

Rotary-Wing Aerospace Vehicles

**Familiarisation with rotary-wing aircraft assemblies and geometry.
Classification of rotary-wing aircraft**

30-11-2017

WITH ONLY TWO EQUATIONS

Peter Bunniss
Visiting Fellow

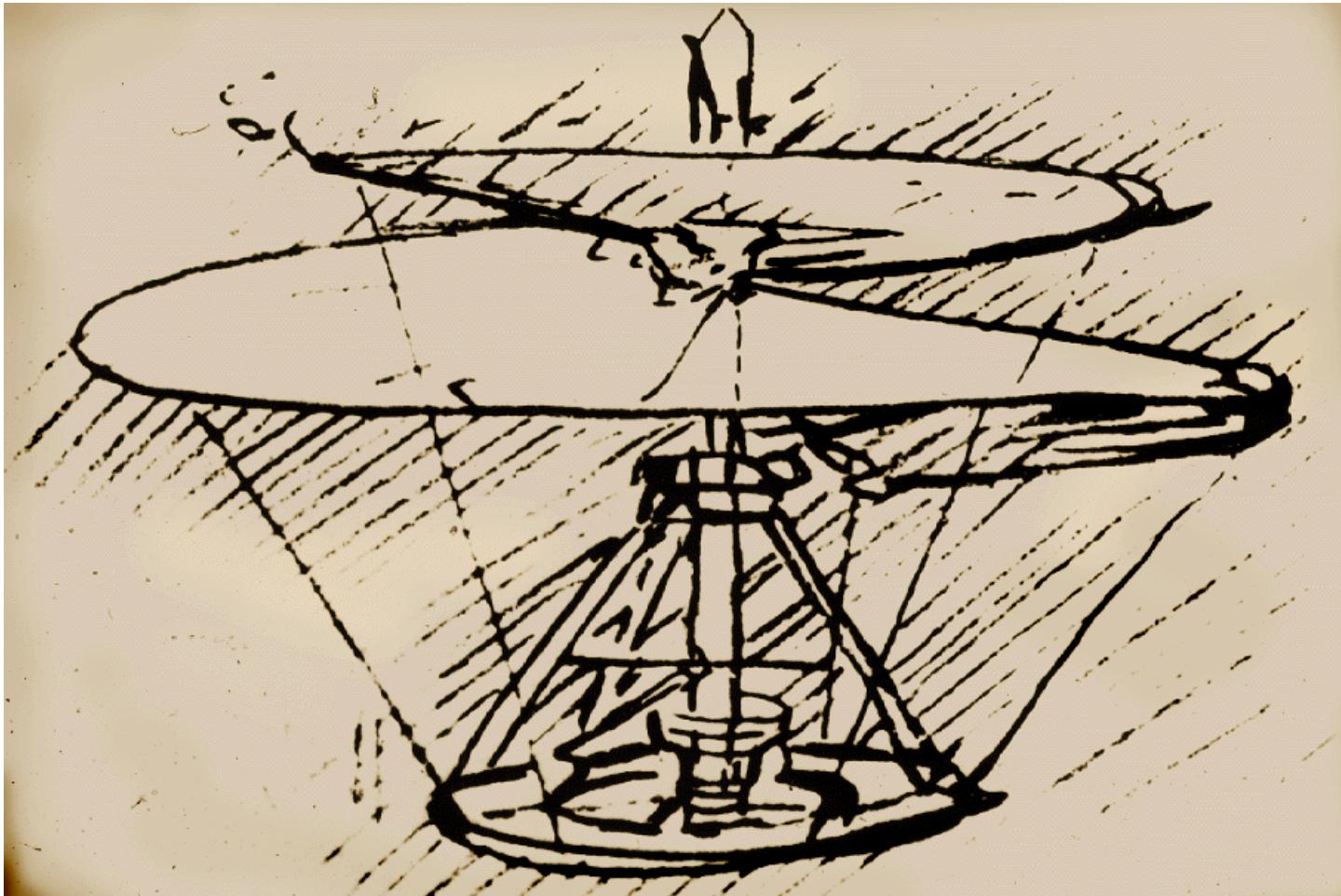
Peter.bunniss@bris.ac.uk

AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1

AENG10001

The normally accepted interpretation of “rotary-wing” aerospace vehicles are those that sustain flight by virtue of a wing that rotates about a shaft affixed to the vehicle. This form of flight is unique to man-made devices as no such mechanism exists in nature.



