

## The Relative Power of Synchronization Operations

lectures 11 & 12 (2025-04-14)

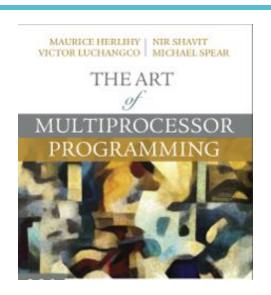
#### Master in Computer Science and Engineering

- Concurrency and Parallelism / 2024-25 -

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#### Outline

- Concurrent Objects
  - Correctness
  - Sequential Objects
  - Quiescent and Sequential Consistency
  - Linearizability
  - Progress Conditions



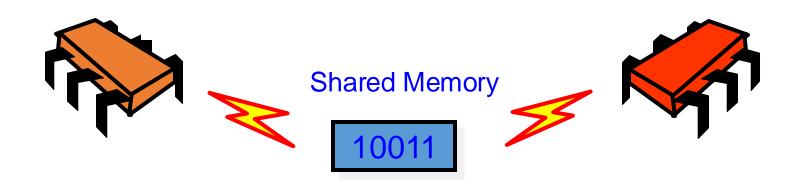
- Bibliography:
  - Chapters 5 of book

Herlihy M., Shavit N., Luchangco V., Spear M.; **The Art of Multiprocessor Programming**; Morgan Kaufmann (2020); ISBN: 978-0-12-415950-1

#### Last Lecture



#### Shared-Memory Computability?



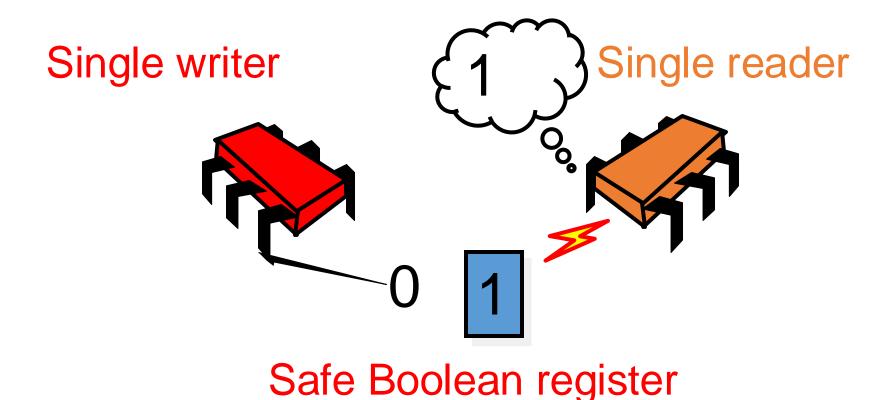
- Mathematical model of concurrent computation
- What is (and is not) concurrently computable
- Efficiency (mostly) irrelevant

### Wait-Free Implementation

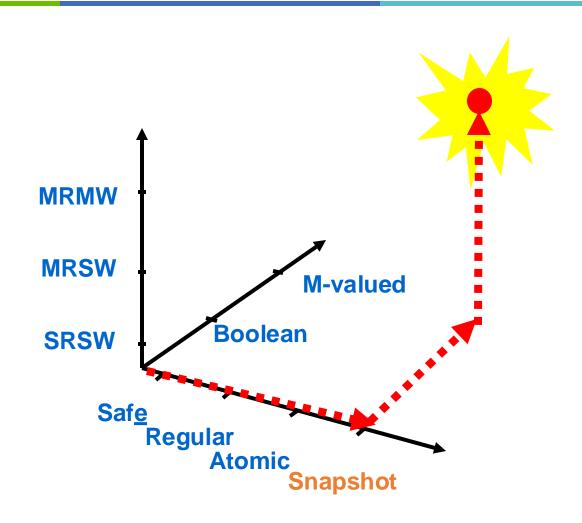
- Every method call completes in finite number of steps
- Implies no mutual exclusion



## From Weakest Register



## All the way to a Wait-free Implementation of Atomic Snapshots



#### Rationale for wait-freedom

 We wanted atomic registers to implement mutual exclusion

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- So we couldn't use mutual exclusion to implement atomic registers

