

tesseract\_environment  
::Command



```
graph BT; A[tesseract_environment::ChangeLinkVisibilityCommand] --> B[tesseract_environment::Command];
```

The diagram illustrates a class hierarchy. At the bottom is a gray-shaded box representing the base class, `tesseract_environment::ChangeLinkVisibilityCommand`. A blue arrow points vertically upwards from this box to a white box above it, representing the derived class, `tesseract_environment::Command`. Both boxes have a black border.

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::ChangeLinkVisibilityCommand