

Aeronautics & Mechanics AENG11301

Lecture 9 Climb and Glide



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Outline for today

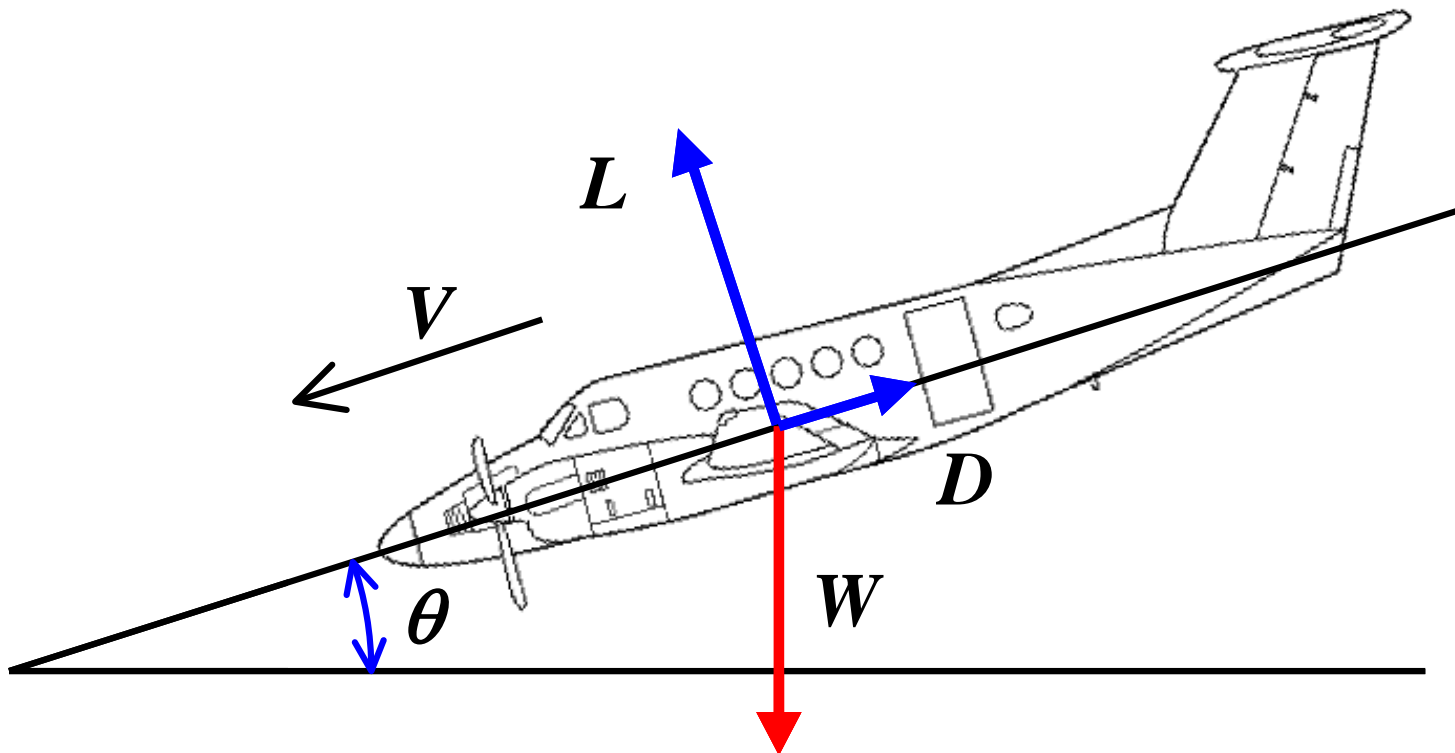
- Gliding flight
 - Force balance
 - Glide angle
 - Sink rate
- Climbing flight
 - Force balance
 - Climb angle
 - Climb rate

Aims for today

- Be able to calculate force balance in gliding flight
- Be able to calculate speed for minimum glide angle and speed for minimum sink rate
- Be able to calculate force balance in climbing flight
- Be able to relate maximum climb angle and maximum rate of climb with engine properties

