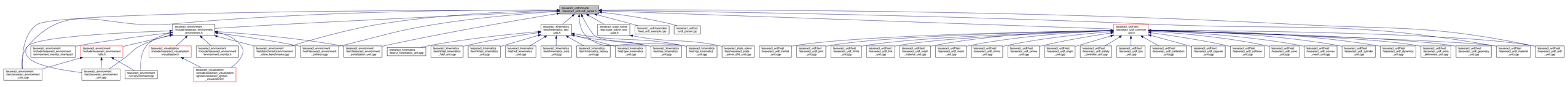
tesseract_urdf/include/tesseract_urdf/urdf_parser.h
tesseract_environment/include/tesseract_environment/environment.h
tesseract_kinematics/test/kinematics_test_utils.h
tesseract_state_solver/test/state_solver_test_utils.h
tesseract_urdf/examples/load_urdf_example.cpp
tesseract_urdf/test/urdf_parser.cpp
tesseract_urdf/test/tesseract_urdf_common_unit.h
tesseract_environment/include/tesseract_environment/environment_monitor_interface.h
tesseract_environment/include/tesseract_environment/utils.h
tesseract_visualization/include/tesseract_visualization/visualization.h
tesseract_environment/include/tesseract_environment/environment_monitor.h
tesseract_environment/test/tesseract_environment_clone_benchmark.cpp
tesseract_environment/test/tesseract_environment_collision.cpp
tesseract_environment/test/tesseract_environment_serialization_unit.cpp
tesseract_kinematics/test/ur_kinematics_unit.cpp
tesseract_kinematics/test/fwd_kinematics_fwd_unit.cpp
tesseract_kinematics/test/kdl_kinematics_unit.cpp
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tesseract_urdf/test/tesseract_urdf_cone_unit.cpp
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tesseract_urdf/test/tesseract_urdf_dynamics_unit.cpp
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tesseract_urdf/test/tesseract_urdf_material_unit.cpp
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tesseract_environment/src/environment.cpp
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