

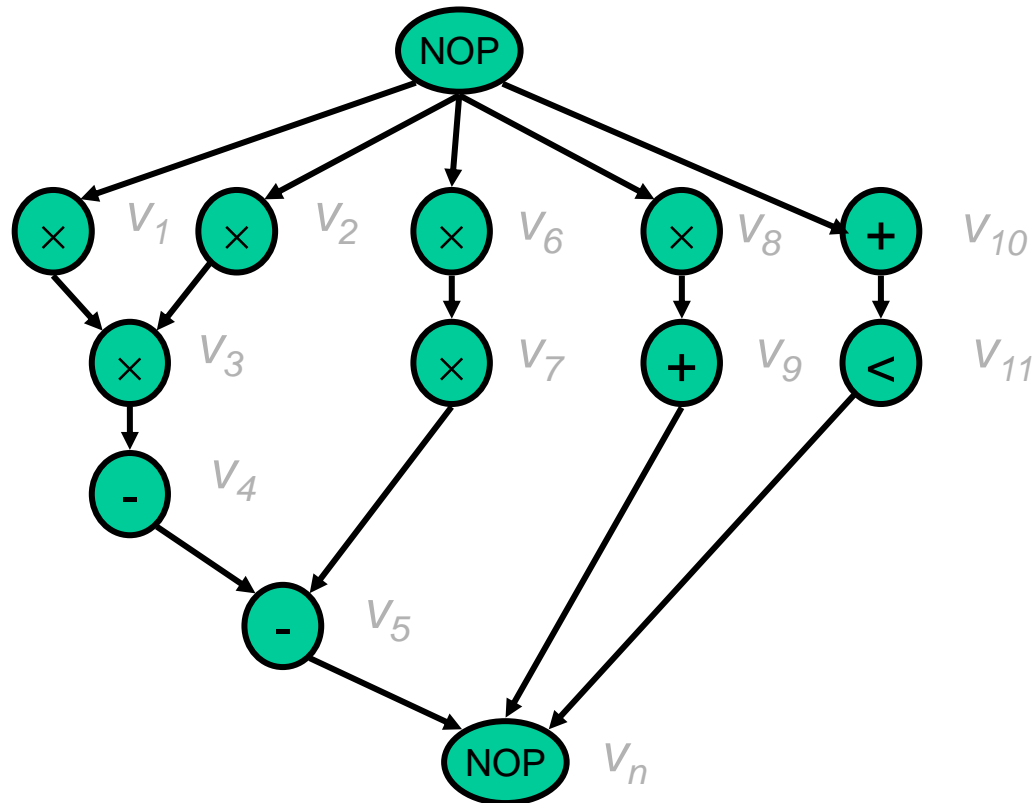
# Mixed Integer Linear Programming

- ❑ A mathematical programming such that:
  - The objective is a linear function
  - All constraints are linear functions
  - Some variables are real numbers and some are integers, i.e., "mixed integer"
- ❑ It is almost like a linear programming, except that some variables are integers

**NP-C problem**

# ILP Scheduling

□ How to construct a mathematical model?



# ILP Formulation of ML-RCS

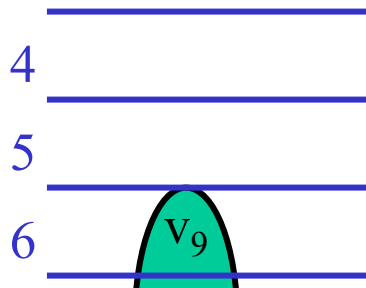
- ❑ Use binary decision variables
  - $i = 0, 1, \dots, n$
  - $l = 1, 2, \dots, \lambda' + 1$        $\lambda'$ : given upper-bound on latency
  - $x_{i,l} = 1$  if operation  $i$  starts at step  $l$ , 0 otherwise.
- ❑ Set of linear inequalities (constraints), and an objective function (min latency)
- ❑ Observations
  - $x_{i,l} = 0$  for  $l < t_i^S$  and  $l > t_i^L$       start time feasibility  
 $(t_i^S = ASAP(v_i), t_i^L = ALAP(v_i))$
  - $t_i = \sum_l l \cdot x_{i,l}$        $t_i$  = start time of op  $i$
  - $\sum_{m=l-d_i+1} x_{i,m} = 1$       If op  $v_i$  takes  $d_i$  steps,  
 is op  $v_i$  (still) executing at step  $l$ ?