Gliding Flight

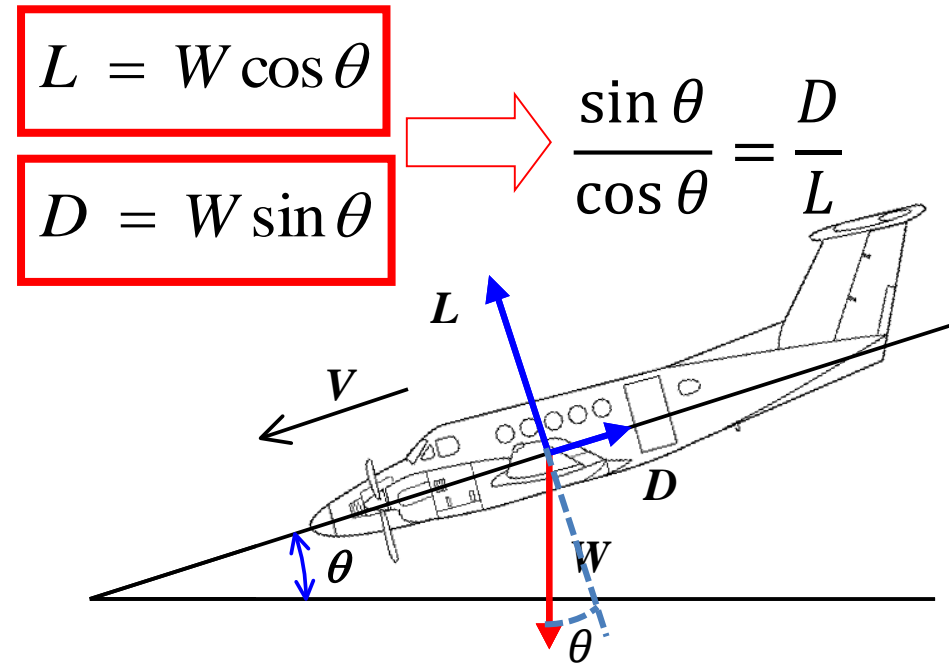
- thrust $T = 0$ but drag $D \neq 0$
 - cannot maintain equilibrium in straight & level flight
 - aircraft descends at **glide angle** θ
 - component of weight along flight path replaces thrust



Force Balance in a Glide

- resolve forces
 - perpendicular to flight path
 - parallel to flight path
- hence

$$\tan \theta = \frac{1}{L/D} = \frac{1}{C_L/C_D}$$



- **glide angle** depends solely on the aerodynamic characteristics
 - weight only affects the speed at which a particular C_L/C_D is achieved
- best (shallowest) glide angle occurs at maximum L/D
 - **minimum glide angle** occurs at minimum drag speed

Glide ratios

	Glide ratio (L/D ratio)
Modern Sailplane	40-60
Lockheed U-2	28
Albatross	20
Boeing 747	17
Herring gull	10
Cessna 150	7
Space Shuttle	4.5
House sparrow	4
Flying squirrel	2



Speed for Minimum Glide Angle

- minimum glide angle occurs at minimum drag condition
 - gives maximum distance from a given start height
 - but corresponding speed depends on glide angle ...

$$V = \sqrt{\frac{L}{\frac{1}{2} \rho S C_L}} = \sqrt{\frac{W \cos \theta}{\frac{1}{2} \rho S C_L}} = \sqrt{\frac{W}{\frac{1}{2} \rho S C_L}} \sqrt{\cos \theta}$$

- **for a given C_L , speed is less than for level flight by the factor $\sqrt{\cos \theta}$**
- for glide angle $< 10^\circ$ error is $< 1\%$
 - *applies for all normal glide performance ... but must check!*
- make small angle assumption $\rightarrow \cos \theta = 1, \sin \theta = \theta$

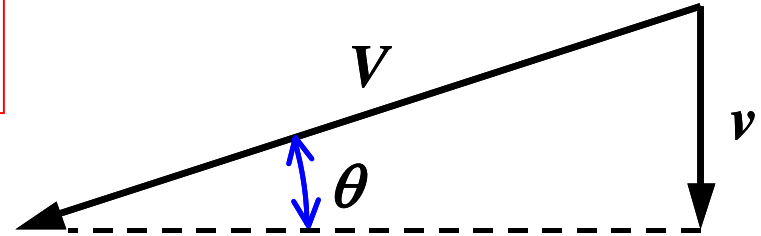
$$\Rightarrow L \approx W \Rightarrow$$

$$V_{\min \theta} \approx V_{MD} = \left(\frac{2W}{\rho S} \right)^{\frac{1}{2}} \left(\frac{K}{C_{D0}} \right)^{\frac{1}{4}}$$

Speed for Minimum Sink Rate

- sinking speed (**rate of sink**) v is vertical component of flight speed V

$$v = V \sin \theta$$



- from force balance and velocity equation

– making small angle assumption, so that $L \approx W$

$$v = V \frac{D}{W} \approx V \frac{D}{L} = V \frac{C_D}{C_L}$$

$$v = \sqrt{\frac{2L}{\rho S C_L}} \frac{C_D}{C_L} \approx \sqrt{\frac{2W}{\rho S}} \frac{C_D}{C_L^{3/2}}$$

