

EMAT10100 Engineering Maths I Lecture 26: Partial Differentiation

John Hogan & Alan Champneys



EngMaths I Lecture 26 Partial Differentiation
Autumn Semester 2017

Derivative in two dimensions

 $\ensuremath{\,\nvDash\,}$ Recall definition for a function of one variable f(x)

$$\frac{d}{dx}f(x) = \lim_{\Delta x \to 0} \frac{f(x+\Delta x) - f(x)}{\Delta x}$$

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$$\frac{\partial f}{\partial x} = \lim_{\Delta x \to 0} \frac{f(x + \Delta x, y) - f(x, y)}{\Delta x}$$

= "derivative in x direction treating y as a constant"

& Similarly, partial derivative of f with respect to (w.r.t.) y:

$$\frac{\partial f}{\partial y} = \lim_{\Delta y \to 0} \frac{f(x, y + \Delta y) - f(x, y)}{\Delta y}$$

K Sometimes use abbreviations: $\frac{\partial f}{\partial x} = f_x$, $\frac{\partial f}{\partial y} = f_y$.

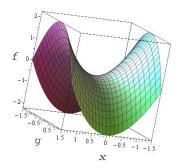
note 'curly d' ∂ is NOT δ



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Functions of several variables

- $\ensuremath{\mathbb{K}}$ So far, only dealt with functions of single variable f(x)
- More typical in engineering to use functions depending on several variables $z=f(x,y,w,u,\ldots)$
- for simplicity, we consider functions of 2 or 3 variables (like matrices & vectors, the principles apply in more dimensions)





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in 3D

 $\norm{\ensuremath{\cancel{k}}}$ What if f is a function of many variables?

e.g.
$$f(x, y, z) = x^2yz^3 + 3xz - 2y$$

- k in this case we would have three partial derivatives
- \mathbf{k} e.g. $\frac{\partial f}{\partial y}$ assumes x and z are constants:

$$\frac{\partial f}{\partial x} = 2xyz^3 + 3z, \quad \frac{\partial f}{\partial y} = x^2z^3 - 2, \quad \frac{\partial f}{\partial z} = 3x^2yz^2 + 3x.$$

- **Exercises**
 - 1. Find partial derivatives w.r.t. x and y of $f(x,y) = x^2 e^{-y} + 3y$
 - 2. Find partial derivatives w.r.t. x, y and z of $f(x, y, z) = 3x^2 \ln y + z^2 \sin(y)(e^x + z)$

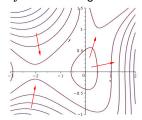
Gradient vector

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✓ Note that gradient, or slope, in two dimensions is a vector:

$$abla f = \operatorname{grad} f = \left(\frac{\partial f}{\partial x} \mathbf{i} + \frac{\partial f}{\partial y} \mathbf{j} \right)$$

 \checkmark direction is uphill (in which f is increasing the most)



 $\ensuremath{\mathbf{k}}$ But how to define the slope (rate of change) of a function f(x,y) in an arbitrary direction?

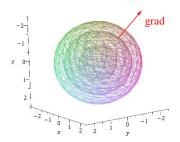
If I walk in an arbitrary direction, what will be the slope I feel?



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Higher dimensional analogies

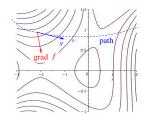
Note that $\nabla f=(f_x,f_y,f_z)$ and directional derivative are well defined in 3D and in higher dimensions



Exercise Compute the directional derivative of $f(x, y, z) = x^2 y^2 z^3$ at the point (3, 2, 1) in the direction of the vector $\mathbf{v} = -2\mathbf{i} - \mathbf{j} + \mathbf{k}$.