# Start Time vs. Execution Time

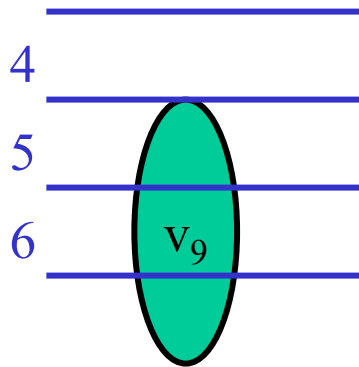
- ❑ For each operation  $v_i$ , only one start time
- ❑ If  $d_i=1$ , then the following questions are the same:
  - Does operation  $v_i$  **start** at step  $l$ ?
  - Is operation  $v_i$  **running** at step  $l$ ?
- ❑ But if  $d_i>1$ , then the two questions should be formulated as:
  - Does operation  $v_i$  **start** at step  $l$ ?
    - Does  $x_{i,l} = 1$  hold?
  - Is operation  $v_i$  **running** at step  $l$ ?
    - Does  $\sum_{m=l-d_i+1}^l x_{i,m} = 1$  hold?

# Operation $v_i$ Still Running at Step $i$ ?

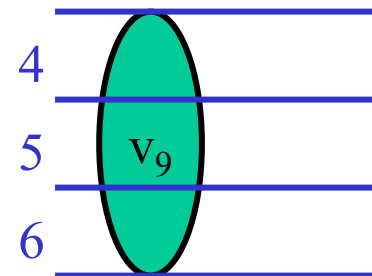
- Assume that  $v_9$  takes 3 steps, is  $v_9$  running at step 6?
  - Is  $x_{9,6} + x_{9,5} + x_{9,4} = 1$ ?



$$x_{9,6}=1$$



$$x_{9,5}=1$$

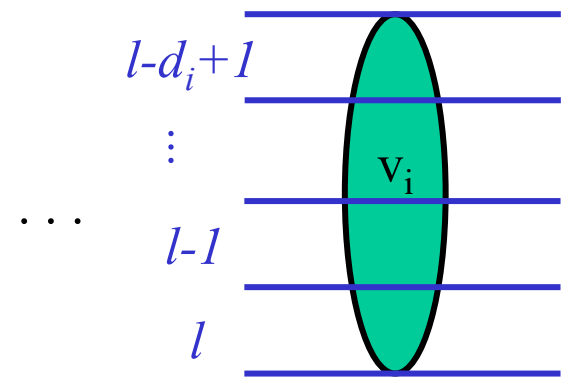
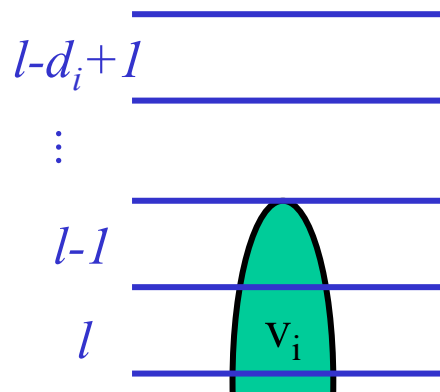
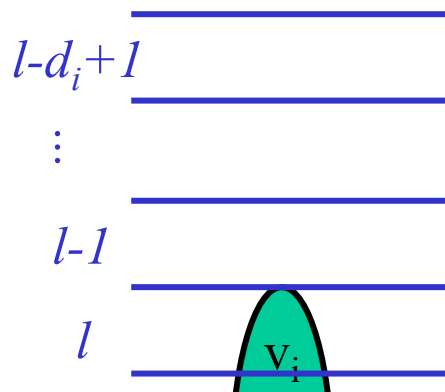


$$x_{9,4}=1$$

- Note:
  - Only one (if any) of the above three cases can happen
  - To meet resource constraints, we have to ask the same question for ALL steps, and ALL operations of that type

# Operation $v_i$ Still Running at Step $l$ ?

- Is  $v_i$  running at step  $l$  ?
  - Is  $x_{i,l} + x_{i,l-1} + \dots + x_{i,l-d_i+1} = 1$  ?



