

$\Rightarrow$  2021 PCS 1017  
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①.  $\rightarrow$  eq. n.  $\rightarrow$

$$2x_1 + x_2 + x_3 = 1$$

$$2x_1 + ax_2 + ax_3 = -1$$

$$-2x_1 + x_2 + x_3 = b$$

converting into matrix  $\rightarrow$

$$\begin{bmatrix} 2 & 1 & 1 \\ 2 & 2 & a \\ -2 & 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ b \end{bmatrix} \Leftrightarrow AX = b$$

Augmented matrix  $\rightarrow$

$$[A|b]$$

$$\rightarrow \begin{bmatrix} 2 & 1 & 1 & | & 1 \\ 2 & 2 & a & | & -1 \\ -2 & 1 & 1 & | & b \end{bmatrix}$$

$$\begin{array}{l} R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 + R_1 \end{array}$$

$$\begin{bmatrix} 2 & 1 & 1 & | & 1 \\ 0 & 1 & a-1 & | & -2 \\ 0 & 2 & 2 & | & b+1 \end{bmatrix}$$

$$\begin{array}{l} R_3 \rightarrow R_3 - 2*R_2 \\ \rightarrow \end{array} \begin{bmatrix} 2 & 1 & 1 & | & 1 \\ 0 & 1 & a-1 & | & -2 \\ 0 & 0 & 4-2a & | & b+5 \end{bmatrix}$$

$$\downarrow R_1 \rightarrow \frac{1}{2} * R_1$$

$$\begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{2} & | & \frac{1}{2} \\ 0 & 1 & a-1 & | & -2 \\ 0 & 0 & 4-2a & | & b+5 \end{bmatrix}$$

②.

$\rightarrow$  for this system to not have any sol.<sup>n.</sup>; pivot element should exist in last col.<sup>n.</sup> for this to happen  $\rightarrow$

$$\rightarrow 4-2a=0 \Rightarrow a=2$$

$$\text{&} b+5 \neq 0 \Rightarrow b \neq -5 \rightarrow \text{for No. sol.} \rightarrow \{a=2, b \neq -5\}$$

{REF-form}.

(b)  $\rightarrow$  for unique sol<sup>m</sup>. to exist  $\rightarrow$

$$4-2a \neq 0$$

$$\boxed{a \neq 2} =$$

calculating sol<sup>m</sup>.

$$(4-2a) \cdot x_3 = (b+5) \Rightarrow \boxed{x_3 = \frac{(b+5)}{(4-2a)}}$$

and  $\rightarrow$

$$x_2 + (a-1) \cdot x_3 = -2$$

$$x_2 = -2 - (a-1) \cdot \frac{(b+5)}{2(2-a)}$$

$$x_2 = -2 + \frac{(a-1)(b+5)}{2(a-2)}$$

$$x_2 = \frac{4a-8+ab+5a-b-5}{2(a-2)}$$

$$\boxed{x_2 = \frac{ab+9a-b-13}{2(a-2)}}$$

and  $\rightarrow$

$$x_1 + \frac{1}{2}x_2 + \frac{1}{2}x_3 = \frac{1}{2}$$

$$x_1 = \frac{1}{2} - \frac{1}{2}(x_2 + x_3) = \frac{1}{2} \left\{ 1 - x_2 - x_3 \right\}$$

$$x_1 = \frac{1}{2} \left\{ 1 - \frac{ab+9a-b-13}{2(a-2)} + \frac{(b+5)}{2(a-2)} \right\}$$

$$x_1 = \frac{1}{2} \left\{ \frac{2a-4-ab-9a+b+13+b+5}{2(a-2)} \right\}$$

$$\boxed{x_1 = \frac{1}{2} \left\{ \frac{-7a+2b+14-ab}{2(a-2)} \right\}}$$

unique sol<sup>m</sup>.  $\{x_1, x_2, x_3\}$  as solved above

①.  $\rightarrow$  To have infinitely many sol.  $\rightarrow$

$$4-2a=0 \Rightarrow a=2$$

$$\text{and} \rightarrow b+5=0 \Rightarrow b=-5$$

so  $\rightarrow$

$$[A|b] \Rightarrow \left[ \begin{array}{ccc|c} 1 & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ 0 & 1 & -1 & -2 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\text{let } x_3 = k,$$