#### Rationale for wait-freedom

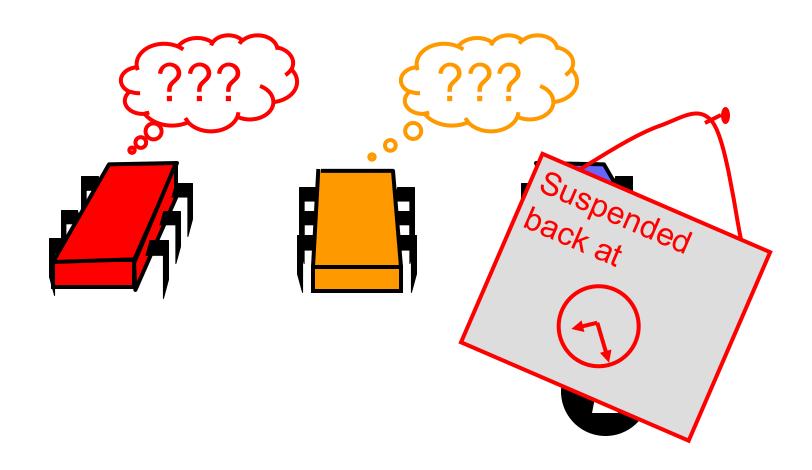
- We wanted atomic registers to implement mutual exclusion
- So we couldn't use mutual exclusion to implement atomic registers
- But wait, there's more!

