resolved by  
379 the Lagrangian survey compared to the mesoscale survey and Aviso (Table 1) are characteristics  
380 consistent with submesoscale frontogenesis.

381 The different horizontal gradients resolved by the mesoscale survey and the Lagrangian survey  
382 lead to contrasting interpretations of frontogenesis. In particular, the sharpening of the front and  
383 positive  $F_{hadv}$  observed by the Lagrangian survey was opposite than predicted by the mesoscale  
384 survey (estimated using a generalized omega equation, Pallàs-Sanz et al. (2010a)) which deduced a  
385 frontolytic circulation resulting from the frontal curvature and associated deformation field. Fronto-  
386 togenesis was a key part of the Lagrangian survey as it strengthened the horizontal buoyancy  
387 gradient and therefore the amount of stratification from horizontal slumping (i.e. through (6)).

388    *e. Vertical Velocity*

389    The float measured pressure and hence depth every 30 s, allowing for direct measurements of  
390    vertical velocity. To minimize high-frequency motions from the float, a LOESS was applied to  
391    30 min of the float's vertical position to obtain an estimate of vertical velocity. During stages 1  
392    and 2 the float was ballasted buoyant and adjusted again before stage 3. During stage 1, the ver-  
393    tical velocity and low stratification were consistent with boundary layer turbulence. After winds  
394    decreased and boundary layer mixing subsided (stages 2 and 3), the float observed four down-  
395    welling events between stratified layers (I–IV on Fig. 13), where the float trajectory implied a  
396    downwelling from the dense side of the front under the lighter side of the front (Fig. 13 c). The  
397    largest of these events was III and is discussed in detail.

398    At yd 216.8 the float's horizontal velocity slowed as it began to downwell at  $1.3 \times 10^{-3}$  mm s<sup>-1</sup>  
399    ( $120$  m d<sup>-1</sup>) across and under the warm side of the front (Fig. 7, Fig. 13 a, c). In the upper 4  
400    m, the float traveled through changes in density and stratification, suggesting the initial sinking was  
401    neither purely turbulent nor purely adiabatic. Below 4 m, the float's density remained constant as  
402    it continued to downwell at  $w = 0.7 \times 10^{-3}$  mm s<sup>-1</sup> ( $60$  m d<sup>-1</sup>). During this time, the float was  
403    caught in an anticyclonic flow as it wrapped westward (Fig. 13a). Throughout the meander, the  
404    float's vertical velocity slowed, nearing zero. At yd 217 the float was automatically set to profile  
405    and no longer tracks the vertical velocity of the water.

406    The downwelling of the float in III occurred on the upstream side of cyclonic flow (Fig. 13a),  
407    with  $\zeta > 0$  and  $\delta < 0$ . This geometry of downwelling was consistent with frontal subduction  
408    observed and modelled previously within larger frontal systems (e.g. Bower and Rossby (1989);  
409    Lindstrom et al. (1997); Spall (1997)). Here, the subduction occurred in the presence of large

410 convergences and a cyclonic flow that could be tied to either along-front variability or IGW, both  
411 which share similar space and time scales and are therefore complicated to separate.

412 The contributions of IGW and frontal dynamics could be achieved theoretically by solving the  
413 Eliassen-Sawyer (ES) equation or the omega equation to obtain the balanced ASC. For exam-  
414 ple, Mahadevan and Tandon (2006) used numerical simulation fields to solve the omega equation  
415 and obtain the contribution of balanced dynamics to the total vertical velocity determined by the  
416 simulation. The residual vertical velocity was then attributed to unbalanced motions. The ES or  
417 omega formulation has been implemented in many mesoscale observations to obtain ACS (e.g.  
418 ES - Thomas (2008), omega equation - Rudnick (1996), generalized omega equation - Pallàs-Sanz  
419 et al. (2010a)). A challenge in this set of observations lies in capturing the nuanced structure of  
420 buoyancy and momentum needed to constrain a submesoscale frontal ASC using these techniques.  
421 This was made unfeasible as the Triaxus survey resolved a narrow and shallow portion of the front  
422 only. The unconstrained boundary conditions influence, and therefore add uncertainty, to the so-  
423 lution. Additionally, the along front curvature, which can play an essential role in a deformation  
424 field, may be aliased IGW and difficult to interpret. The cross frontal extent of the Lagrangian sur-  
425 vey is an example of the trade-off between spatial coverage and temporal aliasing, a balance that  
426 is paramount to observations in the submesoscale regime. The inability to obtain a cross frontal  
427 structure of buoyancy and velocity on a timescale that minimizes temporal aliasing presents a lim-  
428 itation on inversion techniques for submesoscale observations. Any assumptions to approximate  
429 these fields would obfuscate the interpretation of the submesoscale ASC.

430 In lieu of mesoscale inversion techniques, the divergent flow field was used to estimate vertical  
431 velocity (assuming a rigid lid  $w = 0$ )

$$w_\delta = \int_{-8m}^{0m} \delta dz \quad (10)$$

432 with a bottom limit (8 m) set by the vertical extent of the float. During III,  $w_\delta$  predicted down-  
 433 welling, but greatly underestimated the vertical velocities experienced by the float (Fig. 13 b).  
 434 This suggests a highly localized region of downwelling at the front that could not be resolved by  
 435 the 5 km distances used to calculate  $\delta$ . This highly localized vertical velocity is reminiscent of the  
 436 increase in  $\zeta$ ,  $\alpha$ , and  $\delta$  at smaller scales presented in Table 1, and is a feature of the submesoscale  
 437 in general.

438 Finally, the  $T - S$  gradients that comprised the vertical stratification measured by the float were  
 439 similar to the  $T - S$  gradients of the horizontal stratification measured by Triaxus and the ship  
 440 flow-through during the time of subduction (yd 216.8–217, Fig. 13 d), consistent with budgets  
 441 in section 4c. The classic paper by Iselin (1939) recognized the relationship between horizontal  
 442 water mass changes in the winter ML and vertical water mass changes in the thermocline as an  
 443 indicator of wintertime subduction of surface waters into the interior. The horizontal and vertical  
 444  $T - S$  relationship observed by the Lagrangian survey captured this same signature of subduction,  
 445 yet are a result of different dynamics occurring on smaller length and faster temporal scales.

446 *f. Potential vorticity*

447 Ertel potential vorticity (PV)

$$q = (f\hat{\mathbf{z}} + \nabla \times \mathbf{u}) \cdot \nabla b \quad (11)$$

448 is a dynamically relevant tracer and is conserved following fluid parcels unless subject to non-  
 449 conservative forces or diabatic processes (Marshall and Nurser 1992), such that

$$\frac{Dq}{Dt} = 0 \quad (12)$$

450 In the absence of horizontal density gradients, PV conservation implies that the vertical term of  
 451 PV

$$q_v = (f + \zeta)N^2 \quad (13)$$

452 does not change following a fluid parcel. Neglecting derivatives in vertical velocity, the horizontal  
 453 term is

$$q_h = \frac{\partial u}{\partial z} \frac{\partial b}{\partial y} - \frac{\partial v}{\partial z} \frac{\partial b}{\partial x} \quad (14)$$

454 Near fronts, the horizontal term becomes leading order and an important contributor to a fluid  
 455 parcel's PV. If the shear is purely geostrophic, then the horizontal term becomes

$$q_{hg} = -\frac{|\nabla_h b|^2}{f} \quad (15)$$

456 a negative definite quantity in the Northern Hemisphere. The presence of ageostrophic shears  
 457 and surface forcing, which are often crucial to momentum and buoyancy budgets in the ML, can  
 458 influence both  $q_v$  and  $q_h$ . The evolution of PV estimated from this survey (Fig. 14) exhibited two  
 459 different stories: a deeper layer (16 m) where PV was conserved ( $\sim 0$ ), lying underneath a surface  
 460 layer of increasing PV (8 m). The components of PV following the float were used to describe this  
 461 evolution. Thomas (2008) laid out three conditions under which PV at fronts can have near zero

462 PV

463 i. Vertically mixed momentum and buoyancy to create  $N^2 = 0$  and  $|\mathbf{u}_z| = 0$ ;

464 ii. Vortically low PV as  $\zeta \rightarrow -f$  and  $|\nabla_h b| = 0$

465 iii. Baroclinically low PV  $q_h \rightarrow -q_v$

466 In the beginning of the survey, BL turbulence homogenized tracers and momentum throughout the  
 467 ML. This caused a lack of shear and stratification that resulted in close to zero  $q_v$  and  $q_h$  as in (i).

<sup>468</sup> Both terms were smaller than the value associated with geostrophic balance and consistent with  
<sup>469</sup> large ageostrophic shears (Fig. 11).

