

Vibrations 2, Lecture 21

Static Aeroelasticity

Control effectiveness & control reversal

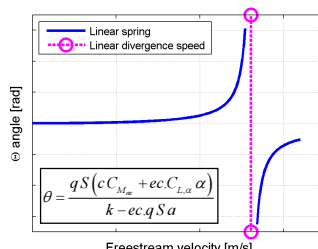
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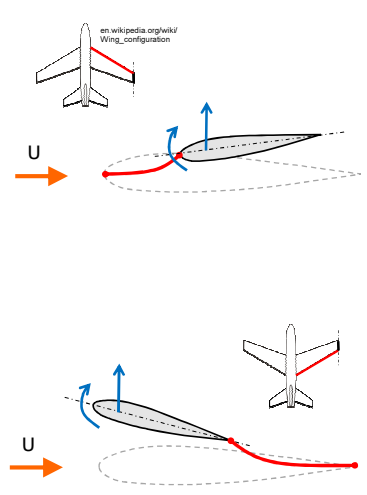
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Lecture 20 review

Divergence:



$$\theta = \frac{qS(cC_{M_{\alpha}} + ecC_{L,\alpha})}{k - ecqSa}$$

$$U_D = \sqrt{\frac{2k}{ecSC_{L,\alpha}\rho}}$$


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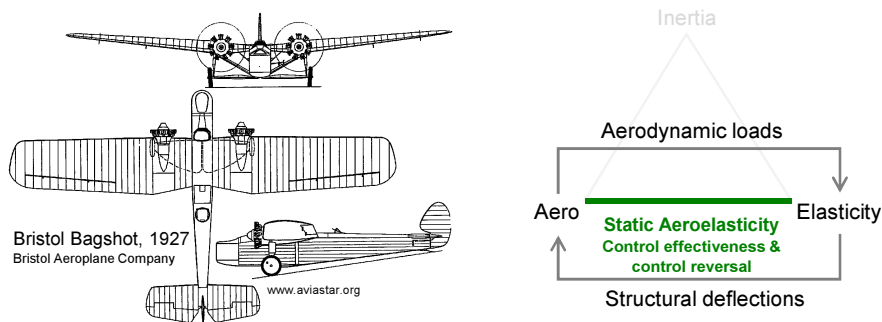
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Background

- Control surfaces
 - Change effective camber of aerofoil and therefore lift
 - Used to manoeuvre aircraft in-flight
- Static aeroelastic deflections
 - Application of control surface rotation causes wing deflection
 - Changes effectiveness of control surfaces
- Reversal speed and Control reversal
 - Speed at which control surfaces have no effect
 - Beyond reversal speed, control surfaces have opposite effect

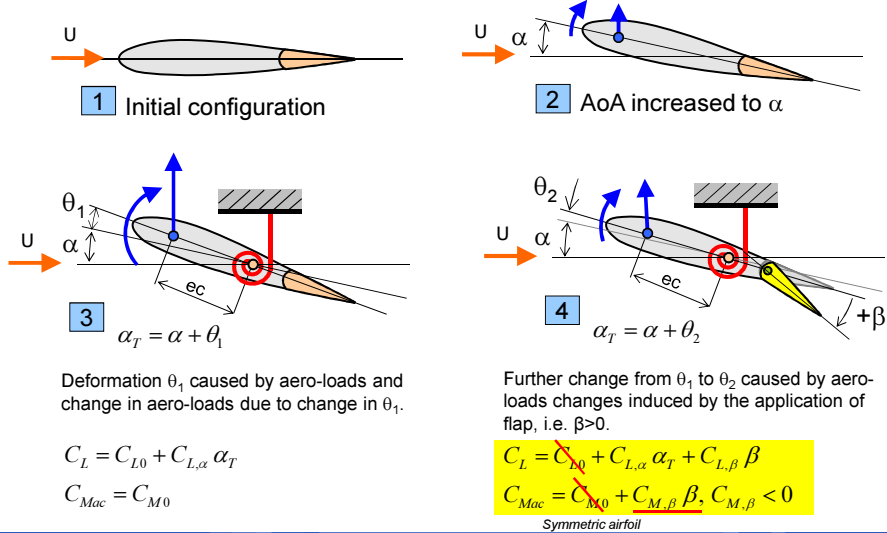
Bristol Bagshot



"The Bagshot was first flown ... at Filton on 15 July 1927 by Cyril Uwins, Bristol's chief test pilot. This first flight was short: 'Always a bad sign' remarks Archibald Russell (later Sir Archibald), who at that time was working in the stress calculations office at Filton. Uwins reported that **control in the roll axis was poor**. A second flight, during which Uwins pushed the speed up to 100 mph, revealed that **the problem became worse as the speed increased**. ... By the time the aircraft reached the agreed speed and height for the trials ... the "**writhing movements**" of the wing were "**large and alarming**" ... **It was concluded that control reversal resulting from twisting of the wing when the ailerons were applied was the cause of the problems. The aircraft was grounded for a structural test to be made.**", https://en.wikipedia.org/wiki/Bristol_Bagshot