– minimum sink occurs at minimum $C_D/C_L^{3/2}$

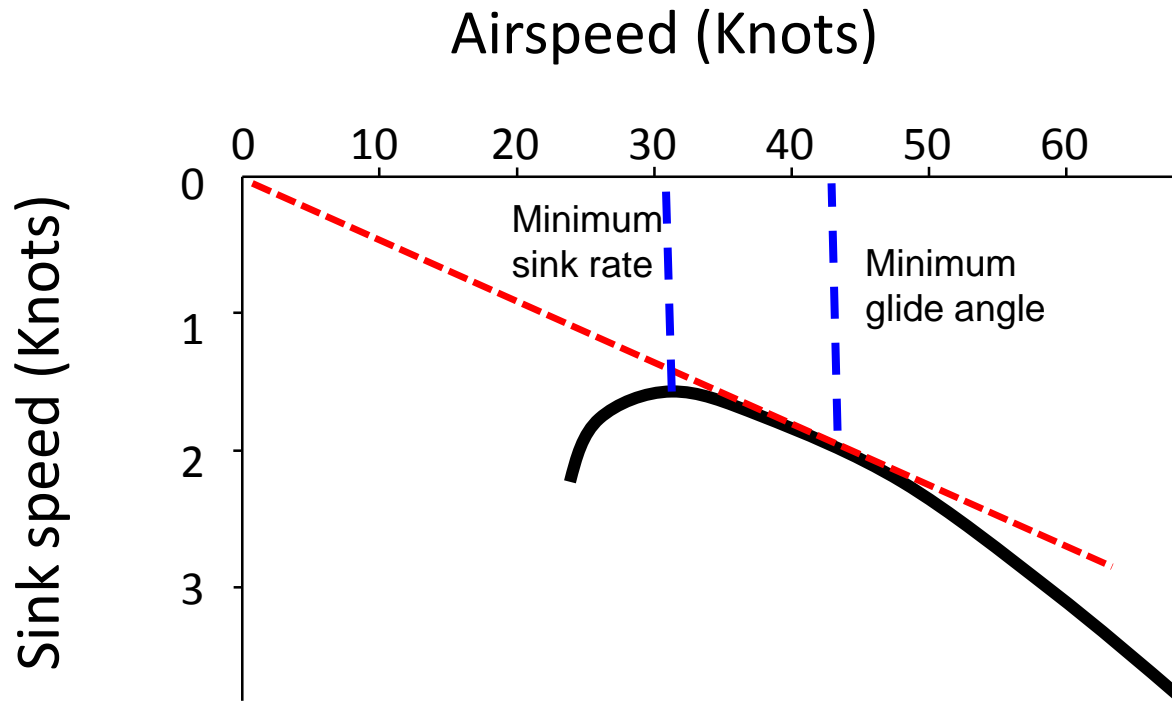
- same as the minimum power condition!

$$V_{min\ sink} \approx V_{MP} = \left(\frac{2W}{\rho S} \right)^{\frac{1}{2}} \left(\frac{K}{3C_{D0}} \right)^{\frac{1}{4}}$$

Glider Polar Diagram

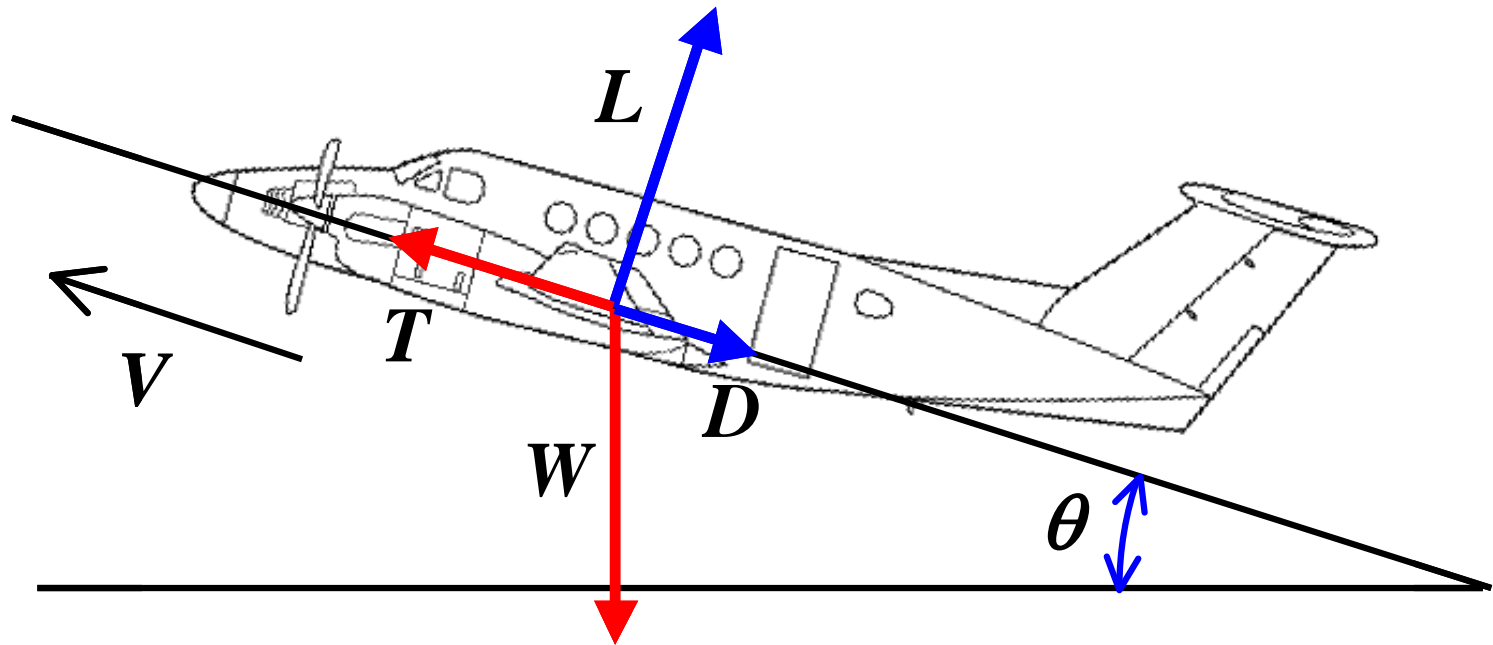
- glider performance usually represented by its 'polar'
 - plot of sink speed v vs forward speed V
 - indicates variation of D/L with speed
 - readily determined in flight test