<sup>470</sup> At the start of stage 2, PV throughout the upper 30 m evolved differently. Deeper in the ML (16  
<sup>471</sup> m), isopycnals began to tilt, causing the once homogeneous ML to stratify and  $q_v$  to increase. The  
<sup>472</sup> tilting of isopycnals (e.g., Fig. 8a) was accompanied by an increase in both horizontal buoyancy  
<sup>473</sup> gradient and vertical shear such that  $q_h$  compensated  $q_v$  as in (iii). This resulted in near zero PV  
<sup>474</sup> through yd 216.7 (at 16 m) after which advective terms may become important and interpretation  
<sup>475</sup> is less clear (see section 2, Fig. 3). At this depth (16 m), changes in  $q_v$  and  $q_h$  tracked  $|\nabla_h b/f|$   
<sup>476</sup> (Fig. 14), demonstrating the balanced state of the front during this time.

<sup>477</sup> PV conservation was not evident in the near surface layer (8 m). During stage 2,  $q_v$  increased  
<sup>478</sup> with stratification. During stage 3,  $q_v$  remained level and decreased slightly as the increase in  
<sup>479</sup> stratification at the end of the survey was offset by a decrease in  $\zeta$  and consistent with the anticy-  
<sup>480</sup> clonic circulation. Unlike the middle of the ML (16 m), changes in  $q_v$  at 8 m were not balanced  
<sup>481</sup> by  $q_h$ . Horizontal buoyancy gradient increased during stage 2, yet strong upfront shear inhibited  
<sup>482</sup> development of  $q_h$  such that  $q_h$  did not approach  $q_{hg}$ . Furthermore, the presence of ageostrophic  
<sup>483</sup> cross-front shear encouraged frontal tilting (Fig. 8) and increased stratification (and therefore  
<sup>484</sup>  $q_v$ ), but did not contribute to  $q_h$  because the along-front buoyancy gradient was, by definition,  
<sup>485</sup> zero. In summary, cross-front shear resulted in an increase in  $q_v$  through  $N^2$ , while along-front  
<sup>486</sup> ageostrophic shear inhibited  $q_h$ , such that  $q_v$  and  $q_h$  did not balance and total  $q$  increased. This  
<sup>487</sup> reveals the importance of ageostrophic shear in modulating PV at 8 m.

<sup>488</sup> The relationship between horizontal and vertical PV is an important part of understanding sub-  
<sup>489</sup> mesoscale frontal dynamics as was captured by the loop method here. This balance was not  
<sup>490</sup> maintained by the objectively mapped fields that underestimated  $q_h$  and therefore predicted an in-  
<sup>491</sup> crease in total  $q$  at 16 m. The difference in PV between the loop method and the objective maps

492 highlights the challenge in estimating and interpreting observed PV at submesoscale fronts, where  
493 the horizontal component of PV plays an essential role and therefore needs to be resolved.

494 **5. Discussion**

495 A Lagrangian survey, processed on spatial scales of 5 km (diameter of the looped survey pattern)  
496 and temporal scales of 2 hours (time-span contained in one data point), revealed surface intensified  
497 gradients of buoyancy and velocity as well as vertical velocities that were larger than the accom-  
498 panying mesoscale survey or estimates from AVISO (Table 1, Fig. 1, Fig. 4). Horizontal gradient  
499 magnitudes were largest near the surface and decayed with depth. These patterns are not consis-  
500 tent with a classic QG framework, but instead are signatures of the submesoscale range. Flows  
501 approaching  $\text{Ro} = \zeta/f \sim 1$ , are better described by a semi-geostrophic framework and result in  
502 shallower velocity spectral slopes of  $\sim k^{-2}$  at high wavenumbers as found in model studies that  
503 resolve the submesoscale (Capet et al. 2008; Klein et al. 2008). This is also consistent with  $\sim k^{-2}$   
504 spectral slopes observed near the surface that are not predicted by estimates using satellite alti-  
505 try or found deeper below the ML (Shcherbina et al. 2013; Callies and Ferrari 2013). Spectral  
506 slopes of  $\sim k^{-2}$  result from a velocity field influenced by frontogenesis, instabilities, and large  
507 ageostrophic motions, all which manifest signatures at this front. Here, the large values of vor-  
508 ticity, divergence and strain may result from a combination of frontal dynamics and IGWs within  
509 the ML. These balanced and unbalanced velocities are intertwined in the ML, yet are decoupled  
510 from an internal wave field observed at depth as gradients of buoyancy and velocity decay below  
511 the pycnocline.

512 The coordinated mesoscale and Lagrangian surveys provided a nested view of this submesoscale  
513 front. Yet the two surveys document different phenomena. The mesoscale survey described by  
514 Pallàs-Sanz et al. (2010a) and Johnston et al. (2011) spanned 130 km meridionally, 70 km zonally

and 16 - 355 m vertically. In contrast, the Lagrangian survey spanned 5 km across the front and 50 km in the along front direction. The Lagrangian survey was located in the northwest quadrant of the mesoscale survey and overlapped with four Seasor tracks that were set 11 km apart (Fig. 4). Pallàs-Sanz et al. (2010b) and Johnston et al. (2011) used a generalized omega equation and the classic QG omega equation, respectively, to discuss the frontal response to deformation fields and its impact on the turbulence and tracer distribution at the front. These results showed that strong ASC developed as a response to the external deformation field (Pallàs-Sanz et al. 2010a) as surrounding mesoscale eddies strain the front. Additionally, Johnston et al. (2011) mapped a deep chlorophyll maximum around 100 m (a feature seen deep in the Triaxus data as well), consistent with strong downwelling on the edge of the neighboring eddy. An ASC derived from the mesoscale fields using a generalized omega equation approach (Pallàs-Sanz et al. 2010a), predicts frontolysis due to ageostrophic velocities from the frontal curvature in the domain of the Lagrangian survey. Conversely, the Lagrangian survey documented frontal strengthening simultaneous with ageostrophic cross-frontal shear, float subduction and tilting isopycnals, consistent with a restratifying ASC, though not formally quantified here. The frontal curvature deviates between the Lagrangian and the mesoscale survey (Fig. 4), a result of the rapidly evolving and tilting submesoscale front and therefore is not comparable to the curve in the mesoscale survey.

The difference in frontogenesis between the two surveys reiterate the multiple scales of processes that occur in a single region and presents an inconsistency with the near surface frontal dynamics and those happening deeper (i.e. 5-20 m vs. 20-100 m). The mesoscale ASC was calculated using an objectively mapped buoyancy and flow field with decorrelation lengths comparable to the entire extent of the Lagrangian survey and a rigid lid assumption that set  $w = 0$  at 16 m. It therefore was not targeted to isolate the large near surface vertical velocities, high shears, or frontal restratification observed in the upper 10 m of the Lagrangian survey. The near

539 surface frontogenesis observed by the Lagrangian survey is reminiscent of the submesoscale fron-  
540 togenesis discussed in Shakespeare and Taylor (2013) and Barkan et al. (2019), distinctly different  
541 from those explored in the classic or generalized omega equations. The mesoscale and Lagrangian  
542 surveys each resolved different frontogenetic regimes, yet neither survey captured the processes  
543 occurring on multiple scales simultaneously.

544 Satellite SST (Fig. 1) revealed filaments and meanders along the upwelling front suggest-  
545 ing along front variability. Furthermore, the Lagrangian survey observed large horizontal gra-  
546 dients, frontogenetic tendency, vertical velocities and possible meandering structures consistent  
547 with frontal baroclinic instabilities (mixed layer instabilities, MLI, (Boccaletti et al. 2007)). MLI  
548 baroclinic waves grow with length-scales that follow  $L_D$  (here, 5 km), and a timescale of days.  
549 These waves release available potential energy by converting horizontal stratification into a verti-  
550 cal one. While the along-front variability of 5–10 km (Fig. 4) may be consistent with growing  
551 baroclinic waves, the rapid stratification of this front (i.e. less than the inertial period,  $T_i = 20.3$   
552 hr) presents an inconsistency between the observations and MLI theory. Additionally, it was im-  
553 possible to isolate the physical along-front variability from temporal IGW. Therefore the role of  
554 MLI remains illusive.

555 A characteristic of this front was the non-conservation of PV near the surface as the ageostrophic  
556 shear impeded growth of the  $q_h$  while stratification ( $q_v$ ) increased. Surface friction due to wind  
557 driven or geostrophic stress can modulate shear and therefore PV. The role of wind driven and  
558 geostrophic shear at fronts are usually explored in steady state (Thomas and Lee 2005; Thompson  
559 2000; Cronin and Kessler 2009; Wenegrat and McPhaden 2015; McWilliams et al. 2015) and  
560 therefore assuming subinertial timescales. Previous observations have isolated ageostrophic shears  
561 in the presence of geostrophic currents on timescales of days (Lee and Eriksen 1996) and months  
562 (Cronin and Kessler 2009) that satisfy the Ekman relation, rotating right and decreasing with depth.

563 Ageostrophic shear averaged throughout this survey reveal a similar rotation profile in depth (not  
564 shown). Not surprisingly, this Ekman like pattern is absent in instantaneous profiles. Additionally,  
565 using average shear in place of instantaneous shear in (6) underestimates stratification by 60%.  
566 These discrepancies highlight the importance of unsteady forcing and superinertial fluctuations in  
567 shear for increasing stratification at this front and modulating PV near the surface.

