

Queens' College Cambridge

Foundations Of Computer Science



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1 OCaml

1.1 OCaml and Functional Programming

- OCaml is a functional programming language, tasks can be approached **mathematically**.
- OCaml provides **imperative** features such as
 - mutable arrays and variables (which are updated using the assignment command)
 - input and output commands

Reason: pure functional methods such as *monads* reduce the clarity of the language.

Features

- Lists. Supports sequential access (scanning left from right).

```
type 'a list = [] | (::) of 'a * 'a list
```

- Balanced tree. In theory, same efficiency as arrays, but in practice slower.
- First class objects: Objects that support all the operations generally available to other objects (such as being returned / applied to functions)
- Pattern matching: Pattern matching is the matching of objects against algebraic data type constructors.
- OCaml's type system is **polymorphic**

- Higher order functions: A function that either (or both) takes a function as an argument or returns a function. e.g. `List.map`, `List.fold`
- Exceptions can be raised and handled, \implies OCaml cannot crash but enter an error state (which is contained).

Evaluation Of Expressions

- **Call-by-value** (strict evaluation):
 - Evaluation rule in OCaml.
 - Rule: To evaluate `f E`, first evaluate `E` then substitute the value into the body of `f`.
 - Conditionals have the rule: if `E_1` is true, evaluate `E_2` otherwise evaluate `E_3`.
- **Call-by-name**:
 - Rule: To evaluate `f E`, substitute `E` into the body of `f`. Then evaluate the body.
 - Good at reducing `f` if `f` doesn't dependent on `E`, but can lead to multiple evaluations of `E`.
- **Call-by-need** (lazy evaluation):
 - Similar to **call-by-name** but ensures `E` is evaluated at most once.
 - Substitutes pointers into the function body, if `E` is evaluated then the value is shared by the other pointers.
 - Pointer structure forms a directed graph.

1.1.1 Concrete Data Types

OCaml Type	Range
<code>int</code>	32 (or 64) bit two's complement integer
<code>float</code>	IEEE double-precision floating point
<code>bool</code>	A boolean, with literals <code>true</code> and <code>false</code>
<code>char</code>	An 8-bit character. Represented using <code>'...'</code>
<code>string</code>	A string. Represented using <code>"..."</code>
<code>unit</code>	Written as <code>()</code> . Used as a null value. <code>unit</code> is often returned by functions that produce side-effect e.g. <code>print_string : string -> unit</code> .

1.1.2 Operators

Operator	Meaning
+	Integer addition
-(infix)	Integer subtraction
*	Integer multiplication
/	Integer division
mod	Integer modulo
-(prefix)	Negation
+.	Floating-point addition
-.	Floating-point negation
*.	Floating-point multiplication
/.	Floating-point division
**	Floating-point exponentiation
@	List concatenation
^	String concatenation
=	Equality
<>	Inequality
<	Less than
<=	Less than or equals
>	Greater than
>=	Greater than or equals
&&	Boolean and
	Boolean or
not(prefix)	Boolean not

1.1.3 Local declarations

- A **declaration** is the process of assigning a name to an expression.
- Local declarations in OCaml begin with the `let` keyword followed by the identifiers of the value. e.g.

```
let <pat1> = e1 and ... and <patn> = en [in u]
```

- Value identifiers are referred to as **variables** (bad use of the word...).
- A variable can be redeclared but not updated.
- The primitive types of values are `int`, `float`, `bool`, `char`, `string`.
- Identifiers can be
 - **alphabetic**: Starts with a letter, followed by zero or more letters, digits, underscores or apostrophe.
 - **symbolic**: One or more of `!,%,&,$,#,+, -, *, /, :, <, =, >, ?, @, \, ~, ', ^`