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- \checkmark First compute $\frac{\partial f}{\partial x}$ and $\frac{\partial f}{\partial y}$.
- From add a direction by defining a vector v,
- Ke Then we define directional derivative of f(x,y) in direction of ${\bf v}$ by taking a dot product:

$$f_{\hat{\mathbf{v}}} := \nabla f \cdot \frac{\mathbf{v}}{|\mathbf{v}|},$$

where $\frac{\mathbf{v}}{|\mathbf{v}|} \equiv \hat{\mathbf{v}}$ is unit vector in the direction of \mathbf{v} .



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Chain rule for partial derivatives

✓ recall chain rule (function of a function) for differentiation in 1D

$$\frac{\mathrm{d}}{\mathrm{d}x}f(g(x)) = \frac{\mathrm{d}g}{\mathrm{d}x} \cdot \frac{\mathrm{d}f}{\mathrm{d}g}$$

- \swarrow Q. how to evaluate $\frac{\partial f}{\partial s}$ and $\frac{\partial f}{\partial t}$?
- ★ A. use the Chain Rule for two variables:

$$\frac{\partial f}{\partial s} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial s}$$
$$\frac{\partial f}{\partial t} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial t} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial t}$$



Example: change of co-ordinates

- **№** Common requirement, change co-ordinates, e.g.: CARTESIAN → POLAR
- \not e.g. given $f(x,y) = x^3 xy + y^3$
- Assume x and y have been expressed in polar coordinates: $x = r\cos(\theta) := x(r,\theta), \quad y = r\sin(\theta) := y(r,\theta)$
- $\norm{\ensuremath{\not{k}}}$ Compute partial derivatives of f w.r.t r and θ .
- Solution: to find $\frac{\partial f}{\partial r}$, write $f(x,y)=f(x(r,\theta),y(r,\theta))$ and use chain rule:

$$\Rightarrow \frac{\partial f}{\partial r} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial r} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial r}$$



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Other versions of the chain rule

 $\not \mathbf{k}$ If f(x(t), y(t)):

$$\frac{\mathrm{d}f}{\mathrm{d}t} = \frac{\partial f}{\partial x} \cdot \frac{\mathrm{d}x}{\mathrm{d}t} + \frac{\partial f}{\partial y} \cdot \frac{\mathrm{d}y}{\mathrm{d}t}$$

 $\not \sqsubseteq \text{ If } f(x(s,t),y(s,t),z(s,t))$

$$\frac{\partial f}{\partial t} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial t} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial t} + \frac{\partial f}{\partial z} \cdot \frac{\partial z}{\partial t}$$

$$\frac{\partial f}{\partial s} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial s} + \frac{\partial f}{\partial z} \cdot \frac{\partial z}{\partial s}$$

ke etc.



$$f(x,y) = x^3 - xy + y^3 \Rightarrow \frac{\partial f}{\partial x} = 3x^2 - y,$$

 $\frac{\partial f}{\partial y} = -x + 3y^2.$

and
$$x(r,\theta) = r\cos(\theta) \Rightarrow \frac{\partial x}{\partial r} = \cos(\theta),$$

 $y(r,\theta) = r\sin(\theta) \Rightarrow \frac{\partial y}{\partial r} = \sin(\theta).$

Combining these we obtain:

$$\begin{split} \frac{\partial f}{\partial r} &= (3x^2 - y)\cos(\theta) + (3y^2 - x)\sin(\theta), \\ \Rightarrow & \frac{\partial f}{\partial r} &= \left[3r^2\cos^2(\theta) - r\sin(\theta)\right]\cos(\theta) + \left[3r^2\sin^2(\theta) - r\cos(\theta)\right]\sin(\theta). \\ &= 3r^2[\cos^3(\theta) + \sin^3(\theta)] - 2r\cos(\theta)\sin(\theta) \end{split}$$

 $\ensuremath{\mathbb{K}}$ Exercise compute $\frac{\partial f}{\partial \theta}$ in a similar manner.