$$\text{so } x_2 + x_3 = -2$$

$$x_2 = (-2 - k)$$

$$\text{and} \rightarrow x_1 + \frac{1}{2}x_2 + \frac{1}{2}x_3 = \frac{1}{2}$$

$$x_1 = \frac{1}{2} \{ 1 - x_2 - x_3 \} = \frac{1}{2} \{ 1 + 2 + k - k \}$$

$$x_1 = \frac{3}{2}$$

so, sol.  $\rightarrow$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \frac{3}{2} \\ -2 - k \\ k \end{bmatrix} \Rightarrow \begin{bmatrix} \frac{3}{2} \\ -2 \\ 0 \end{bmatrix} + k \cdot \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}; k \in \mathbb{R}$$

②.  $\rightarrow$  for homogeneous in above case  $\rightarrow$

$$A = \left[ \begin{array}{ccc} 1 & \frac{1}{2} & \frac{1}{2} \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{array} \right]$$

We'll cal.  $\text{NULL}(A) \rightarrow$

bcoz  $A\vec{x}=0$ ; then  $\vec{x} \in N(A)$

$$\Rightarrow x_2 + x_3 = 0$$

$$x_2 = -k$$

$$\text{and} \rightarrow x_1 + \frac{1}{2}x_2 + \frac{1}{2}x_3 = 0$$

$$x_1 - \frac{k}{2} + \frac{k}{2} = 0$$

$$x_1 = 0$$

$$\text{let } x_3 = Q$$

$$\text{So } \rightarrow \text{ sol. n. set} \rightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ -Q \\ Q \end{bmatrix} \Rightarrow Q \cdot \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

$$\text{for } Q=L \rightarrow \Rightarrow \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

$$\text{So } \rightarrow \text{ Basis of } N(A) \rightarrow \left\{ \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \right\} = \boxed{\text{Answer}}.$$

Ques (2)  $\rightarrow$

$$A = \begin{bmatrix} 1 & -1 & 0 \\ 2 & 1 & a \\ -2 & 1 & 3 \end{bmatrix}; \text{ Since it is invertible so, all col's should have pivots.}$$

$$\begin{array}{l} R_2 \rightarrow R_2 - 2 * R_1 \\ R_3 \rightarrow R_3 + 2 * R_1 \end{array}$$

$$\begin{bmatrix} 1 & -1 & 0 \\ 0 & 3 & a \\ 0 & -1 & 3 \end{bmatrix}$$

$$R_2 \rightarrow \frac{1}{3} * R_2$$

$$\begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & \frac{a}{3} \\ 0 & -1 & 3 \end{bmatrix}$$

$$R_3 \rightarrow R_3 + R_2$$

$$\begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & \frac{a}{3} \\ 0 & 0 & 3 + \frac{a}{3} \end{bmatrix}$$

so, even Ref form should have pivots in all col's as well.  $\text{So } \rightarrow 3 + \frac{a}{3} \neq 0 \Rightarrow \frac{a}{3} \neq -3$

$$\boxed{a \neq -9} = \boxed{\text{Answer}}$$

Now to find 3<sup>rd</sup> col. of inverse  $\rightarrow$

$$\begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix} \cdot \begin{bmatrix} \vec{e}_3 \\ A^{-1} \end{bmatrix} = \begin{bmatrix} \vec{e}_3 \\ I \end{bmatrix}$$

So  $\rightarrow$   $A \cdot \vec{u}_3 = \vec{e}_3$ , let  $\vec{u}_3 = \{u_1, u_2, u_3\}$