1.1.4 Pattern Matching

- A **pattern** is defined as an expression consisting of variables, constructors and wildcards. Constructors are
 - literals (e.g. ints, floats, strings, etc)
 - algebraic data type value constructors
- **Pattern matching** is the process of checking whether a value matches a given pattern. (they are usually matched using FSMs).
- e.g. Consider matching on a `maybe` value, then

```
let f x = match x with
| Nothing -> raise (Invalid_argument "f")
| Just x -> x
```


- Patterns have the general grammar

```

<pat> ::= _
        | <var>
        | <ValCons> <pat>
        | <ValCons> (<pat>, <pat>, ..., <pat>)

```

1.1.5 Control Structures

Sequence

- The sequence expression has the form

```
E_1 ; ... ; E_n
```

- The expression first evaluates E_1 , then E_2 , ..., then E_n and returns the value of E_n .
- The type of $(E_1 : t_1) ; \dots ; (E_n : t_n)$ is t_n .

Conditional

- Conditional expressions have the form

```
if E_1 then E_2 else E_3
```

where E_1 is an expression of type `bool`, and E_2 , E_3 are expressions of type `'a`. The type of conditional is `'a`.

- `else E_3` can be omitted, in which case it defaults to `else ()` (useful for imperative programming)

Match Expression

- The match expression has the form

```

match E_1, ..., E_n with
| <pat11>, ..., <pat1n> [when cond_1] -> e_1
| ...
| <patm1>, ..., <patmn> [when cond_m] -> e_m

```

Exception Handling

- An **exception** is an datatype, that once **raised**, disrupts the normal flow of the program's execution
- They are defined using the following syntax:

```
exception E [of t]
```

where **E** is an exception constructor name and **t** is some optional type.
e.g.

```
exception Problem of string
```

- To raise an exception value **e**, use the **raise** function.
e.g. `raise $ Invalid_argument "foldr1"`
- To handle an exception, we use the following syntax

```
try E_0 with
| pat1 -> E_1
.
.
.
| patn -> E_n
```

where **E_0** is some expression that might raise an exception. If no exception is raised, then the **try** expression evaluates to **E_0**. Otherwise, if it does raise some exception value **v**, the value **v** is matched against the patterns. e.g.

```
try hd [] with
| Invalid_argument s -> s
```

1.2 Functions

1.2.1 Function Definitions

- Non-recursive functions are defined as:

```
let f x1 x2 ... xn = e
```

Recursive functions require the `rec` keyword:

```
let rec f x1 x2 ... xn = e
```

- We can use type annotations to explicitly denote types. e.g.
`let f (x : int) : int = x + 2.`
- Mutually recursive functions are defined with the `and` keyword e.g.

```
let rec even n = n = 0 || odd (n - 1)
and      odd  n = n = 1 || even (n - 1)
```

- Function types are

```
t1 -> t2 -> ... -> tn -> u
```

where `x1 : t1, ..., xn : tn` are the metavariables indicating types and `e : u`.

- The type operator `->` is right associative (curried functions).

1.2.2 Anonymous Functions

- An anonymous function is a function definition that is not bound to an identifier.
- In OCaml, there are two different types of syntax for anonymous functions:
 1. `function` creates an anonymous function that can match 1 variable to n patterns using

```
function
| <pat1> [when cond1] -> E_1
.
.
.
| <patn> [when condn] -> E_n
```

2. **fun** creates an anonymous function that can match n variables to 1 pattern each

```
fun <pat1> ... <patn> -> E
```

- They're often arguments being passes to higher-order functions, or used for constructing the results of a higher-order function.

1.2.3 First-Class Objects

- A first-class object is an entity which supports all the operations generally available to other objects. e.g. being passes as an argument, returned from a function, etc.
- OCaml functions are first-class objects.