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Exercises

1. Elliptic co-ordinates can be defined by

$$x(s,t) = \cosh s \cos t,$$
 $y(s,t) = \sinh s \sin t$

Use the chain rule to find $\frac{\partial f}{\partial x}$ and $\frac{\partial f}{\partial t}$ for $f(x,y)=x^2+y^2$

2. A space rocket has a trajectory in three-dimensional space given by

$$x(t) = at$$
, $y(t) = b\sin(\omega t)$, $z(t) = ct^2 - kt^3$,

Use the chain rule to calculate the speed

$$\frac{\mathrm{d}r}{\mathrm{d}t} = \frac{\mathrm{d}}{\mathrm{d}t}\sqrt{x(t)^2 + y(t)^2 + z(t)^2}$$

in terms of the constants a, b, ω, c and k



EMAT10100 Engineering Maths I Lecture 26: More on Partial Differentiation

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I. Higher order derivatives

- \mathbf{k} in 1D we have the notion of 2nd derivatives, 3rd derivatives etc: $\frac{d}{dx}[f(x)] = f'(x), \frac{d}{dx}[f'(x)] = f''(x), \dots \frac{d}{dx}[f^{(n-1)}(x)] = f^{(n)}(x).$
- K Similarly, we can define higher-order partial derivatives:

$$rac{\partial}{\partial x}[f(x,y)] = f_x(x,y), \quad rac{\partial}{\partial x}[f_x(x,y)] = f_{xx}(x,y), ext{ etc.}$$

$$rac{\partial}{\partial y}[f(x,y)]=f_y(x,y), \ \ rac{\partial}{\partial y}[f_y(x,y)]=f_{yy}(x,y),$$
 etc.
 We There is another 2nd derivative though:

- There is another 2nd derivative though: what happens though if we differentiate $f_x(x, y)$ w.r.t. yor equivalently $f_y(x, y)$ w.r.t. x?

$$\frac{\partial f_x}{\partial y} = f_{xy}, \quad \frac{\partial f_y}{\partial x} = f_{yx}$$

Note that $f_{xy}=f_{yx}$ provided the functions f_x and f_y are smooth (1)=1 always read the small print



This lecture

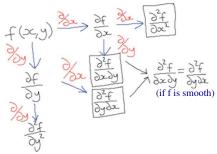
There are two topics in this lecture:

- I. Higher-order partial derivatives
- II. Total differentials and error estimation



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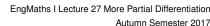
Calculating 2nd derivatives



K Exercise: Compute the 2nd partial derivatives of

$$f(x,y) = x^2y^3 + 3y + x$$

and show explicitly that $f_{xy} = f_{yx}$ in this case.





Partial differential equations

- equations that involve partial derivatives of physical quantities that evolve in space and time
- & e.g. wave equation for displacement of u(x,t):

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$$

 $c = \mathsf{wave} \; \mathsf{speed}$

Exercise show that the function

$$u(x,t) = \cos(kx + \phi)\cos(kct + \psi)$$

solves wave eqn. for any constants k, ϕ and ψ .

to find the constants, we need to use boundary conditions (see 2nd year Maths)



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The total differential

- This gives good approximation of the total increment to a function, given small increment in each of its variables.
- ★ That is

$$\Delta u \approx \frac{\partial f}{\partial x} \Delta x + \frac{\partial f}{\partial y} \Delta y.$$

 $\norm{\ensuremath{\not{k}}}$ By taking limits as small quantities $\to 0$

$$\Delta x \to dx$$
, $\Delta y \to dy$ $\Delta u \to du$

 \normall Then, formally, we define the total differential of u as:

$$du = \frac{\partial f}{\partial x}dx + \frac{\partial f}{\partial y}dy.$$



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II Total differentials & error analysis

