

STAT575  
Large Sample Theory

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## Abstract

This is a graduate-level theoretical statistics course taught by [Georgios Fellouris](#) at University of Illinois Urbana-Champaign, aiming to provide an introduction to asymptotic analysis of various statistical methods, including weak convergence, Lindeberg-Feller CLT, asymptotic relative efficiency, etc.

We list some references of this course, although we will not follow any particular book page by page: *Asymptotic Statistics* [[Vaa98](#)], *Asymptotic Theory of Statistics and Probability* [[Das08](#)], *A course in Large Sample Theory* [[Fer17](#)], *Approximation Theorems of Mathematical Statistics* [[Ser09](#)], and *Elements of Large-Sample Theory* [[Leh04](#)].



This course is taken in Spring 2024, and the date on the cover page is the last updated time.

# Contents

<b>1</b>	<b>Introduction</b>	<b>2</b>
1.1	Parametrized Approach . . . . .	2
1.2	Hypothesis Testing . . . . .	3
1.3	Different Modes of Convergence . . . . .	3

# Chapter 1

## Introduction

### Lecture 1: Introduction to Large Sample Theory

Say we first collect  $n$  data points  $x_1, \dots, x_n \in \mathbb{R}^d$ , large sample theory concerns with the limiting theory as  $n \rightarrow \infty$ . We may treat  $x_i$  as a realization of a random vector  $X_i$  on a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ . In this course, we will primarily consider the case that  $X_i$ 's are i.i.d., i.e., independent and identically distributed from a distribution function, or the *cumulative density function* (CDF)  $F$  such that 16 Jan. 9:30

$$X = (X^1, \dots, X^d) \sim F(x_1, \dots, x_d) \equiv \mathbb{P}(X^1 \leq x_1, \dots, X^d \leq x_d)$$

for all  $x_i \in \mathbb{R}$ . If we have access to  $F$ , we can compute the corresponding *probability density function* (PDF)  $\mathbb{P}$ , and then have access to  $\mathbb{P}(X \in A)$  for all (measurable)  $A \subseteq \mathbb{R}^d$  of interest.

**Remark.** If we know any of the above, we know every thing about the population.

Hence, the goal is to compute this by collecting data  $x_i$ 's, which is a statistical inference problem.

### 1.1 Parametrized Approach

There are various ways of doing this task, one way is the so-called parametrized approach. By postulating a family of CDFs  $\{F_\theta, \theta \in \Theta\}$  where  $\Theta$  is often a subset of  $\mathbb{R}^m$  for some  $m$  (generally  $\neq n$ ), the goal is to select a member of this family that is the “closest”, or the “best fit” to the truth, i.e.,  $F$ , based on the data.

**Note.** To emphasize that this depends on the data, we sometimes write the function we found as  $\hat{\theta}_n(x_1, \dots, x_n)$  so that  $F_{\hat{\theta}_n(x_1, \dots, x_n)}$  is our proxy for  $F$ .

Now, assume that the family is initially given, the problem is then how to select  $\hat{\theta}_n$ .

**Example.** Fisher suggested that we should look at the maximum likelihood estimator (MLE).

The justification for MLE is not about finite  $n$ , but about its asymptotic behavior when  $n \rightarrow \infty$ . Specifically, we have the following theorem due to Fisher (informally stated).

**Theorem 1.1.1 (Fisher).** If  $F \in \{F_\theta: \theta \in \Theta\}$ , i.e., if  $F = F_{\theta^*}$  for some  $\theta^* \in \Theta$ , then under certain conditions,  $\hat{\theta}_n$  will be “close” to  $\theta^*$  as  $n \rightarrow \infty$ . Under some other conditions,  $\sqrt{n}(\hat{\theta}_n - \theta)$  is approximately Gaussian with variance being the “best possible” in some sense.

