# Advanced Bending and Torsion Unsymmetric Bending – Direct Stresses

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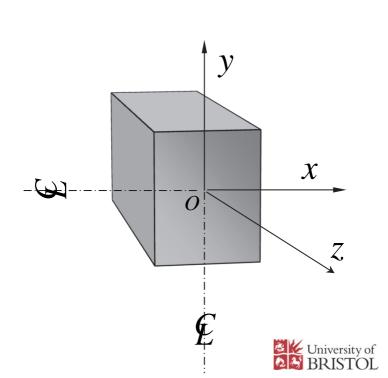
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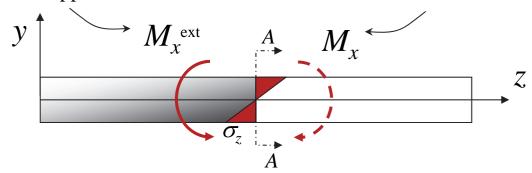
# Symmetric bending

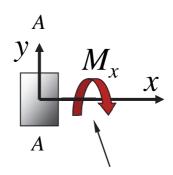
- Loading is applied in a principal plane of the cross section so that the neutral axis is coincident with a principal axis and the resulting deflection is in plane of loading only
- Example: beam of rectangular cross-section loaded in a plane of symmetry
- Assumptions:
  - Loading is applied in a principal plane
  - Deformations are small
  - Plane sections remain plane
  - Shear deformation is neglected
  - Material response is linear elastic



External applied moment at *A-A* 

Internal 'stress resultant' moment at A-A





We recall the simple bending relation from StM1:

elation from StM1: Right-hand rule 
$$\sigma = E$$

- Note that it only applies to symmetric bending
  - i.e. bending about principal axes
- Therefore we need to 'expand' our beam theory to account for offaxis bending

Suffixes are usually omitted for 2D bending:

$$M = M_{\chi}$$
  $I = I_{\chi\chi}$   $\chi = \chi_p$   $\sigma = \sigma_z$   $\varepsilon = \varepsilon_z$ 

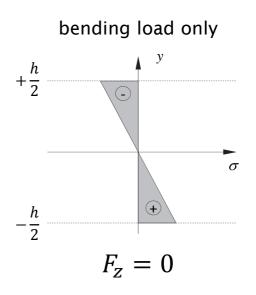


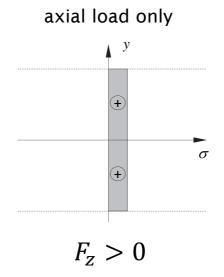
### **StM1** Recap: Stress-Resultant Axial Forces

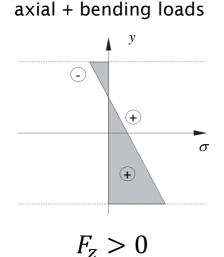
For a constant width b, the resultant internal axial force  $F_z$  can be interpreted as the 'summation' of the 'areas' under the curves of stress distribution through the thickness

 $F_Z = b \int_{-\frac{h}{2}}^{\frac{n}{2}} \sigma_Z \, \mathrm{d}y$ 

(Note that these areas can have different 'signs')







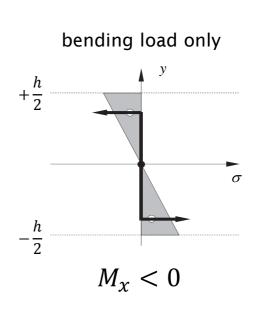


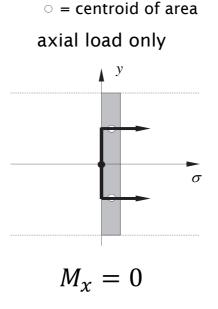
## **StM1** Recap: Stress-Resultant Bending Moment