1.2.4 Currying and Partial Application

- Currying is the process of transforming a function that takes multiple arguments in a tuple, into a function that takes a single argument and returns another function. e.g. $f : a \rightarrow (b \rightarrow c)$ is the curried form of $g : (a,b) \rightarrow c$
- Note that \rightarrow is right associative.
- Curried functions are more convenient because it allows partial application.
- Partial application is where less arguments than the full number of arguments are applied to a function. e.g.

```
let add x y = x + y
let add_one = add 1
```

Note that function application is left associative e.g.

$$f\ E_1\ E_2\ \dots\ E_n = (\dots ((f\ E_1)\ E_2)\ \dots)\ E_n$$

1.2.5 Higher Order Functions

- A **higher-order function** is a function that takes other functions as arguments or returns a function as a result. e.g.

```
(* curry : ('a * 'b -> 'c) -> 'a -> 'b -> 'c *)
let curry f a b = f (a, b)
(* uncurry : ('a -> 'b -> 'c) -> ('a * 'b -> 'c) *)
let uncurry f (a, b) = f a b
```

1.2.6 Polymorphic Functions

- OCaml's functions and abstract data types support parametric polymorphism (and subtype polymorphism).
- Parametric polymorphism refers to when the type of a value contains one or more type parameters. e.g.

```
let id x = x
- val id : 'a -> 'a = <fun>
```

1.2.7 Operators as Functions

- In OCaml, infix operators can be used as prefix functions by surrounding them with parentheses:

```
( + );;
- : int -> int -> int = <fun>
```

- We can define our own infix operators using the same syntax:

```
let ( <.> ) f g = fun x -> f (g x)
```

1.3 Imperative Features

1.3.1 References

- In OCaml we use a data abstraction of the computer's memory, via references to memory cells. A reference with initial contents of E is created using `ref E`. `ref` is a function of type `'a -> 'a ref`.
- The function `!` applied to the reference `p` is used to return the current contents of the reference `p`. This operation is known as dereferencing. It has the type `'a ref -> 'a`.
- To update the contents of a reference, the assignment operator `:=` is used. `p := E` assigns the contents of `p` to the value of `E`. `:=` has the type `'a ref -> 'a -> ()`.
- Two references are said to be equal if and only if they have the same contents.

1.3.2 Control Structures

- There are two iterative control structures in OCaml:
 - The for loop, with the syntax

```
for <name> = E_1 to E_2 do
  E_3
done
```

where `E_1` is the initial value `<name>`. The body of the for loop `E_3` is evaluated until `<name> = E_2`. The entire type of the for loop structure is `()`. e.g.

```
for x = 1 to 4 do print_int x; print_newline () done
```

prints the integers 1,2,3,4.

- The while loop, with syntax

```
while B do  
  E  
done
```

This evaluates the Boolean expression `B`. `E` is evaluated zero or more times until `B` evaluates to `false`.

- For branching structures, we `if - then - else` and the `match` constructs.

2 Concepts in OCaml

2.1 Data Structures

2.1.1 Algebraic Data Types

- An algebraic data type in OCaml has the following form:

```
type ('a, 'b, ..., 'c) alg_data_type =  
    Constructor1  
  | Constructor2  
    .  
    .  
    .  
  | ConstructorK  
  | ConstructorK' of t11 * t12 * ... * t1m  
    .  
    .  
    .  
  | ConstructorN of tn1 * tn2 * ... * tnm
```

where `alg_data_type` is the name of the type of arity > 0 , `'a`, `'b`, ..., `'c` are distinct type parameters and `Constructor1`, ... are the value constructors that describe the ways in which the values of the `alg_data_type` type can be constructed.

- Algebraic data types can be polymorphic, via the use of type parameters.

e.g. Consider the `maybe` type (often called `option`).

```
type 'a maybe = Nothing | Just of 'a
```


We can then have `int maybe`, `float maybe`, `string maybe`, ... types.

- All non-recursive algebraic data types can be represented using the `disjoint_sum` data type.

```
type ('a,'b) disjoint_sum = Ln1 of 'a | Ln2 of 'b
```

Consider the type `maybe`, then

```
let nothing = Ln1 ()  
let just x = Ln2 x
```

Provided we use a unique `disjoin_sum` value in each of our value constructor representation functions then we can represent the original non-recursive type.