# ILP Formulation of ML-RCS (Cont.)

## □ Constraints:

– Unique start times:  $\sum_l x_{i,l} = 1, \quad i = 0, 1, \dots, n$

– Sequencing (dependency) relations must be satisfied

$$t_i \geq t_j + d_j \quad \forall (v_j, v_i) \in E \Rightarrow \sum_l l \cdot x_{i,l} \geq \sum_l l \cdot x_{j,l} + d_j$$

– Resource constraints

$$\sum_{i: T(v_i)=k} \sum_{m=l-d_i+1}^l x_{i,m} \leq a_k, \quad k = 1, \dots, n_{res}, \quad l = 1, \dots, \bar{\lambda} + 1$$

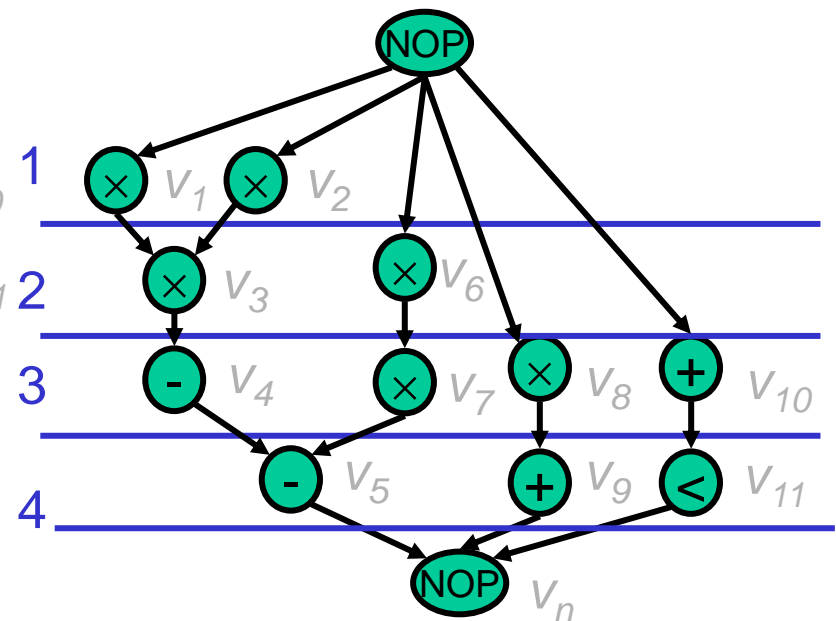
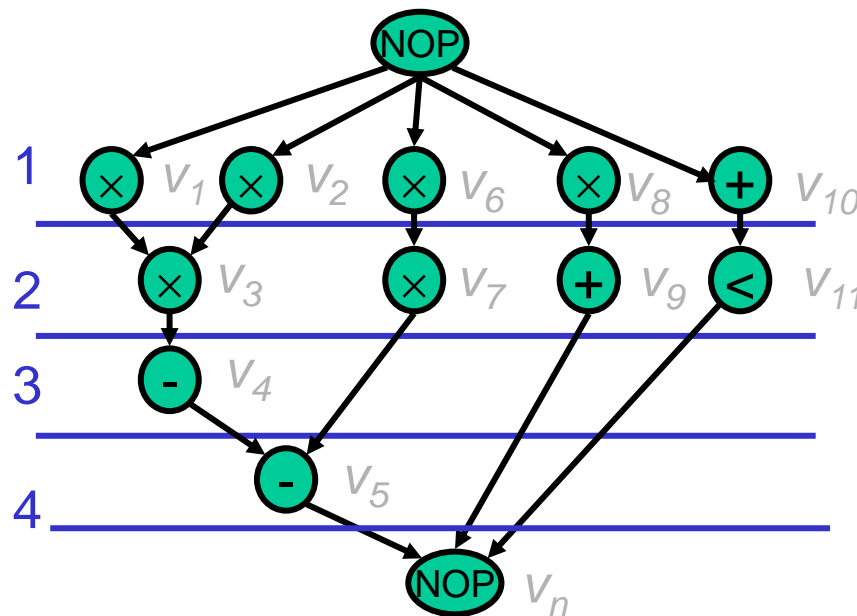
## □ Objective: $\min \mathbf{c}^T \mathbf{t}$ .