On the other hand, in the misspecified case, i.e.,  $F \notin \{F_\theta, \theta \in \Theta\}$ , we can still compute the MLE, which leads to another justification for MLE since even in this case,  $\hat{\theta}_n$  will still be “close” to  $\theta^*$  such that  $F_{\hat{\theta}_n}$  is, in some sense, the “closest” to  $F$  among all possible  $F_\theta$  (minimizing divergence, to be precise).

## 1.2 Hypothesis Testing

We will also develop theory for hypothesis testing for some hypothesis we're interested in, e.g., whether the data we collect is really i.i.d., or whether our proposed family is reasonable enough. Say now  $X_i$ 's are scalar random variable with  $\mathbb{E}[X] = \mu$ , and we want to test the null hypothesis  $H_0: \mu = 0$ .

**Example.** Consider a controlled group  $Z$  and a treatment group  $Y$ , and we observe  $Z_1, \dots, Z_n$ , and  $Y_1, \dots, Y_n$ , respectively, and compute  $X_i = Z_i - Y_i$  for all  $i$ . Testing  $H_0$  on the distribution of  $X$  will show the effect of the treatment.

To do this, a well-known method is the so-called  $t$ -test. Let  $s_n$  to be the sample standard derivation, then we can compute

$$T_n = \frac{\bar{X}_n}{s_n/\sqrt{n}} \sim t_{n-1}$$

as long as  $X$  is Gaussian, i.e., the  $t$ -statistics for  $H_0$ . What if  $X$  is not an Gaussian? We will show that even if  $X$  is not Gaussian, this result is “approximately valid” when  $n$  is “large enough” as long as  $\text{Var}[X] < \infty$ .

**Remark (Sample Size).** When we say  $n$  is “large enough”, what we mean really depends on how fast the underlying distribution will approach Gaussian as  $n$  grows. Hence, if we can say more about the underlying population, we can say more about when does  $n$  is “large enough”; otherwise such a limiting theory might be completely useless in practice.

What if now  $\text{Var}[X]$  doesn't exit? When the population has a heavy tail distribution, then second moment may not exit.

**Example (Cauchy distribution).** The Cauchy distribution doesn't have finite moment of order greater than 1.

In this case, some other test is needed. A simple test would be looking at the sign of  $X_i$ , i.e., the sign test.

**Example (Sign test).** We might reject  $H_0$  if  $\sum_{i=1}^n \mathbb{1}_{X_i > 0}$  is large. Note that under  $H_0$ ,  $\sum_{i=1}^n \mathbb{1}_{X_i > 0} \sim \text{Bin}(n, 1/2)$ , and this test is valid even if expectation doesn't exist.

We see that without saying anything about  $F$ , the sign test is valid even for  $n = 3$  or  $5$  as the sum is exactly binomial distribution under  $H_0$ . Although simple and have good property, only looking at the sign of  $X_i$  might be too weak. A natural idea is to look at the absolute value of  $X_i$ .

**Example (Wilcoxon's rank-sum test).** Let  $R_{i,n}$  to be the rank of  $|X_i|$ , then consider the so-called *Wilcoxon's rank-sum test*

$$\sum_{i=1}^n \mathbb{1}_{X_i > 0} R_{i,n}.$$

As one can imagine, the closed form of the above sum will be complicated; however, asymptotically, the above statics will follow Gaussian again, such that the rate of convergence doesn't depend on the underlying population.

Finally, we also ask how can we compare these different tests? This will also be addressed in this course.

## Lecture 2: Modes of Convergence

### 1.3 Different Modes of Convergence

18 Jan. 9:30

Given a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ , consider a sequence of  $d$ -dimensional random vectors  $(X_n)$  and a random vector  $X$ , i.e.,  $X_n, X: \Omega \rightarrow \mathbb{R}^d$ . We now discuss different modes of convergence for  $(X_n)$ .

**Definition 1.3.1 (Point-wise convergence).**  $(X_n)$  *point-wise converges* to  $X$ , denoted as  $X_n \rightarrow X$ , if  $X_n(\omega) \rightarrow X(\omega)$  for all  $\omega \in \Omega$ .