- Algebraic data types can be recursive. e.g. `list` type.

```
type 'a list = [] | (::) of 'a * 'a list
```

2.1.2 Lists

- In OCaml, “lists” are singly-linked lists consisting of a finite sequence of elements.
- They are defined as

```
type 'a list = [] | (::) of 'a * 'a list
```

- There are three syntactic forms for building lists:

```
[] (*nil*)  
e1 :: (* cons *) e2  
[e1; e2; ...; en] <=> e1 :: e2 :: ... :: en :: []
```

- The cons operation is right associative.
- All elements in a list must have the same type. (However, the use of ADTs may subvert this condition).

```
module type List = sig
  exception Empty
  type 'a list

  val hd : 'a list -> 'a
  val tl : 'a list -> 'a list

  val is_empty : 'a list -> bool
  val empty : 'a list

  val foldl : ('b -> 'a -> 'b) -> 'b -> 'a list -> 'b
  val foldr : ('a -> 'b -> 'b) -> 'b -> 'a list -> 'b

  val zip : 'a list -> 'b list -> ('a * 'b) list
  val unzip : ('a * 'b) list -> 'a list * 'b list

  val length : 'a list -> int
  val rev : 'a list -> 'a list
  val (@) : 'a list -> 'a list -> 'a list

  val map : ('a -> 'b) -> 'a list -> 'b list
  val filter : ('a -> bool) -> 'a list -> 'a list

end

module List : List = struct
  type 'a list = [] | (::) of 'a * 'a list
  exception Empty

  let hd xs = match xs with
    | x :: _ -> x
    | _ -> raise Empty
```

```
let tl xs = match xs with
  | _ :: xs -> xs
  | _ -> raise Empty

let empty = []

let is_empty = match xs with
  | [] -> true
  | _ -> false

let rec foldl f acc xs = match xs with
  | [] -> acc
  | x :: xs -> foldl f (f acc x) xs

let rec foldr f acc xs = match xs with
  | [] -> acc
  | x :: xs -> f x (foldr f acc xs)

let rec zip xs ys = match xs, ys with
  | x :: xs, y :: ys -> (x, y) :: zip xs ys
  | _, _ -> []

let unzip = foldr (fun (x, y) (xs, ys) -> (x :: xs, y :: ys)) ([], [])

let length = foldl (fun acc _ -> acc + 1) 0

let cons x xs = x :: xs
let rev = fold cons []
let (@) xs ys = foldr cons ys xs

let map f = foldr (fun x xs -> f x :: xs) []
let filter f = foldr (fun x xs -> if f x then x :: xs else xs) []

end

(* useful list functions *)

let rec nth xs n = match xs, n with
```

```

| [], _ -> raise Empty
| _, n when n < 0 -> raise (Invalid_argument "nth")
| x :: _, 0 -> x
| x :: xs, n -> nth xs (n - 1)

let flatten = foldr (@) []
let exists f = foldl (fun acc x -> f x || acc) false
let all f = foldl (fun acc x -> f x && acc) true
let member x = exists ((=) x)
let partition f = foldr (fun x (xs, ys) -> if f x then ) ([], [])

```

2.1.3 Tuples

- Pairs are tuples of 2 values e.g. $(e1, e2) : 'a * 'b$
- n -tuples are created by an expression of the form $(e1, e2, \dots, en)$.
In ML, tuples have the form $(e1, \dots, en) = (e1, (e2, (\dots, (en-1, en) \dots)))$.
Hence n -tuples can be implemented as extended pairs.
- A 0-tuple (denoted $()$) is a null value of type `unit`. Often used in function that produce side-effects, such as `print_string : string -> unit`.