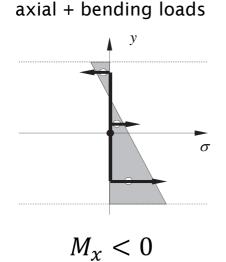
The internal bending moment is given by the integral:

$$M_{x} = b \int_{-\frac{h}{2}}^{\frac{h}{2}} \sigma_{z} y \, \mathrm{d}y$$

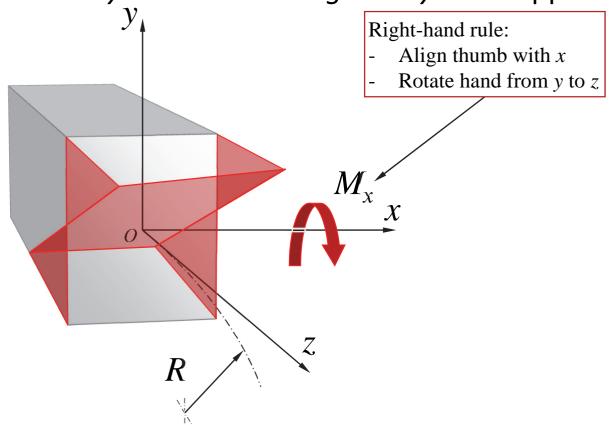
• This can be interpreted as the 'moment of area' of the stress distribution:





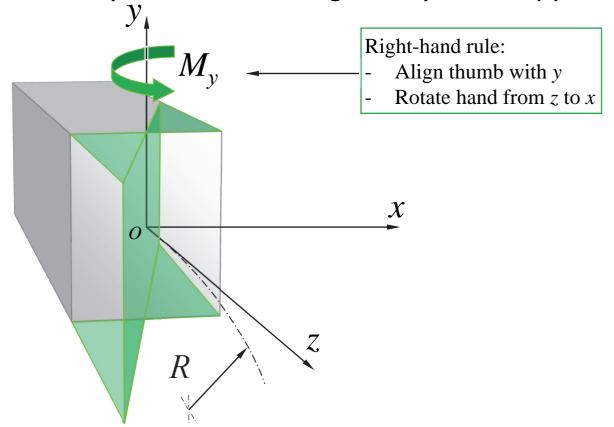






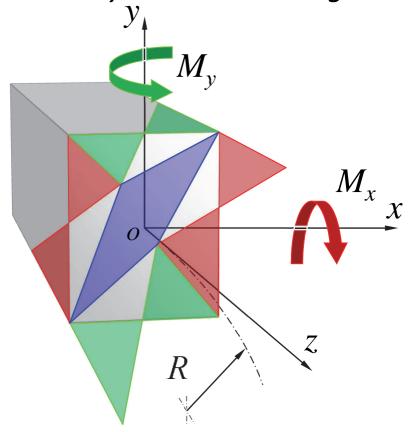
- Internal sign convention: tension = positive, compression = negative
- External sign convention: right-hand rule about all each axis





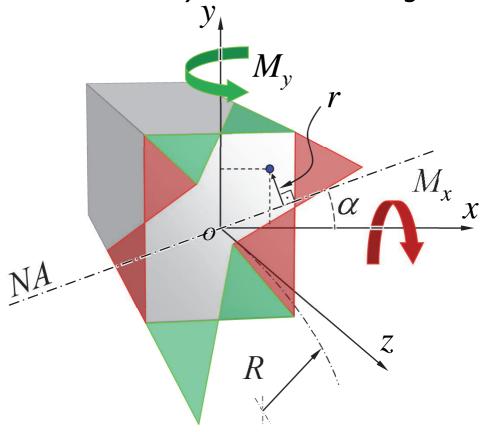
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- Internal sign convention: tension = positive, compression = negative
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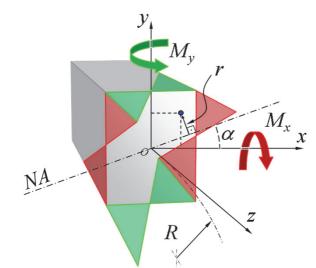


