

# Flight Dynamics and Control 2

## Lecture 1 - Introduction

Dr Tom Richardson & Professor Mark Lowenberg  
Department of Aerospace Engineering  
University of Bristol  
*thomas.richardson@bristol.ac.uk*

February 19, 2019

# Contact Information

- ▶ Professor Mark Lowenberg - Rm 1.37  
Email: [M.Lowenberg@bristol.ac.uk](mailto:M.Lowenberg@bristol.ac.uk)
- ▶ Dr Tom Richardson - Rm 1.53  
Email: [thomas.richardson@bristol.ac.uk](mailto:thomas.richardson@bristol.ac.uk)



100  
years!



1903 Wright Flyer

*Smithsonian National Air and Space Museum*



## Dr Tom Richardson - Microlight





- Sensors in the loop
- Air-to-air refuelling
- Real-time operation
- Full nonlinear simulation environment

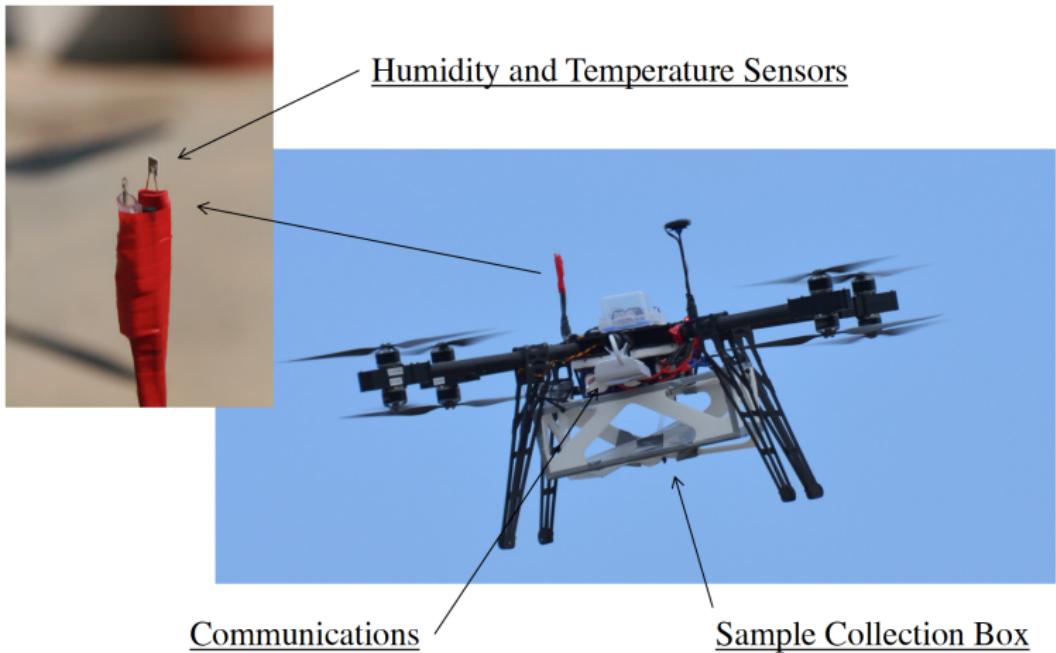


# Machine Learning - Dr Tom Richardson





# Final Flight Vehicle

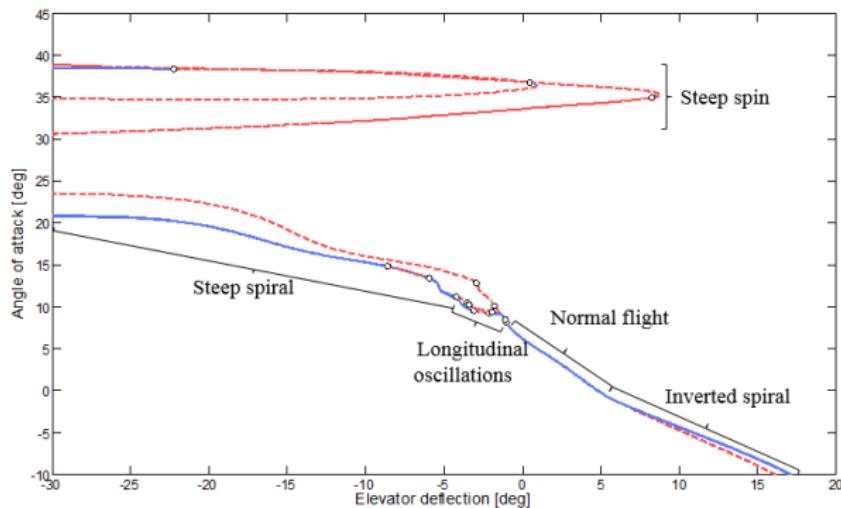




Ascension Island 2014-2015

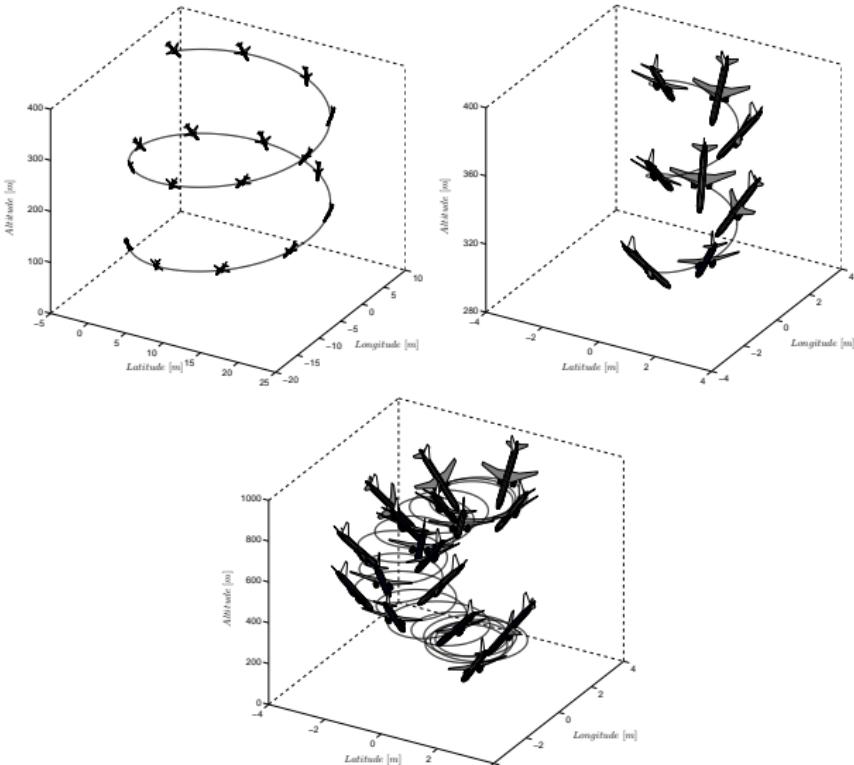
# Mark Lowenberg: airliner loss-of-control studies

NASA Generic Transport Aircraft (GTM) model



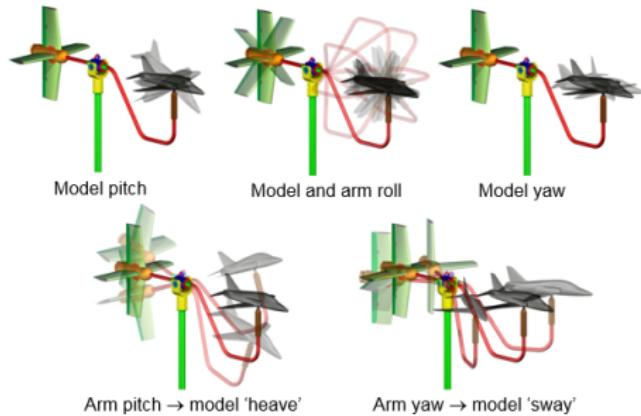
# Mark Lowenberg: airliner loss-of-control studies