**As previously seen.** From analysis,  $X_n(\omega) \rightarrow X(\omega)$  if and only if for every  $\epsilon > 0$ , there exists  $n_0(\omega) \in \mathbb{N}$  such that for every  $n \geq n_0$ ,  $\|X_n(\omega) - X(\omega)\|_2 < \epsilon$ .

However, since we don't care about measure zero sets, we may instead consider the following.

**Definition 1.3.2 (Almost-surely convergence).**  $(X_n)$  *almost-surely converges* to  $X$ , denoted as  $X_n \xrightarrow{\text{a.s.}} X$ , if  $\mathbb{P}(X_n \rightarrow X) = 1$ .

In other words, **almost-surely convergence** means that  $X_n(\omega) \rightarrow X(\omega)$  for all  $\omega \in \Omega \setminus N$  where  $\mathbb{P}(N) = 0$ . However, this might still be too strong.

**Definition 1.3.3 (Convergence in probability).**  $(X_n)$  *converges in probability* to  $X$ , denoted as  $X_n \xrightarrow{p} X$ , if for every  $\epsilon > 0$ ,  $\mathbb{P}(\|X_n - X\| > \epsilon) \rightarrow 0$  as  $n \rightarrow \infty$ .

**Remark.**  $X_n \rightarrow X$  if and only if  $\|X_n - X\| \rightarrow 0$ . The same also holds for  $\xrightarrow{p}$  and  $\xrightarrow{\text{a.s.}}$ .

A related notion is the following, where we now sum over  $n$ .

**Definition 1.3.4 (Converges completely).**  $(X_n)$  *converges completely* to  $X$ , denoted as  $X_n \xrightarrow{\text{comp}} X$ , if for every  $\epsilon > 0$ ,  $\sum_{n=1}^{\infty} \mathbb{P}(\|X_n - X\| > \epsilon) < \infty$ .

Finally, we have the following.

**Definition 1.3.5 (Converges in  $L^p$ ).** Let  $p > 0$ , we say  $X_n \xrightarrow{L^p} X$  if  $\mathbb{E}[\|X_n - X\|^p] \rightarrow 0$  as  $n \rightarrow \infty$ .

### 1.3.1 Connection Between Modes of Convergence

We have the following connections between different modes of convergence.

$$\text{completely} \implies \text{almost-surely} \implies \text{in probability} \Longleftarrow \text{in } L^p$$

To show the above, the following characterization for **almost-surely convergence** is useful.

**Proposition 1.3.1.** For a sequence of random vectors  $(X_n)$  and a random vector  $X$ , we have

$$\begin{aligned} X_n \xrightarrow{\text{a.s.}} X &\Leftrightarrow \mathbb{P}(\|X_k - X\| > \epsilon \text{ for some } k \geq n) \xrightarrow{n \rightarrow \infty} 0 \\ &\Leftrightarrow \mathbb{P}(\|X_n - X\| > \epsilon \text{ for infinitely many } n\text{'s}) = 0 \\ &\Leftrightarrow \mathbb{P}(\limsup_{n \rightarrow \infty} \|X_n - X\| > \epsilon) = 0, \end{aligned}$$

where the above holds for every  $\epsilon > 0$ .

From **Proposition 1.3.1**, it's clear that  $\xrightarrow{\text{a.s.}}$  implies  $\xrightarrow{p}$  since

$$\mathbb{P}(\|X_k - X\| > \epsilon \text{ for some } k \geq n) \geq \mathbb{P}(\|X_n - X\| > \epsilon),$$

hence if the former goes to 0, so does the latter. On the other hand,  $\xrightarrow{\text{comp}}$  implies  $\xrightarrow{\text{a.s.}}$  follows from the third equivalence. Lastly, the **convergence in  $L^p$**  implies the **convergence in probability** since

$$\mathbb{P}(\|X_n - X\| > \epsilon) \leq \frac{1}{\epsilon^p} \mathbb{E}[\|X_n - X\|^p]$$

from Markov's inequality. However, the converse is not always true.

