

EMAT10100 Engineering Maths I Lecture 12: Determinants and the matrix inverse

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Three by three determinants

- Main idea: any (big) determinant can be built up out of smaller ones:
- k Here's how it works for n=3:

$$\begin{vmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{2,1} & a_{2,2} & a_{2,3} \\ a_{3,1} & a_{3,2} & a_{3,3} \end{vmatrix} = a_{1,1} \begin{vmatrix} a_{2,2} & a_{2,3} \\ a_{3,2} & a_{3,3} \end{vmatrix} - a_{1,2} \begin{vmatrix} a_{2,1} & a_{2,3} \\ a_{3,1} & a_{3,3} \end{vmatrix} + \frac{a_{1,3}}{a_{3,1}} \begin{vmatrix} a_{2,1} & a_{2,2} \\ a_{3,1} & a_{3,2} \end{vmatrix}$$

- ✓ General principle? How to do for bigger matrices?
- Are there short cuts?



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Looking back looking forward

Last time:

- \bigvee Square $n \times n$ matrices as transformations on n-vectors
 - linear: maps straight lines to straight lines
 - ightharpoonup special case of n=2: transformations of the plane scaling, rotation, reflexion and shear
- Leterminants give area (or volume) scale factor
 - formula for two by two case
- ₭ Singular matrices (determinant equals zero)
- Identity and diagonal matrices

This time:

- ✓ Determinant of general square matrices
- Inverse of general square matrices
- Warning: This lecture has a lot of theory in it



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Four by four determinants

$$\begin{vmatrix} a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\ a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\ a_{3,1} & a_{3,2} & a_{3,3} & a_{3,4} \\ a_{4,1} & a_{4,2} & a_{4,3} & a_{4,4} \end{vmatrix} = a_{1,1} \begin{vmatrix} a_{2,2} & a_{2,3} & a_{2,4} \\ a_{3,2} & a_{3,3} & a_{3,4} \\ a_{4,2} & a_{4,3} & a_{4,4} \end{vmatrix} - a_{1,2} \begin{vmatrix} a_{2,1} & a_{2,3} & a_{2,4} \\ a_{3,1} & a_{3,3} & a_{3,4} \\ a_{4,1} & a_{4,3} & a_{4,4} \end{vmatrix} + a_{1,3} \begin{vmatrix} a_{2,1} & a_{2,2} & a_{2,4} \\ a_{3,1} & a_{3,2} & a_{3,4} \\ a_{4,1} & a_{4,2} & a_{4,4} \end{vmatrix} - a_{1,4} \begin{vmatrix} a_{2,1} & a_{2,2} & a_{2,4} \\ a_{3,1} & a_{3,2} & a_{3,3} \\ a_{4,1} & a_{4,2} & a_{4,3} \end{vmatrix} - a_{1,4} \begin{vmatrix} a_{2,1} & a_{2,2} & a_{2,3} \\ a_{3,1} & a_{3,2} & a_{3,3} \\ a_{4,1} & a_{4,2} & a_{4,3} \end{vmatrix}$$

 ★ General principle is in terms of minors and cofactors



Minors and Cofactors

- \mathbf{k} Minor $M_{i,j}$ of matrix \mathbf{A} is determinant of matrix obtained by deleting ith row and jth column of \mathbf{A}

$$A_{i,j} = (-1)^{i+j} M_{i,j}$$

 \bigvee Determinant expanded by ith row is given by

$$\det \mathbf{A} = \sum_{j=1}^{n} a_{i,j} A_{i,j} \qquad \left(= \sum_{j=1}^{n} (-1)^{i+j} a_{i,j} M_{i,j} \right)$$

ightharpoonup previous examples used first row, i.e. had i=1



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Example

₭ Show that (schematically)

$$\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \mathbf{a} \times \mathbf{k}$$



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Exercise 1

$$\mathbf{A} = \begin{pmatrix} 3 & -2 & 3 \\ -1 & 0 & -3 \\ 2 & 3 & -2 \end{pmatrix}$$

and identify the minors, cofactors etc. involved in the calculation



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Pattern of signs in cofactors

★ How to remember the pattern of signs in cofactor calculations:

$$\begin{pmatrix} + & - \\ - & + \end{pmatrix}, \quad \begin{pmatrix} + & - & + \\ - & + & - \\ + & - & + \end{pmatrix}, \quad \begin{pmatrix} + & - & + & - \\ - & + & - & + \\ + & - & + & - \\ - & + & - & + \end{pmatrix},$$

$$\begin{pmatrix} + & - & + & - & + \\ - & + & - & + & - \\ + & - & + & - & + \\ - & + & - & + & - \\ + & - & + & - & + \end{pmatrix}$$
 and so on.