## 568 6. Conclusion

569 A highly detailed process study captured the restratification of a surface intensified submesoscale  
570 front in the California Current System on superinertial timescales. The survey pattern allowed for  
571 reliable calculation of vertical and horizontal gradients in a Lagrangian framework and showed  
572 that vertical gradients in  $b$ ,  $T$ , and  $S$  were a result of differential advection of horizontal gradi-  
573 ents by ageostrophic cross front vertical shear. The increase in stratification resulting from frontal  
574 slumping was equivalent to a flux of buoyancy of  $2000 \text{ W m}^{-2}$ , compared to an average heat  
575 flux of  $100 \text{ W m}^{-2}$  during the restratification phases (2 and 3). Strong ageostrophic circulation  
576 was accompanied by vertical velocities reaching  $1.3 \times 10^{-3} \text{ mm s}^{-1}$  ( $120 \text{ m d}^{-1}$ ), as well as  $\zeta$ ,  $\delta$   
577 and  $\alpha$  that approached the Coriolis frequency. These features are a departure from the classic QG  
578 framework and are characteristic of a submesoscale regime. Frontogenesis and the strengthening  
579 of the horizontal buoyancy gradient played a key role in frontal evolution, transferring energy to  
580 smaller scales (through frontal sharpening) and influencing the upper ocean buoyancy budget (by  
581 increasing stratification due to horizontal slumping). The increase in stratification was accompa-  
582 nied by an increase in the vertical component of PV. In the middle of the ML (16 m), the increase  
583 in vertical PV was balanced by decreases in horizontal PV and evidence of PV conservation. This  
584 relationship did not exist near the surface (8 m), as vertical PV increased without compensation  
585 from the horizontal component. The results presented here point to the importance of near sur-

586 face Ekman dynamics and frontal instabilities, which are explored in a companion manuscript  
587 combining these observations with idealized models.

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TABLE 1. Values for scalars, velocities, and their gradients resolved at different observational scales.

	AVISO	SEASOAR	TRIAXUS	FLOAT
SCALES	>100 km	12 km	5 km	0.5 km
$\zeta$	$0.03f\text{ s}^{-1}$	$0.15f\text{ s}^{-1}$	$0.7f\text{ s}^{-1}$	—
$\delta$	$0.001f\text{ s}^{-1}$	$0.03f\text{ s}^{-1}$	$0.7f\text{ s}^{-1}$	—
$\alpha$	$0.10f\text{ s}^{-1}$	$0.13f\text{ s}^{-1}$	$1.2f\text{ s}^{-1}$	—
$\nabla_h b$	—	$0.32 \times 10^{-6}\text{ s}^{-2}$	$1.4 \times 10^{-6}$	—
KE	$0.12\text{ m}^2\text{ s}^{-2}$	$0.27\text{ m}^2\text{ s}^{-2}$	$0.27\text{ m}^2\text{ s}^{-2}$	—
$w$	—	$5 \times 10^{-5}\text{ m s}^{-1}$	$20 \times 10^{-5}\text{ m s}^{-1}$	$100 \times 10^{-5}\text{ m s}^{-1}$

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- Fig. 1.** SST off the California Coast on 4 August 2006 from the Group for High Resolution SST (GHRSSST - <https://podaac.jpl.nasa.gov>). Contours are AVISO positive (solid) and negative (dashed) mean sea level anomaly. White dots outline the mesoscale survey ship track described in Pallàs-Sanz et al. (2010b); Johnston et al. (2011). Block dots outline the Lagrangian survey ship track. Inset) Detail of sea surface temperature (SST), the mesoscale survey (white), and the Lagrangian float track (black dots). The ship track is colored with ship underway temperature. . . . .

**Fig. 2.** a) Example of loops from underway data. A plane was fit to each loop, e.g. n1 (blue), n (red), and n+1 (green). Values from each plane fit were averaged together to form a single value for n. Each loop contained one hour of data, therefore each value for n contained two hours of data. b) An example plane fit to potential density over one loop of Traixus data at 4 m. Black circles are the observed data, and grey circles are projections of the observations onto the plane fit (1). The difference between the grey and black dots were used to estimate 95% confidence interval,  $\epsilon$  in (2). . . . .

**Fig. 3.** Lagrangian analysis - Deformation distance at depth from initial volume. x-dist is the cross-frontal distance in the reference frame of the float as a function of time. The dashed line is the ship track, where each zigzag in time represents one loop. Colored lines are  $d^{xf}$  as described in section 2 and represent the distance a particle of water at depth z has been advected relative to the float. This can be used to assess the Lagrangian assumption of the survey. For example, at yd=216.7 (dashed line),  $d^{xf}$  implies that flow at 20 m is no longer true to the Lagrangian reference set at the beginning of the survey. While flow at 8 m is considered in the Lagrangian reference frame throughout the span of the observations. . . . .

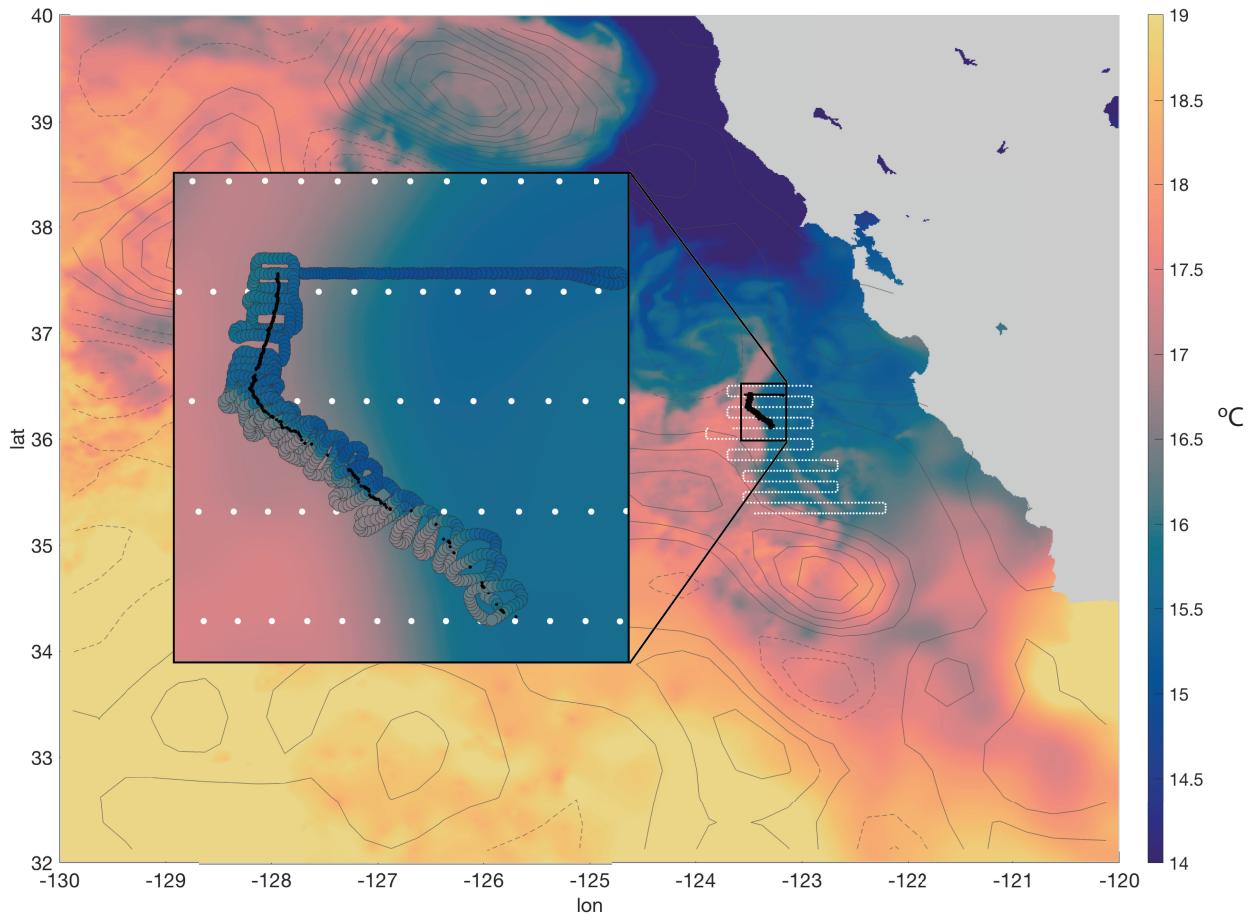
**Fig. 4.** Objective maps of potential density for the mesoscale survey at 16 m (background) in both a) and b), and the Lagrangian survey (foreground) at a) 4 m and b) 16 m). Distances are meridional (y-axis) and zonal (x-axis). Contours outline isopycnals every  $0.1 \text{ kg m}^{-3}$ . The float track (grey dots) and SeaSoar transect (white triangles) are included for reference. Yearday at two latitudes show time separation between the mesoscale and Lagrangian surveys. The tightly looped Traixus track has been excluded for clarity, refer to Fig. 1. . . . .