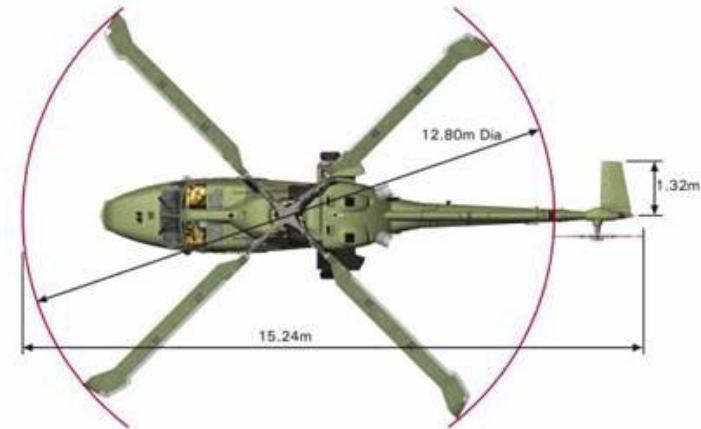
The purpose of this lecture is to:

- Differentiate between rotary-wing sustained flight and vertical take-off and landing (VTOL) capability. (true helicopters, autogyros, tilt rotors, tilt wings, prop-hangers).
- Give a brief history of rotary-wing flight. (early steam powered models, manned-“hoppers”, autogyros, helicopters).
- Follow through the path of development to the modern helicopter. (power-to-weight ratio, blade design, control issues).
- Consider the attributes of the different configurations within this class of aircraft. (conventional, coaxial, tandem, side-by-side, tip-jet, syncropter, notar).
- Provide a basic understanding of the physical performance limitations. (weight, speed, altitude, range).
- Investigate the existing and future roles for such aircraft. (MedEvac, Search And Rescue, utility work, transport, attack, heavy lift, Mars missions).
- Consider possible future configurations. (lift and thrust compounding, Advancing Blade Concept, Stopped Rotor).

AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Differentiate between rotary-wing sustained flight and vertical take-off and landing (VTOL) capability. (true helicopters, autogyros, tilt rotors, tilt wings, prop-hangers).

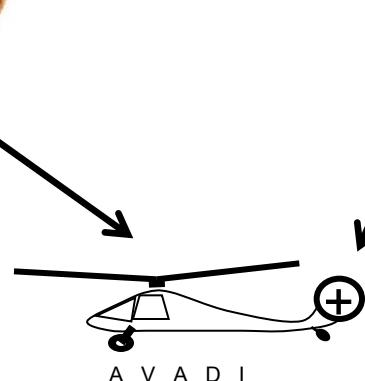


Just to go back to the term “Conventional configuration” again.

This is the most popular helicopter configuration and is generally referred to as the “*Penny Farthing*” helicopter. This is because it has a single main rotor and a single, smaller, tail rotor. It got its name from two British coins that existed before decimalisation of the British currency in 1971.



Many of you may not have known this.



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Differentiate between rotary-wing sustained flight and vertical take-off and landing (VTOL) capability. (true helicopters, autogyros, tilt rotors, tilt wings, prop-hangers).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Differentiate between rotary-wing sustained flight and vertical take-off and landing (VTOL) capability. (true helicopters, autogyros, tilt rotors, tilt wings, prop-hangers).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Differentiate between rotary-wing sustained flight and vertical take-off and landing (VTOL) capability. (true helicopters, autogyros, tilt rotors, tilt wings, prop-hangers).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

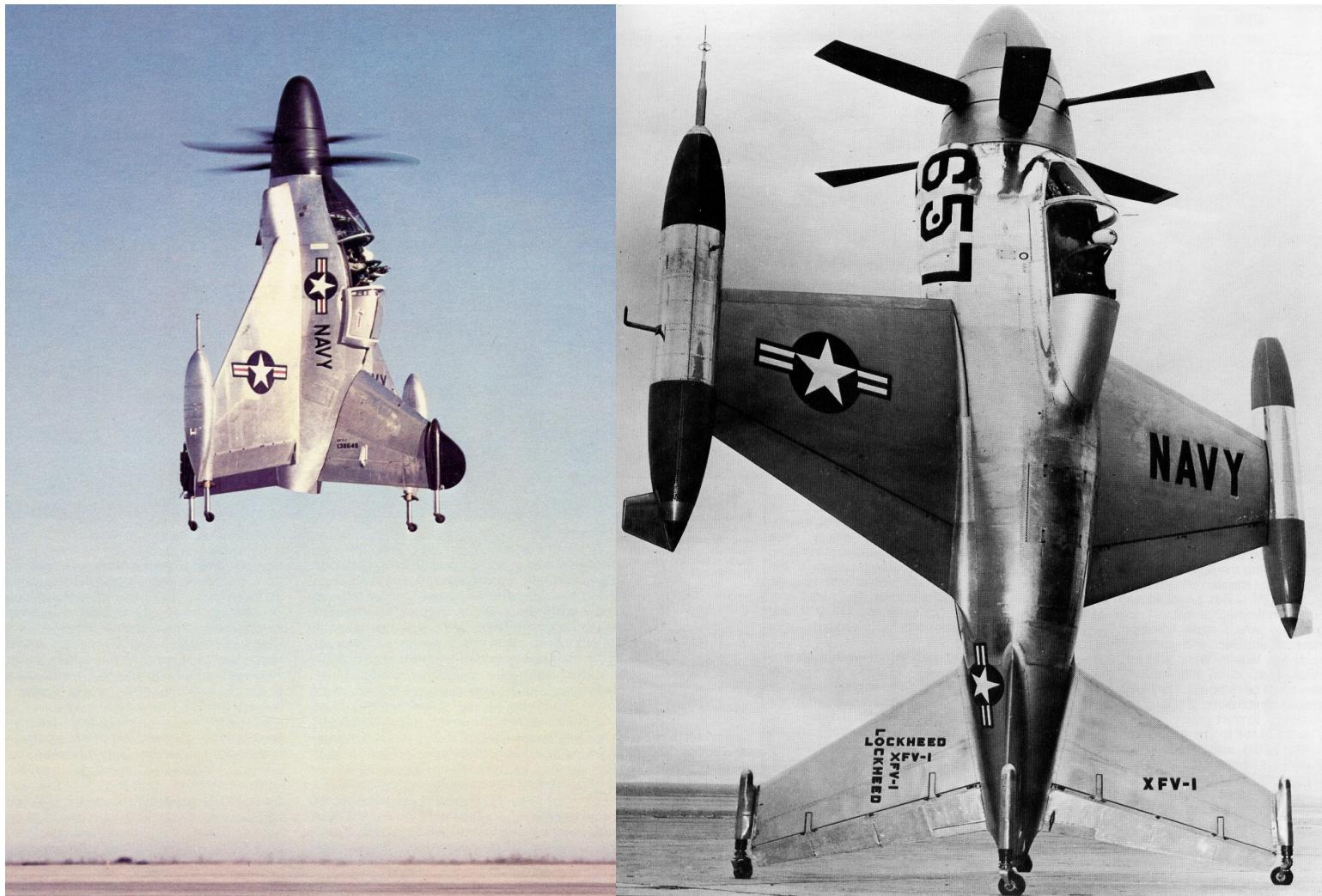
Differentiate between rotary-wing sustained flight and vertical take-off and landing (VTOL) capability. (true helicopters, autogyros, tilt rotors, tilt wings, prop-hangers).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Differentiate between rotary-wing sustained flight and vertical take-off and landing (VTOL) capability. (true helicopters, autogyros, tilt rotors, tilt wings, prop-hangers).