$$\frac{v}{V} = \sin \theta = \frac{D}{W} \approx \frac{D}{L}$$



Climbing Flight

- thrust $T > \text{drag } D$
 - cannot maintain equilibrium in straight & level flight
 - aircraft ascends at **climb angle** θ
 - horizontal component of weight opposes thrust



Force Balance in a Climb

- resolve forces
 - perpendicular to flight path

$$L = W \cos \theta$$

- parallel to flight path

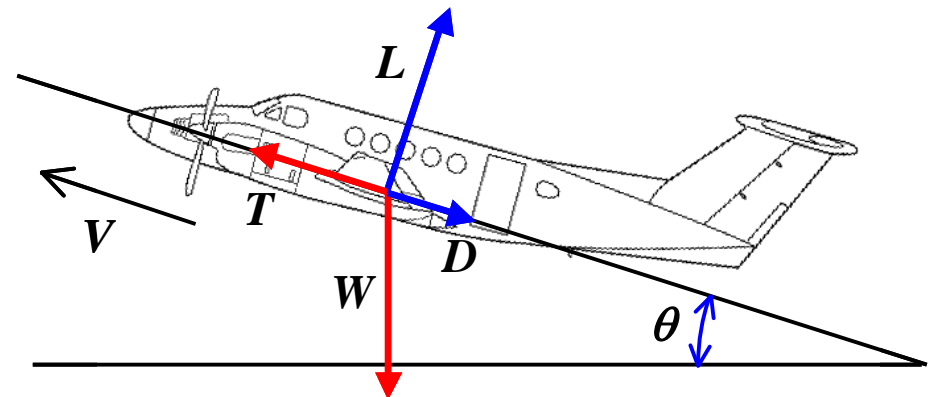
$$T - D = W \sin \theta$$

- hence **climb angle** is

$$\sin \theta = \frac{T - D}{W}$$

- rate of climb** v is then

$$v = V \sin \theta = \frac{V(T - D)}{W}$$



$$Wv = TV - DV$$

rate of increase
of potential energy

power
available power
required

excess power

Climb Performance

- maximum angle of climb requires maximum **excess thrust** ($T - D$)

$$\sin \theta = \frac{T - D}{W}$$

- maximum rate of climb requires maximum **excess power** ($TV - DV$)

$$v = V \sin \theta = \frac{V(T - D)}{W}$$

- do not occur together
 - depend on propulsion thrust/power characteristics
 - cannot make small angle assumptions – calculate numerically