So  $\rightarrow$

$$\begin{bmatrix} 1 & -1 & 0 \\ 2 & 1 & a \\ -2 & 1 & 3 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

augmented mat  $\rightarrow$

$$\left[ \begin{array}{ccc|c} 1 & -1 & 0 & 0 \\ 2 & 1 & a & 0 \\ -2 & 1 & 3 & 1 \end{array} \right]$$

$$\begin{aligned} R_2 &\rightarrow R_2 - 2 \cdot R_1 \\ R_3 &\rightarrow R_3 + 2 \cdot R_1 \end{aligned}$$

$$\left[ \begin{array}{ccc|c} 1 & -1 & 0 & 0 \\ 0 & 3 & a & 0 \\ 0 & -1 & 3 & 1 \end{array} \right]$$

$$R_2 \rightarrow \frac{1}{3} \cdot R_2$$

$$\left[ \begin{array}{ccc|c} 1 & -1 & 0 & 0 \\ 0 & 1 & \frac{a}{3} & 0 \\ 0 & -1 & 3 & 1 \end{array} \right]$$

$$R_3 \rightarrow R_3 + R_2$$

$$\left[ \begin{array}{ccc|c} 1 & -1 & 0 & 0 \\ 0 & 1 & \frac{a}{3} & 0 \\ 0 & 0 & 3 + \frac{a}{3} & 1 \end{array} \right]$$

$$\text{So } \rightarrow (3 + \frac{g}{3}) \cdot x_3 = 1$$

$$x_3 = \frac{3}{9+g}$$

$$\xrightarrow{2} x_2 + \frac{g}{3} \cdot x_3 = 0$$

$$x_2 = -\frac{g}{3} \cdot \frac{x_3}{a+g} \Rightarrow$$

$$x_2 = \left( -\frac{g}{a+g} \right)$$

3 →

$$x_1 - x_2 = 0$$

$$x_1 = x_2 = \frac{-g}{a+g}$$

So → 3<sup>rd</sup> col. of A →

$$\begin{bmatrix} \left( -\frac{g}{a+g} \right) \\ \left( -\frac{g}{a+g} \right) \\ \left( \frac{3}{a+g} \right) \end{bmatrix}$$

Ques. 6 →  $A = a \cdot \begin{bmatrix} 1 & -2 & 2 \\ -2 & 4 & -4 \\ 2 & -4 & 4 \end{bmatrix} \Rightarrow \text{Symmetric matrix.}$

$$[A - \lambda I] = \begin{bmatrix} a - \lambda & -2a & 2a \\ -2a & 4a - \lambda & -4a \\ 2a & -4a & 4a - \lambda \end{bmatrix}$$

$$\det(A - \lambda I) = 0$$

$$(a - \lambda) \{ (4a - \lambda)^2 - 16a^2 \} + 2a \cdot \{ -8a^2 + 2a\lambda + 8a^2 \} + 2a \cdot \{ 8a^2 - 8a^2 + 2a\lambda \} = 0$$

$$(a - \lambda) \cdot \{ 16a^2 + \lambda^2 - 8a\lambda - 16a^2 \} + 4a^2\lambda + 4a^2\lambda = 0$$

$$(a-\lambda) \cdot (\lambda^2 - 8a\lambda) + 8a^2\lambda = 0$$

$$a\lambda^2 - 8a^2\lambda - \lambda^3 + 8a\lambda^2 + 8a^2\lambda = 0$$

$$\lambda^3 - 9a\lambda^2 = 0$$

$$\boxed{\lambda^2(\lambda - 9a) = 0}$$

$$\boxed{\lambda = 0, 0, 9a}$$

E.V. corresponding to  $\lambda = 9a \rightarrow$

$$(A - \lambda I) \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -8a & -2a & 2a \\ -2a & -5a & -4a \\ 2a & -4a & -5a \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} -8a & -2a & 2a \\ -2a & -5a & -4a \\ 0 & -9a & -9a \end{bmatrix} \quad \downarrow R_3 \rightarrow R_3 + R_2$$

$$\downarrow R_1 \rightarrow \frac{1}{4} \times R_1$$

$$\begin{bmatrix} -2a & -\frac{a}{2} & \frac{a}{2} \\ -2a & -5a & -4a \\ 0 & -9a & -9a \end{bmatrix}$$

