# Algorithm Theory, Tutorial 1

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#### **General Hints**

- Contact tutor (johannes.kalmbach@gmail.com) for questions concerning corrections etc.
- Contact forum (daphne.informatik.uni-freiburg.de) for everything else
- Suggestion: Submit in groups of two (better for understandable algorithms)
- Submit readable solutions (LaTeX as pdf, CLEAN handwriting (+ good scan if necessary))
- Spend enough time on exercise sheets and writeup (you and I have to understand your submission).

### Algorithm Writeups

- Pseudocode, limit to important aspects
- Reader must be able to understand and implement it.
- E.g "Split Array A in two evenly-sized halves L and R"

### Shortest Triangle in 2D

- Extend lecture algorithm to triangles
- Complete writeup or only state differences (both is possible)
- Important: what are the pre- and postconditions of recursive algorithms
- Important: Why can we do stuff in a certain runtime

## Shortest Triangle in 2D

- Function MinTriangle(P)
  - Return the smallest triangle size
  - Arguments: List of points P
  - Requires / Precondition: P sorted in x-direction
  - Ensures / Postcondition : P sorted in y-direction
- if  $|P| \leq \text{THRESHOLD}$ :
  - Sort P by y-coordinate (constant)
  - Compute Triangle trivially by  $n^3$  computation on constant input

- if |P| > THRESHOLD:
  - Split P in middle according to x-coordinate (it is sorted!)
  - Recurse on  $P_I$  and  $P_r$
  - (We now know the size *d* of smallest triangle that is completely on one of the two sides)
  - Find all Points closer than d to the border.
  - Build Boxes of size d × d like in lecture and find triangles in boxes.
    (Only constant number of points in each box, exactly the same as in the lecture).
  - Merge  $P_I$  and  $P_r$  according to y-coordinate
  - (P is now sorted by y-coordinate,  $P_I$  and  $P_r$  were sorted by postcondition of recursive call).
  - Return the smallest triangle.