Gross simplification

– but useful for preliminary performance work

- **Jet aircraft**

→ **thrust** T remains constant with speed

→ power $P = TV$ increases with speed

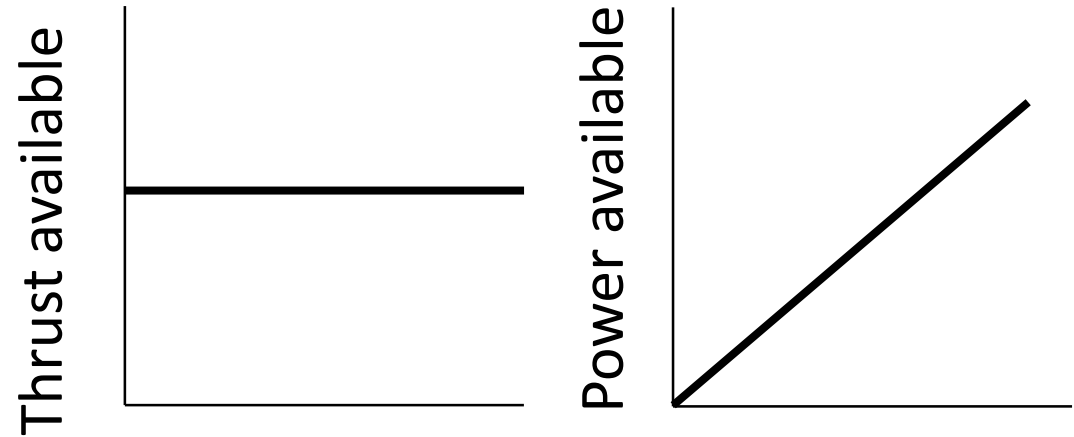
- **Propeller aircraft**

→ **power** output P remains constant with speed

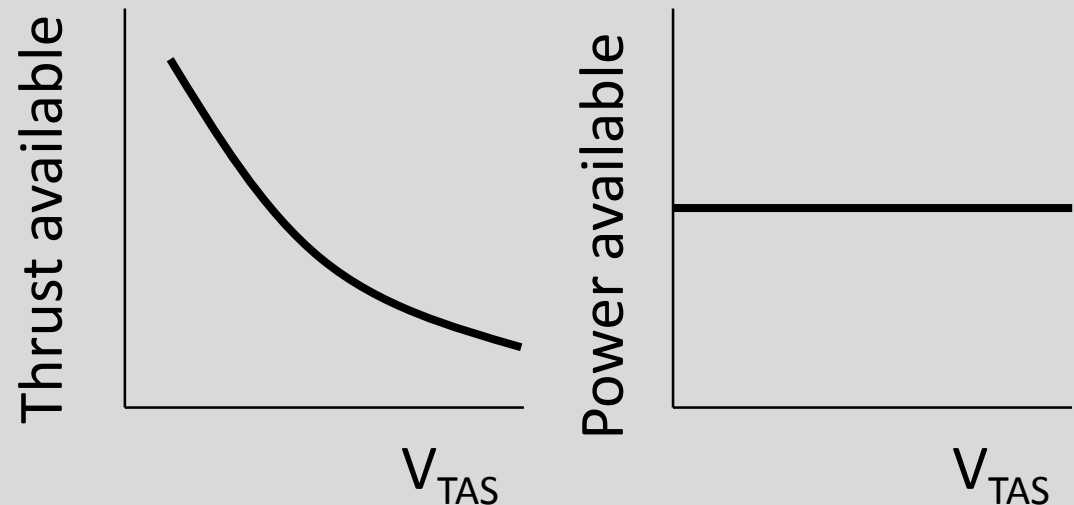
→ thrust $T = P/V$ reduces with speed

Propulsion type

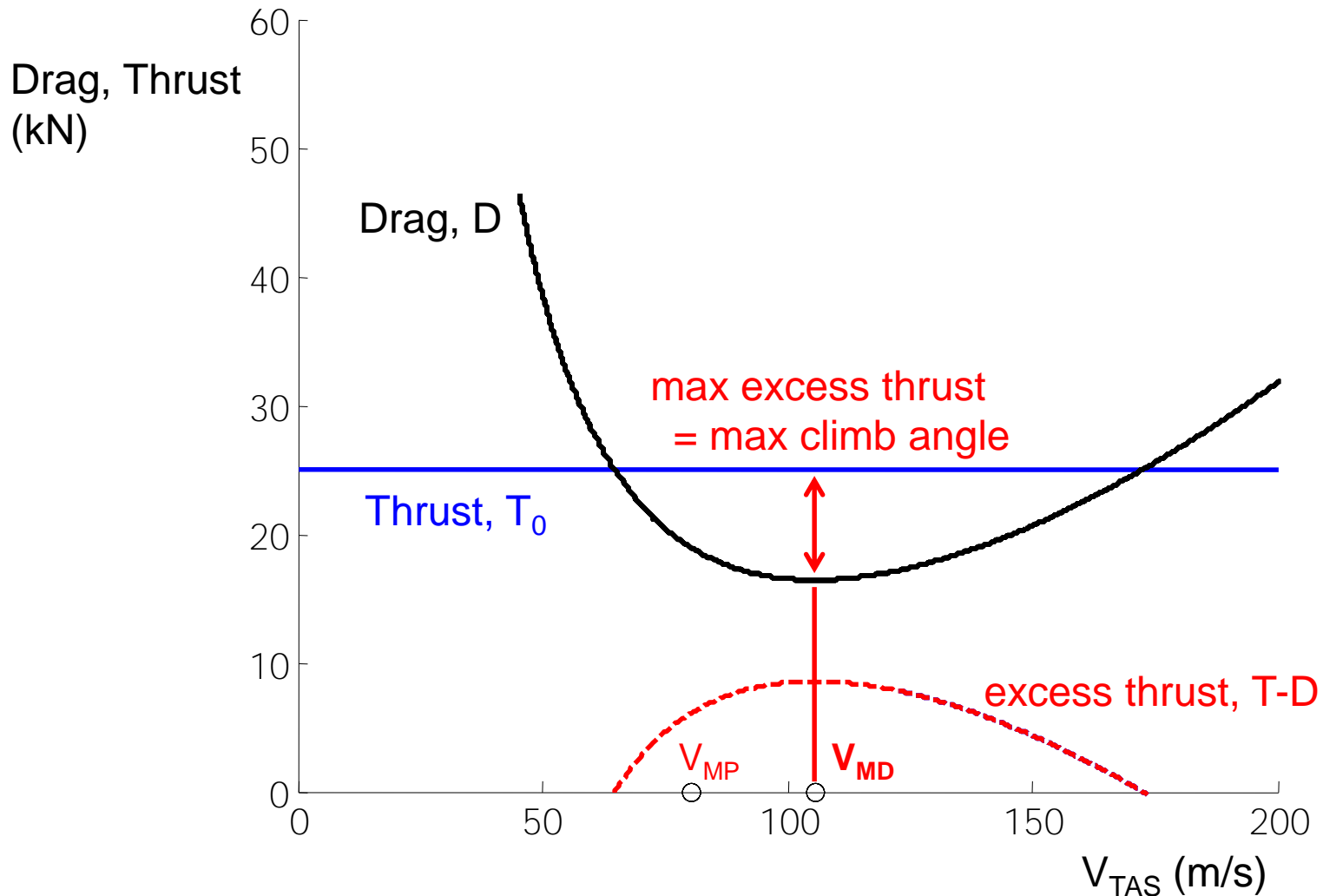
Jet



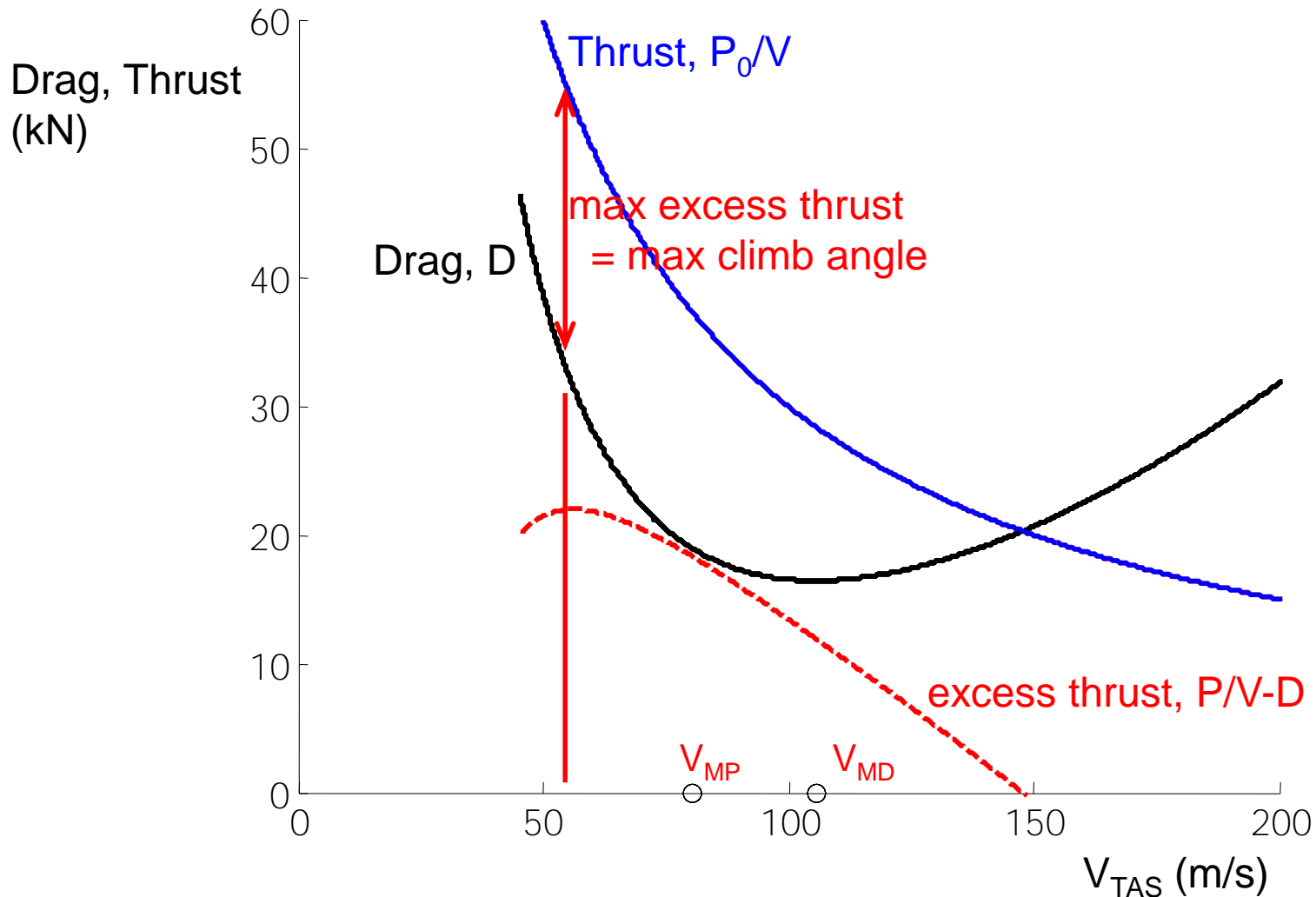
Propeller



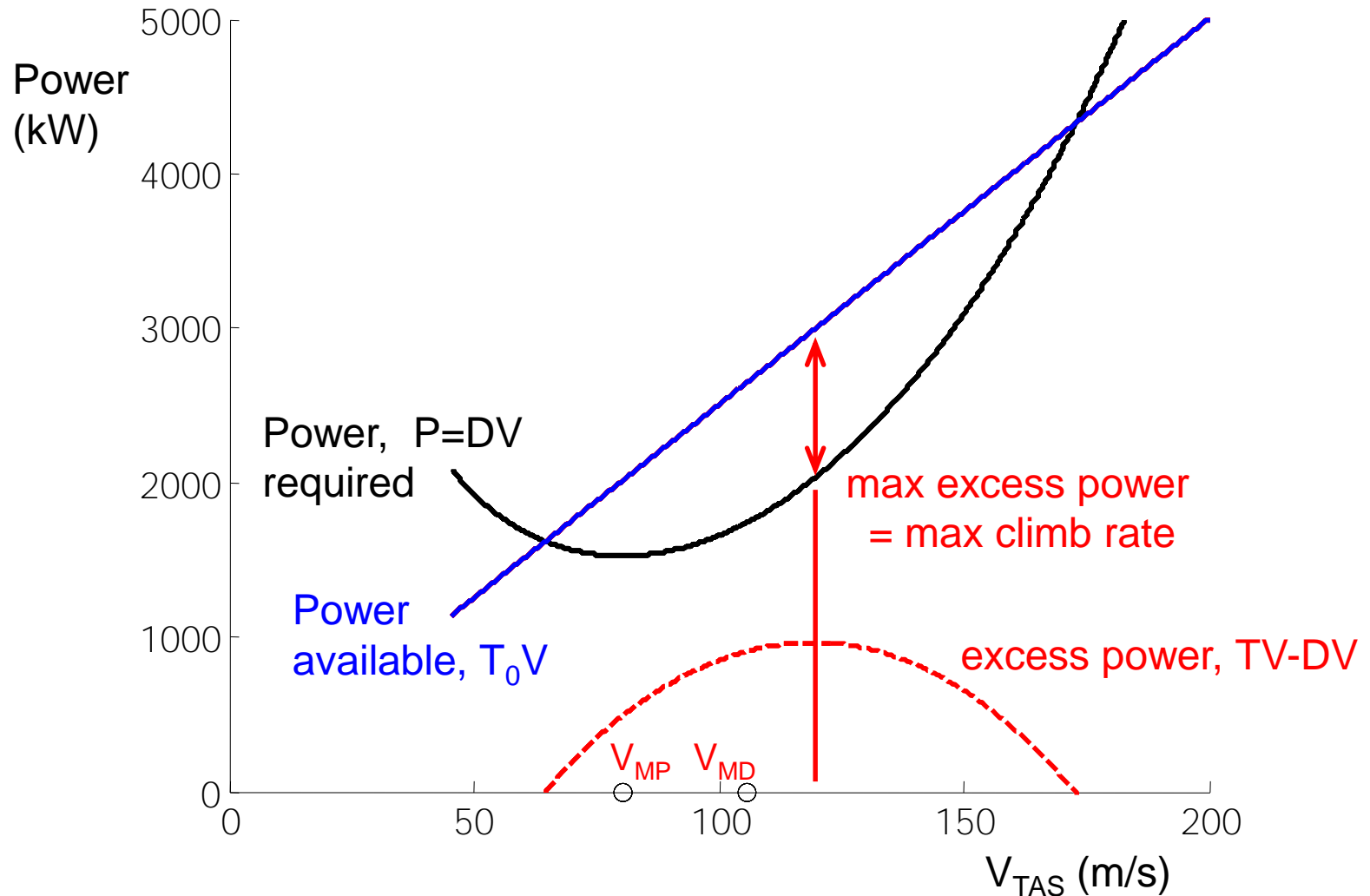
Climb Angle - Jet