University of
BRISTOL

Yr 17-18 Helicopters



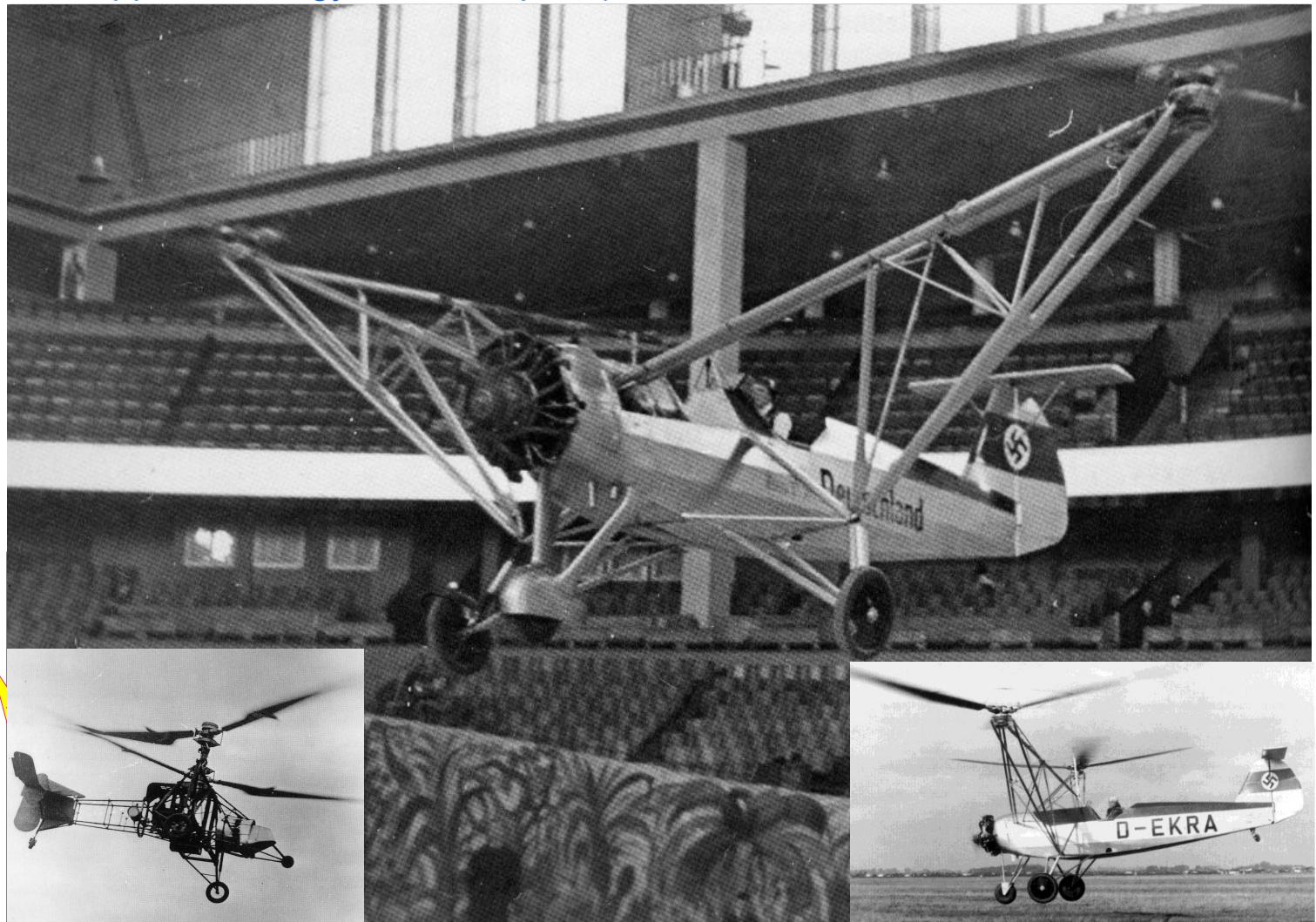
© University of Bristol
Department of Aerospace Engineering



