

# Background Information

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## Project Overview

This project focuses on developing a real-time data acquisition and synchronization system for integrating motor position data from Harmonic Drive FHA actuators with Spike2 data analysis software. Using a CANUSB adapter, the system will translate CANopen protocol data from the motors into USB format for PC integration. In Spike2, this motor data will synchronize with experimental signals captured by a 1401 ADC/DAC converter, enabling comprehensive, real-time analysis of motor and biological signals.

## System Goals

1. **Real-Time Data Synchronization:** Capture, convert, and synchronize motor data with biological signals in Spike2, supporting real-time analysis.
2. **Data Integrity:** Ensure consistent, reliable data transfer across multiple protocols and hardware interfaces.
3. **Usability:** Provide a documented, user-friendly system for straightforward operation and maintenance.

## Key Components and Protocols

### CANopen Protocol

CANopen is a communication protocol built on the Controller Area Network (CAN) standard, widely used for precise real-time control in automation and robotics. Harmonic Drive FHA motors use CANopen to transmit position, velocity, and status information.

- **Protocol Characteristics:** CANopen's structured data packets allow low-latency data transfer, ideal for real-time motion control.
- **Data Transmission Requirements:** To maintain low-latency data flow into Spike2, the system requires a reliable CAN-to-USB interface with minimal delay.

### CANUSB Adapter

The CANUSB adapter translates CAN messages from the Harmonic Drive motors into USB format, enabling data transfer to a computer where Spike2 can process and synchronize it with other experimental data.

- **Considerations:** Timing and data integrity can be affected by high-throughput demands. Effective error handling and precise timing protocols are necessary to prevent data loss and maintain synchronization.

### Spike2 Software

Spike2 is a powerful data acquisition and analysis platform designed for biological research. Integrating motor data into Spike2 provides a synchronized view of motor activity alongside neural and other experimental signals, crucial for analyzing sensorimotor coordination in real-time.

- **SDK and Integration:** The Spike2 C++ SDK allows customization for seamless handling of external data sources. By synchronizing CANopen motor data within Spike2, researchers can study precise relationships between sensory inputs, motor outputs, and biological responses.

## 1401 ADC/DAC Converter

The 1401 ADC/DAC converter records various analog and digital signals, enabling Spike2 to acquire experimental data from multiple sources. Synchronizing motor data with signals recorded through the 1401 provides a unified timeline for analyzing sensory-motor coordination.

- **Capabilities:** The 1401 offers high-speed, high-resolution waveform capture and simultaneous digital output, supporting complex, multitasking experiments that involve precisely timed motor control and sensory feedback.

## Project Challenges

1. **Real-Time Data Processing:** Ensuring low-latency data conversion and transfer to support Spike2's real-time analysis capabilities.
2. **Precise Timing Synchronization:** Aligning CANopen motor data with biological signals captured by the 1401, which is essential for experiments examining fine-grained sensorimotor timing.
3. **Error Handling:** Developing robust error-handling mechanisms to manage protocol, USB, and timing errors that may occur during continuous, real-time operation.
4. **Performance Optimization:** Designing a multi-threaded architecture to handle simultaneous data streams without bottlenecks or performance degradation.

## Benefits of the Proposed System

1. **Enhanced Experimental Insight:** Real-time synchronization of motor and biological data enables more detailed studies on sensory-motor processing, supporting research into neural control of movement.
2. **Maintainability:** The system's documentation and streamlined architecture ensure straightforward maintenance and potential for future enhancements.
3. **Adaptability:** A robust, scalable design enables future integration with additional hardware and experimental protocols, facilitating research expansion.

This project will deliver a reliable, high-performance data acquisition system that supports Dr. Stay's research on sensorimotor control by providing a unified, real-time view of motor and biological signals.