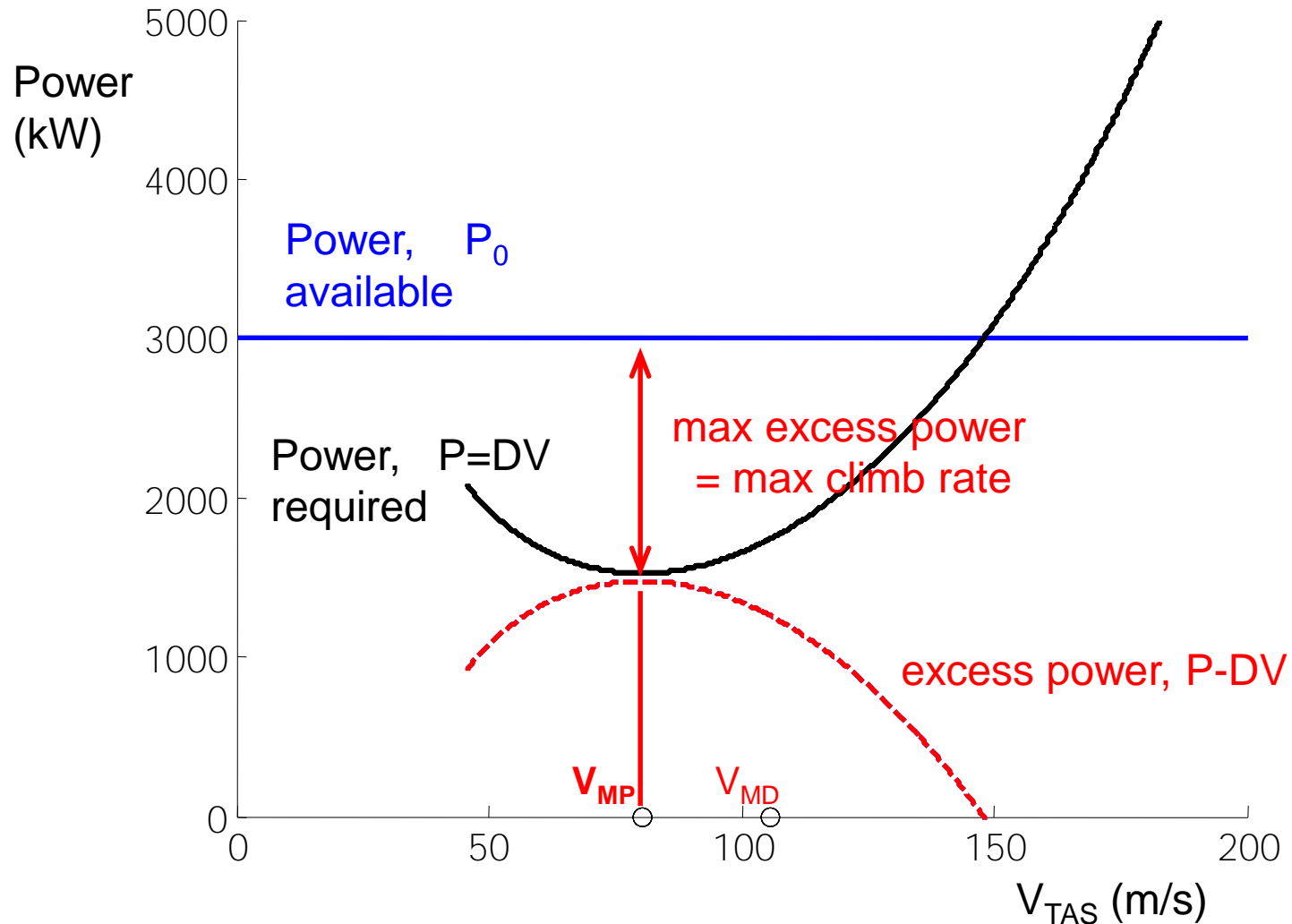
Climb Angle - Propeller



Rate of Climb - Jet



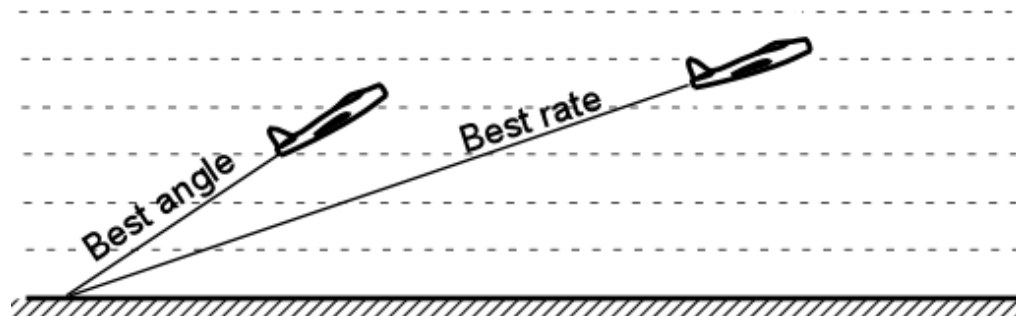
Rate of Climb - Propeller



Climb Performance Summary

- maximum excess **power** = maximum **rate of climb**
- maximum excess **thrust** = maximum **climb angle**

	Propeller Aircraft	Jet Aircraft
Max Rate of Climb	at minimum power speed V_{MP}	$> V_{MP}$
Max Climb Angle	$< V_{MD}$	at minimum drag speed V_{MD}



Example – Glider



Mass = 350 kg

Wing area, $S = 11 \text{ m}^2$

Max lift to drag, $(L/D)_{max} = 42$