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

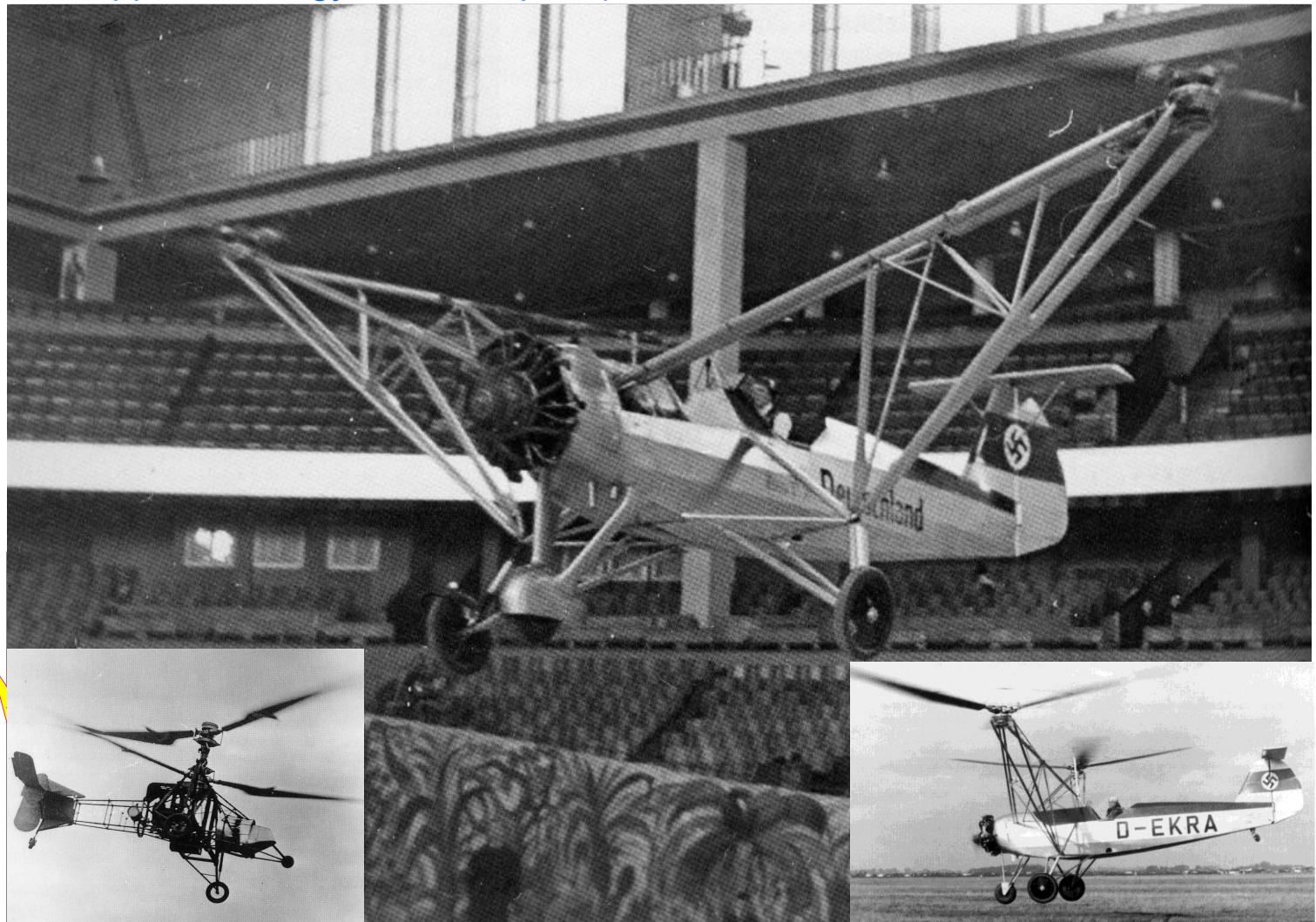
Give a brief history of rotary-wing flight. (early steam powered models, manned-“hoppers”, autogyros, helicopters).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Give a brief history of rotary-wing flight. (early steam powered models, manned-“hoppers”, autogyros, helicopters).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