#### This Lecture

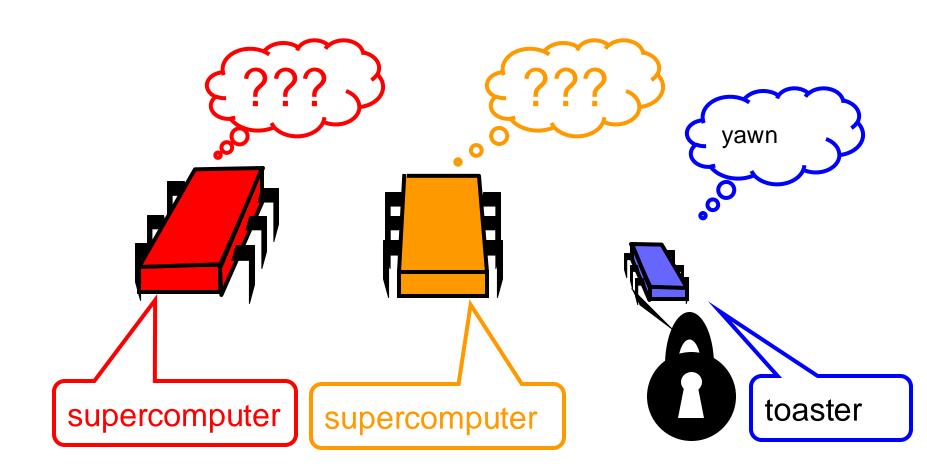


# Why is Mutual Exclusion so wrong?

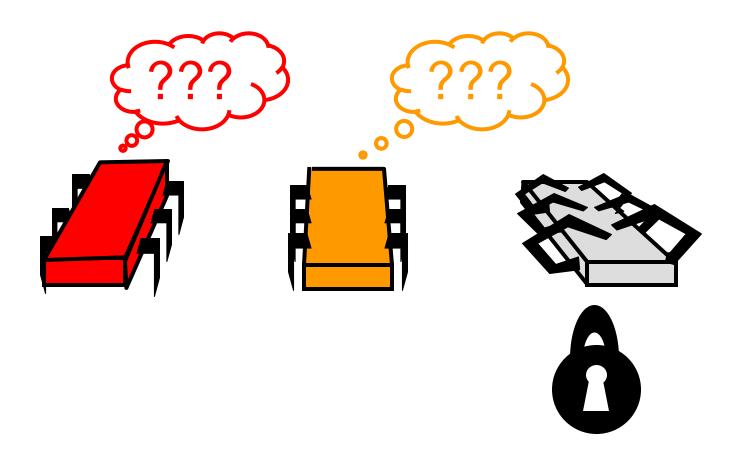
## Asynchronous Interrupts



## Heterogeneous Processors



#### Fault-tolerance



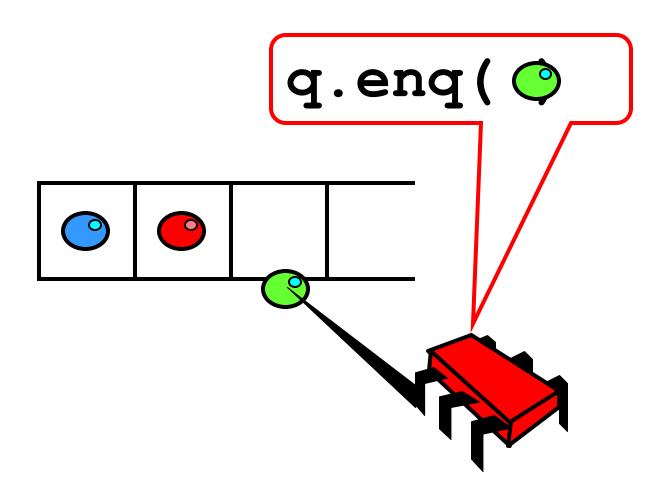
#### **Basic Questions**

 Wait-Free synchronization might be a good idea in principle

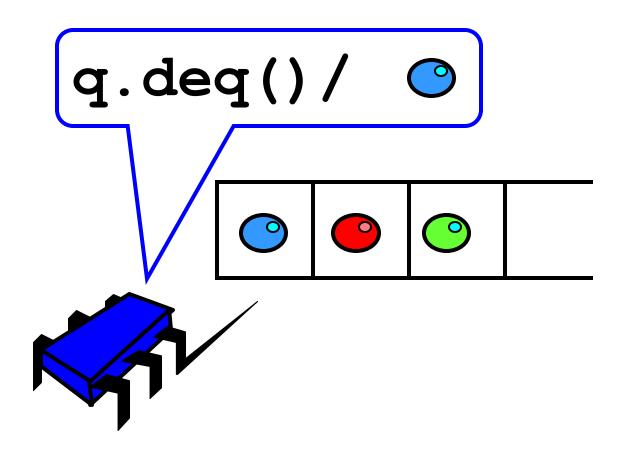
#### **Basic Questions**

- Wait-Free synchronization might be a good idea in principle
- But how do you do it ...
  - Systematically?
  - Correctly?
  - Efficiently?

#### FIFO Queue: Enqueue Method



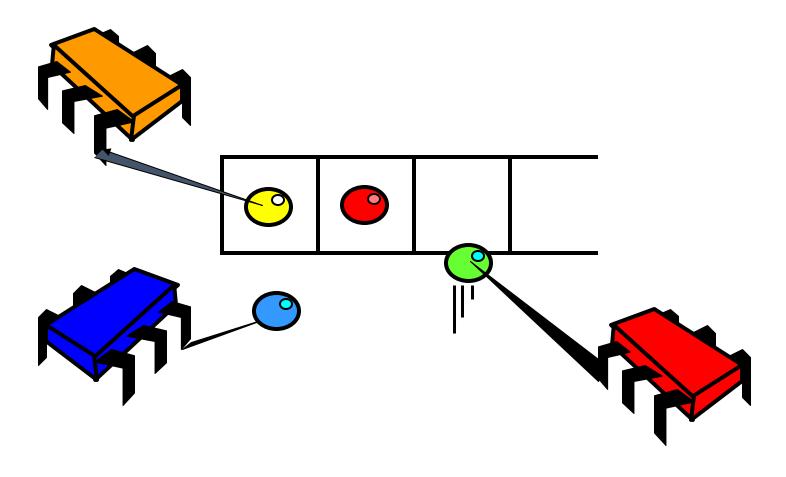
#### FIFO Queue: Dequeue Method



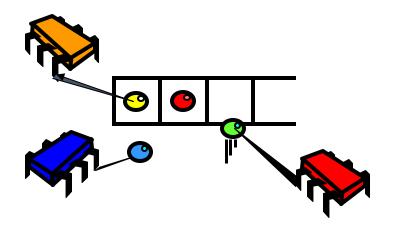
#### Two-Thread Wait-Free Queue

```
public class WaitFreeQueue {
                                   head
                                            tail
 int head = 0, tail = 0;
                                 capacity_
 Item[QSIZE] items;
 public void eng(Item x) {
  while (tail-head == QSIZE) {};
  items[tail % QSIZE] = x; tail++;
 public Item deq() {
  while (tail-head == 0) {}
  Item item = items[head % QSIZE];
  head++; return item;
} }
```

#### What About Multiple Dequeuers?



### Grand Challenge



Only new aspect

- Implement a FIFO queue
  - Wait-free
  - Linearizable
  - From atomic read—write registers
  - Multiple dequeuers