## NASA Generic Transport Aircraft (GTM) model



# Mark Lowenberg: experimental nonlinear flight dynamics

## University of Bristol Manoeuvre Rig



# Controlled Atmospheric Flight



- Forces & Moments
- Stability
- Modelling & Simulation
- Control

# Context within the four year Aerospace MEng course



# Degree Programme

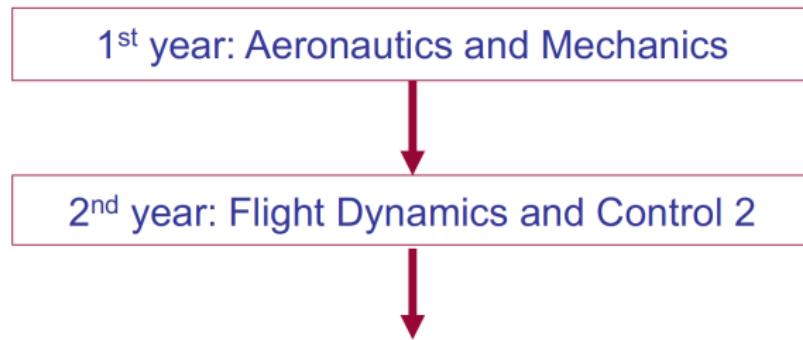
1<sup>st</sup> year: Aeronautics and Mechanics



# Aeronautics and Mechanics

- ▶ Introduces the concepts of static and dynamic mechanics
- ▶ Introduces basic aerodynamic principles
- ▶ Characteristics and performance of aircraft in flight
- ▶ Introduces some other aspects of aviation through specialised lectures

# Degree Programme

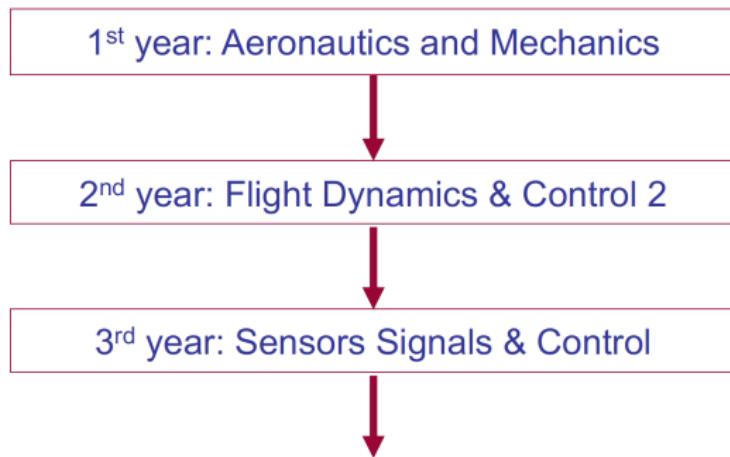




# Flight Dynamics and Control 2

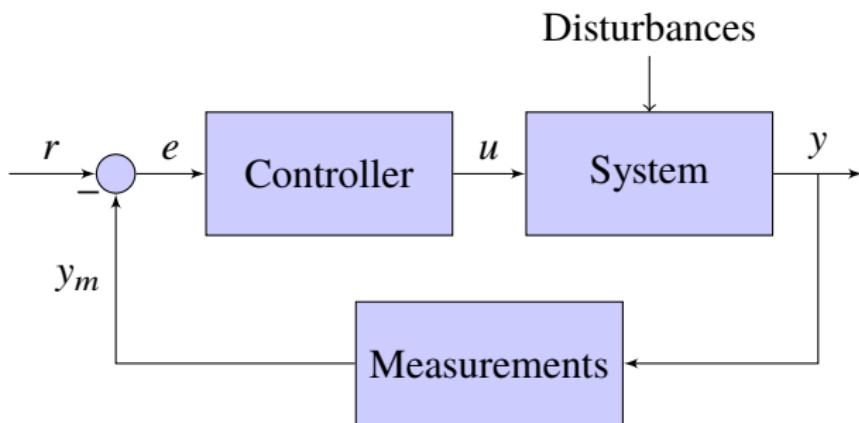
- ▶ Multi-degree of freedom systems - i.e. Aircraft
- ▶ Methods for predicting principle forces acting on the whole aircraft - e.g. strip theory
- ▶ Static flight balance and aircraft stability
- ▶ Equations of motion
- ▶ Methods for stability analysis
- ▶ Mathematical descriptions of aircraft motions - e.g. phugoid and short period