**Theorem 1.3.1** (Dominated convergence theorem). If  $X_n \xrightarrow{p} X$  and  $\|X_n - X\| \leq Z$  for all  $n \geq 1$  where  $\mathbb{E}[\|Z\|^p] < \infty$ , then  $X_n \xrightarrow{L^p} X$ .

**Theorem 1.3.2** (Scheffé's theorem). If  $X_n \xrightarrow{p} X$  and  $\limsup_{n \rightarrow \infty} \mathbb{E}[\|X_n\|^p] \leq \mathbb{E}[\|X\|^p] < \infty$ , then  $X_n \xrightarrow{L^p} X$ .

### 1.3.2 Applications to Statistics

Let  $(X_n) \stackrel{\text{i.i.d.}}{\sim} F$  where  $F$  is a distribution function. Say we're interested in some aspect of  $F$ , for example, some parameter  $\theta = T(F) \in \mathbb{R}^m$ . By collecting data  $X_1, \dots, X_n$ , we estimate  $\theta$  by computing an estimator  $\hat{\theta}_n$  of  $\theta$ .<sup>1</sup>

**Definition 1.3.6** (Consistent).  $\hat{\theta}_n$  is *consistent* of  $\theta$  if  $\hat{\theta}_n \xrightarrow{p} \theta$  as  $n \rightarrow \infty$ .

**Definition 1.3.7** (Strongly consistent).  $\hat{\theta}_n$  is *strongly consistent* of  $\theta$  if  $\hat{\theta}_n \xrightarrow{\text{a.s.}} \theta$  as  $n \rightarrow \infty$ .

Let's first see the most well-known estimation problem, the mean estimation.

**Example** (Mean estimation). Suppose  $d = 1$ , and let  $X$  be non-negative. Say we're interested in  $\theta = \mathbb{E}[X]$ . It's standard that in this case, we can compute  $\mathbb{E}[X]$  by

$$\theta = \mathbb{E}[X] = \int_0^\infty \mathbb{P}(X > t) dt = \int_0^\infty (1 - F(t)) dt.$$

On the other hand, if  $X$  has a PMF  $f$ , then

$$\mathbb{E}[X] = \sum_x x f(x) = \sum_x x \Delta F(x),$$

where  $f(x) = \Delta F(x) \equiv F(x) - F(x_-)$ . And if  $X$  has a PDF  $f$ , then

$$\mathbb{E}[X] = \int_0^\infty x f(x) dx = \int_0^\infty x F(dx)$$

where  $F(dx) := f(x)dx$  in a measure-theoretical sense.

Now, let  $\hat{\theta}_n$  to be the sample mean, i.e.,  $\hat{\theta}_n = \bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$ . From the strong law of large number,  $\bar{X}_n \xrightarrow{\text{a.s.}} \mathbb{E}[X]$ , which implies that  $\hat{\theta}_n$  is a **strongly consistent estimator** of  $\theta$ .

On the other hand, if  $\text{Var}[X] < \infty$ , then  $\bar{X}_n \xrightarrow{L^2} \mathbb{E}[X]$ , which further implies  $\bar{X}_n \xrightarrow{p} \mathbb{E}[X]$ , hence  $\hat{\theta}_n$  is **consistent**.<sup>a</sup>

<sup>a</sup>The latter is true even without  $\text{Var}[X] = \infty$  as we expect.

**Proof.** We show the last statement. Since  $\text{Var}[X] < \infty$ , then

$$\frac{\text{Var}[X]}{n} = \text{Var}[\bar{X}_n] = \mathbb{E}[(\bar{X}_n - \mathbb{E}[X])^2] \rightarrow 0$$

as  $n \rightarrow \infty$ , which implies  $\bar{X}_n \xrightarrow{p} \mathbb{E}[X]$ . \*

Another interesting problem is the supremum estimation.