**Fig. 5.** Initial transect used to identify the front before placement of the float. a) cross-frontal potential density from the ship flow through system. b) cross-frontal potential density from Traixus. Black lines are isopycnal contours of  $0.1 \text{ kg m}^{-3}$  and the dark black line is the  $24.4 \text{ kg m}^{-3}$  isopycnal. . . . .

**Fig. 6.** Scalars and velocity of the front surrounding the float throughout the Lagrangian survey in depth and time. Values are means from the loops (see section 2). a) potential density and float depth (grey dots); b)  $N^2$ ; c) along-front wind stress (green) and cross-front wind stress (purple),  $Q_{NET}$  positive into the ocean (grey); d) salinity; e) zonal velocity  $u$ ; f) zonal shear  $u_z$ ; g) temperature; h) meridional velocity  $v$ ; and i) meridional shear  $v_z$ . Dashed grey lines denote the three stages outlined in section 4. . . . .

**Fig. 7.** Raw Traixus salinity [PSU] a) at the beginning of the survey, stage 1, yd 216.1 and b) at the end of the survey, stage 3, yd 216.8. Potential density is contoured every  $0.1 \text{ kg m}^{-3}$  with the solid contour marking the  $24.3 \text{ kg m}^{-3}$  isopycnal. Circles denote the position of the float within  $\pm 15$  min of the transect and are colored by the average salinity measured by the float's sensors. . . . .

819	<b>Fig. 8.</b>	a) Objective map of potential density at 4 m. The map has been rotated to follow the float 820 trajectory (orange dots) during stages 2 and 3. The grey scale lines denote the $24.4 \text{ kg m}^{-3}$ 821 isopycnal at different depths. b) Vertical gradients discussed in section 4a. top to bottom: 822 $N^2$ , $\partial T/\partial z$ , and $\partial S/\partial z$ at 8 m. Black lines are observations, purple lines are integrated 823 values from (6). Blue dashed lines are the difference between the observations (black) and 824 integrated (purple) values. The red line in the top plot is $N^2$ calculated from (3). Green line 825 in the middle plot is estimated from (5). Scaled float depth is included for reference. Shaded 826 regions are 95% confidence intervals ( $\epsilon$ ). . . . .	49
827	<b>Fig. 9.</b>	(a) $\zeta/f$ , (b) $\alpha/f$ , (c) $\delta/f$ , and (d) $\nabla_h b/f^2$ plotted against time at depths 4 through 20 m 828 and averaged between 100-140 m. Float depth scaled by $\times 10^3$ (grey dots) are included for 829 reference. Shaded regions are 95% confidence intervals ( $\epsilon$ ) at 4 m. . . . .	50
830	<b>Fig. 10.</b>	$ \nabla_h b  [\text{s}^{-2}]$ calculated along the ship track (color) and float positions (grey dots) rotated 831 along the average trajectory of the float during stage 2 and 3. Inset) example of a cross-front 832 transect of potential density resolved by the underway (purple) and Triaxus at 4 m (blue). . . . .	51
833	<b>Fig. 11.</b>	Geostrophic shear, $\widehat{k \times (\nabla_h b f^{-1})}$ (red), ageostrophic shear (purple), and total shear (blue) 834 for a) along-front ( $u_z^{af}$ ) at 8 m, b) cross-front ( $u_z^{xf}$ ) at 8 m, c) along-front ( $u_z^{af}$ ) at 16 m, d) 835 cross-front ( $u_z^{xf}$ ) at 16 m. All terms have been rotated to align with $\nabla_h b$ at 4 m (section 2.2). 836 Shaded regions are 95% confidence intervals ( $\epsilon$ ). . . . .	52
837	<b>Fig. 12.</b>	Frontogenetic tendency ( $F_{hadv} [\text{s}^{-5}]$ ) as a function of time at $z = 8 \text{ m}$ . Shaded regions are 838 95% confidence intervals ( $\epsilon$ ). . . . .	53
839	<b>Fig. 13.</b>	Vertical velocity and float subduction. a) 3-D float subduction. The float's positions (circles) 840 are colored by salinity. The float's trajectory is shown at the surface (black) and pro- 841 jected again at 10 m. Each float location and velocity vector is connected by a dashed grey 842 line. b) Vertical velocity estimated directly from the pressure measured by the float (purple) 843 and using the divergence calculated from Triaxus (green). c) Cross-frontal distance of the 844 float as it downwelled under the front during events I–IV. d) $T - S$ diagram during down- 845 welling events III. The float's two sensors (P1, yellow and P2, gold) and Triaxus (green) 846 captured $T - S$ changes of the vertical stratification during the downwelling event, while the 847 ship underway (purple) provided $T - S$ changes of the horizontal stratification. In all plots, 848 downwelling events are labeled according to section 4e . . . . .	54
849	<b>Fig. 14.</b>	PV ( $q$ , black), the vertical term of PV ( $q_v$ , blue) and the horizontal term of PV ( $q_h$ , green) at 850 a) 8 m and b) 16 m. Both plots include planetary PV ( $N^2 f$ , purple) and the horizontal term 851 in PV if the flow were in thermal wind balance ( $q_{hg}$ , dashed blue and $-q_{hg}$ , dashed green). 852 Shaded regions are 95% confidence intervals ( $\epsilon$ ). . . . .	55



853 FIG. 1. SST off the California Coast on 4 August 2006 from the Group for High Resolution SST -  
 854 https://podaac.jpl.nasa.gov). Contours are AVISO positive (solid) and negative (dashed) mean sea level anomaly.  
 855 White dots outline the mesoscale survey ship track described in Pallàs-Sanz et al. (2010b); Johnston et al.  
 856 (2011). Block dots outline the Lagrangian survey ship track. Inset) Detail of sea surface temperature (SST),  
 857 the mesoscale survey (white), and the Lagrangian float track (black dots). The ship track is colored with ship  
 858 underway temperature.

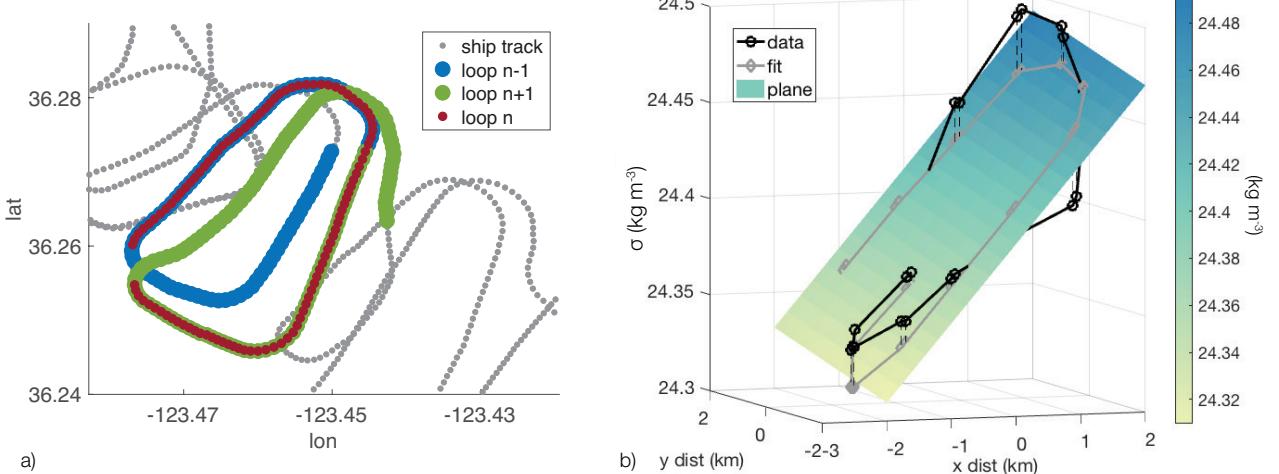
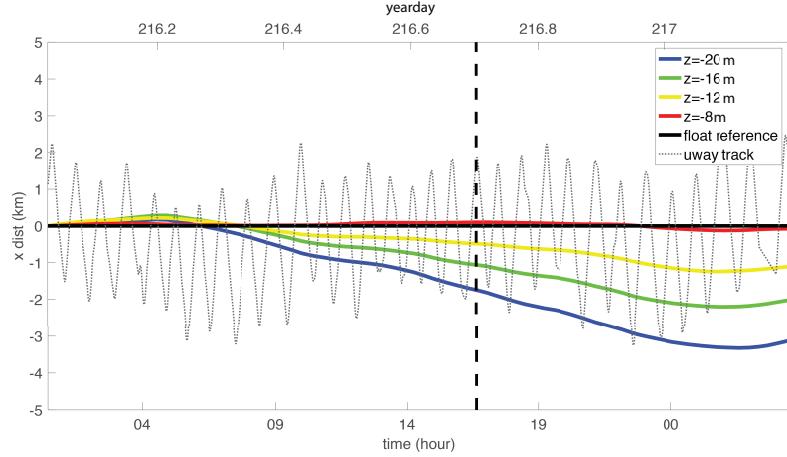


FIG. 2. a) Example of loops from underway data. A plane was fit to each loop, e.g. n1 (blue), n (red), and n+1 (green). Values from each plane fit were averaged together to form a single value for n. Each loop contained one hour of data, therefore each value for n contained two hours of data. b) An example plane fit to potential density over one loop of Traixus data at 4 m. Black circles are the observed data, and grey circles are projections of the observations onto the plane fit (1). The difference between the grey and black dots were used to estimate 95% confidence interval,  $\epsilon$  in (2).