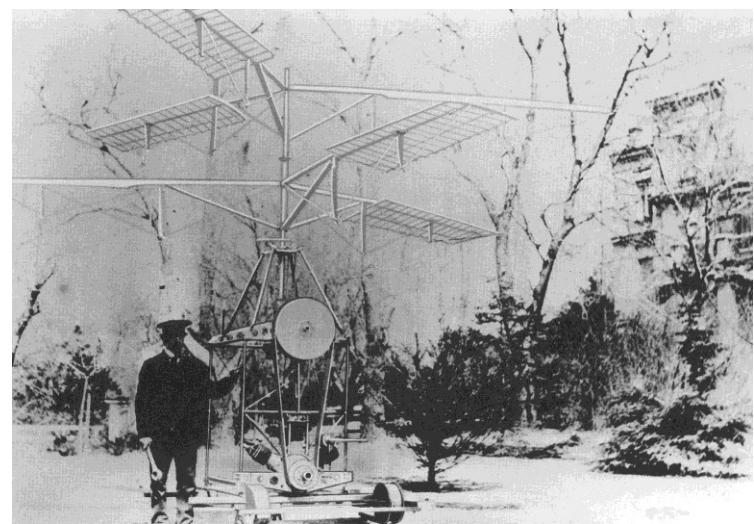
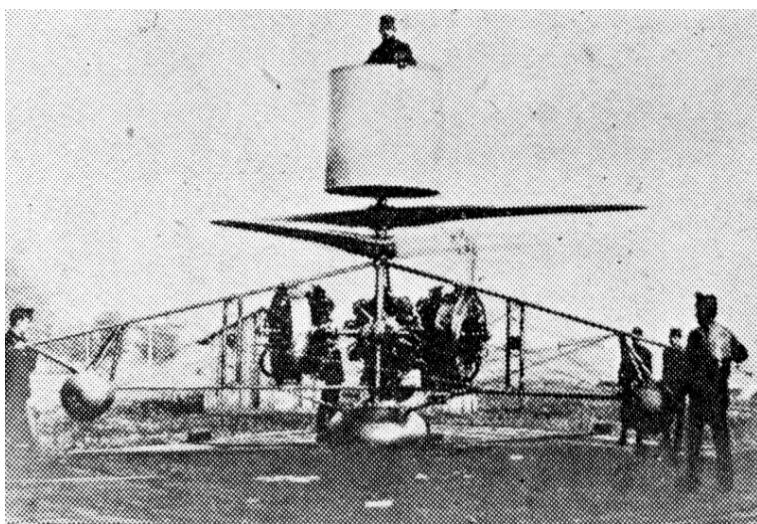
AVDASI 1
AENG10001



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Follow through the path of development to the modern helicopter.
(power-to-weight ratio, blade design, control issues).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Follow through the path of development to the modern helicopter.
(power-to-weight ratio, blade design, control issues).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Follow through the path of development to the modern helicopter.
(power-to-weight ratio, blade design, control issues).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Follow through the path of development to the modern helicopter.
(power-to-weight ratio, blade design, control issues).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Follow through the path of development to the modern helicopter.
(power-to-weight ratio, blade design, control issues).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Follow through the path of development to the modern helicopter.
(power-to-weight ratio, blade design, control issues).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Consider the attributes of the different configurations within this class of aircraft. (conventional, coaxial, tandem, side-by-side, tip-jet, syncropter, notar).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Consider the attributes of the different configurations within this class of aircraft. (conventional, coaxial, tandem, side-by-side, tip-jet, syncropter, notar).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Consider the attributes of the different configurations within this class of aircraft. (conventional, coaxial, tandem, side-by-side, tip-jet, syncropter, notar).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Consider the attributes of the different configurations within this class of aircraft. (conventional, coaxial, tandem, side-by-side, tip-jet, syncropter, notar).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Consider the attributes of the different configurations within this class of aircraft. (conventional, coaxial, tandem, side-by-side, tip-jet, syncropter, notar).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Consider the attributes of the different configurations within this class of aircraft. (conventional, coaxial, tandem, side-by-side, tip-jet, syncropter, notar).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Consider the attributes of the different configurations within this class of aircraft. (conventional, coaxial, tandem, side-by-side, tip-jet, syncropter, notar).



Provide a basic understanding of the physical performance limitations. (weight, speed, altitude, range).

Now we do need to consider some basic mechanics.....

Force = Mass x Acceleration

for every action (force) there is an equal and opposite reaction (force)

Rotor lift (force) is the reaction to accelerating a mass of air downwards

large mass x small acceleration = force = small mass x large acceleration



↑
22,000 lbs
↓



measured in hours

← *hovering endurance* →

measured in minutes



Provide a basic understanding of the physical performance limitations.
(weight, speed, altitude, range).