**Example** (Supremum estimation). Suppose there is a  $\theta \in \mathbb{R}$  where distribution function  $F$  such that  $F(\theta - \epsilon) < 1 = F(\theta)$  for all  $\epsilon > 0$ . This means  $\theta = \sup_\omega X(\omega)$  since  $\mathbb{P}(X \leq \theta - \epsilon) = F(\theta - \epsilon)$

<sup>1</sup> $\hat{\theta}_n$  is a function of  $X_i$ 's.

and  $F(\theta) = \mathbb{P}(X \leq \theta)$ .<sup>a</sup> The natural estimator for  $\theta$  would be  $\hat{\theta}_n = \max_{1 \leq i \leq n} X_i$ , and it's indeed **strongly consistent**.

<sup>a</sup>Such a distribution exists, for example,  $\mathcal{U}(0, \theta)$ .

**Proof.** We see that for any  $\epsilon > 0$ ,

$$\begin{aligned} \mathbb{P}(|\hat{\theta}_n - \theta| > \epsilon) &= \mathbb{P}(\hat{\theta}_n > \theta + \epsilon) + \mathbb{P}(\hat{\theta}_n < \theta - \epsilon) \\ &= \mathbb{P}\left(\bigcup_{i=1}^n \{X_i > \theta + \epsilon\}\right) + \mathbb{P}\left(\bigcap_{i=1}^n \{X_i < \theta - \epsilon\}\right) \\ &\leq \sum_{i=1}^n \underbrace{\mathbb{P}(X > \theta + \epsilon)}_0 + \prod_{i=1}^n \mathbb{P}(X_i < \theta - \epsilon) = (\mathbb{P}(X_1 < \theta - \epsilon))^n \leq (F(\theta - \epsilon))^n \rightarrow 0 \end{aligned}$$

as  $n \rightarrow \infty$  since  $F(\theta - \epsilon) < 1$ . This shows that  $\hat{\theta}_n$  is indeed **consistent**. Moreover, since  $\mathbb{P}(|\hat{\theta}_n - \theta| > \epsilon)$  decays exponentially, so this is absolutely summable, hence it's also **strongly consistency**.  $\circledast$

Proving convergence of  $\hat{\theta}_n$  is useful, but this might not be enough.

**Example.** Consider any deterministic sequence  $(a_n)$  in  $\mathbb{R}$  which converges to 0. Adding  $a_n$  to  $\hat{\theta}_n$  will not change the convergence of  $\hat{\theta}_n$ . This shows that being **consistent** might not be enough in some cases.

The above suggests that we should look at the *distribution* of  $\hat{\theta}_n - \theta$  in order to say how does  $\hat{\theta}_n \rightarrow \theta$ .

**Example (Mean estimation for Gaussian).** Suppose  $X \sim \mathcal{N}(\theta, 1)$ . Then  $\hat{\theta}_n = \bar{X}_n \sim \mathcal{N}(\theta, 1/n)$ , i.e.,  $\sqrt{n}(\hat{\theta}_n - \theta) \sim \mathcal{N}(0, 1)$ . This implies that we can write down a confidence interval (CI) such that  $\hat{\theta}_n \pm 1.96/\sqrt{n}$  with 95% CI for  $\hat{\theta}_n$ .

Doing this for other kind of estimators and  $F$  is not that straightforward and will be challenging.

**Remark.** Let  $(X_n)$  and  $X$  be  $d$ -dimensional random vectors,  $h: \mathbb{R}^d \rightarrow \mathbb{R}^m$ , and  $c \in \mathbb{R}^d$  constant.

- (a) If  $X_n \rightarrow c$ , then  $h(X_n) \rightarrow h(c)$  if  $h$  is continuous at  $c$ .<sup>a</sup> This also holds for  $\xrightarrow{\text{a.s.}}$  and  $\xrightarrow{P}$ .
- (b) If  $X_n \rightarrow X$ , then  $h(X_n) \rightarrow h(X)$  if  $h$  is continuous. This also holds for  $\xrightarrow{\text{a.s.}}$  and  $\xrightarrow{P}$ .