865 FIG. 3. Lagrangian analysis - Deformation distance at depth from initial volume.  $x\text{-dist}$  is the cross-frontal  
 866 distance in the reference frame of the float as a function of time. The dashed line is the ship track, where each  
 867 zigzag in time represents one loop. Colored lines are  $d^{xf}$  as described in section 2 and represent the distance a  
 868 particle of water at depth  $z$  has been advected relative to the float. This can be used to assess the Lagrangian  
 869 assumption of the survey. For example, at  $yd=216.7$  (dashed line),  $d^{xf}$  implies that flow at 20 m is no longer true  
 870 to the Lagrangian reference set at the beginning of the survey. While flow at 8 m is considered in the Lagrangian  
 871 reference frame throughout the span of the observations.

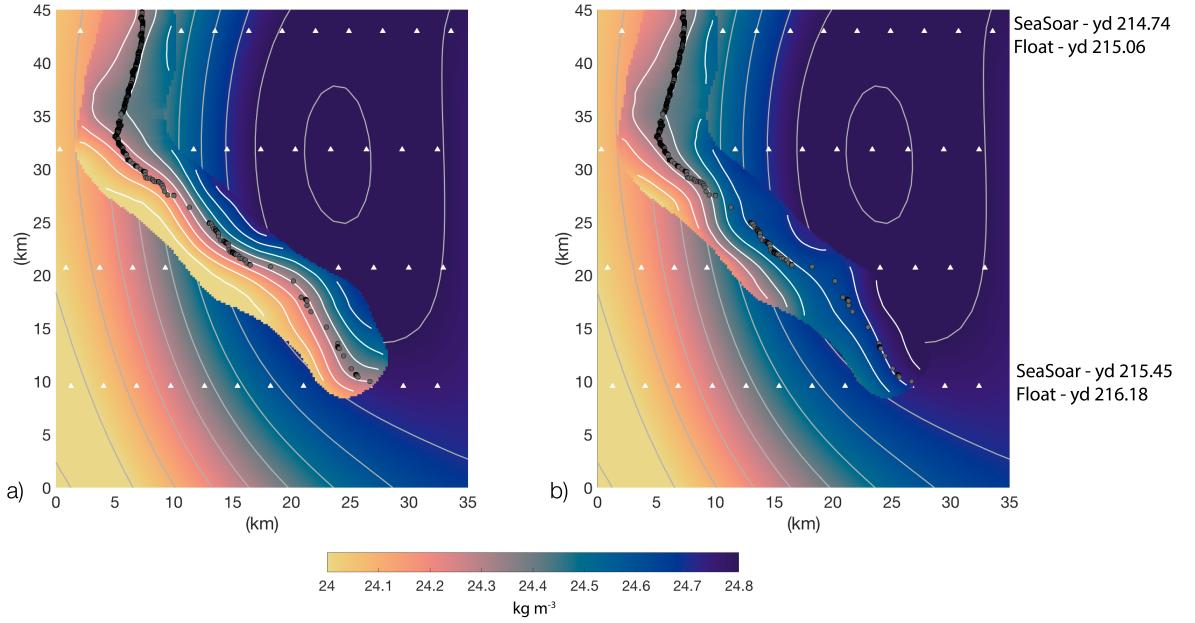
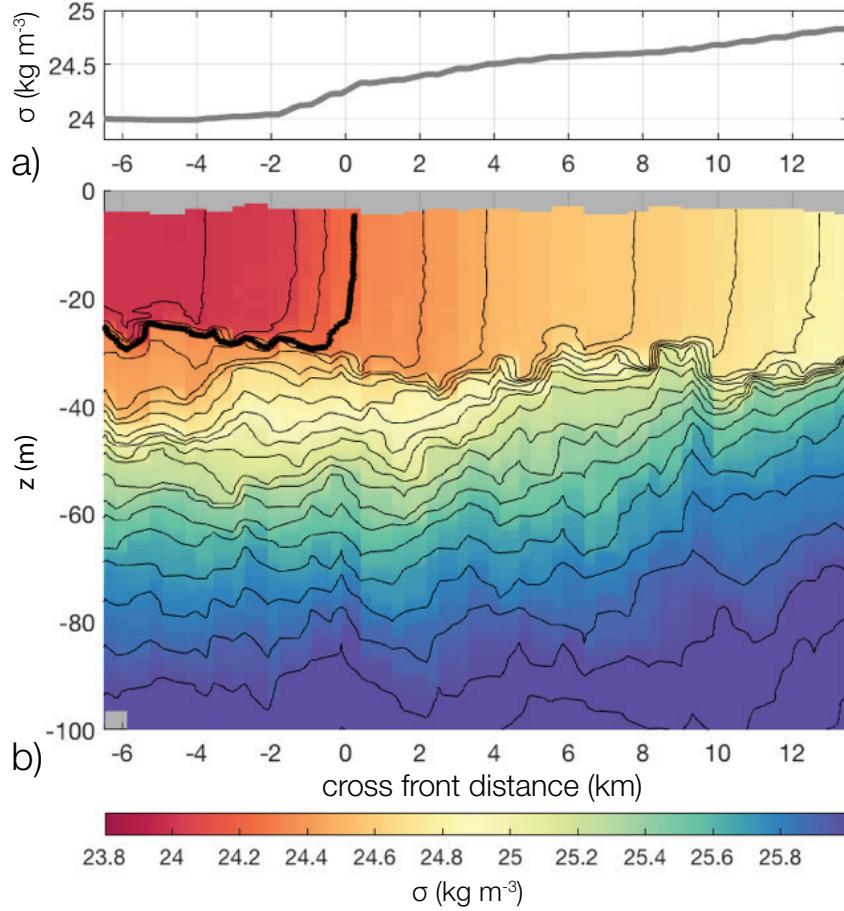


FIG. 4. Objective maps of potential density for the mesoscale survey at 16 m (background) in both a) and b), and the Lagrangian survey (foreground) at a) 4 m and b) 16 m). Distances are meridional (y-axis) and zonal (x-axis). Contours outline isopycnals every  $0.1 \text{ kg m}^{-3}$ . The float track (grey dots) and SeaSoar transect (white triangles) are included for reference. Yearday at two latitudes show time separation between the mesoscale and Lagrangian surveys. The tightly looped Triaxus track has been excluded for clarity, refer to Fig. 1.



877 FIG. 5. Initial transect used to identify the front before placement of the float. a) cross-frontal potential density  
 878 from the ship flow through system. b) cross-frontal potential density from Triaxus. Black lines are isopycnal  
 879 contours of  $0.1 \text{ kg m}^{-3}$  and the dark black line is the  $24.4 \text{ kg m}^{-3}$  isopycnal.