- Internal sign convention: tension = positive, compression = negative
- External sign convention: right-hand rule about all each axis



# 3D Bending Stresses

- Plane sections remain plane:  $\varepsilon_z = \frac{1}{R}r$
- Linear elasticity:  $\sigma_z = E \ \varepsilon_z = \frac{E}{R} r$
- NA rotation:  $r = -x \sin \alpha + y \cos \alpha$
- Re-writing:  $\sigma_z = \frac{E}{R}(-x \sin \alpha + y \cos \alpha)$



Now replacing in the 'stress resultant' moment equations:

$$M_x = \int y \, \sigma_z \, \mathrm{d}A$$

$$M_{y} = \int x \, \sigma_{z} \, \mathrm{d}A$$

$$M_{x} = \frac{E}{R} \int y \left( -x \sin \alpha + y \cos \alpha \right) dA$$

$$M_{y} = -\frac{E}{R} \int x \left( -x \sin \alpha + y \cos \alpha \right) dA$$

$$M_{x} = -\frac{E}{R}\sin\alpha \int x y \, dA + \frac{E}{R}\cos\alpha \int y^{2} \, dA$$

$$M_{y} = \frac{E}{R} \sin \alpha \int x^{2} dA - \frac{E}{R} \cos \alpha \int x y dA$$

$$M_{x} = \frac{E}{R}\cos\alpha \ I_{xx} - \frac{E}{R}\sin\alpha \ I_{xy}$$

$$M_{y} = \frac{E}{R}\sin\alpha \ I_{yy} - \frac{E}{R}\cos\alpha \ I_{xy}$$



$$M_{x} = \frac{E}{R}\cos\alpha \ I_{xx} - \frac{E}{R}\sin\alpha \ I_{xy}$$

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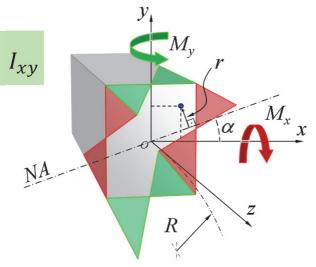
• Re-writing in terms of  $\frac{E}{R}\cos\alpha$  and  $\frac{E}{R}\sin\alpha$ :

$$\frac{E}{R}\sin\alpha = \frac{-M_y I_{xx} - M_x I_{xy}}{I_{xx} I_{yy} - I_{xy}^2}$$

$$\frac{E}{R}\cos\alpha = \frac{M_x I_{yy} + M_y I_{xy}}{I_{xx} I_{yy} - I_{xy}^2}$$

• Substituting in  $\sigma_z = \frac{E}{R}(-x \sin \alpha + y \cos \alpha)$  gives:

$$\sigma_z = \frac{M_y I_{xx} + M_x I_{xy}}{I_{xy}^2 - I_{xx} I_{yy}} x + \frac{M_x I_{yy} + M_y I_{xy}}{I_{xx} I_{yy} - I_{xy}^2} y$$





• For composite beams where  $I_{xx}$ ,  $I_{yy}$  and  $I_{xy}$  are obtained using the 'scaled area' method, the assumption that 'plane sections remain plane' (i.e. 'iso-strain' assumption in composites terminology) gives:

$$\sigma_{z} = \left(\frac{M_{y} I_{xx} + M_{x} I_{xy}}{I_{xy}^{2} - I_{xx} I_{yy}} x + \frac{M_{x} I_{yy} + M_{y} I_{xy}}{I_{xx} I_{yy} - I_{xy}^{2}} y\right) n_{i}$$