$$\downarrow R_2 \rightarrow R_2 - R_1$$

$$\begin{bmatrix} -2a & -\frac{a}{2} & \frac{a}{2} \\ 0 & -9\frac{a}{2} & -9\frac{a}{2} \\ 0 & -9a & -9a \end{bmatrix}$$

$$\downarrow R_3 \rightarrow R_3 - 2 \times R_2$$

$$\begin{bmatrix} -2a & -\frac{a}{2} & \frac{a}{2} \\ 0 & -9\frac{a}{2} & -9\frac{a}{2} \\ 0 & 0 & 0 \end{bmatrix}$$

let  $x_3 = k$ :

$$\left(-\frac{9a}{2}\right)x_2 - \left(\frac{9a}{2}\right)x_3 = 0$$

$$-\left(\frac{9a}{2}\right) \cdot x_2 = x_3 \cdot \left(\frac{9a}{2}\right)$$

$$x_2 = (-k)$$

$$\text{and } (-2a)x_1 - \frac{a}{2}x_2 + \frac{a}{2}x_3 = 0$$

$$-2x_1 + \frac{k}{2} + \frac{k}{2} = 0$$

$$x_1 = k/2$$

and →

$$(-2a)x_1 - \frac{a}{2}x_2 - k = 0 \quad \text{and } k = 0$$

so →

E.V. ⇒

$$\begin{bmatrix} 0 \\ -k \\ k \end{bmatrix}$$

$$\text{so, for } k \neq 0$$

$$\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

so → E.V. for  $k=1$

$$\begin{bmatrix} 1/2 \\ -1 \\ 1 \end{bmatrix}$$

so, Normal

$$\text{E.V.} \Rightarrow \begin{bmatrix} 1/3 \\ -2/3 \\ 2/3 \end{bmatrix}$$

orthonormal

$$\begin{bmatrix} 0 \\ 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$

for  $\lambda=0$

$$(A - \lambda I) \cdot x = 0$$

$$\begin{bmatrix} a & -2a & 2a \\ -2a & 4a & -4a \\ 2a & -4a & 4a \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{aligned} R_2 &\rightarrow R_2 + 2R_1 \\ R_3 &\rightarrow R_3 - 2R_1 \end{aligned}$$

$$\begin{bmatrix} a & -2a & 2a \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\text{let } x_1 = P \quad \text{and } x_3 = Q;$$

$$\text{so } ax_1 + (-2a)x_2 + (2a)x_3 = 0$$

$$u_1 - 2P + \alpha Q = 0$$

$$\boxed{u_1 = \alpha P - \alpha Q}$$

for  $(P, Q) = (1, 0)$   $\rightarrow$

sol. n.  $\rightarrow$

$$\begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} \Rightarrow \frac{\text{Normal}}{\|E\|} \Rightarrow \begin{bmatrix} 2/\sqrt{5} \\ 1/\sqrt{5} \\ 0 \end{bmatrix}$$

& for  $(P, Q) = (0, 1)$   $\rightarrow$

sol. n.  $\rightarrow$

$$\begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \Rightarrow \frac{\text{Normal}}{\|E\|} \Rightarrow \begin{bmatrix} -2/\sqrt{5} \\ 0 \\ 1/\sqrt{5} \end{bmatrix}$$

→ Both of them are not orthogonal to each other

so, applying gram-schmidt  $\rightarrow$

$$u_1 = \frac{v_1}{\|v_1\|} \Rightarrow u_1 =$$

$$\begin{bmatrix} 2/\sqrt{5} \\ 1/\sqrt{5} \\ 0 \end{bmatrix}$$

$$u_2 = v_2 - \langle v_2, u_1 \rangle \cdot u_1 \Rightarrow$$

$$\begin{bmatrix} -2/\sqrt{5} \\ 0 \\ 1/\sqrt{5} \end{bmatrix} + \frac{4}{5} \cdot \begin{bmatrix} 2/\sqrt{5} \\ 1/\sqrt{5} \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} -\frac{2}{5\sqrt{5}} \\ \frac{4}{5\sqrt{5}} \\ \frac{1}{\sqrt{5}} \end{bmatrix}$$