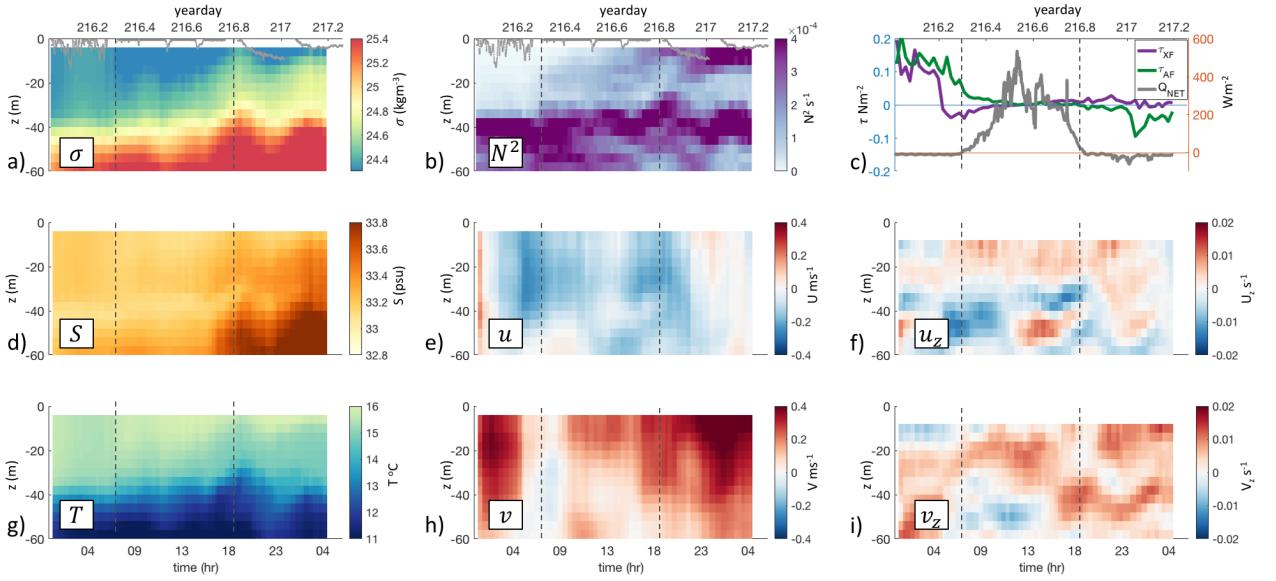
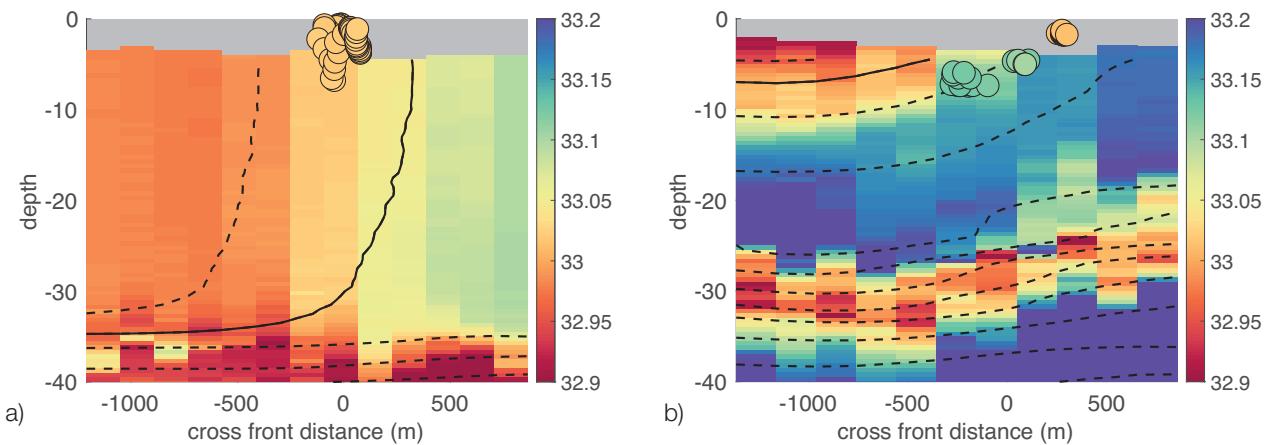


FIG. 6. Scalars and velocity of the front surrounding the float throughout the Lagrangian survey in depth and time. Values are means from the loops (see section 2). a) potential density and float depth (grey dots); b)  $N^2$ ; c) along-front wind stress (green) and cross-front wind stress (purple),  $Q_{NET}$  positive into the ocean (grey); d) salinity; e) zonal velocity  $u$ ; f) zonal shear  $u_z$ ; g) temperature; h) meridional velocity  $v$ ; and i) meridional shear  $v_z$ . Dashed grey lines denote the three stages outlined in section 4.



885 FIG. 7. Raw Triaxus salinity [PSU] a) at the beginning of the survey, stage 1, yd 216.1 and b) at the end of the  
 886 survey, stage 3, yd 216.8. Potential density is contoured every  $0.1 \text{ kg m}^{-3}$  with the solid contour marking the  
 887  $24.3 \text{ kg m}^{-3}$  isopycnal. Circles denote the position of the float within  $\pm 15$  min of the transect and are colored  
 888 by the average salinity measured by the float's sensors.

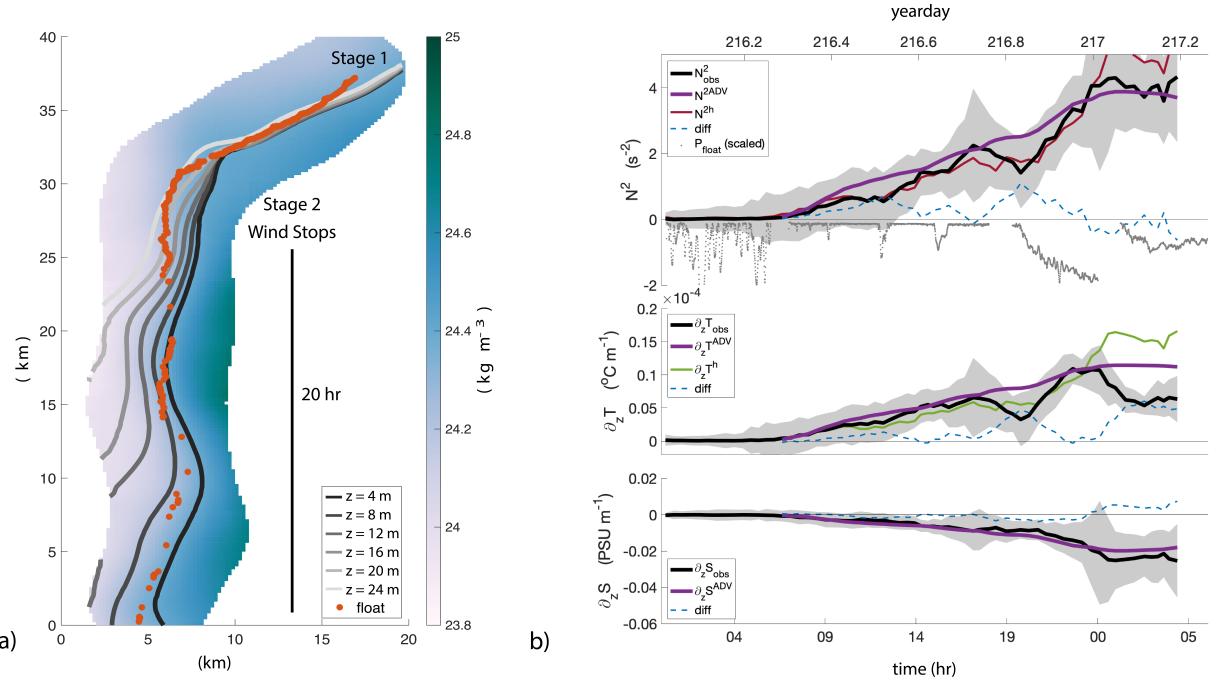


FIG. 8. a) Objective map of potential density at 4 m. The map has been rotated to follow the float trajectory (orange dots) during stages 2 and 3. The grey scale lines denote the  $24.4 \text{ kg m}^{-3}$  isopycnal at different depths. b) Vertical gradients discussed in section 4a. top to bottom:  $N^2$ ,  $\partial T / \partial z$ , and  $\partial S / \partial z$  at 8 m. Black lines are observations, purple lines are integrated values from (6). Blue dashed lines are the difference between the observations (black) and integrated (purple) values. The red line in the top plot is  $N^2$  calculated from (3). Green line in the middle plot is estimated from (5). Scaled float depth is included for reference. Shaded regions are 95% confidence intervals ( $\epsilon$ ).

