

# Structural Loads in Trusses

## Method of Joints

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## 1.2.1 Method of Joints

## 1.2.2 Method of Sections

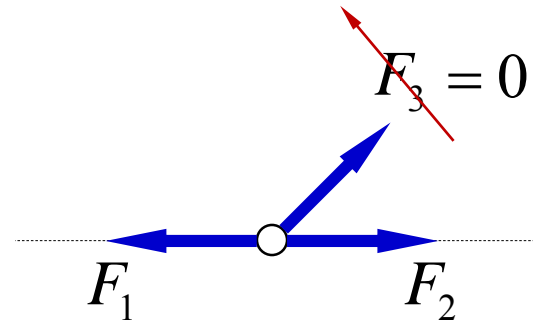
## 1.2.3 Method of Tension Coefficients

- In two dimensions (2D)
- In three dimensions (3D)

Some **internal forces** or some **reaction forces** in a pin-jointed truss might be **zero**. Often these 'zero loads' can be spotted early if we check for the **two collinearity rules**:

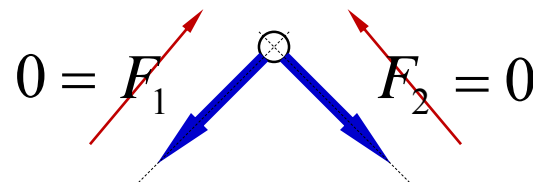
## Rule 1:

If there are **exactly three forces** acting on a pin joint, and **two of these are collinear**, then the **non-collinear force must be zero**



## Rule 2:

If there are **exactly two forces** acting on a pin joint and these are **not collinear**, then **both forces must be zero**

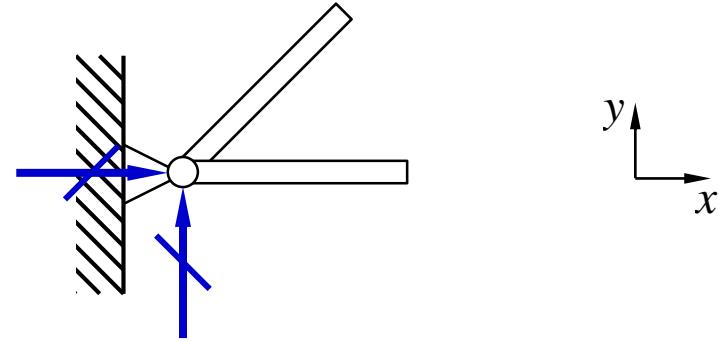


If the sense or direction of a force is unknown, assume positive values

- This applies to internal & external sign conventions

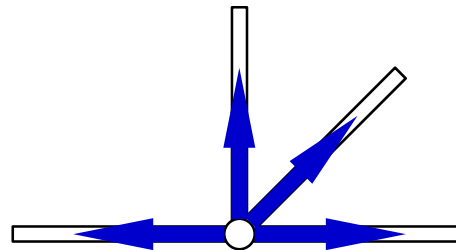
Reaction forces (external sign convention):

- **Horizontal:** positive 'to the right'
- **Vertical:** positive 'upwards'



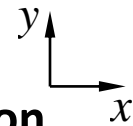
Member forces (internal sign convention):

- Assume **tension**
  - As if forces were 'flowing out' of each pin joint



1. Calculate the degree of redundancy **before** finding unloaded members!
2. Apply our **collinearity rules** to identify unloaded members
3. Create a **global FBD** for the entire structure

- Draw positive reaction forces following the **external sign convention**

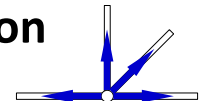


- Write the **three** equilibrium equations:
 
$$\sum F_x = 0 \quad \sum F_y = 0 \quad \sum M = 0$$
  - Find the reaction forces at supports

↑  
Choose an  
appropriate joint as  
the reference point!