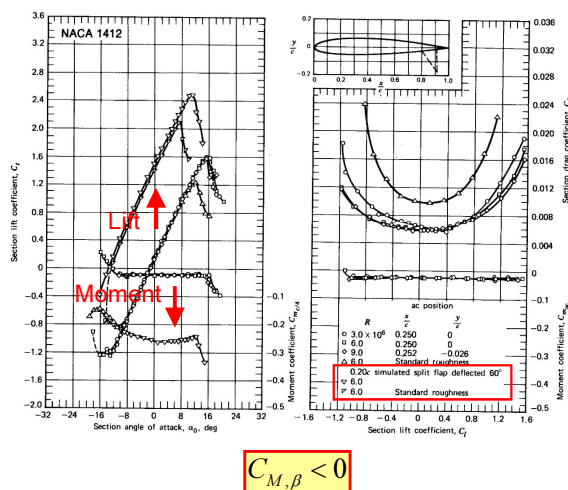
Aeroelastic response with flap

Torsionally supported rigid wing with a control surface placed in airstream:



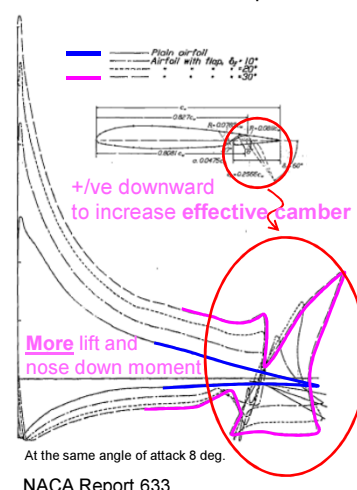
Static airfoil characteristics

e.g. NACA charts:



$$C_{M,\beta} < 0$$

Pressure distribution change over an airfoil with a slotted flap



Equation of moment equilibrium

Aerodynamics:

$$C_L = C_{L,\alpha} \alpha + C_{L,\beta} \beta$$

$$C_{Mac} = C_{L,\alpha} \alpha_T + C_{M,\beta} \beta$$

Static equilibrium:

$$\sum_{(i)} M_i = 0$$

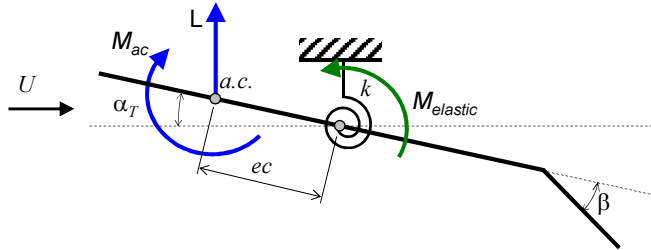
$$ec.L + M_{ac} = M_{elastic}$$

$$ec.qS(C_{L,\alpha} \alpha_T + C_{L,\beta} \beta) + qSc(C_{M,\beta} \beta) = k\theta$$

$$ec.qS(C_{L,\alpha} (\alpha_r + \theta) + C_{L,\beta} \beta) + qSc(C_{M,\beta} \beta) = k\theta$$

Aeroelastic response:

$$\theta = \frac{qS(ec.C_{L,\alpha} \alpha_r + (cC_{M,\beta} + ec.C_{L,\alpha})\beta)}{k - ec.qSC_{L,\alpha}}$$



Lift:

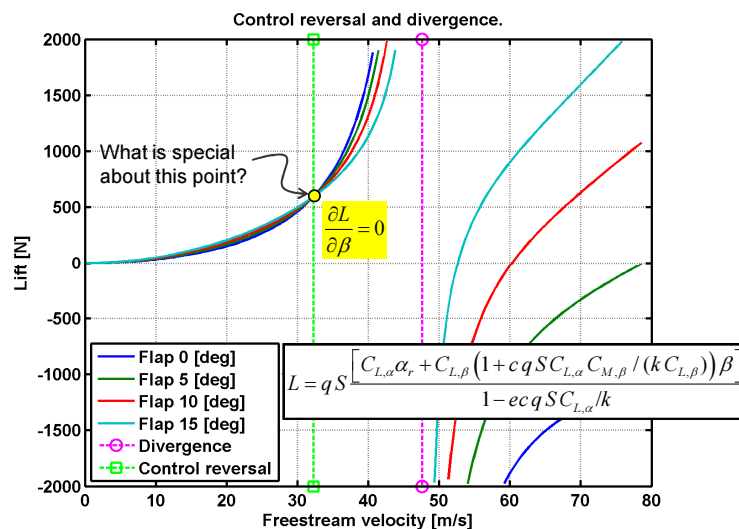
$$L = qSC_L = qS(C_{L,\alpha}(\alpha_r + \theta) + C_{L,\beta}\beta) = \dots$$