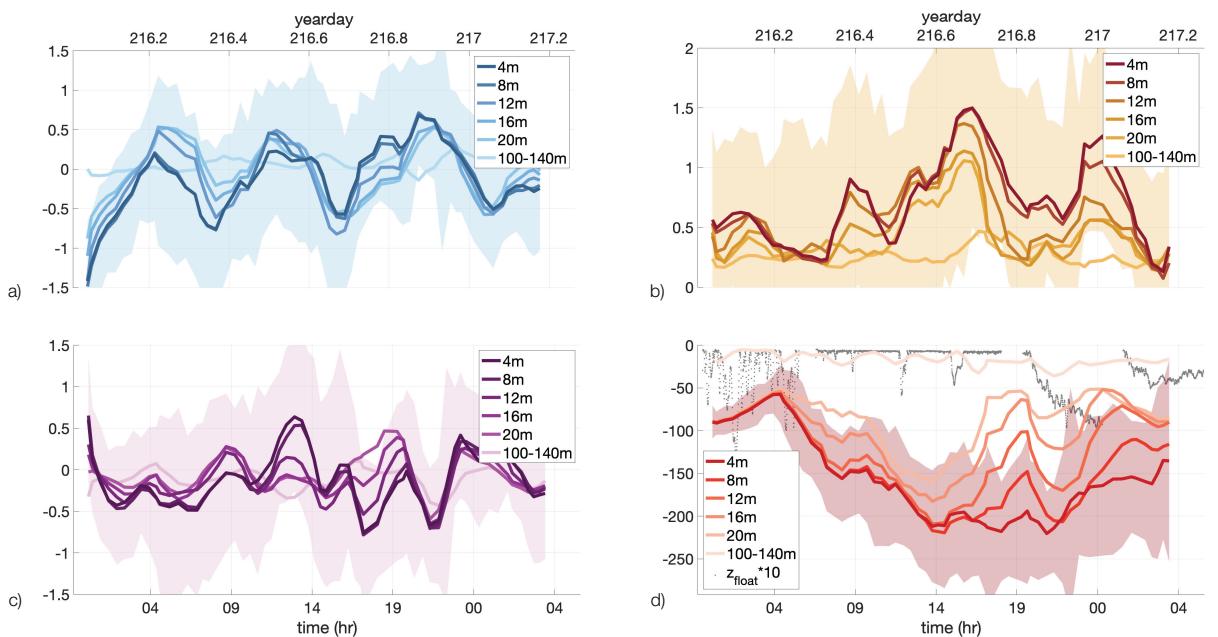
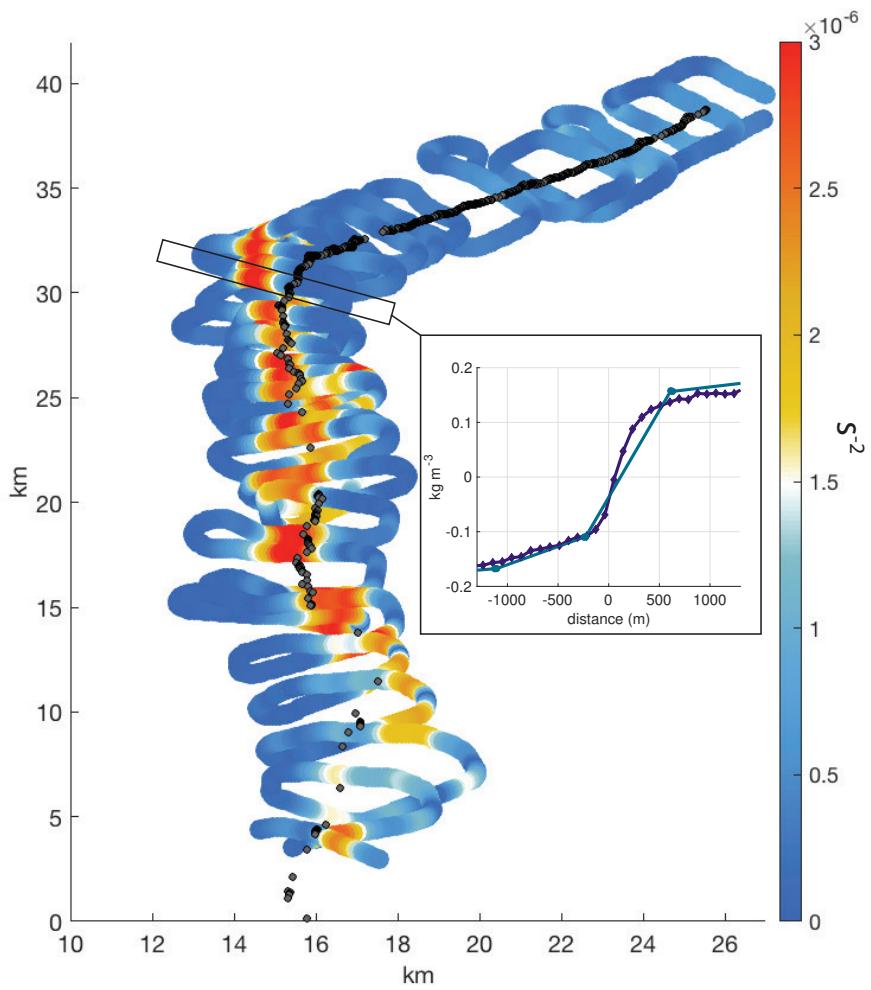
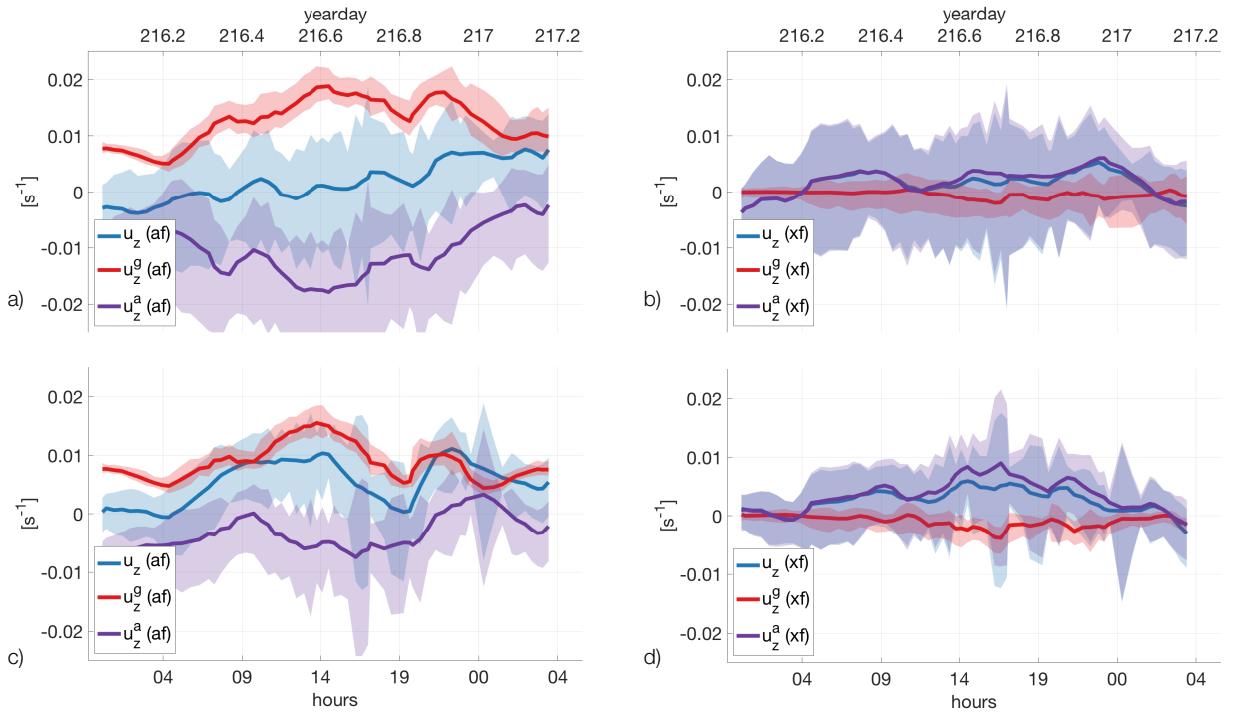


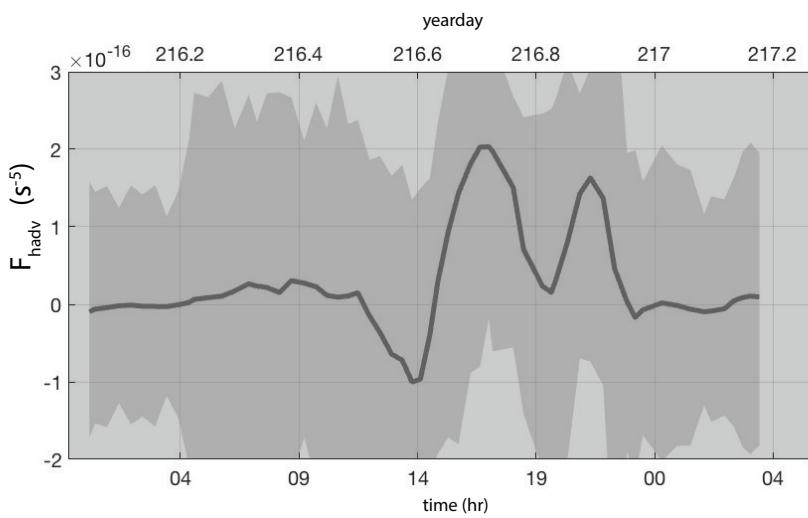
FIG. 9. (a)  $\zeta/f$ , (b)  $\alpha/f$ , (c)  $\delta/f$ , and (d)  $\nabla_h b / f^2$  plotted against time at depths 4 through 20 m and averaged between 100-140 m. Float depth scaled by  $\times 10^3$  (grey dots) are included for reference. Shaded regions are 95% confidence intervals ( $\varepsilon$ ) at 4 m.