4. Analyse **mini FBDs** of each individual joint

- Draw positive internal forces following the **internal sign convention**



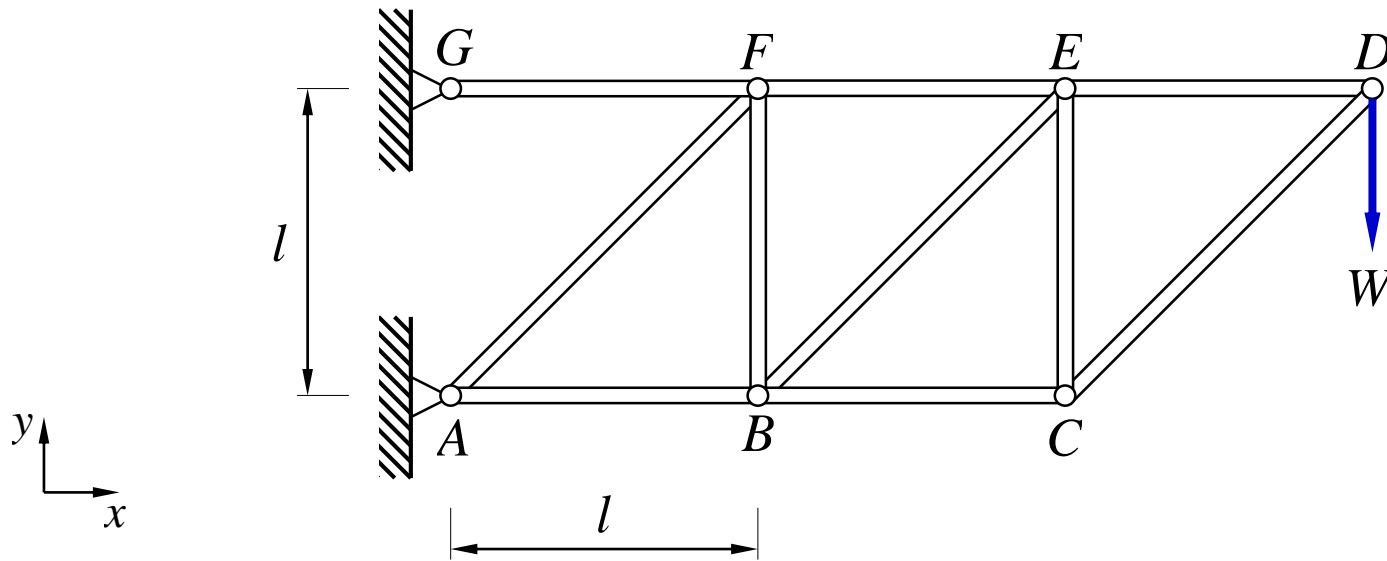
- Start by joints with known forces or reactions

- Write the **two** equilibrium equations:

$$\sum F_x = 0 \quad \sum F_y = 0$$

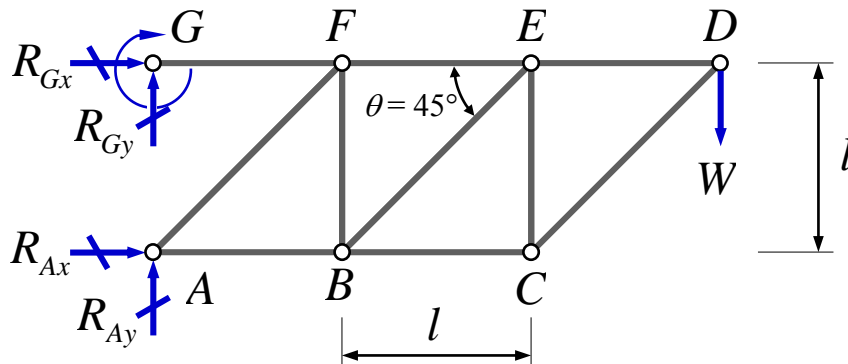
- Find the unknown internal forces
- Move on to the next joint (again, choose an 'easy' joint!)

For the pin-jointed truss below:



- Find the magnitude and sense (up/down/left/right) of the **reaction forces** at **all supports**
- Find the magnitude and sense (tension/compression) of the **internal forces** in **every member**

## Step 1.1: Global FDB → find reaction forces

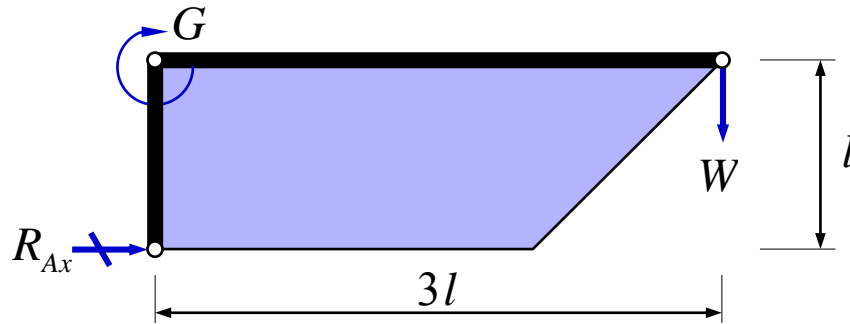


The entire truss can then be seen as a single 'rigid body' which should not rotate about our reference joint