- $\norm{\ensuremath{\checkmark}}$ Suppose we have a physical quantity u=f(x,y)
- \bigvee If we can estimate error in x and y, how do we estimate error in u?
- More generally, given small changes in x and y, what is corresponding small change in u?
- \swarrow Let Δx and Δy be changes x and y, then

$$\begin{array}{lcl} \Delta u & = & f(x+\Delta x,y+\Delta y) - f(x,y) \\ \\ & = & [f(x+\Delta x,y+\Delta y) - f(x,y+\Delta y)] + [f(x,y+\Delta y) - f(x,y)] \\ \\ & = & \frac{f(x+\Delta x,y+\Delta y) - f(x,y+\Delta y)}{\Delta x} \Delta x + \frac{f(x,y+\Delta y) - f(x,y)}{\Delta y} \Delta y \\ \\ & \approx & \frac{\partial f}{\partial x} \Delta x + \frac{\partial f}{\partial y} \Delta y \end{array}$$



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Example

Compute the total differential of

$$z = x^2 y^3 := f(x, y).$$

Solution: We need to compute

$$dz = \frac{\partial f}{\partial x}dx + \frac{\partial f}{\partial y}dy.$$

$$\frac{\partial f}{\partial x} = 2xy^3, \qquad \frac{\partial f}{\partial y} = 3x^2y^2,$$

$$\Rightarrow dz = 2xy^3dx + 3x^2y^2dy$$

K Exercise compute the total differential of

$$f(r, \theta, \phi) = r^2 \sin^2(\theta) \cos(\phi)$$



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Application to error analysis

- Kee Example The volume of a cylinder of radius r cm and height h cm is given by $V(r.h)_{\cdot} = \pi r^2 h := V(r,h)$
 - and that measurements are taken such that:
 - $r=3\pm0.01~{\rm cm}:=r_0\pm\Delta r,\quad h=5\pm0.005~{\rm cm}:=h_0\pm\Delta h,$ find the maximum possible error in the calculation of V.
- **K** Solution: We want to compute ΔV , given Δr and Δh .

$$|\Delta V| \approx |\frac{\partial V}{\partial r} \Delta r + \frac{\partial V}{\partial h} \Delta h|,$$

$$\leq |(2\pi r_0 h_0)||\Delta r| + |(\pi r_0^2)||\Delta h|$$

& Substituting in the values of r_0 , Δr , h_0 and Δh we obtain

$$|\Delta V| \approx 0.3\pi + 0.045\pi$$

Therefore we can state that $V=\pi(45\pm0.345)$



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Homework

- Please read James
 - Section 9.6.1–9.6.9
- and do exercises 4th edition
 - ► Sec. 9.6.4, Qns. 39–41, 44,
 - Sec. 9.6.6, Qns. 47, 48, 54, 55
 - ► Sec. 9.6.8 Qns. 56–59
 - Sec. 9.6.10 Qns. 65.67.69.72
- and do exercises 5th edition
 - Sec. 9.6.4, Qns. 39–41, 44,
 - Sec. 9.6.6, Qns. 47, 48, 54, 55
 - ► Sec. 9.6.8 Qns. 57–60
 - Sec. 9.6.10 Qns. 69,70,75



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Relative and percentage error

- From previous expressions we get:

$$\frac{\Delta f}{f} \approx \frac{\partial f}{\partial x} \frac{\Delta x}{f} + \frac{\partial f}{\partial y} \frac{\Delta y}{f}$$

- \mathbf{k} Example find relative error in $f(x,y) = (x^2 + y^2 + xy)$ in terms of relative errors in x and y.
- Solution : from above formula

$$\frac{\Delta f}{f} = (2x+y)\frac{\Delta x}{x^2+y^2+xy} + (2y+x)\frac{\Delta y}{x^2+y^2+xy}$$
$$= \frac{2x^2+xy}{x^2+y^2+xy}\left(\frac{\Delta x}{x}\right) + \frac{2y^2+xy}{x^2+y^2+xy}\left(\frac{\Delta y}{y}\right)$$

Keeper Exercise If $v=\sqrt{(3x/y)}$ find maximum percentage error in v due to errors of 1% in x and 3% in y.