Aspect ratio, $AR = 21$

Oswald efficiency, $e = 0.95$

Altitude, $h = 5000 \text{ m}$
(where $\rho \approx 0.74 \text{ kg/m}^3$)

Calculate:

- 1) the minimum glide angle
- 2) horizontal distance glider will cover in still air
- 3) C_L at minimum glide angle
- 4) minimum glide angle
airspeed
- 5) how this changes if add
150 kg of water ballast

Summary

Gliding

$$L = W \cos \theta$$

$$D = W \sin \theta$$

$$\tan \theta = \frac{1}{L/D} = \frac{1}{C_L/C_D}$$

- Minimum glide angle occurs at minimum drag speed
- Minimum sink rate occurs at minimum power required speed

Climbing

$$L = W \cos \theta$$

$$T - D = W \sin \theta$$

- Maximum climb rate is at maximum excess Power
- Maximum climb angle is at maximum excess Thrust

	Propeller Aircraft	Jet Aircraft
Max Rate of Climb	at minimum power speed V_{MP}	$> V_{MP}$
Max Climb Angle	$< V_{MD}$	at minimum drag speed V_{MD}

Follow-up materials

To help with exam:

- Introduction to Flight – 6.8, 6.9

To aid in understanding:

- Introduction to Flight – 6.4, 6.6

For interest:

How to use glide polars as a glider pilot

- <http://avia.tion.ca/documentation/polar/>