2.1.4 Binary Trees

- A binary tree is a rooted tree (a connected simple graph with no cycles) where each vertex has at most two *children* (the left and right child).
- The number of nodes n on a binary tree of height $h \geq 0$ is

$$h + 1 \leq n \leq 2^{h+1} - 1.$$

```

module Tree = struct
  type 'a tree = EmptyTree | Vertex of 'a * 'a tree * 'a tree
  exception Empty

  let rec max t = match t with
    | EmptyTree -> raise Empty
    | Vertex (v, _, EmptyTree) -> v

```

```

    | Vertex (_, _, r) -> max r

let rec min t = match t with
  | EmptyTree -> raise Empty
  | Vertex (v, EmptyTree, _) -> v
  | Vertex (_, l, _) -> min l

let rec insert t v = match t with
  | EmptyTree -> Vertex (v, EmptyTree, EmptyTree)
  | Vertex (u, l, r) when v = u -> Vertex (v, l, r)
  | Vertex (u, l, r) when v < u -> Vertex (u, insert l v, r)
  | Vertex (u, l, r) -> Vertex (u, l, insert r v)

let rec delete t v = match t with
  | EmptyTree -> EmptyTree
  | Vertex (u, l, r) when v < u -> Vertex (u, delete l v, r)
  | Vertex (u, l, r) when v > u -> Vertex (u, l, delete r v)
  | Vertex (u, l, r) -> match t with
    | Vertex (_, EmptyTree, EmptyTree) -> EmptyTree
    | Vertex (_, EmptyTree, r) -> r
    | Vertex (_, l, EmptyTree) -> l
    | Vertex (_, l, r) ->
      let v' = min r in
      let r' = delete r v'
      in Vertex (v', l, r')

let rec search t v = match t with
  | EmptyTree -> raise Empty
  | Vertex (u, _, _) when v = u -> t
  | Vertex (u, l, _) when v < u -> search l v
  | Vertex (u, _, r) -> search r v

end

```

- A *dictionary* is a collection of key-value pairs, such that each key appears at most once in the collection. An ordered dictionary is a dictio-

nary in which keys have some total ordering.

```

module type Dictionary = sig
  type key
  type 'a dict
  exception NotFound

  val empty : 'a dict

  val insert : 'a dict -> key -> 'a -> 'a dict
  val search : 'a dict -> key -> 'a
end

```

- A *binary search tree* is a binary tree in which each vertex stores a key-value pair (k, v) , such that for all keys k_l in the left subtree l satisfies $k_l < k$ (and vice-versa).
- A binary search tree implements an ordered dictionary.

```

module BST : Dictionary = struct
  include Tree

  type key = string
  type 'a dict = (key * 'a) tree
  exception NotFound

  let empty = EmptyTree

  let rec insert d k v = match d with
  | EmptyTree -> Vertex ((k, v), EmptyTree, EmptyTree)
  | Vertex ((k', v'), l, r) when k = k' ->
    Vertex ((k', v'), l, r)
  | Vertex ((k', v'), l, r) when k < k' ->
    Vertex ((k', v'), insert l k v, r)
  | Vertex ((k', v'), l, r) ->
    Vertex ((k', v'), l, insert r k v)
end

```

```

let rec search t k = match t with
| EmptyTree -> raise NotFound
| Vertex ((k', v'), _, _) when k = k' -> v'
| Vertex ((k', _), l, _) when k < k' -> search l k
| Vertex ((k', _), _, r) -> search r k

end

```

2.1.5 Queues

- A queue is a first in first out (FIFO) data structure, where elements are removed from the head and inserted at the tail.
- Functional queue $x_1, \dots, x_m, y_n, \dots, y_1$ represented by a pair of lists

$$\underbrace{([x_1, \dots, x_m])}_{\text{front}}, \underbrace{[y_1, \dots, y_n]}_{\text{rear}}.$$

- Enqueue to the rear of the queue and dequeue from the front.
- Amortized time per operation is $O(1)$.
- **Implementation:**

```

module type Queue = sig
  exception Empty

  type 'a queue
  val empty : 'a queue

  val is_empty : 'a queue -> bool

  val enqueue : 'a queue -> 'a -> 'a queue
  val dequeue : 'a queue -> 'a queue

  val hd : 'a queue -> 'a
end