<sup>a</sup>This is an if and only if condition if this holds for any  $h$ .

Let's see some examples.

**Example.** If  $d = 1$ , and  $X_n \rightarrow \theta \neq 0$ . Then  $1/X_n \rightarrow 1/\theta$  where

$$h(x) = \begin{cases} \frac{1}{x}, & \text{if } x \neq 0; \\ c, & \text{if } x = 0 \end{cases}$$

for any  $c \in \mathbb{R}$ . The same holds for  $\xrightarrow{\text{a.s.}}$  and  $\xrightarrow{P}$ .

**Example.** If  $X_n \rightarrow X$  and  $Y_n \rightarrow Y$ , then  $(X_n Y_n) \rightarrow (X, Y)$ .<sup>a</sup> The same holds for  $\xrightarrow{\text{a.s.}}$  and  $\xrightarrow{P}$ .

<sup>a</sup>The converse is also true since projections are continuous.

**Proof.** To show  $\|(X_n, Y_n) - (X, Y)\| \rightarrow 0$ , we have

$$\|(X_n, Y_n) - (X, Y)\| \leq \|X_n - X\| + \|Y_n - Y\|$$



for all  $n \geq 1$ .<sup>a</sup> The latter two terms goes to 0 (in whatever sense) by assumption. ⊛

<sup>a</sup>This can be seen from  $\sqrt{x+y} \leq \sqrt{x} + \sqrt{y}$ .

## Lecture 3: Weak Convergence and

### 1.3.3 Weak Convergence

25 Jan. 9:30

Again, consider working in a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ .

**Definition 1.3.8 (Total variation).** The *total variation* distance between  $X$  and  $Y$  in  $\Omega$  is defined as

$$\text{TV}(X, Y) = \sup_{B \in \mathcal{F}} |\mathbb{P}(X \in B) - \mathbb{P}(Y \in B)|$$

Returning to our situation, consider a sequence of random variables  $(X_n)$  and a random variable  $X$ .

**Remark.** If  $X_n$  has density  $f_n$  and  $X$  has density  $f$ , then  $\text{TV}(X_n, X) = \frac{1}{2} \int |f_n - f|$ .

**Definition 1.3.9 (Convergence in total variation).**  $X_n$  *converges in total variation* to  $X$ , denoted as  $X_n \xrightarrow{\text{TV}} X$ , if  $\text{TV}(X_n, X) \rightarrow 0$  as  $n \rightarrow \infty$ .

**Remark.** If  $X_n$  has density  $f_n$  and  $X$  has density  $f$ ,  $f_n \rightarrow f$  implies  $X_n \xrightarrow{\text{TV}} X$ .

**Note.** The above could make sense even if  $X_n$  was defined on different  $(\Omega_n, \mathcal{F}_n, \mathbb{P}_n)$  for every  $n$ .

Let's see some examples.

**Example.** Consider  $X_n \sim \text{Bin}(n, p_n)$  such that  $np_n \rightarrow \lambda \in \mathbb{R}$ . As this happens,

$$X_n \sim \text{Bin}(n, p_n) \xrightarrow{\text{TV}} X \sim \text{Pois}(\lambda).$$

**Example.** Let  $X_n \sim f_{\theta_n}$  where  $f_{\theta_n}(x) = f(x)e^{\theta x - \psi(\theta)}$  for some  $\theta \in \Theta$ . If  $\theta_n \rightarrow \theta$ , then  $X_n \xrightarrow{\text{TV}} X \sim f_{\theta}$ . For example, if  $X_n \sim \text{Pois}(\theta_n)$  and  $\theta_n \rightarrow \theta$ , then  $X_n \xrightarrow{\text{TV}} X \sim \text{Pois}(\theta)$ .