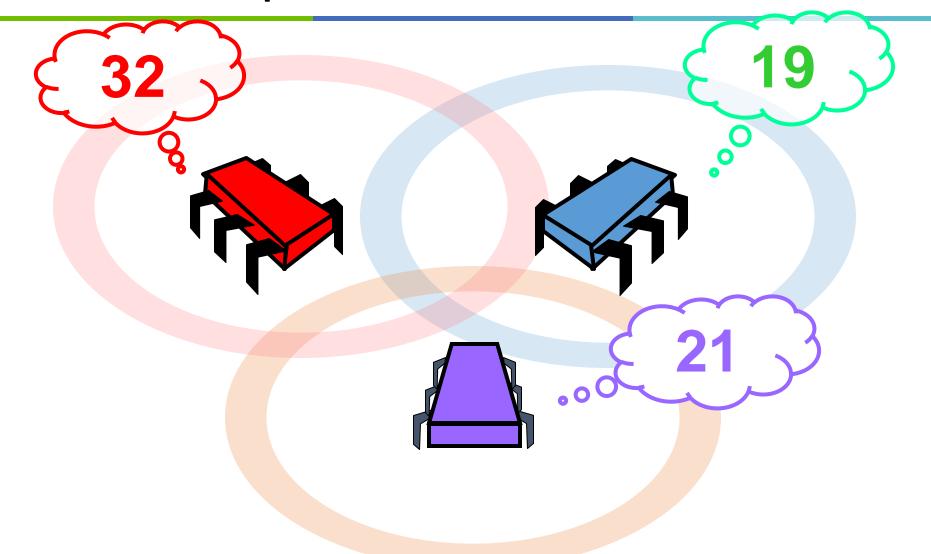
#### Puzzle

While you are ruminating on the grand challenge ...

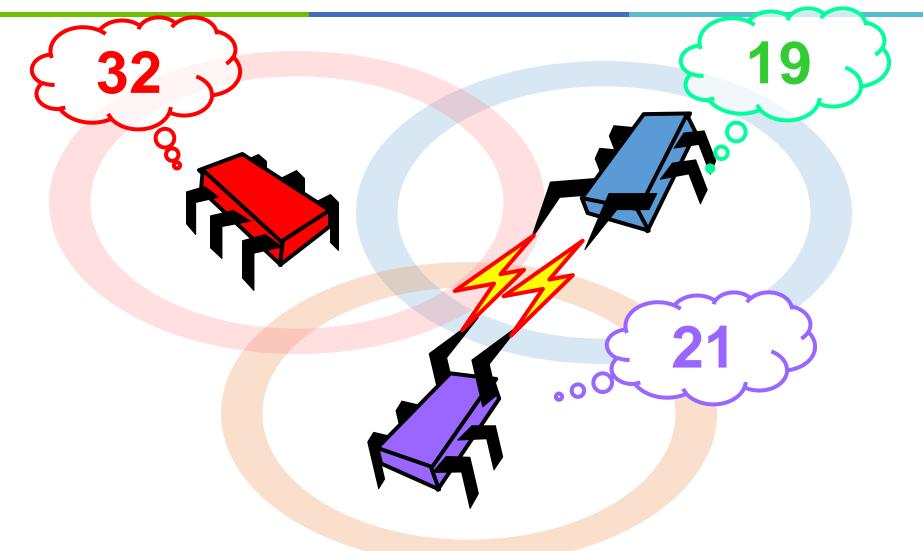
We will give you another puzzle ...

Consensus!

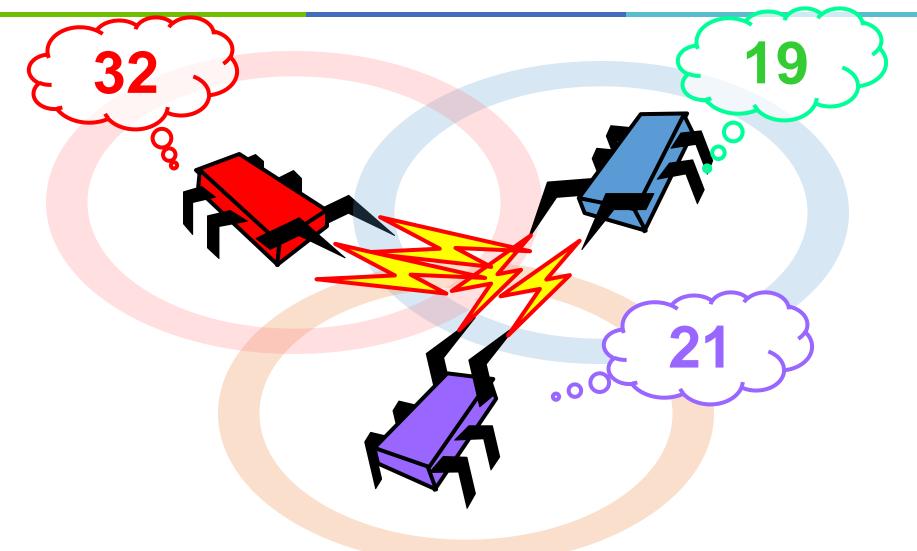
## Consensus: Each Thread has a Private Input