```

```

module FunctionalQueue : Queue = struct
  exception Empty

  type 'a queue = 'a list * 'a list
  let empty = ([], [])

  let is_empty q = match q with
    | ([], []) -> true
    | _ -> false

  let norm q = match q with
    | ([], ys) -> (List.rev ys, [])
    | q -> q

  let enqueue (xs, ys) y = norm (xs, y :: ys)
  let dequeue q = match q with
    | (x :: xs, ys) -> norm (xs, ys)
    | _ -> raise Empty

  let hd q = match q with
    | (x :: _, _) -> x
    | _ -> raise Empty
end

```

2.2 Algorithms

2.2.1 Sorting

- **Problem Of Sorting:** Given sequence $\langle x_1, x_2, \dots, x_n \rangle$. Return permutation of sequence $\langle x'_1, x'_2, \dots, x'_n \rangle$ such that $x'_1 \leq x'_2 \leq \dots \leq x'_n$ (monotonically increasing)
- **Insertion Sort:**
 - Tail recursive (or iterative) comparison sorting algorithm.
 - At each recursive call, we remove an element (the head) and insert it in the correct position in the sorted sublist.


```

let rec insert e xs = match xs with
| [] -> [e]
| x :: xs when e <= x -> e :: x :: xs
| x :: xs -> x :: (insert e xs)

let rec insertion_sort xs = match xs with
| [] -> []
| x :: xs -> insert x (insertion_sort xs)

```

– **Analysis:**

- * **Worst Case:** Occurs when the list `xs` is reverse sorted. `insert` takes $\Theta(j)$ time for list `xs` of size j (in worst case). Hence

$$T(n) = \sum_{j=1}^n \Theta(j) = \Theta(n^2).$$

- * **Average Case:** Average case time complexity is $\Theta(n^2)$. See algorithms notes for analysis.

- Variants such as *binary insertion sort* exist, reducing # of comparisons, but still have time complexity of $O(n^2)$

• **Quicksort:**

- Divide and conquer comparison sorting algorithm:

- * **Divide:** Partition the list to be sorted into two sublists around a pivot x , such that elements in the lower sublist satisfy $\leq x$ and elements in the upper sublist satisfy $> x$.
- * **Conquer:** Recursively sort the lower and upper sublists using quicksort
- * **Combine:** Combine the sorted sublists by appending them together.

```

let rec quicksort xs = match xs with
| [] -> []
| x :: xs ->
    let (l, r) = partition (sw (<=) $ x) xs in
    quicksort l @ x :: r

```

– **Analysis:**

- * **Worst Case:** Partition produces one sublist of length $n - 1$ and one of length 0. `partition` takes $\Theta(n)$ time. So we have

$$\begin{aligned} T(n) &= T(n - 1) + T(0) + \Theta(n) \\ &= T(n - 1) + \Theta(n) \end{aligned}$$

Hence $T(n) \in \Theta(n^2)$. See algorithms notes for formal analysis.

- * **Average Case:** The average case time complexity is $O(n \log_2 n)$. See algorithms notes for formal analysis.

– A tail recursive variant

```
let rec quicksort xs sorted = match xs with
| [] -> sorted
| x :: xs ->
    let (l, r) = partition (sw (<=) $ x) xs in
    quicksort l (x :: quicksort r sorted)
```

• **Merge Sort:**

– Divide and conquer comparison sorting algorithm:

- * **Divide:** Divide the n element list `xs` into two sublists `l`, `r` of sizes $\lfloor n/2 \rfloor$ and $\lceil n/2 \rceil$ respectively.
- * **Conquer:** Recursively sort the two sublists using merge sort.
- * **Combine:** Merge the two sorted sublists using `merge`.

```
let rec merge xs ys = match xs, ys with
| [], ys -> ys
| xs, [] -> xs
| x :: xs, y :: ys ->
    if x <= y then x :: merge xs (y :: ys)
    else y :: merge (x :: xs) ys
```

```
let rec merge_sort xs = match xs with
| [] -> []
| [x] -> [x]
| xs ->
```

```

let k = length xs / 2
and l = merge_sort (take xs k)
and r = merge_sort (drop xs k) in
merge l r

```

– **Analysis:**

- * Let $T(n)$ be the time cost function of `merge_sort` where n is the length of `xs`. We have

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1 \\ 2T\left(\frac{n}{2}\right) + \underbrace{\Theta(n)}_{\text{merge}} & \text{otherwise.} \end{cases}$$

since `merge` performs $m' + n' - 1$ comparisons (in the worst case) where m' and n' are the lengths of `xs` and `ys` respectively. Hence $\Theta(n)$ time.

So by master theorem, we have

$$T(n) \in \Theta(n \log_2 n).$$

- Merge sort's worst case doesn't depend on the initial permutation of `xs`, whereas quicksort does.

2.2.2 Traversals

- **Tree Traversal:** A form of graph traversal in which each vertex of the tree data structure is visited exactly *once*. Classified by order in which vertices are visited.
- **Depth-first Searches.** A depth-first search (DFS) starts at a root vertex and explores as far as possible along each branch of the tree before backtracking. General recursive pattern (for a binary tree) with root x :
 - (L) Recursively traverse x 's left subtree l .
 - (V) Process the current vertex x .
 - (R) Recursively traverse x 's right subtree r .

Common DFS traversals:

– **Pre-order** (VLR):

- * Process current vertex, recursively traverse l then recursively traverse r .
- * Produces a topologically sorted list

```
let rec preorder x = match x with
  | EmptyTree -> []
  | Vertex (v, l, r) -> [v] @ preorder l @ preorder r
```
- * Tail-recursive variant removes append

```
let rec preorder x acc = match x with
  | EmptyTree -> acc
  | Vertex (v, l, r) -> v :: preorder l (preorder r acc)
```

– **In-order** (LVR):

- * Recursively traverse l , process current vertex x then recursively traverse r .
- * In BST, in-order traversal produces a sorted list of vertex keys.

```
let rec inorder x = match x with
  | EmptyTree -> []
  | Vertex (v, l, r) -> inorder l @ [v] @ inorder r
```
- * Tail-recursive variant

```
let rec inorder x acc = match x with
  | EmptyTree -> acc
  | Vertex (v, l, r) -> inorder l (v :: inorder r acc)
```

– **Post-order** (LRV):

- * Recursively traverse l , recursively traverse r then process current vertex x .

```
let rec postorder x = match x with
  | EmptyTree -> []
  | Vertex (v, l, r) -> postorder l @ postorder r @ [v]
```

* Tail-recursive variant

```
let rec postorder x acc = match x with
  | EmptyTree -> []
  | Vertex (v, l, r) -> postorder l (postorder r (v :: acc))
```

- **Analysis:** Worst case time complexity of implementations using `@` are $O(|V|^2)$ (due to append). Tail-recursive variants have a worst-case complexity of $\Theta(|V|)$.

- **Breadth-first Searches.** A Breadth-first search (BFS) starts at a root vertex and explores all of the neighbours at the current depth prior to moving onto the next depth level.

