

# Structural Loads in Trusses

## Method of Sections

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## 1.2.1 Method of Joints

## 1.2.2 Method of Sections

## 1.2.3 Method of Tension Coefficients

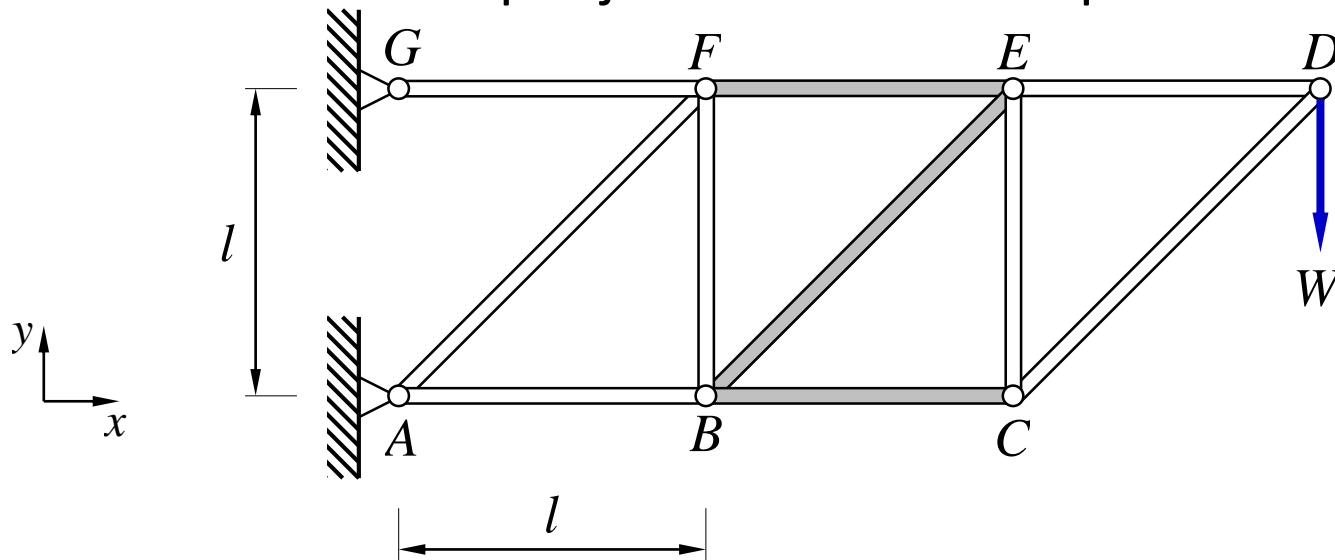
- In two dimensions (2D)
- In three dimensions (3D)

- Based on the **same principles** and **assumptions** as before
- Especially useful for **slender** trusses – i.e. ‘long and thin’
- Consists of **sectioning** the truss along a certain plane to expose a **maximum of three** internal forces
- Using the **three equilibrium equations** we can then determine these internal forces
- **Does not replace** the method of joints – in fact you still need the latter to find remaining internal forces

1. Calculate the degree of redundancy **before** finding unloaded members
2. Apply our **collinearity rules** to identify unloaded members
3. Create a **global FBD** for the entire structure
  - Draw positive reaction forces following the **external sign convention**
  - Write the **three** equilibrium equations:  $\sum F_x = 0 \quad \sum F_y = 0 \quad \sum M = 0$ 
    - Find the reaction forces at supports
4. ‘Section’ the truss to **expose internal forces** (maximum of 3)
  - Take one of the sectioned parts and treat it as an **independent truss**
  - Again, use the **three** equilibrium equations:  $\sum F_x = 0 \quad \sum F_y = 0 \quad \sum M = 0$ 
    - Find the ‘exposed’ internal forces
5. If necessary, use the **method of joints** to find other internal forces!