–  $\mathbf{t}$ =start times vector,  $\mathbf{c}$ =cost weight (ex: [0 0 ... 1])

– When  $\mathbf{c}=[0 \ 0 \ \dots \ 1]$ ,  $\mathbf{c}^T \mathbf{t} = \sum_l l \cdot x_{n,l}$

# ILP Example

- ❑ Assume  $\bar{\lambda} = 4$
- ❑ First, perform ASAP and ALAP
  - (we can write the ILP without ASAP and ALAP, but using ASAP and ALAP will simplify the inequalities)





# ILP Example: Unique Start Times Constraint

□ Without using ASAP and ALAP values:

$$x_{1,1} + x_{1,2} + x_{1,3} + x_{1,4} = 1$$

$$x_{2,1} + x_{2,2} + x_{2,3} + x_{2,4} = 1$$

...

...

...

$$x_{11,1} + x_{11,2} + x_{11,3} + x_{11,4} = 1$$

□ Using ASAP and ALAP:

$$x_{1,1} = 1$$

$$x_{2,1} = 1$$

$$x_{3,2} = 1$$

$$x_{4,3} = 1$$

$$x_{5,4} = 1$$

$$x_{6,1} + x_{6,2} = 1$$

$$x_{7,2} + x_{7,3} = 1$$

$$x_{8,1} + x_{8,2} + x_{8,3} = 1$$

$$x_{9,2} + x_{9,3} + x_{9,4} = 1$$

...

# ILP Example: Dependency Constraints

- Using ASAP and ALAP, the non-trivial inequalities are: (assuming unit delay for + and \*)

$$2 \cdot x_{7,2} + 3 \cdot x_{7,3} - 1 \cdot x_{6,1} - 2 \cdot x_{6,2} - 1 \geq 0$$

$$2 \cdot x_{9,2} + 3 \cdot x_{9,3} + 4 \cdot x_{9,4} - 1 \cdot x_{8,1} - 2 \cdot x_{8,2} - 3 \cdot x_{8,3} - 1 \geq 0$$

$$2 \cdot x_{11,2} + 3 \cdot x_{11,3} + 4 \cdot x_{11,4} - 1 \cdot x_{10,1} - 2 \cdot x_{10,2} - 3 \cdot x_{10,3} - 1 \geq 0$$

$$4 \cdot x_{5,4} - 2 \cdot x_{7,2} - 3 \cdot x_{7,3} - 1 \geq 0$$

$$5 \cdot x_{n,5} - 2 \cdot x_{9,2} - 3 \cdot x_{9,3} - 4 \cdot x_{9,4} - 1 \geq 0$$

$$5 \cdot x_{n,5} - 2 \cdot x_{11,2} - 3 \cdot x_{11,3} - 4 \cdot x_{11,4} - 1 \geq 0$$

# ILP Example: Resource Constraints

- ❑ Resource constraints (assuming 2 adders and 2 multipliers)

$$x_{1,1} + x_{2,1} + x_{6,1} + x_{8,1} \leq 2$$

$$x_{3,2} + x_{6,2} + x_{7,2} + x_{8,2} \leq 2$$

$$x_{7,3} + x_{8,3} \leq 2$$

$$x_{10,1} \leq 2$$

$$x_{9,2} + x_{10,2} + x_{11,2} \leq 2$$

$$x_{4,3} + x_{9,3} + x_{10,3} + x_{11,3} \leq 2$$

$$x_{5,4} + x_{9,4} + x_{11,4} \leq 2$$

- ❑ Objective:

- Since  $\lambda=4$  and sink has no mobility, any feasible solution is optimum, but we can use the following anyway:  $\text{Min } 1 \cdot x_{n,1} + 2 \cdot x_{n,2} + 3 \cdot x_{n,3} + 4 \cdot x_{n,4} + 5 \cdot x_{n,5}$

# ILP Formulation of MR-LCS

- ❑ Dual problem to ML-RCS
- ❑ Objective:
  - Goal is to optimize total resource usage,  $\mathbf{a}$ .
  - Objective function is  $\mathbf{c}^T \mathbf{a}$ , where entries in  $\mathbf{c}$  are respective area costs of resources
- ❑ Constraints:
  - Same as ML-RCS constraints, plus:
  - Latency constraint added:

$$\sum_l l \cdot x_{n,l} \leq \bar{\lambda} + 1$$

- Note: unknown  $\mathbf{a}_k$  appears in constraints.

# Further Study

- ❑ Linear programming

- <http://www.cs.sunysb.edu/~algorithm/files/linear-programming.shtml>

- ❑ Linear programming tools

- [https://en.wikipedia.org/wiki/List\\_of\\_optimization\\_software](https://en.wikipedia.org/wiki/List_of_optimization_software)