Helicopters have very large diameter rotors

just like fix wing aircraft, for efficiency it helps to work with a large mass of air



BUT... for performance and noise reasons, blade tip speed is limited and for conventional helicopters therefore so is weight, speed, altitude and range.

more weight = more lift = more power = larger rotor = slower rotation = more torque

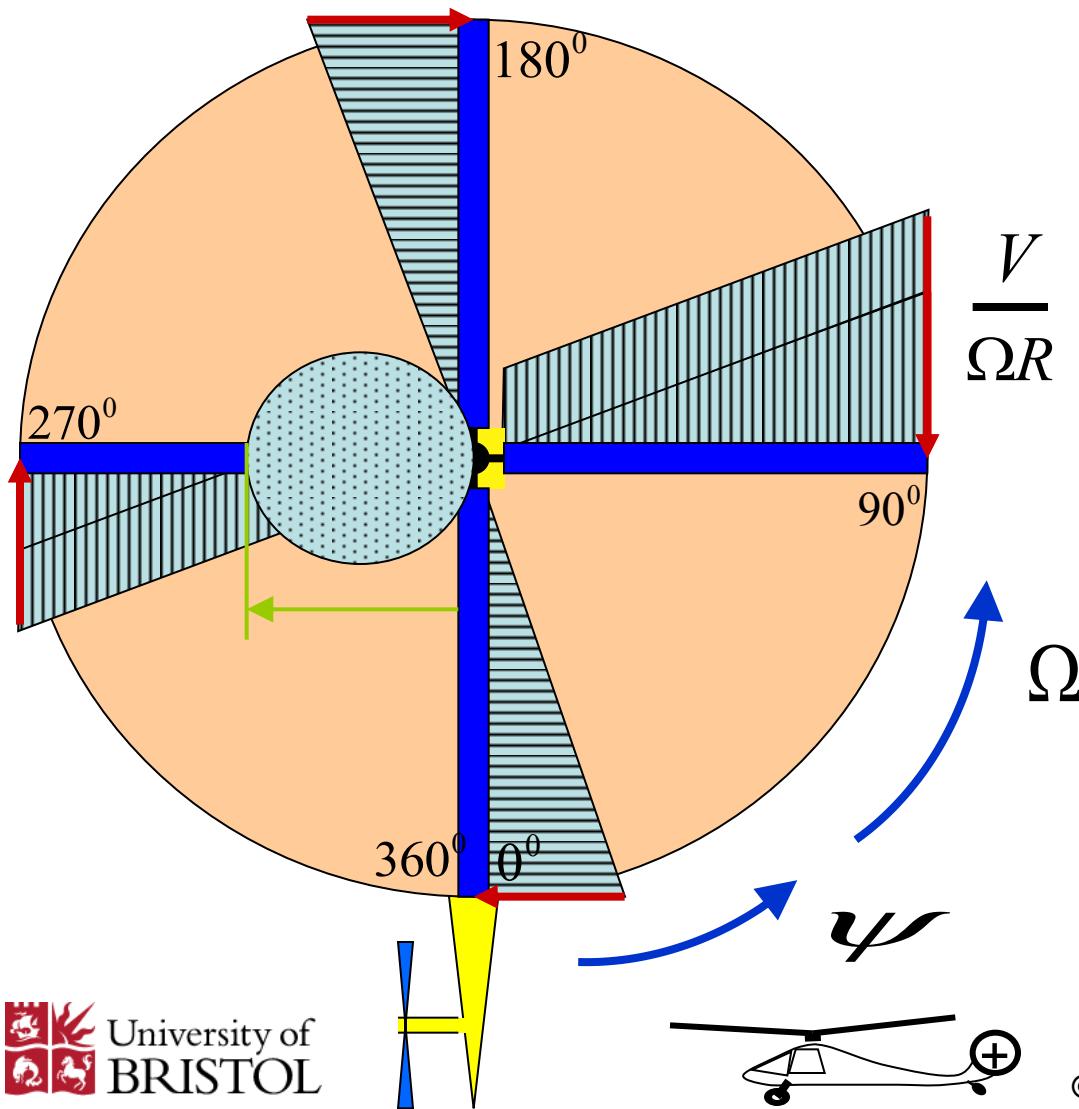
more torque = heavier gearbox = more weight = more lift.....

AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1

AENG10001

Provide a basic understanding of the physical performance limitations.
(weight, speed, altitude, range).



$$\frac{V}{\Omega R} = \mu$$

In addition to the blade velocity due to rotation
there is a common velocity
acting on all elements due
to edge-wise flight.

AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Investigate the existing and future roles for such aircraft. ([MedEvac](#), [Search And Rescue](#), Utility Work, Attack, Transport, Heavy Lift, Mars Missions).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Investigate the existing and future roles for such aircraft. ([MedEvac](#), [Search And Rescue](#), [Utility Work](#), [Attack](#), [Transport](#), [Heavy Lift](#), [Mars Missions](#)).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Investigate the existing and future roles for such aircraft. ([MedEvac](#), [Search And Rescue](#), [Utility Work](#), [Attack](#), [Transport](#), [Heavy Lift](#), [Mars Missions](#)).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Investigate the existing and future roles for such aircraft. ([MedEvac](#), [Search And Rescue](#), [Utility Work](#), [Attack](#), [Transport](#), [Heavy Lift](#), [Mars Missions](#)).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Investigate the existing and future roles for such aircraft. ([MedEvac](#), [Search And Rescue](#), Utility Work, Attack, Transport, Heavy Lift, Mars Missions).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