- Assume **positive reactions** following the **external sign convention**
- Considering the **balance of moments** about a joint, e.g.  $G$ :

$$\sum M_G = 0 \quad \text{CW (arbitrary)}$$

## Step 1.1: Global FDB → find reaction forces



The entire truss can then be seen as a single 'rigid body' which should not rotate about our reference joint

- Assume **positive reactions** following the **external sign convention**
- Considering the **balance of moments** about a joint, e.g.  $G$ :

$$\sum M_G = 0 \quad \text{(arbitrary)}$$

$$W \times (\text{horizontal moment arm}) - R_{Ax} \times (\text{vertical moment arm}) = 0$$

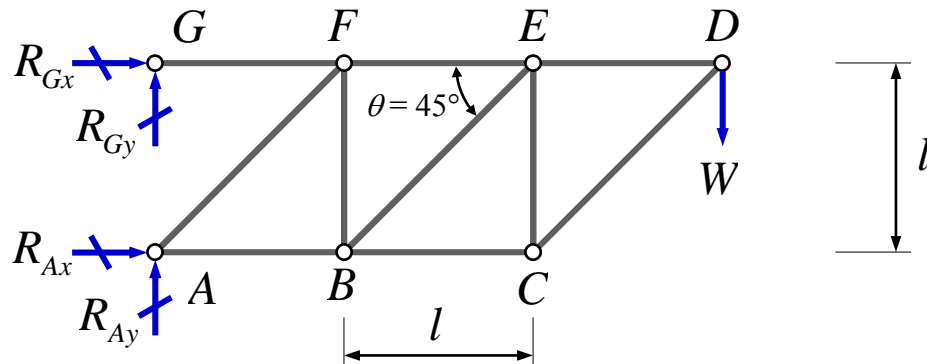
$$W(3l) - R_{Ax}(l) = 0$$

 $\therefore$ 

$$R_{Ax} = 3W$$



**Step 1.2:** Global FDB → find reaction forces



- Now the equilibrium of **horizontal forces**:

$$\sum F_x = 0$$

- There are only two terms:

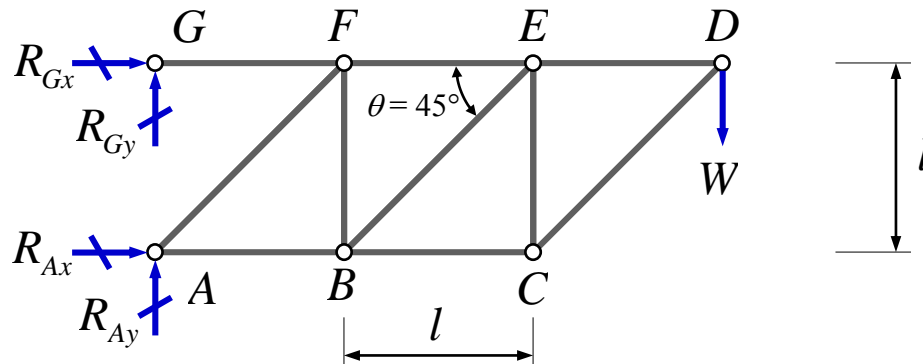
$$R_{Ax} + R_{Gx} = 0$$

 $\therefore$ 

$$R_{Gx} = -3W$$

→ A negative sign means that the actual force is in the opposite direction!

**Step 1.3:** Global FDB → find reaction forces



- Finally, the equilibrium of **vertical forces**:

$$\sum F_y = 0$$

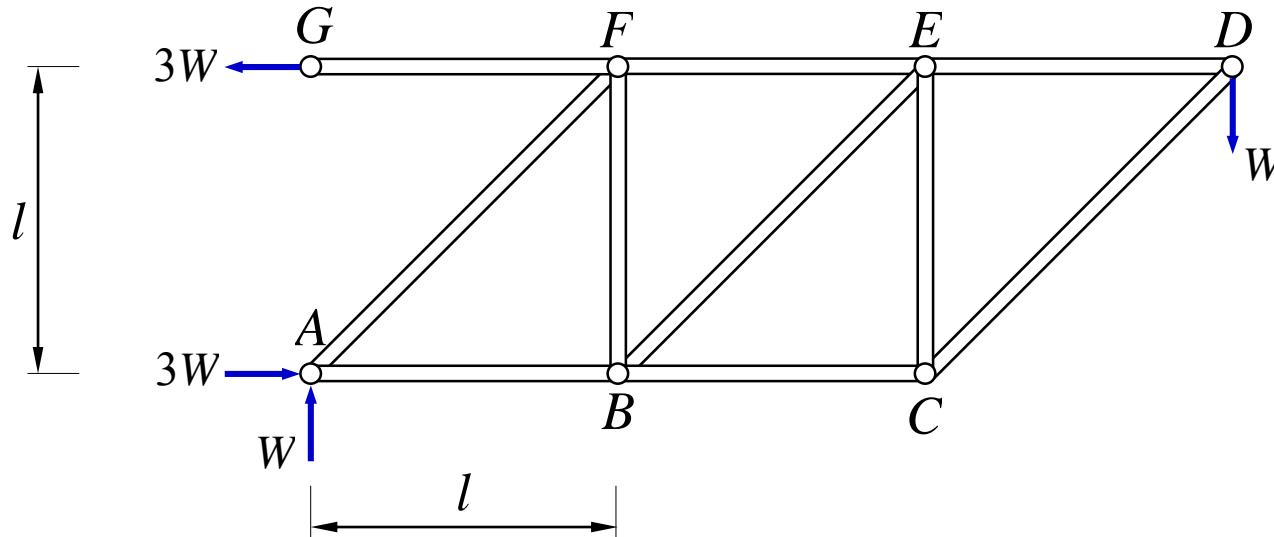
- Joint **G** has no vertical or diagonal members, hence  $R_{Gy} = 0$
- And the two remaining terms give

$$R_{Ay} - W = 0$$

∴

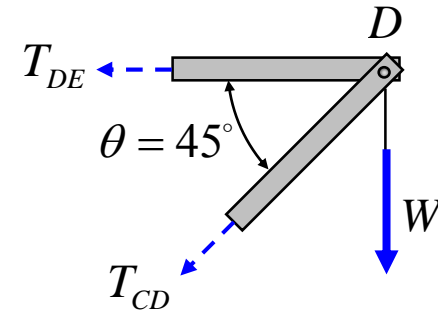
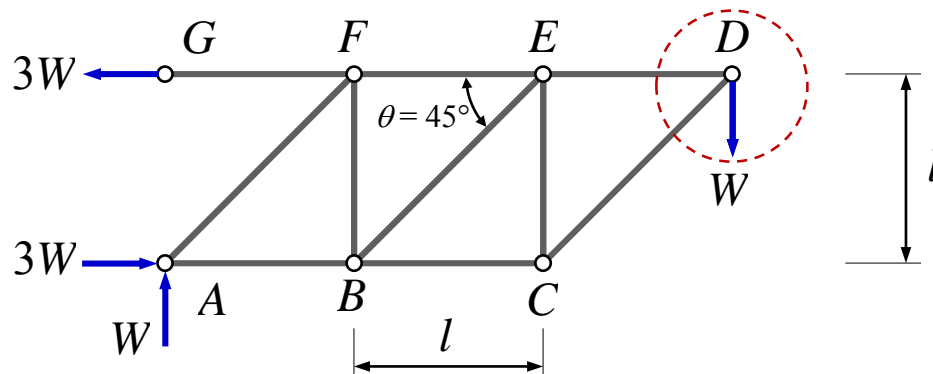
$$R_{Ay} = W$$

All reactions are now known:



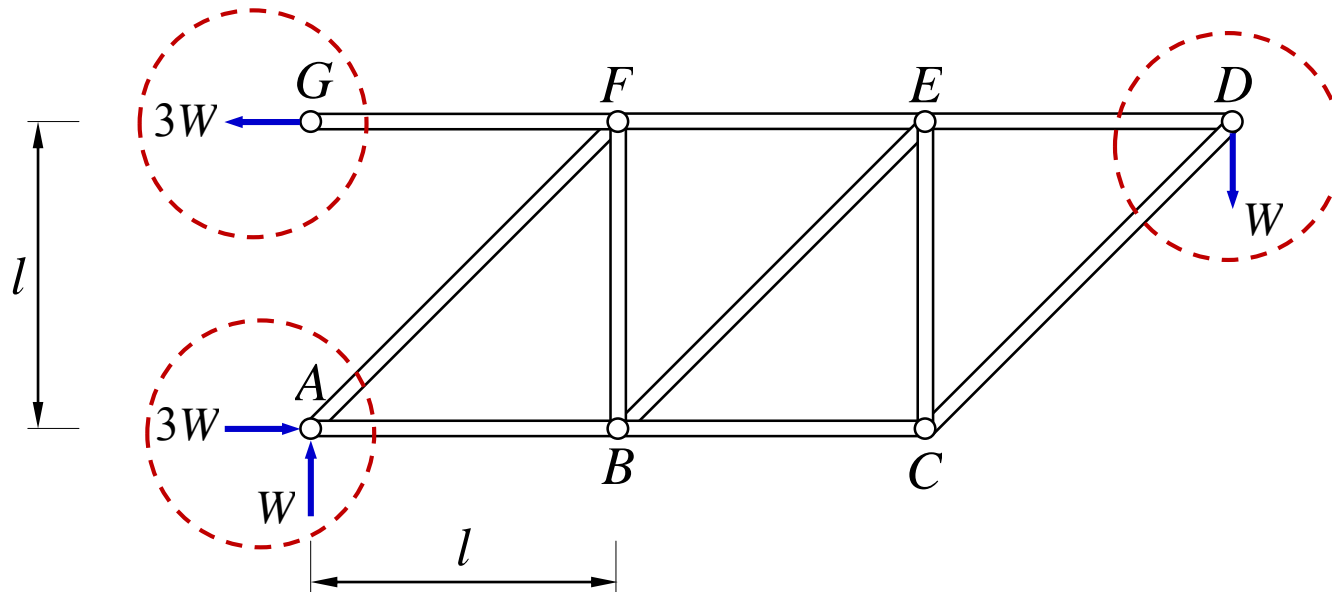
- Find the magnitude and sense (up/down/left/right) of the **reaction forces at all supports** → **Done**
- Find the magnitude and sense (tension/compression) of the **internal forces in every member**

### Step 2: Draw mini-FBDs for each joint



- Create FBDs at joints by **cutting across** joining members
- **Always** assume unknowns to act in positive sense (tension or 'pulling')
  - The correct sense will be determined by the solution of the equilibrium equations
- Next step: write the vertical and horizontal equilibrium for each joint
  - **Important: always start from joints with only 2 unknowns!**

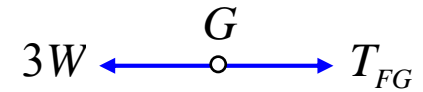
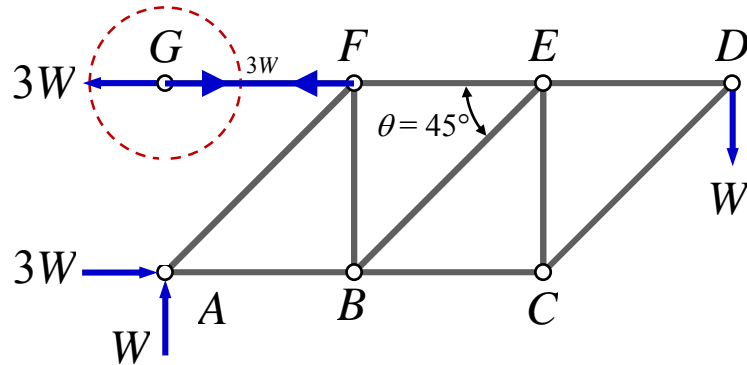
Which joints have initially two (or less) unknown forces?



**Answer:**

- Usually the joints with known **applied forces** or **reaction forces**

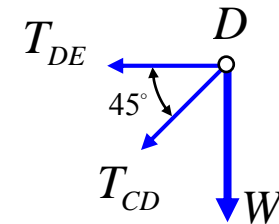
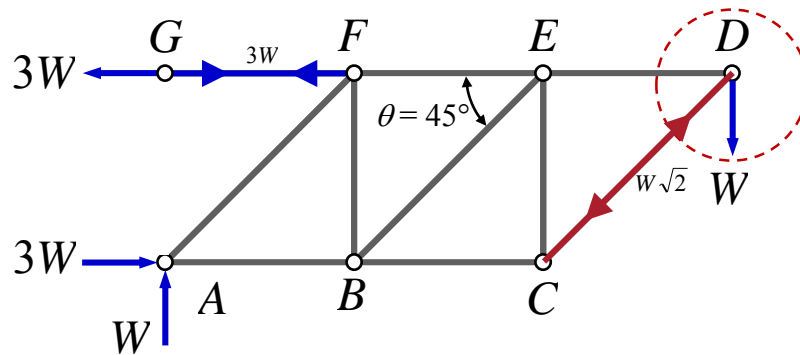
## Step 3.1: Equilibrium @ joint $G$



$$\sum F_x = 0 \quad \therefore \quad T_{FG} - 3W = 0 \quad \therefore \quad \boxed{T_{FG} = 3W}$$