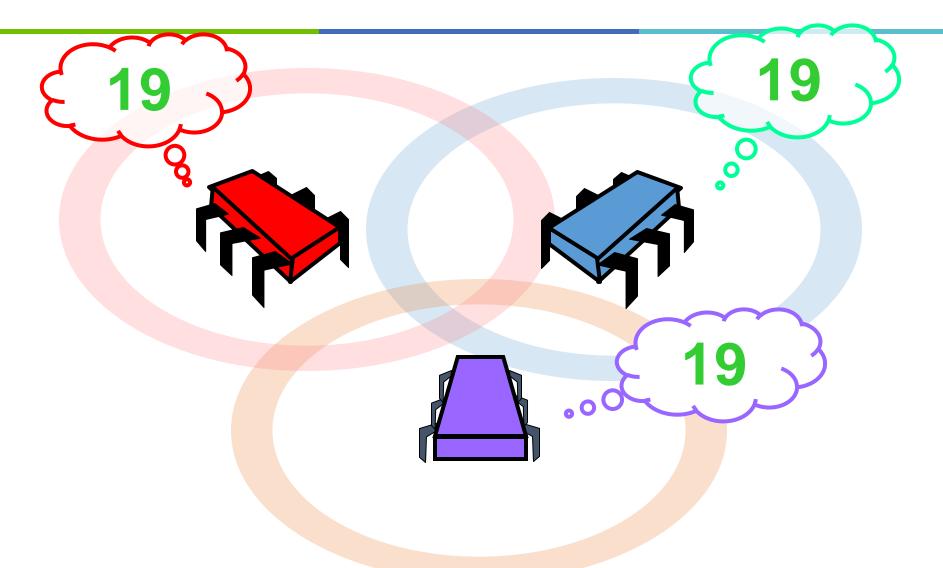
## They Communicate



## They Communicate



#### They Agree on One Thread's Input



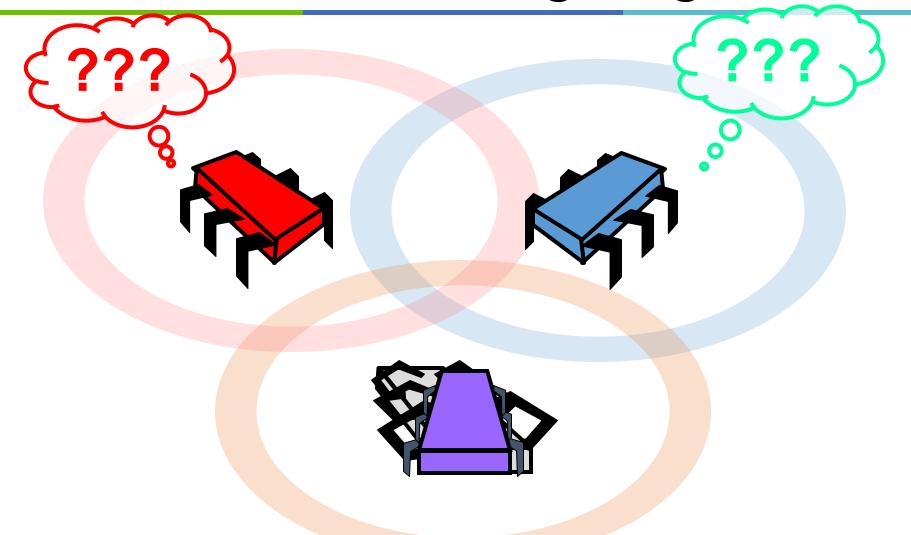
### Formally: Consensus

- Consistent:
  - all threads decide the same value

#### Formally: Consensus

- Consistent:
  - all threads decide the same value
- Valid:
  - the common decision value is some thread's input