...

$$L = qS \left[\frac{C_{L,\alpha} \alpha_r + C_{L,\beta} \left(1 + \frac{ec q S C_{L,\alpha} C_{M,\beta}}{k C_{L,\beta}} \right) \beta}{1 - \frac{ec q S C_{L,\alpha}}{k}} \right]$$

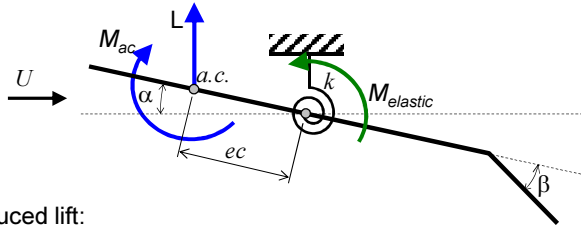
... from this: Lift sensitivity = $dL/d\beta$

Lift = function(U,beta)



Download example script from BB: ae_controlrev.m

Control reversal speed U_R



Resulting induced lift:

$$L = qS \left[C_{L,\alpha} \alpha_r + C_{L,\beta} \left(1 + \frac{c q S C_{L,\alpha} C_{M,\beta}}{k C_{L,\beta}} \right) \beta \right]$$

Divergence pressure:

$$1 - \frac{ec q S C_{L,\alpha}}{k} = 0 \Rightarrow q_D = \frac{k}{ec S C_{L,\alpha}}$$

Control reversal point:

$$\frac{\partial L}{\partial \beta} = qS \frac{C_{L,\beta} \left(1 + \frac{c q S C_{L,\alpha} C_{M,\beta}}{k C_{L,\beta}} \right)}{1 - \frac{ec q S C_{L,\alpha}}{k}} = 0$$

$$q S C_{L,\beta} \left(1 + \frac{c q S C_{L,\alpha} C_{M,\beta}}{k C_{L,\beta}} \right) = 0$$

$$q_R(U_R) = - \frac{k C_{L,\beta}}{Sc C_{L,\alpha} C_{M,\beta}} \quad \text{Reversal pressure}$$

Lift effectiveness

Rigid aerofoil: $k \rightarrow \text{Infinity}$

$$\frac{\partial L}{\partial \beta} = q S C_{L,\beta} \frac{1 + \frac{c q S C_{L,\alpha} C_{M,\beta}}{k C_{L,\beta}}}{1 - \frac{ec q S C_{L,\alpha}}{k}} \rightarrow \frac{\partial L}{\partial \beta} \Big|_{\text{rigid}} = q S C_{L,\beta}$$

Divergence and control reversal dynamic pressures:

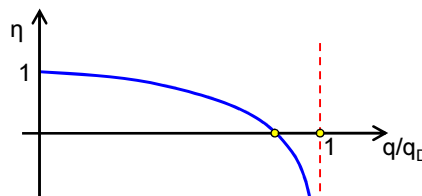
$$q_D = \frac{k}{ec \cdot S C_{L,\alpha}} \quad q_R = - \frac{k C_{L,\beta}}{Sc C_{L,\alpha} C_{M,\beta}}$$

Then, lift sensitivity to control:

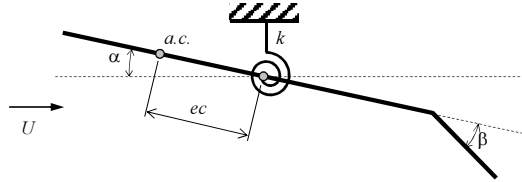
$$\frac{\partial L}{\partial \beta} = q S C_{L,\beta} \frac{(1 - q/q_R)}{(1 - q/q_D)}$$

Finally, **lift effectiveness**:
(or normalized lift sensitivity)

$$\eta = \frac{\partial L / \partial \beta|_{\text{elastic}}}{\partial L / \partial \beta|_{\text{rigid}}} = \frac{1 - q/q_R}{1 - q/q_D}$$



Control reversal and roll control



Downward displacement of aileron causes extra lift:

- (a) rolling moment
- (b) nose-down pitching moment:
elastic deformation \rightarrow reduced lift \rightarrow reduced rolling moment!

At a critical speed, the net effect of deflecting the aileron becomes zero, in which case the aileron is totally ineffective! This is the *critical aileron reversal speed*.

- Below critical speed, right aileron deflection left wing tip down,
- Above critical speed, right aileron deflection right wing tip down,
- Aileron becomes more ineffective nearer to critical speed.

Summary

- Control reversal (flaps, ailerons, etc.):
 - **Definition:** Control reversal is the loss, due to the flexibility of the primary aerostructure, of aircraft maneuvering loads induced by control surfaces [Platanitis & Strganac, 2005].
- Important parameters:
 - Torsional stiffness,
 - Aerodynamic derivatives.