A positive  $T_{FG}$  means that member  $FG$  is under **tension**

## Step 3.2: Equilibrium @ joint $D$



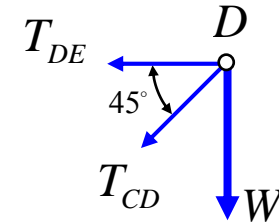
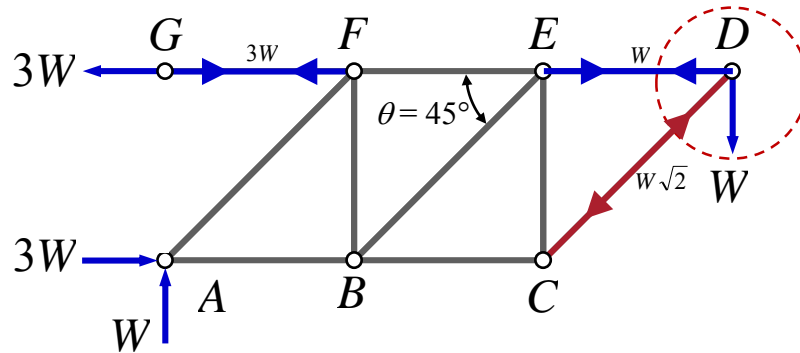
$$\sum F_y = 0 \quad \therefore \quad \overbrace{-W - T_{CD} \sin \theta}^{\text{LHS}} = 0 \quad \therefore \quad \boxed{T_{CD} = -W\sqrt{2}}$$

$\sin \theta = \frac{1}{\sqrt{2}}$

A negative  $T_{CD}$  means that member  $CD$  is under **compression**

- For the equilibrium equations write all terms on the **left-hand side (LHS)** to allow a consistent interpretation of signs
- Define the sign of each term on the LHS based on a certain reference (e.g. follow the external sign convention)

## Step 3.2: Equilibrium @ joint $D$



And horizontal equilibrium gives:

$$\sum F_x = 0 \quad \therefore \quad -T_{DE} - T_{CD} \cos \theta = 0 \quad \therefore \quad T_{DE} = W$$

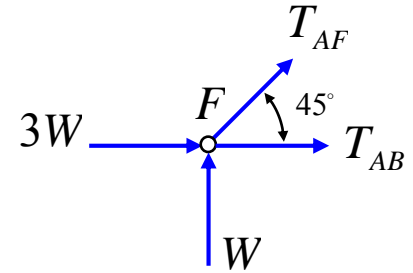
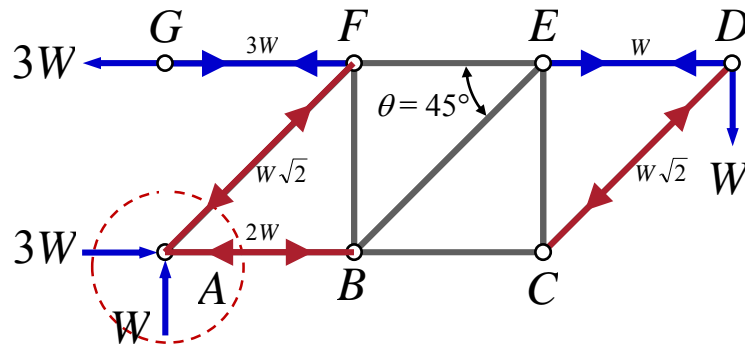
$T_{CD} = -W\sqrt{2}$

$\cos \theta = \frac{1}{\sqrt{2}}$

A positive  $T_{DE}$  means that member  $DE$  is under **tension**



## Step 3.3: Equilibrium @ joint A



Vertical equilibrium:

$$\sum F_y = 0 \quad \therefore \quad W + T_{AF} \sin \theta = 0 \quad \therefore \quad T_{AF} = -W\sqrt{2}$$

$\sin \theta = \frac{1}{\sqrt{2}}$

Horizontal equilibrium:

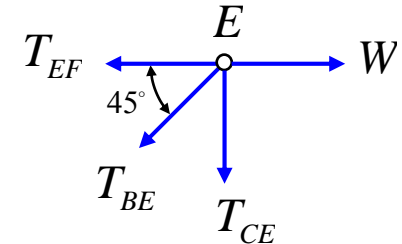
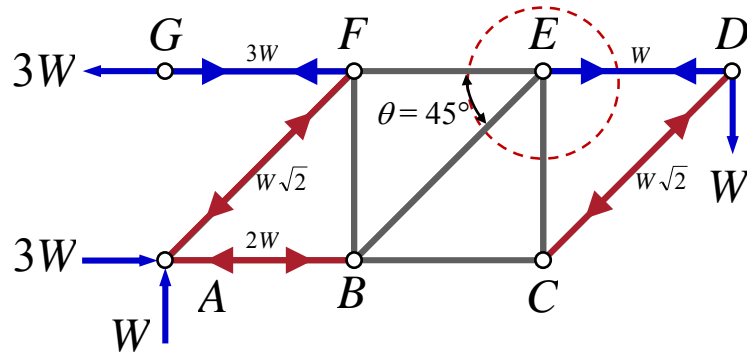
$$\sum F_x = 0 \quad \therefore \quad 3W + T_{AB} + T_{AF} \cos \theta = 0 \quad \therefore \quad T_{AB} = -2W$$

$T_{AF} = -W\sqrt{2}$

$\cos \theta = \frac{1}{\sqrt{2}}$

Negative  $T_{AF}$  and  $T_{AB}$  mean that members  $AF$  and  $AB$  are both under **compression**

**Step 3.4: Equilibrium @ joint  $E$**  → Cannot be solved yet!



Vertical equilibrium:

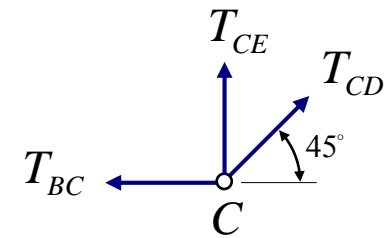
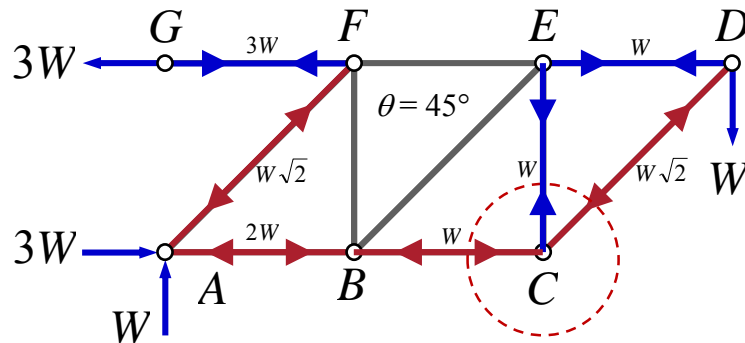
$$\sum F_y = 0 \quad \therefore \quad -T_{CE} - T_{BE} \sin \theta = 0$$

Horizontal equilibrium:

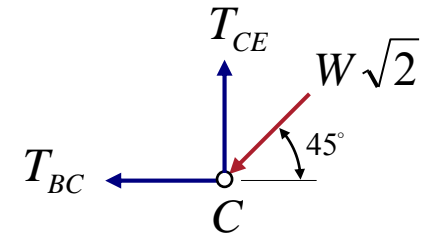
$$\sum F_x = 0 \quad \therefore \quad W - T_{EF} - T_{BE} \cos \theta = 0$$

**Too many unknowns** – no direct solution. Must choose another joint instead!

**Step 3.4:** Equilibrium @ joint  $C$  instead..



NB. We could also have drawn joint C like this:



Vertical equilibrium:

$$\sum F_y = 0 \quad \therefore \quad T_{CE} + \boxed{T_{CD} = -W\sqrt{2}} \sin \theta = 0 \quad \therefore \quad \boxed{T_{CE} = W}$$

$$\boxed{\sin \theta = \frac{1}{\sqrt{2}}}$$

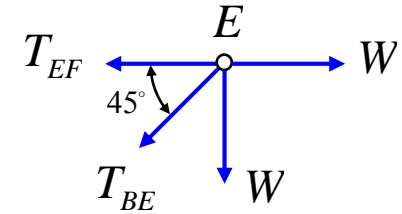
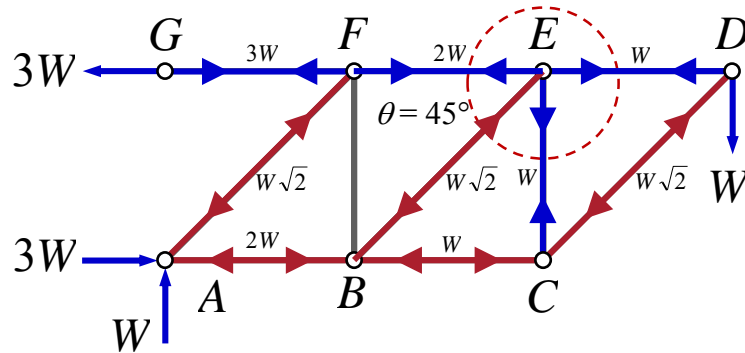
Horizontal equilibrium:

$$\sum F_x = 0 \quad \therefore \quad -T_{BC} + \boxed{T_{CD} = -W\sqrt{2}} \cos \theta = 0 \quad \therefore \quad \boxed{T_{BC} = -W}$$

$$\boxed{\cos \theta = \frac{1}{\sqrt{2}}}$$

A negative  $T_{BC}$  means that member  $BC$  is under **compression**

## Step 3.5: Equilibrium @ joint $E$ (again)



Vertical equilibrium:

$$\sum F_y = 0 \quad \therefore \quad -W - T_{BE} \sin \theta = 0 \quad \therefore \quad T_{BE} = -W\sqrt{2}$$

$\sin \theta = \frac{1}{\sqrt{2}}$

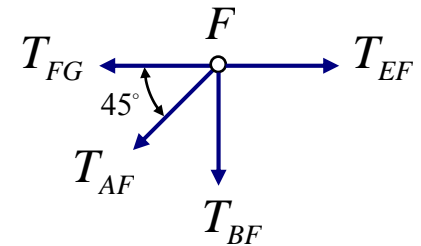
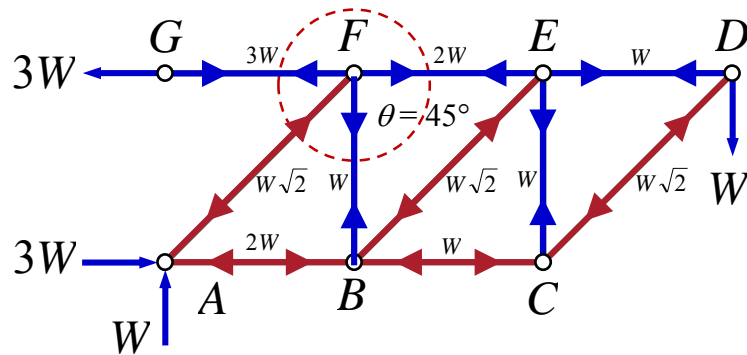
Horizontal equilibrium:

$$\sum F_x = 0 \quad \therefore \quad W - T_{EF} - T_{BE} \cos \theta = 0 \quad \therefore \quad T_{EF} = 2W$$

$\cos \theta = \frac{1}{\sqrt{2}}$

A negative  $T_{BE}$  means that member  $BE$  is under **compression**

## Step 3.6: Equilibrium @ joint $F$



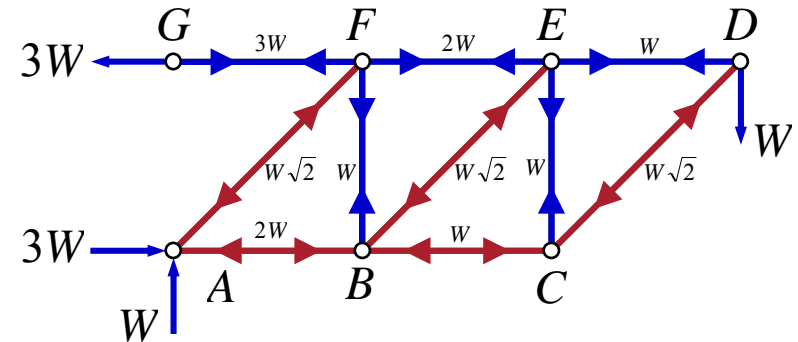
Vertical equilibrium:

$$\sum F_y = 0 \quad \therefore \quad -T_{BF} - T_{AF} \sin \theta = 0 \quad \therefore \quad T_{BF} = W$$

$T_{AF} = -W\sqrt{2}$   
 $\sin \theta = \frac{1}{\sqrt{2}}$

And this completes our map of internal forces!

**Result:** Magnitude and sense of all forces:



Always conduct a final ‘sanity check’:

- Imagine the **deformed geometry** and check whether your forces have the correct sense
- Don’t worry, you should get better at this with time and practice

Results of a computer (Finite Element) simulation:

- Member forces are in perfect agreement with our hand-calcs!