However, [convergence in total variation](#) might be too strong to work with.

**Example.** Let  $X_n \sim \mathcal{U}\{0, 1/n, \dots, (n-1)/n\}$ , which should be converging to  $X \sim \mathcal{U}(0, 1)$ . However, this doesn't happen in total variation distance as we can take  $B$  to be  $\mathbb{Q}$ .

This suggests that we should look at something weaker.

**Definition 1.3.10 (Weak convergence).**  $X_n$  *converges weakly* to  $X$ , denoted as  $X_n \xrightarrow{w} X$ , if for all continuous and bounded  $g: \mathbb{R}^d \rightarrow \mathbb{R}$ ,  $\mathbb{E}[g(X_n)] \rightarrow \mathbb{E}[g(X)]$ .

To see how is [weak convergence](#) compared to [convergence in total variation](#), we revisit the above example.

**Example.** Let  $X_n \sim \mathcal{U}\{0, 1/n, \dots, (n-1)/n\}$ . which should be converging to  $X \sim \mathcal{U}(0, 1)$ . We have

$$\mathbb{E}[g(X_n)] = \sum_{k=0}^{n-1} g(k/n) \left( \frac{k+1}{n} - \frac{k}{n} \right) \rightarrow \int_0^1 g(x) dx = \mathbb{E}[g(X)]$$

as  $g$  is continuous and bounded on  $[0, 1]$ , hence Riemann integrable.

The following theorem characterizes [weak convergence](#).

**Theorem 1.3.3 (Portmanteau theorem).** The following are equivalent.

- (a)  $X_n \xrightarrow{w} X$ .
- (b)  $\mathbb{E}[g(X_n)] \rightarrow \mathbb{E}[g(X)]$  for all  $g: \mathbb{R}^d \rightarrow \mathbb{R}$ , Lipschitz and bounded.
- (c)  $\mathbb{P}(X \in A) \leq \liminf_{n \rightarrow \infty} \mathbb{P}(X_n \in A)$  for all  $A \subseteq \mathbb{R}^d$  open.
- (d)  $\mathbb{P}(X \in A) \geq \limsup_{n \rightarrow \infty} \mathbb{P}(X_n \in A)$  for all  $A \subseteq \mathbb{R}^d$  closed.
- (e)  $\mathbb{P}(X_n \in A) \rightarrow \mathbb{P}(X \in A)$  for all  $A$  such that  $\mathbb{P}(X \in \partial A) = 0$ .

Before we prove [Portmanteau theorem](#), we need some result from analysis. Specifically, although we might think of we're working in Euclidean spaces, all our discussion can be extended to metric spaces. Recall some results from metric spaces.

**Claim.** Given a metric space  $(S, \rho)$ ,  $\rho(\cdot, A)$  is Lipschitz for any  $A \subseteq S$ , i.e., for any  $x, y \in S$ ,

$$|\rho(x, A) - \rho(y, A)| \leq \rho(x, y).$$

**Proof.** Since for any  $z \in S$ ,  $\rho(x, z) \leq \rho(x, y) + \rho(y, z)$ , hence  $\rho(x, A) - \rho(y, A) \leq \rho(x, y)$  by taking the infimum over  $z \in A$ . Interchanging  $x$  and  $y$  gives another inequality.  $\circledast$

**Claim.** Given a metric space  $(S, \rho)$ , for any  $A \subseteq S$ ,  $x \in \bar{A} \Leftrightarrow \rho(x, A) = 0$ .

