Sarthak Ahuja

CONTACT INFORMATION

Working remotely from Washington, WA

sarthakahuja.org sarthakahuja[at]outlook[dot]com

EDUCATION

Robotics Institute, Carnegie Mellon University, Pittsburgh

Master of Science, Robotics, GPA 4.24/4.33

Aug. 2018 - Aug. 2020

Courses: Computer Vision, Machine Learning, Visual Learning and Representation,

Planning for Robotics, Deep Reinforcement Learning

Indraprastha Institute of Information Technology, Delhi

Bachelor of Technology (Honors), Computer Science, GPA 9.1/10.0

Aug. 2012 - May 2016

EXPERIENCE

Machine Learning Engineer II, Amazon Alexa AI

Aug. 2020 onwards

Member of the Intelligent Decisions group and Dynamic Routing Science team building automated and scalable self-learning ML systems that predict and dynamically route user intents to appropriate Alexa actions.

Graduate Research Assistant, Robotics Institute

Oct. 2019 to Aug. 2020

Master's thesis research advised by Prof. Henny Admoni and Prof. Aaron Steinfeld. Worked on improving a robot's self-assessment capabilities - particularly reasoning about the effects of a robot's actions on the operating environment; learning vision-based physics intuition models that guide robots to conduct safe manipulation decisions.

Research Software Engineer, IBM Research India

July 2016 to July 2018

Member of the Collaborative AI team. Lead developer and researcher for IBM Watson Recruitment, a real-time data analytics platform that shortlists the most qualified candidates for a given job. Research focused in the domains of natural language processing (dynamic taxonomy generation and semantic similarity computation) and multi-agent systems (human behavior modeling in repeated social dilemmas).

Research Associate, PreCog Research Group, IIIT-Delhi

May 2016 to July 2016

Advised by Prof. Ponnurangam Kumaraguru. Developer on Project-O, Precog's social media analytics platform. Research focused in the domain of social systems and computer vision - particularly on patch-based visual summarization of social media events using discriminative learning.

Research Intern, Infosys Center for AI, IIIT-Delhi

May 2015 to July 2015

Core member of IIIT-Delhi's Autonomous Car Team - Swarath. Led a team of two, to design and develop the car's perception system; explored and deployed multiple SLAM algorithms for visual positioning and navigation using wearable and vehicle dashboard monocular cameras.

SELECTED PEER-REVIEWED PUBLICATIONS

- Newman, B*; Biswas, A*, **Ahuja, S.**, Admoni, H.; Examining the Effects of Anticipatory Robot Assistance on Human Decision Making, International Conference on Social Robotics (ICSR) 2020
- Ahuja, S., Admoni, H., Steinfeld, A.; Learning Vision-Based Physics Intuition Models for Non-Disruptive Object Extraction from Clutter, International Conference on Intelligent Robots and Systems (IROS) 2020
- Vallam, R., **Ahuja**, **S.**, Chaudhuri, R., Sajja, S., Pimplikar, R., Mukherjee, K., Parija, G.; Interactive POMDPs for Social Decision Making with Dynamic Focus on Agents, Proceedings of the International Conference on Autonomous Agents and Multi-Agent Systems (AAMAS) 2019 (pp. 674-682)
- Goel, S., **Ahuja, S.**, Subramanyam, A., Kumaraguru, P.; #VisualHashtags: Visual Summarization of Social Media Events Using Mid-Level Visual Elements, Proceedings of the ACM International Conference on Multimedia (ACMMM) 2017, (pp. 1434-1442)

PATENT APPLICATIONS

- Ahuja, S., Mukherjee, K., Mondal, J., Singh, S.; App-lause Automatic Audience Generation and Simulation for Immersive Rehearsals U.S. Patent No. 10970898 (2021)
- Ahuja, S., Singh, S., Parija, G., Chaudhuri, R., Kuchhal, M., Kataria, M.; SIdeal: System and Method for Attribute Weight Induction in a Multiple Recruiter Setting Exploiting Public Goods Games Framework, U.S. Patent Application No. 15/842,066 (pending)
- George, D., Mondal, J., Singh, S., **Ahuja, S.**, Medicke, J., Klabzuba, A.; System and Method to Produce Generalized Representation of Job Description Documents and Calculate Similarity Using the Representation in Recruitment Domain, U.S. Patent Application No. 15/854,837 (pending)

POSTER PRESENTATIONS

- Ahuja, S., Admoni, H., Steinfeld, A.; Learning Physics Intuition Models for Non-Disruptive Object Extraction from Clutter, Northeast Robotics Colloquium 2019, University of Pennsylvania

SELECTED PROJECTS

Informed Multi-Representation Multi-Heuristic A*

- Implemented an informed version of MRMHA* that uses past plans to control future state expansions; Used Conditional-VAEs to learn a sampling distribution (Ichter et al. ICRA 2018) over state expansions on subsets of the state-space to better schedule expansions from their corresponding queues.