So  $\rightarrow$

$$\begin{bmatrix} 2/\sqrt{5} \\ 1/\sqrt{5} \\ 0 \end{bmatrix} + \begin{bmatrix} -\frac{2}{5\sqrt{5}} \\ \frac{4}{5\sqrt{5}} \\ \frac{1}{\sqrt{5}} \end{bmatrix}$$

$$\begin{bmatrix} -\frac{2}{5\sqrt{5}} \\ \frac{4}{5\sqrt{5}} \\ \frac{1}{\sqrt{5}} \end{bmatrix}$$

Answer → next page.

$$\text{So } P = \begin{bmatrix} \frac{1}{3} & \frac{2\sqrt{5}}{5} & -\frac{2}{5\sqrt{5}} \\ -\frac{2}{3} & \frac{1}{5\sqrt{5}} & \frac{4}{5\sqrt{5}} \\ \frac{2}{3} & 0 & \frac{1}{\sqrt{5}} \end{bmatrix}$$

Que ④  $\rightarrow$  ①  $\rightarrow$  [True], since A is matrix of quadratic form,  
we can say that A is symmetric  $\Rightarrow$   
so, using spectral decomposition  $\rightarrow$

$$A = P D P^T$$

$\hookrightarrow$  we can write this as  $\rightarrow$

$$AP = PD$$

$\hookrightarrow$  since P is orthogonal.

②  $\rightarrow$  [false].

$$\text{R.H.S.} \rightarrow (A-B) \cdot (B-A)^T \cdot (A+B)$$

$$\Rightarrow A^2 + A \cdot B - B \cdot A - B^2$$

$$\Rightarrow (A^2 - B^2) + \underbrace{(AB - BA)}$$

not always equal to 0.

$\neq$  L.H.S.

~~Ques ③~~ ~~True~~ ~~False~~ ~~True~~ ~~False~~ ~~(ATA)~~ ~~(ATA)~~

③  $\rightarrow$  [True]. bcoz.  $ATA$  is a symm. matrix as  $(ATA)^T = ATA$   
and as we have studied during SVD, that  
all the eigen values of  $(ATA)$  will be positive, similarly here  
as well. So  $\rightarrow$  {pos definite}

④.  **True**  **false**  $\Rightarrow$   $\mathbf{U}$  is echelon form & there are only  $k$  zero rows.  $(m-k)$  diff. rows.  
 $\text{Dim.}(\text{Row space}) = (m-k)$

$$\text{Dim.}(\text{Null space}) = m - \text{Dim.}(\text{Rank})$$
$$\Rightarrow m - (m-k)$$
$$\Rightarrow k.$$

⑤.  **True.**  $\rightarrow$  since  $\text{Dim}(B) = \text{Dim}(B')$

$$\begin{aligned} & c_1(v_1 + v_2) + c_2(v_2 + v_3) + c_3(v_3 + v_4) + c_4(v_4 + v_1) \\ \text{Lin Comb: } & \Rightarrow v_1(c_1 + c_4) + v_2(c_1 + c_2) + v_3(c_2 + c_3) + v_4(c_3 + c_1) \\ \text{So } \rightarrow & \text{span}(B) = \text{span}(B') \end{aligned}$$

Thus, basis.

⑥.  **True**. Diagonalization is only possible when  $[AM = GM]$ .

⑦.  **True**. Using pythagoras theorem, if just one diff. that dir. of vector  $\vec{v}$  is reversed.

$$\text{So } \rightarrow \|u + (-v)\|^2 = \|u\|^2 + \|v\|^2 ; \text{ if } u \perp v$$

⑧.  **false**.  $\rightarrow$  only true if it is square matrix which means transforming from same dimensional space to same.

Ques 3  $\rightarrow$  To find the least squared sol.<sup>n</sup>; we need to minimize  $\|b - Ax\|^2$  distance

So  $\rightarrow$  if it is a consistent system then directly we can calc. particular sol.<sup>n</sup>

Q.W.  $\rightarrow$  minimize  $\{ \|b - Ax\|^2 ; x \in \mathbb{R}^n \}$ .

