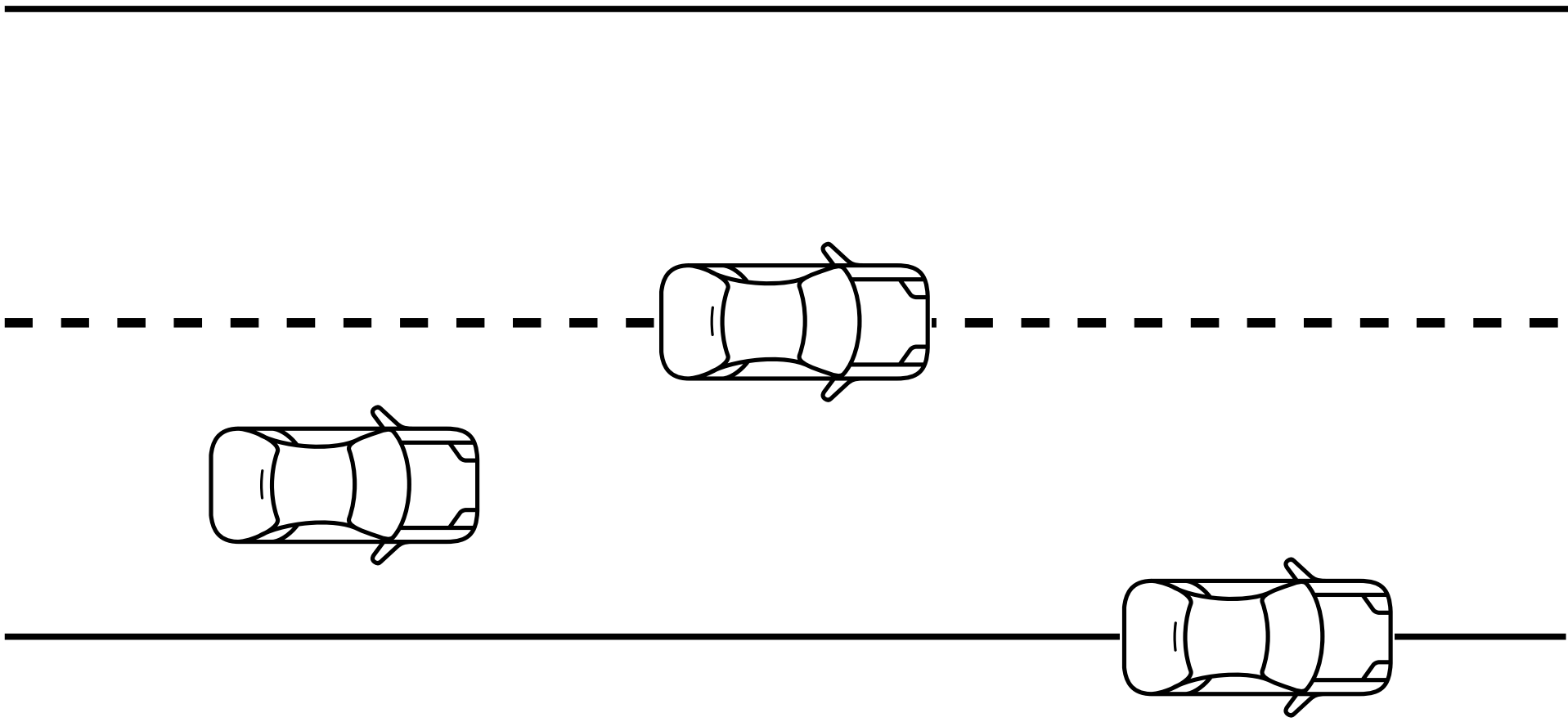


lane centeredness

0

+1

-1



yaw angle

45°