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Facts about the determinant

All these can be shown (hard) by using minors formula:

$$\operatorname{det}(\mathbf{A}^{\mathrm{T}}) = \operatorname{det}(\mathbf{A}). \quad \operatorname{det}(\mathbf{A}\mathbf{B}) = \operatorname{det}(\mathbf{A})\operatorname{det}(\mathbf{B}).$$

ightharpoonup the sign of $\det {f A}$ flips

 \mathbf{k} If one row of \mathbf{A} is multiplied by a scalar λ

 $lackbox \det \mathbf{A}$ is muliplied by λ

₭ If A has two identical rows

 $det \mathbf{A} = 0$

If two rows of A are added together:

▶ det A is unchanged



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Exercise 2

Where possible, use shortcuts to work out determinants of following:

$$\mathbf{A} = \begin{pmatrix} 1 & 3 \\ 2 & -1 \end{pmatrix}, \quad \mathbf{B} = \begin{pmatrix} 1 & 2 \\ 3 & -1 \end{pmatrix}, \quad \mathbf{C} = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 1 \\ 3 & 0 & 0 \end{pmatrix},$$
$$\mathbf{D} = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 1 & 1 \\ 1 & 2 & 0 \end{pmatrix}, \quad \mathbf{E} = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 5 & 5 \\ 3 & 0 & 0 \end{pmatrix}$$



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Example

$$\mathbf{A} = \begin{pmatrix} 1 & 3 & -1 & 0 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & -2 & 3 \\ 0 & 0 & 0 & 3 \end{pmatrix}$$

₩ HINT: a determinant is zero if it has complete row or column of zeros



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Matrix inverse (I)

ke Identity matrix: $n \times n$ matrix which leaves $n \times 1$ and other $n \times n$ matrices unchanged under multiplication

E.g.
$$\mathbf{I}_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$
, $\mathbf{I}_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ etc.

<u>Inverse matrix</u>: given a square $n \times n$ matrix **A**, its inverse \mathbf{A}^{-1} (if it exists) is the $n \times n$ matrix for which

$$\mathbf{A}^{-1}\mathbf{A} = \mathbf{I} = \mathbf{A}\mathbf{A}^{-1}$$

As a transformation, ${\bf A}^{-1}$ does the opposite of ${\bf A}$, so that combined they have no effect

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Matrix inverse (II)

How to compute the inverse matrix?

Cramer's rule: (don't worry, it just works)

K Given

$$\mathbf{A} = \begin{pmatrix} a_{1,1} & a_{1,2} & \dots & a_{1,n} \\ a_{2,1} & a_{2,2} & \dots & a_{2,n} \\ \vdots & \vdots & \dots & \vdots \\ a_{n,1} & a_{n,2} & \dots & a_{n,n} \end{pmatrix} \text{ then } \mathbf{A}^{-1} = \frac{1}{\det \mathbf{A}} \begin{pmatrix} A_{1,1} & A_{2,1} & \dots & A_{n,1} \\ A_{1,2} & A_{2,2} & \dots & A_{n,2} \\ \vdots & \vdots & \dots & \vdots \\ A_{1,n} & A_{2,n} & \dots & A_{n,n} \end{pmatrix}$$

where $A_{i,j}$ denotes cofactor

 $\slash\hspace{-0.6em}\mathbf{\mathsf{NB}}$: inverse \mathbf{A}^{-1} only exists when $\det \mathbf{A} \neq 0$

▶ hence why we say ${\bf A}$ is non-invertible if $\det {\bf A} = 0$



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Matrix inverse (III)

Exercise: Find the inverse of

$$\mathbf{A} = \begin{pmatrix} 1 & 2 & 4 \\ -1 & 0 & 3 \\ 3 & 1 & -2 \end{pmatrix}$$

- ₭ Bit tedious isn't it? We will return to this later
- ★ Take home message: (repeat out loud!)

"The Inverse of a square matrix is the transpose of the matrix of cofactors divided by the determinant"

 $\mbox{$\mbox{$\mbox{$\&$}$}$}$ "transpose of matrix of co-factors" also known as the adjoint of A, written $\mbox{adj}(A)$. So the above matra can be written mathematically as:

$$A^{-1} = \frac{1}{\det(A)} \operatorname{adj}(A)$$

Two by two inverse

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LEARN THIS: If $\mathbf{A}=\begin{pmatrix} a_{1,1} & a_{1,2} \\ a_{2,1} & a_{2,2} \end{pmatrix}$ then

$$\mathbf{A}^{-1} = \frac{1}{a_{1,1}a_{2,2} - a_{1,2}a_{2,1}} \begin{pmatrix} a_{2,2} & -a_{1,2} \\ -a_{2,1} & a_{1,1} \end{pmatrix}$$

Exercise: find inverse of

$$\mathbf{A} = \begin{pmatrix} 1 & 3 \\ 2 & -1 \end{pmatrix}$$

and verify by multiplication that it is the inverse



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Homework

- - Exercises 5.3.1, Q. 35, 38
 - Exercises 5.4.1, Q. 51, 52
- Revise for the class test (Monday 23rd Oct) by:
 - Only questions on complex numbers and vectors
 - ► Read through notes and relevent bits of *James*
 - ▶ Use online QMP tests to check basic understanding
 - ► Revise using more basic examples from *James*
 - Go to Thurs and Fri drop-in sessions to get help
- But remember, the class test does not contribute to the unit mark, it's just to check progress.
 - ▶ It's important you also keep up with regular homeworks and QMP tests
 - Especially as this lecture and next few have a lot of theory in them.