Suppose sol.<sup>n</sup> is  $\hat{x}$ . So  $\rightarrow$

$\min_m = \|b - A\hat{x}\|^2$ ; where  $A\hat{x} = \text{proj}_{\text{col}(A)}(b)$

To find  $x \rightarrow$  for  $AX=b$

if we write  $b = b_1 + b_2$ ; such that

$$b_1 \in \text{col.}(A)$$

$$b_2 \in N(A^T)$$

so, we can say, we want

$$A\hat{x} = b_1$$

$$\text{Now } \rightarrow b - b_1 = b_2$$

$$\text{So } \rightarrow b - A\hat{x} = b_2 \in N(A^T)$$

$$A^T(b - A\hat{x}) = A^T b_2 = 0$$

$$\text{So } \rightarrow A^T b = A^T A\hat{x}; \text{ this is Normal eq.}^m, \text{ using this, we can find } \hat{x}.$$

⑥  $\rightarrow$  True. Least squared sol<sup>m</sup> will be unique bcoz  
 $A^T A$  will be an invertible matrix.

Ques ③  $\rightarrow$  ①. Let  $\vec{v} = (v_1, v_2, v_3, \dots, v_n)$

$$\vec{u} = (u_1, u_2, u_3, \dots, u_n)$$

Now  $\rightarrow c_1 \vec{u} + c_2 \vec{v} = (c_1 u_1 + c_2 v_1, c_1 u_2 + c_2 v_2, \dots, c_1 u_n + c_2 v_n)$

$\xrightarrow{\text{So}} T(c_1 \vec{u} + c_2 \vec{v}) = (0, c_1 u_1 + c_2 v_1, c_1 u_2 + c_2 v_2, \dots, c_1 u_n + c_2 v_n)$

$$\Rightarrow (0, c_1 u_1, c_1 u_2, \dots, c_1 u_n) + (0, c_2 v_1, c_2 v_2, \dots, c_2 v_n)$$

$$\Rightarrow c_1 \cdot (0, u_1, u_2, \dots, u_n) + c_2 \cdot (0, v_1, v_2, \dots, v_n)$$

$$\Rightarrow c_1 \cdot T(\vec{u}) + c_2 \cdot T(\vec{v})$$

$\xrightarrow{\text{So}}$  T(c<sub>1</sub>  $\vec{u}$  + c<sub>2</sub>  $\vec{v}$ ) = c<sub>1</sub> · T( $\vec{u}$ ) + c<sub>2</sub> · T( $\vec{v}$ )

So, T is a linear transformation

⑦  $\rightarrow$  Logic  $\rightarrow$  in each transformation, one element from left is getting '0'. and values being shifted to right.

so  $\rightarrow$  point  $\rightarrow$  if we keep on applying ~~the~~ linear transformation on the result, then after

a certain point, all the values in the ~~vector~~ vector will be 0.

$$\text{So } T(\vec{v}) = \vec{u}$$

$$T(\vec{u}) = \vec{x}$$

after some point result  $\Rightarrow$  zero vector

$$\Rightarrow (\vec{0})$$

$$T^m(\vec{v}) = (\vec{0})$$

we can say that

$$A^m = 0$$

$$(T \cdot A)$$

Now  $\rightarrow$   $m = \text{Rank}(A)$ ; ~~bcz~~ it'll take these many steps to make  $A^m = 0$ .

[logic-wise]  $\rightarrow$

Ques ②  $\rightarrow$   $A, B$  are symmetric  $\Rightarrow$   $A^T = A$ ;

$$A^T = A$$

$$B^T = B$$

since we know that eigen values of  $(A+B)$  will be  $\rightarrow$  (eigen value of  $A$ ) + (eigen value of  $B$ )

$$\text{bcz} \rightarrow AX = \lambda_1 X$$

$$\& BX = \lambda_2 X$$

$$(A+B) \cdot X = (\lambda_1 + \lambda_2) \cdot X$$

so, eigen values of  $(A+B)$  will also be (-ve).