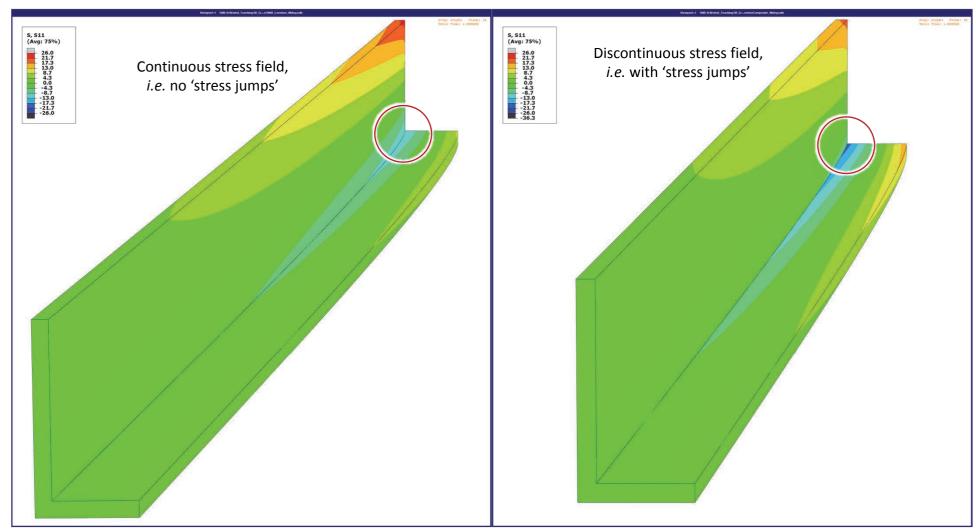
- So the stress field is now discontinuous, i.e. there are 'stress jumps' between domains i with different Young's moduli
- Domains with higher modulus will have higher stresses and therefore a greater contribution towards the load carrying capacity of the structure



# 3D Bending Stresses – Composite Beams

#### Aluminium Alloy

#### Aluminium Alloy + Steel





#### 3D Bending Stresses – Neutral Axis

$$\sigma_z = \frac{M_y I_{xx} + M_x I_{xy}}{I_{xy}^2 - I_{xx} I_{yy}} x + \frac{M_x I_{yy} + M_y I_{xy}}{I_{xx} I_{yy} - I_{xy}^2} y$$

 Bending stresses are <u>zero</u> along the neutral axis, therefore:

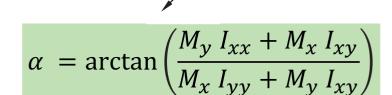
$$\frac{M_y I_{xx} + M_x I_{xy}}{I_{xy}^2 - I_{xx} I_{yy}} x_{NA} + \frac{M_x I_{yy} + M_y I_{xy}}{I_{xx} I_{yy} - I_{xy}^2} y_{NA} = 0$$

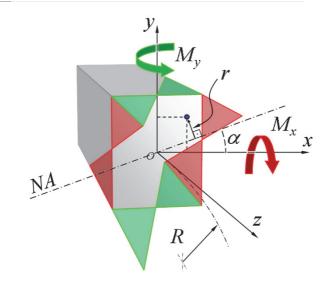
$$\frac{M_x I_{yy} + M_y I_{xy}}{I_{xx} I_{yy} - I_{xy}^2} y_{NA} = -\left(\frac{M_y I_{xx} + M_x I_{xy}}{I_{xy}^2 - I_{xx} I_{yy}}\right) x_{NA}$$

$$\frac{M_x \, I_{yy} + M_y \, I_{xy}}{I_{xx} \, I_{yy} - I_{xy}^2} y_{NA} = -\left(\frac{-M_y \, I_{xx} - M_x \, I_{xy}}{I_{xx} \, I_{yy} - I_{xy}^2}\right) x_{NA}$$

$$y_{NA} = -\left(\frac{-M_{y} I_{xx} - M_{x} I_{xy}}{M_{x} I_{yy} + M_{y} I_{xy}}\right) x_{NA}$$

$$\tan \alpha = \frac{M_y I_{xx} + M_x I_{xy}}{M_x I_{yy} + M_y I_{xy}}$$





This also applies to composite beams since  $I_{xx}$ ,  $I_{yy}$  and  $I_{xy}$  are 'scaled' properties