**Proof.** If  $x \in \bar{A}$ , there exists  $(x_n)$  in  $A$  such that  $\rho(x_n, x) \rightarrow 0$ . Then for any  $z \in A$ ,  $\rho(x, z) \leq \rho(x, x_n) + \rho(x_n, z)$ , implying

$$\rho(x, A) \leq \rho(x, x_n) + \rho(x_n, A) \rightarrow 0,$$

hence  $\rho(x, A) = 0$ . On the other hand, suppose  $\rho(x, A) = 0$ . As  $\rho(x, A) = \inf_{y \in A} \rho(x, y)$ , there exists  $(y_n)$  in  $A$  such that  $\rho(x, y_n) \rightarrow \rho(x, A) = 0$ , i.e.,  $x \in \bar{A}$ .  $\circledast$

**Lemma 1.3.1.** Given a metric space  $(S, \rho)$  and let  $A \subseteq S$  be a closed subset. Then there exists  $g_k: S \rightarrow \mathbb{R}$  decreasing in  $k$  which is bounded and Lipschitz such that  $g_k(x) \searrow \mathbb{1}_A(x)$ .

**Proof.** Since  $A$  is closed,  $A = \bar{A}$  and

$$\mathbb{1}_A(x) = \begin{cases} 1, & \text{if } x \in A \Leftrightarrow \rho(x, A) = 0; \\ 0, & \text{if } x \notin A \Leftrightarrow \rho(x, A) > 0. \end{cases}$$

Now, we let

$$g_k(x) = \begin{cases} 0, & \text{if } \rho(x, A) > \frac{1}{k}; \\ 1 - k\rho(x, A), & \text{otherwise;} \end{cases} = 1 - (k\rho(x, A) \wedge 1).$$

We see that

- if  $x \in A$ :  $\mathbb{1}_A(x) = 1$ , and  $g_k(x) = 1$  since  $\rho(x, A) = 0$ ;
- if  $x \notin A$ :  $\mathbb{1}_A(x) = 0$ , and  $\rho(x, A) > 0$  since  $A$  closed, and  $g_k(x) = 0$  for all large enough  $k$ .

Finally, it's clear that  $g_k(x)$  takes values in  $[0, 1]$ , and we now show it's Lipschitz. We have

$$|g_k(x) - g_k(y)| = |(k\rho(x, A) \wedge 1) - (k\rho(y, A) \wedge 1)| \leq k\rho(x, y)$$

for all  $x, y \in S$ . ■

Then we can prove the [Portmanteau theorem](#).

**Proof of Theorem 1.3.3.** (a)  $\Rightarrow$  (b) is clear. And note that (c)  $\Leftrightarrow$  (d) since the following.

**Claim.** (d)  $\Rightarrow$  (c).

**Proof.** Since when  $A$  is open,

$$\begin{aligned}\mathbb{P}(X \in A) &= 1 - \mathbb{P}(X \in A^c) \\ &\leq 1 - \limsup_{n \rightarrow \infty} \mathbb{P}(X_n \in A^c) \\ &= 1 - \limsup_{n \rightarrow \infty} (1 - \mathbb{P}(X_n \in A)) = \liminf_{n \rightarrow \infty} \mathbb{P}(X_n \in A).\end{aligned}$$

⊗

(c)  $\Rightarrow$  (d) is exactly the same, hence (c)  $\Leftrightarrow$  (d). Next, we prove (b)  $\Rightarrow$  (d).

**Claim.** (b)  $\Rightarrow$  (d).

**Proof.** Assuming  $A$  is closed, then

$$\mathbb{P}(X_n \in A) = \mathbb{E} [\mathbb{1}_A(X_n)] \leq \mathbb{E} [g_k(X_n)]$$

This is true for every  $k$  and  $n$  since  $g_k \geq \mathbb{1}_A$ . Take the limit as  $n \rightarrow \infty$ , we have

$$\limsup_{n \rightarrow \infty} \mathbb{P}(X_n \in A) \leq \mathbb{E} [g_k(X)] \rightarrow \mathbb{E} [\mathbb{1}_A(X)] = \mathbb{P}(X \in A)$$

as  $k \rightarrow \infty$ .

⊗

Hence, we now have (a)  $\Rightarrow$  (b)  $\Rightarrow$  (d)  $\Leftrightarrow$  (c). ■

# Appendix

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