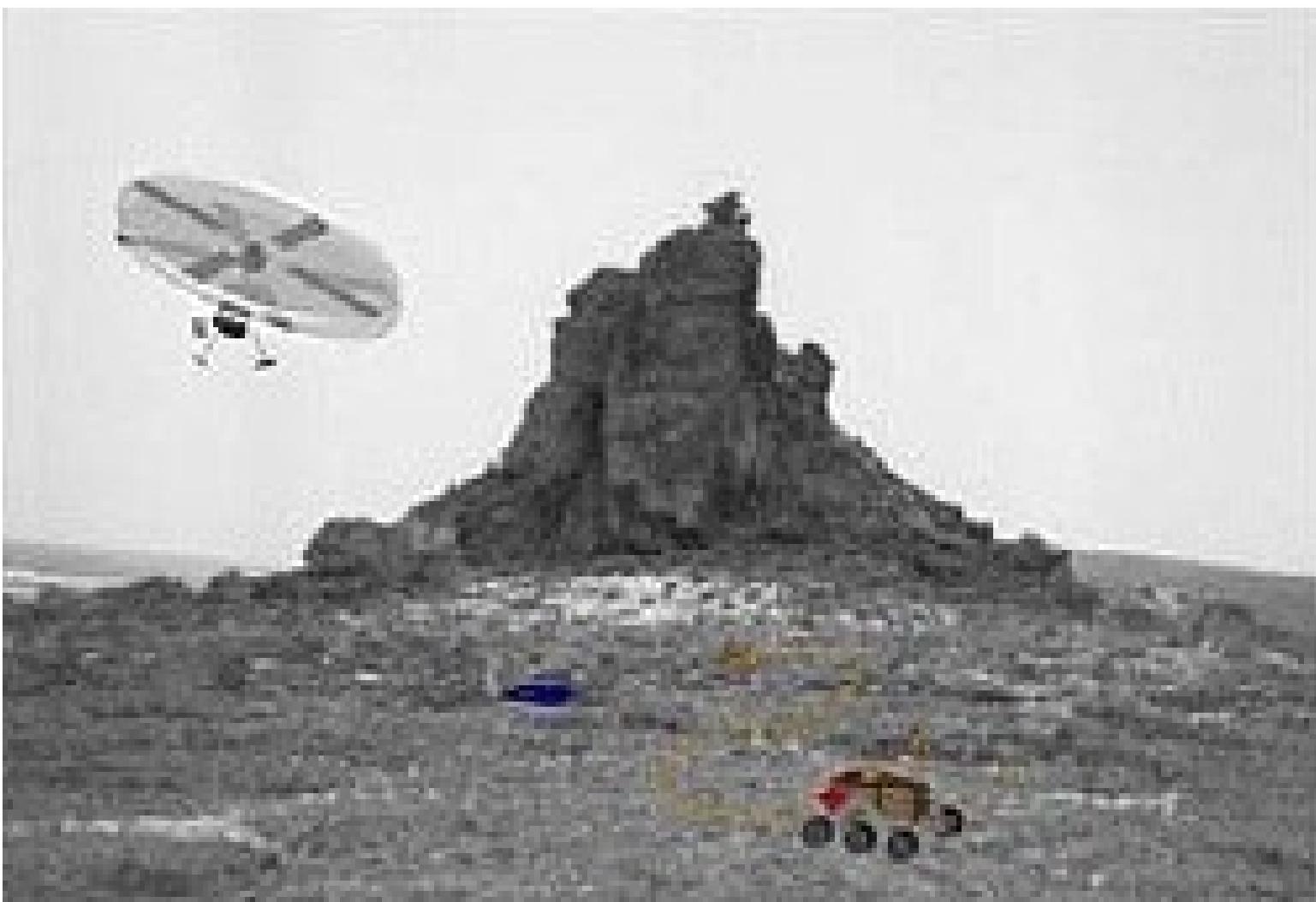
Investigate the existing and future roles for such aircraft. ([MedEvac](#), [Search And Rescue](#), [Utility Work](#), [Attack](#), [Transport](#), [Heavy Lift](#), [Mars Missions](#)).



AVDASI 1 – Introduction to Rotary-Wing Aerospace Vehicles

AVDASI 1
AENG10001

Investigate the existing and future roles for such aircraft. ([MedEvac](#), [Search And Rescue](#), Utility Work, Attack, Transport, Heavy Lift, Mars Missions).



Consider possible future configurations. ([lift and thrust compounding](#), [Advancing Blade Concept](#), [Stopped Rotor](#), [Snitch](#)).

For higher speed, we can't do much about the physics but we can reduce the duty of the rotor:



Consider possible future configurations. ([lift and thrust compounding](#), [Advancing Blade Concept](#), [Stopped Rotor](#), [Snitch](#)).

For higher speed, we can't do much about the physics but we can reduce the duty of the rotor:



Consider possible future configurations. ([lift and thrust compounding](#), [Advancing Blade Concept](#), [Stopped Rotor](#), [Snitch](#)).