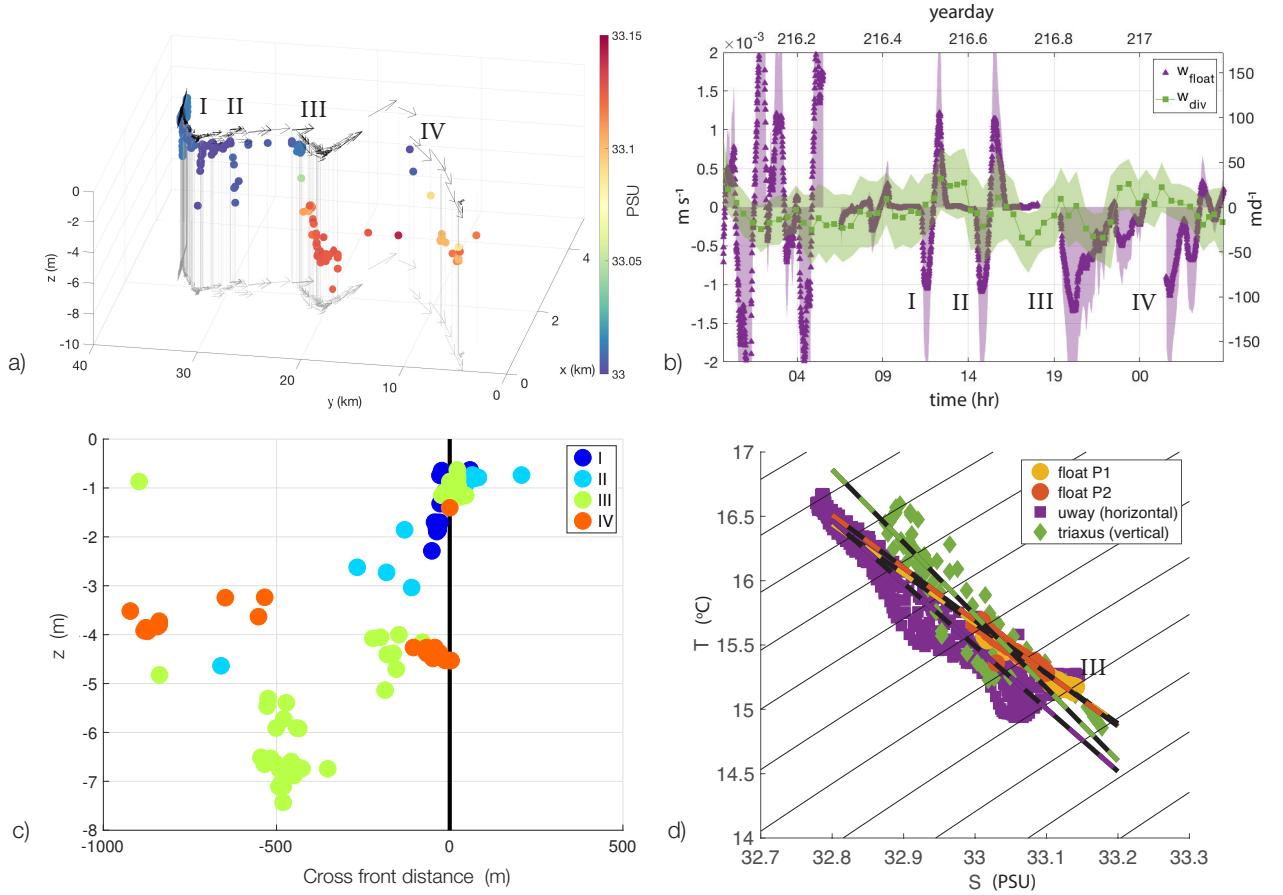
899 FIG. 10.  $|\nabla_h b|$  [ $\text{s}^{-2}$ ] calculated along the ship track (color) and float positions (grey dots) rotated along the  
 900 average trajectory of the float during stage 2 and 3. Inset) example of a cross-front transect of potential density  
 901 resolved by the underway (purple) and Triaxus at 4 m (blue).



902 FIG. 11. Geostrophic shear,  $\hat{k} \times (\nabla_h b f^{-1})$  (red), ageostrophic shear (purple), and total shear (blue) for a)  
903 b) cross-front ( $u_z^{xf}$ ) at 8 m, c) along-front ( $u_z^{af}$ ) at 16 m, d) cross-front ( $u_z^{xf}$ ) at 16 m.  
904 All terms have been rotated to align with  $\nabla_h b$  at 4 m (section 2.2). Shaded regions are 95% confidence intervals  
905 ( $\varepsilon$ ).



906 FIG. 12. Frontogenetic tendency ( $F_{hadv}$  [ $s^{-5}$ ]) as a function of time at  $z = 8$  m. Shaded regions are 95%  
907 confidence intervals ( $\varepsilon$ ).



908 FIG. 13. Vertical velocity and float subduction. a) 3-D float subduction. The float's positions (circles) are  
909 colored by salinity. The float's trajectory is shown at the surface (black) and projected again at 10 m. Each  
910 float location and velocity vector is connected by a dashed grey line. b) Vertical velocity estimated directly  
911 from the pressure measured by the float (purple) and using the divergence calculated from Triaxus (green). c)  
912 Cross-frontal distance of the float as it downwelled under the front during events I–IV. d)  $T - S$  diagram during  
913 downwelling events III. The float's two sensors (P1, yellow and P2, gold) and Triaxus (green) captured  $T - S$   
914 changes of the vertical stratification during the downwelling event, while the ship underway (purple) provided  
915  $T - S$  changes of the horizontal stratification. In all plots, downwelling events are labeled according to section  
916 4e .

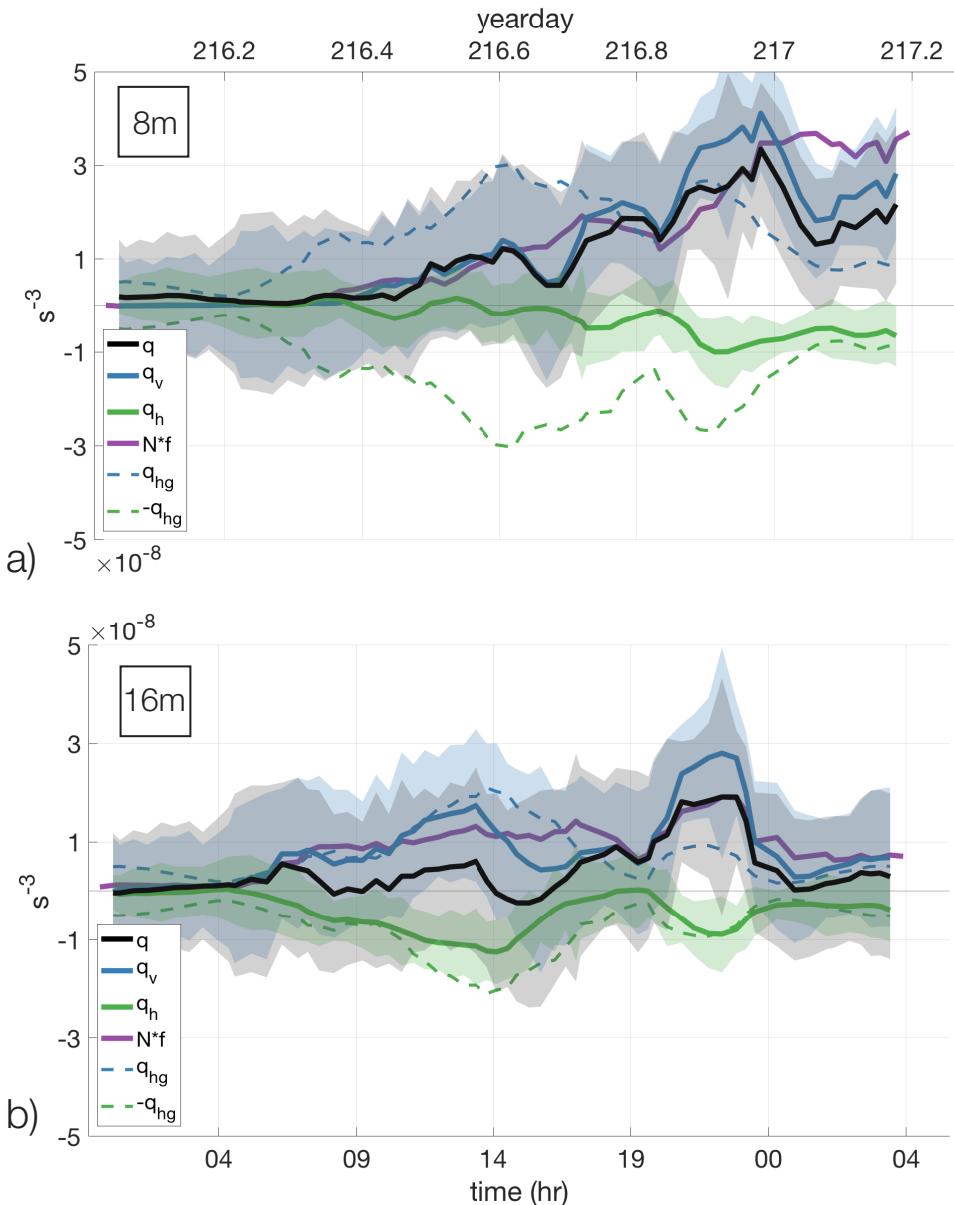


FIG. 14. PV ( $q$ , black), the vertical term of PV ( $q_v$ , blue) and the horizontal term of PV ( $q_h$ , green) at a) 8 m and b) 16 m. Both plots include planetary PV ( $N^2 f$ , purple) and the horizontal term in PV if the flow were in thermal wind balance ( $q_{hg}$ , dashed blue and  $-q_{hg}$ , dashed green). Shaded regions are 95% confidence intervals ( $\varepsilon$ ).