# Degree Programme

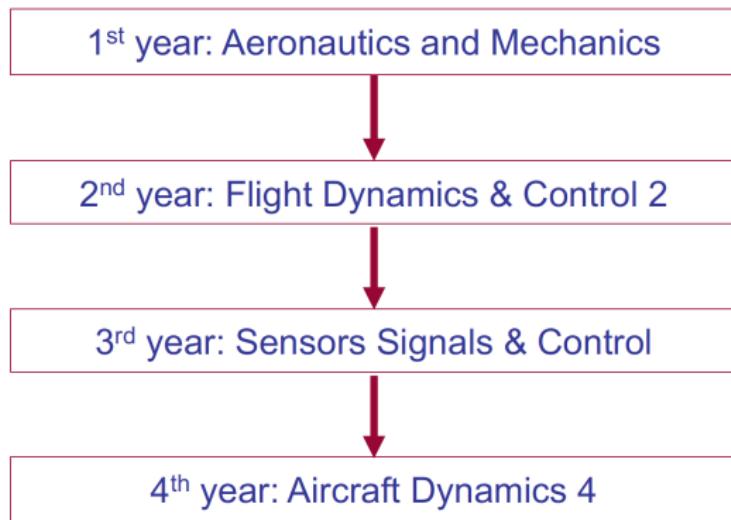


# Sensors, Signals and Control

Introduces the analysis and design of **control systems**, with particular reference to aerospace applications.



# Degree Programme



# Aircraft Dynamics 4

Brings together elements of **flight dynamics** and **control theory** into the context of aircraft design and response.

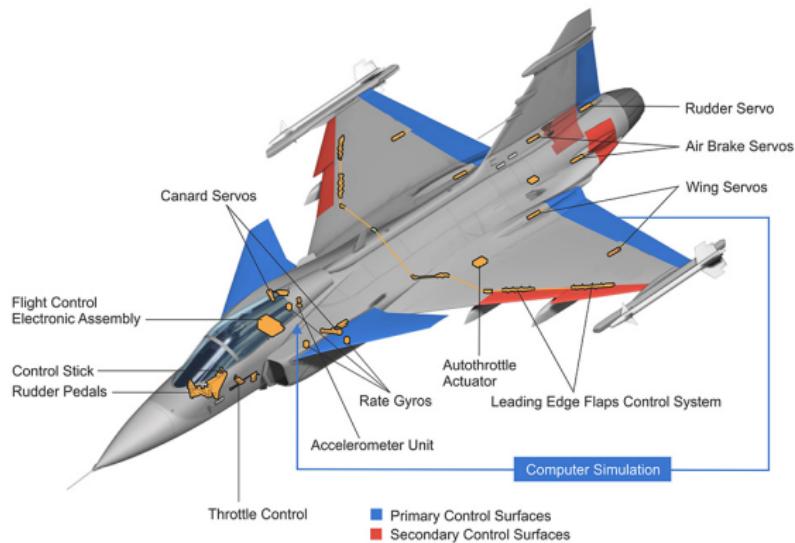


Figure: Saab Gripen - <https://saabaircraftindustry.com/>

# Flight Dynamics and Control 2 - Assessment

- ▶ 75% - examination in May/June
- ▶ 25% - flight dynamics coursework including exercises on the flight simulators.

# Flight Simulation



# Flight Dynamics and Control 2 - Course Content I

- ▶ General Introduction - References
- ▶ Notation & Reference Axes - Co-ordinate axis system and sign conventions
- ▶ Control surfaces - definitions & effect
- ▶ Strip theory
- ▶ Rigid-body equations of motion - 6 DoF
- ▶ Inertial terms
- ▶ Longitudinal balance
- ▶ Elevator angle to trim

# Flight Dynamics and Control 2 - Course Content II

- ▶ Static stability and static margin
- ▶ Manoeuvre margin
- ▶ Trimming & Linearisation
- ▶ Aircraft Modes
- ▶ Handling Qualities
- ▶ Matlab example & Assignment
- ▶ Introduction to closed loop control
- ▶ Revision lecture

# Flight Dynamics and Control 2 - References

1. Etkin, B, Reid, L.D. *Dynamics of Flight, Stability and Control*. Wiley, New York, 2011.
2. McLean, D. *Automatic Flight Control Systems*. Prentice-Hall, Hemel Hempstead 1997.
3. Prouty, R. W. *Helicopter performance, stability, and control*. 2nd edition, Krieger Publishing Company, Florida, 2001.
4. Russell, J.B. *Performance and Stability of Aircraft*. Arnold, London, 1996.
5. Cook, M.V. *Flight Dynamics Principles*. Arnold, London, 2012.

# Applications?



## Suggested Background Reading

Cook, M.V. *Flight Dynamics Principles*. Arnold, London, 2012.

Lecture 1 - *Introduction*

Lecture 2 - *Systems of axes and notation -  
Earth, Body and Euler axes*

Next Lecture

Reference Axes