Assistive Sketching and Animation Using Shape-Aware Moving Least Squares Deformations

- Developed an end-to-end sketching platform which assists an artist to draw complex non-convex 2D characters and dynamically animate them using a Kinect; Implemented drawing tools using bezier curves, distancetransform based skeletonization, and shape-aware deformations (Sharma et al. SA 2015).

Semi-Supervised Stance Detection in Tweets

- Implemented a heuristic-based semi-supervised learning approach, LDA2Vec (Moody CoNLL 2016) for stance detection that learns a coherent and informed embedding comparable to Para2Vec, concurrently bolstering interpretability of topics by creating representations similar to those in Latent Dirichlet Allocation.

Deep Learning Based Dynamic Taxonomy Generation

- Developed a semi-supervised learning approach for dynamically generating a large taxonomy over a large dataset of keywords; Proposed a novel LSTM based architecture that learns over random branches of a small seed taxonomy and uses the trained model to place unseen words under an appropriate parent word.

Speech-Based Distress Detection

- Created an android application that uses a two-stage contextual supervised learning algorithm (Sharma et al. TASLP 2015) to robustly detect speech based distress activity in urban spaces; Developed a web dashboard to monitor the generated alarms and mine for large-scale occurrence patterns in real-time data.

Multi-Agent Path Planning (MAPP) for Warehouse Butlers

- Hacked an implementation of Pacman to create a simulator with multiple robots trying to reach their resp. goals simultaneously. Implemented a Multi-Agent Path Planning Algorithm (Wang et al. ECAI 2010) and analyzed characteristic warehouse designs and how they affect the quality of the generated plans.

CoDrive: Crowd Sourced Memory Sharing

- Built a crowd-sourcing based android application to allow temporary sharing of phone memory space among peers easily and securely.

ACADEMIC SERVICE

- Reviewer, Conference on Information and Knowledge Management 2019
- Reviewer, International Conference on Robotics and Automation 2021
- Reviewer, International Conference on Intelligent Robots and Systems 2021
- Reviewer, IEEE Robotics and Automation Letters 2021

Workshops ATTENDED

International Institute of Information Technology, Hyderabad

July 2016

Summer School, Deep Learning in Computer Vision

SELECTED Honors and AWARDS

- Nominated for Best Student Paper at IROS 2020 for the paper "Learning Vision-Based Physics Intuition Models for Non-Disruptive Object Extraction from Clutter".
- Awarded the Graduate Student Conference Funding by the Graduate Student Assembly and the Provosts Office to present research at AAMAS 2019.
- J.N. Tata Scholar Awarded the J.N. Tata Scholarship 2019 for pursuing graduate studies at CMU.
- Runners-Up, Space Innovation Challenge 2018, CMU Tepper School of Business.
- Winning Team, Consensys Award at HackInOut 2017, for the developing "VoteChain Blockchains for Decentralized Elections".
- Awarded the IBM Manager's Choice Award 2016.
- Awarded the All Round Performance Medal for the overall performance in curricular and extracurricular activities in the B.Tech. (CSE) program 2016.
- First Prize in the Technical Paper Presentation event at Cogenesis 2016, Delhi Technological University for "Multi-Sensor Data Fusion for Human Activity Recognition".
- Best Demo Award in the Elevator Pitch Event at IIIT-Delhi Research Showcase 2015 for "Distress Detection".

TEACHING

Teaching Assistant

- 46-891: Mining Unstructured Data, CMU

Fall 2018

- CSE344/544: Computer Vision, IIIT-Delhi

Winter 2016

- CSE201: Advanced Programming, IIIT-Delhi

 ${\bf Monsoon}~2015$

- CSE102: Data Structures and Algorithms, IIIT-Delhi

Winter 2015

- CSE101: Introduction to Programming, IIIT-Delhi

Monsoon 2014

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EXPERIENCE