Exactly as before

- Consider the same pin-jointed truss example:



- Suppose we are only interested in members  $EF$ ,  $BE$  and  $BC$
- As seen earlier we apply the three global equilibrium equations to find the reactions:

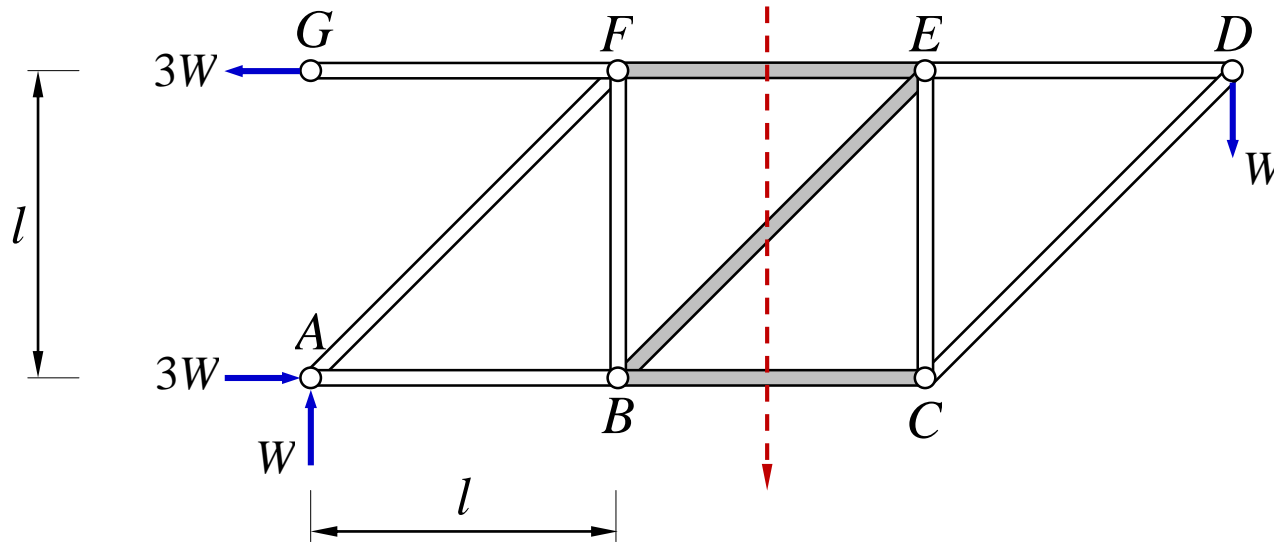
$$R_{Ax} = 3W$$

$$R_{Ay} = W$$

$$R_{Gx} = -3W$$

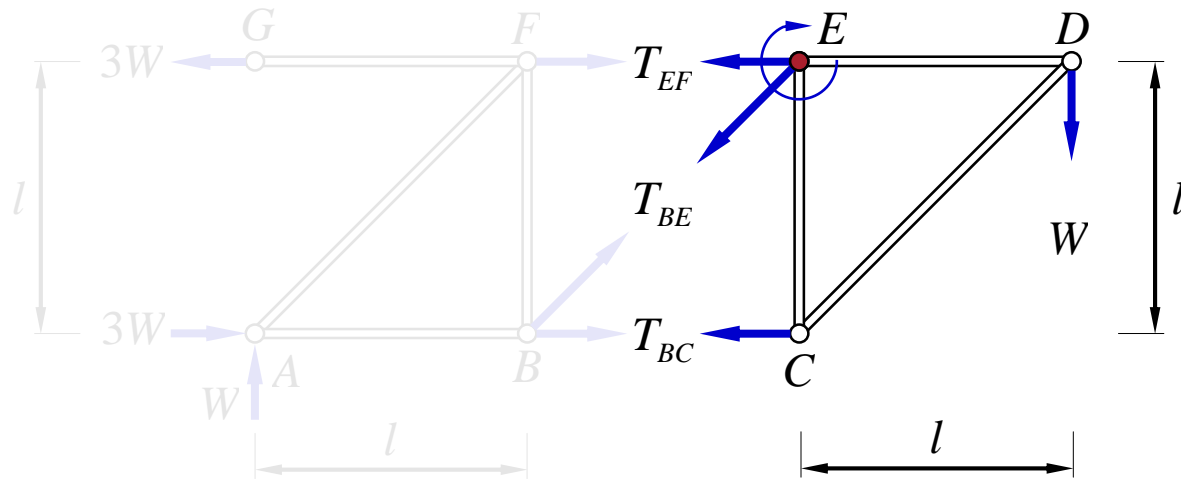
$$R_{Gy} = 0$$

- Now all reactions and external forces are known:



- Suppose we are only interested in members  $EF$ ,  $BE$  and  $BC$
- By **sectioning** the truss along a vertical line we can 'expose' the three wanted internal forces

- The sectioned truss would look like this:



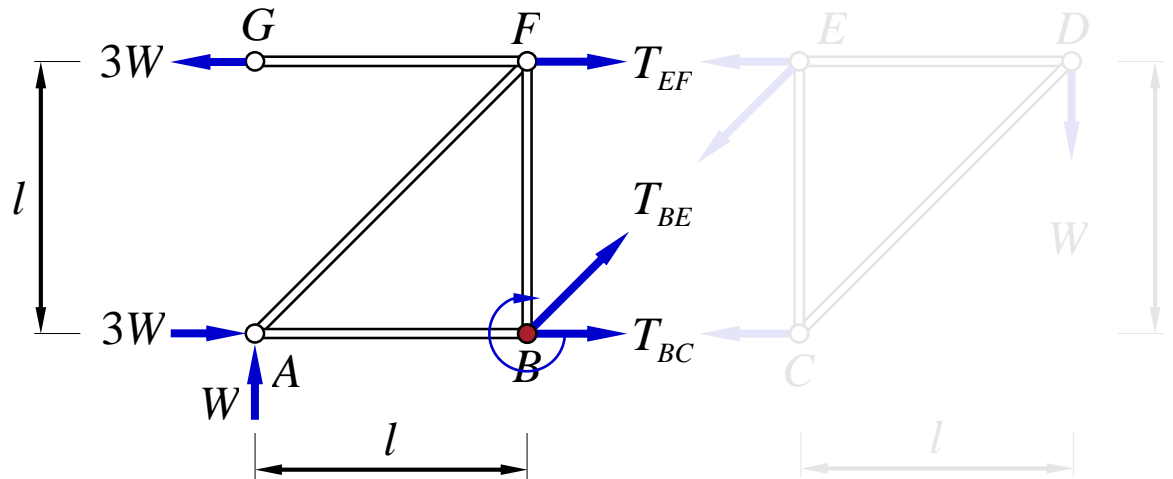
- Starting by the right-hand-side (RHS), the convenient pivot is joint  $E$

$$\sum M_{@E}^{CW} = 0 \quad \therefore \quad W(l) + T_{BC}(l) = 0 \quad \therefore \quad T_{BC} = -W$$

- We can also analyse the vertical equilibrium of the entire RHS:

$$\sum F_y = 0 \quad \therefore \quad -W - T_{BE} \sin \theta = 0 \quad \therefore \quad T_{BE} = -W\sqrt{2}$$

- Now the LHS. The convenient pivot for balancing the moments is joint  $B$



$$\sum M_{@B}^{CW} = 0 \quad \therefore \quad T_{EF}(l) + W(l) - 3W(l) = 0 \quad \therefore \quad T_{EF} = 2W$$

- We can also apply horizontal equilibrium to the entire LHS:

$$\sum F_x = 0 \quad \therefore \quad 3W - 3W + T_{EF} + T_{BC} + T_{BE} \cos \theta = 0 \quad \therefore \quad T_{BC} = -W$$

- The **remaining unknowns** are then obtained by the **method of joints**