For higher speed, we can't do much about the physics but we can reduce the duty of the rotor:



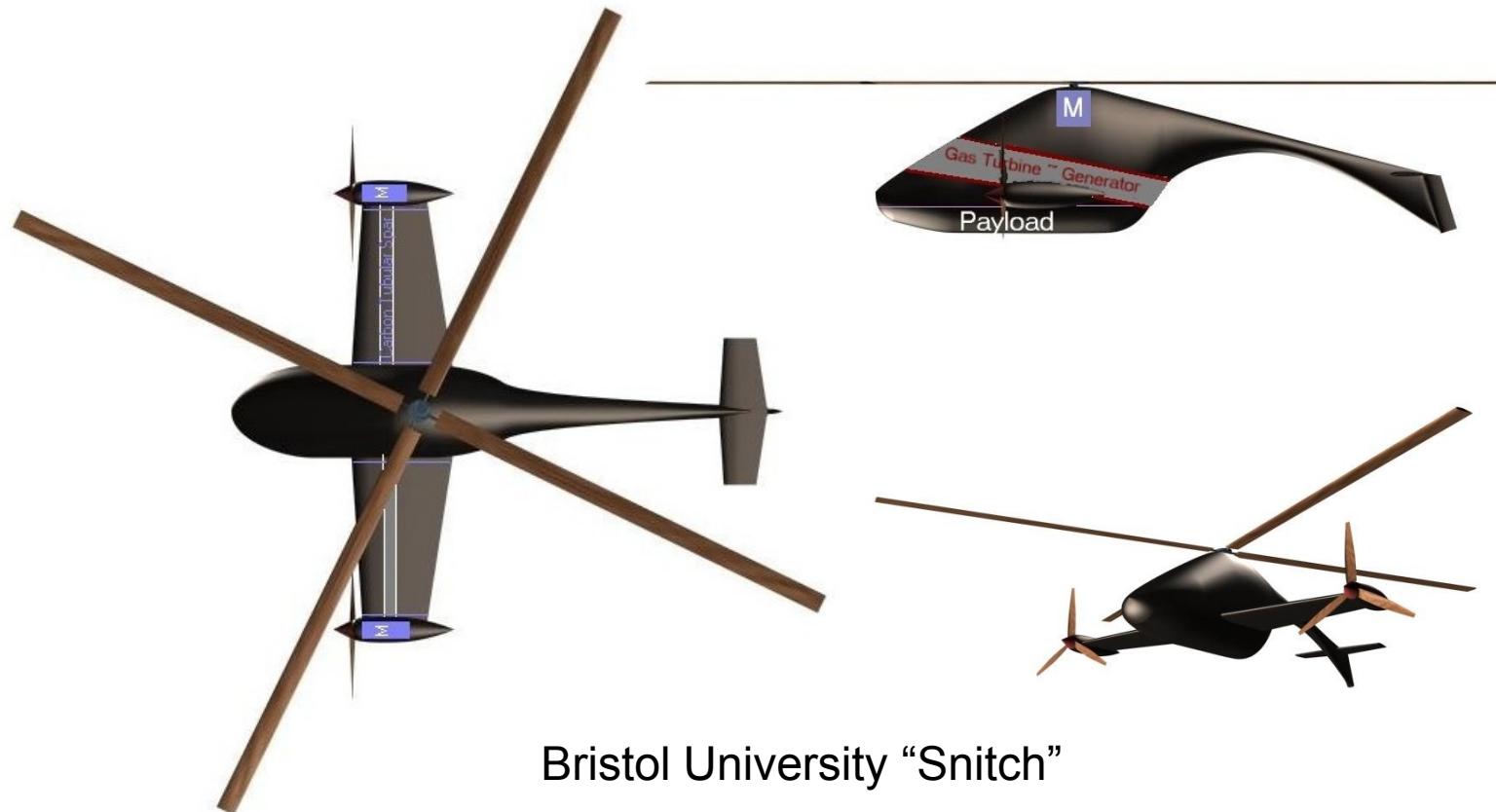
Consider possible future configurations. ([lift and thrust compounding](#), [Advancing Blade Concept](#), [Stopped Rotor](#), [Snitch](#)).

For higher speed, we can't do much about the physics but we can reduce the duty of the rotor:



Consider possible future configurations. ([lift and thrust compounding](#), [Advancing Blade Concept](#), [Stopped Rotor](#), [Snitch](#)).

For higher speed, we can't do much about the physics but we can reduce the duty of the rotor:



The modern helicopter is a very capable machine, uniquely able to fly in all directions and more importantly hover for useful periods of time.



Whilst the helicopter can be a machine of war, it is a pleasing fact that it is far more often performing the role of saving lives than it is taking lives.

The Search and Rescue (SAR) helicopter is often the only form of transport that can access survivors in the aftermath of floods, hurricanes, earthquake and many more natural disasters that we believe to be due to climate change.



Rotorcraft lectures & research opportunities for the next 3 years!

Year 2 – Six formal lectures as part of Aerodynamics 2

Year 3/4 – Helicopter Aerodynamics & Dynamics optional course

Year 4 – Design task in conjunction with AgustaWestland (optional)

Year 4 – Rotorcraft related research for final year project