Implementations :

- **Naïve Implementation.** Use a list `xs` to store all vertices that will be visited. Each iteration removes a vertex from the head of the list and appends it's subtrees at the end of the list (FIFO ordering).

```
let rec bfs xs = match xs with
  | [] -> []
  | EmptyTree :: xs -> bfs xs
  | Vertex (v, l, r) :: xs -> v :: bfs (xs @ [l; r])
```

```
bfs : 'a tree list -> 'a list
```

- **Queue Implementation.** We use a functional queue implementation with enqueue and dequeue operations with amortized costs $O(1)$.

```
open FunctionalQueue
```

```
let rec bfs q =
  if is_empty q then []
  else
    match hd q with
    | EmptyTree -> bfs (dequeue q)
    | Vertex (v, l, r) ->
```

```
v :: bfs (enqueue (enqueue (dequeue q) 1) r)
```

```
bfs : 'a tree queue -> 'a list
```

Analysis: BFS to depth d with branching factor b (average degree) examines $O(b^d)$ vertices

$$n = 1 + b + \dots + b^d = \frac{b^{d+1} - 1}{b - 1} = \frac{b}{b - 1}(b^d - b^{-1}) \in O(b^d),$$

with time factor $\frac{b}{b-1}$.

- **Iterative deepening DFS.** Iterative deepening DFS (IDDFS) is a search algorithm in which DFS depth-limited algorithm is repeatedly run until the search goal (solution) is found. ‘

Analysis: The vertices at depth d are explored once, the vertices at $d - 1$ are explored twice, \dots , the root vertex is explored $d + 1$ times. So we have the following arithmetic-geometric sequence

$$\begin{aligned} b^d + 2b^{d-1} + 3b^{d-2} + \dots db + (d + 1) &= \sum_{k=0}^d (d + 1 - k)b^k \\ &= b^d \sum_{k=0}^d (d + 1 - k)b^{k-d} \\ &\leq b^d \sum_{k=1}^{\infty} k(b^{-1})^{k-1} \\ &= b^d \frac{d}{d(b^{-1})} \sum_{k=0}^{\infty} (b^{-1})^k \\ &= b^d \left(1 - \frac{1}{b}\right)^{-2} \in O(b^d) \end{aligned}$$

For the space complexity, the `dfs` function stores a stack of maximum depth d , hence space complexity of IDDFS is $O(d)$.

Advantages:

- BFS complete search on infinite trees while having DFS space complexity.
- Despite revisiting vertices, IDDFS is extremely efficient.

2.3 Sequences

- Implement lazy lists (sequences) in OCaml using delayed evaluation on the tail of the list.
- Delayed evaluation is implemented using a function `fun () -> e : () -> 'a`, delayed under a closure (not a lazy block). `e` is not evaluated until the function is called, thus delaying the evaluation of `e`.

```
module type Seq = sig
  type 'a seq
  exception Empty

  val hd : 'a seq -> 'a
  val tl : 'a seq -> 'a seq

  val empty : 'a seq
  val is_empty : 'a seq -> bool

  val map : ('a -> 'b) -> 'a seq -> 'b seq
  val filter : ('a -> bool) -> 'a seq -> 'a seq

  val (@) : 'a seq -> 'a seq -> 'a seq
  val interleave : 'a seq -> 'a seq -> 'a seq
end

module Seq : Seq = struct
  type 'a seq = Nil | Cons of 'a * (unit -> 'a seq)
  exception Empty

  let hd xs = match xs with
    | Cons (x, _) -> x
    | _ -> raise Empty

  let tl xs = match xs with
    | Cons (_, xf) -> xf ()
    | _ -> raise Empty
end
```

```
let empty = Nil
let is_empty xs = match xs with
  | Nil -> true
  | _ -> false

let rec map f xs = match xs with
  | Nil -> Nil
  | Cons (x, xf) -> Cons (f x, fun () -> map f (xf ()))

let rec filter f xs = match xs with
  | Nil -> Nil
  | Cons (x, xf) when f x -> Cons (x, fun () -> filter f (xf ()))
  | Cons (x, xf) -> filter f (xf ())

let rec (@) xs ys = match xs with
  | Nil -> ys
  | Cons (x, xf) -> Cons (x, fun () -> (xf ()) @ ys)

let rec interleave xs ys = match xs with
  | Nil -> ys
  | Cons (x, xf) -> Cons (x, fun () -> interleave ys (xf ()))

end
```