## No Wait-Free Implementation of Consensus using Registers



## Formally

#### Theorem

 There is no wait-free implementation of n-thread consensus from read-write registers

## Formally

#### Theorem

 There is no wait-free implementation of n-thread consensus from read-write registers

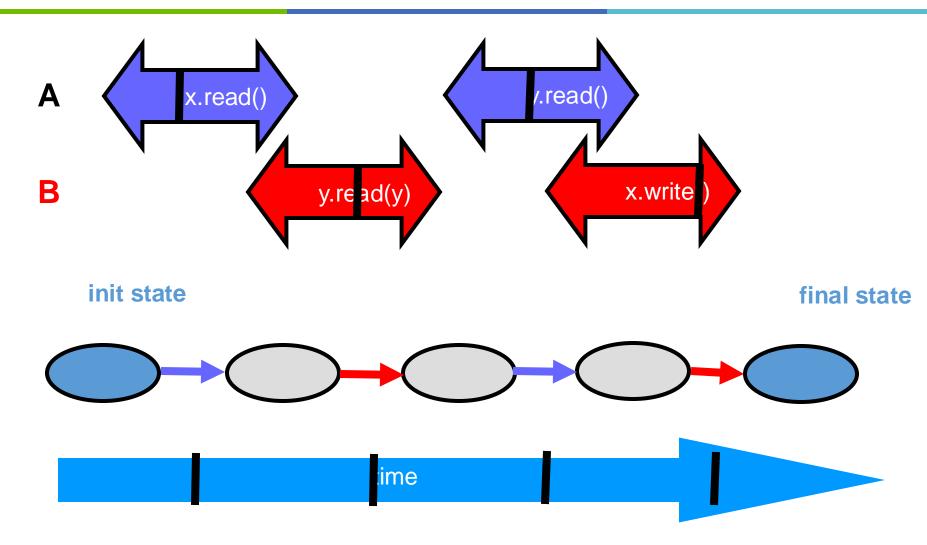
#### Implication

Asynchronous computability ≠ sequential (Turing) computability

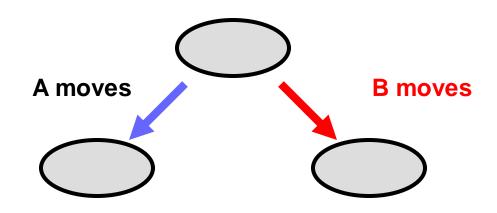
#### Proof

Read the book chapter 5

#### Protocol Histories as State Transitions

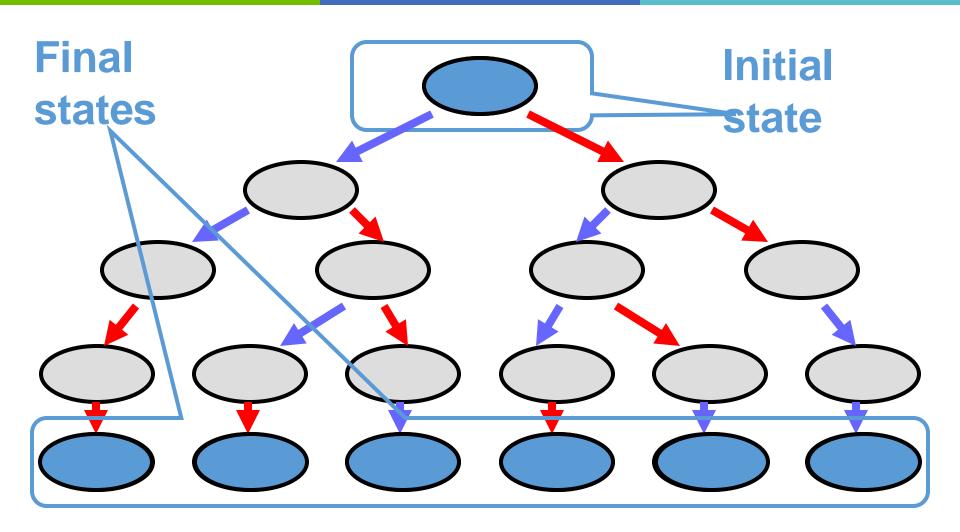


#### Wait-Free Computation

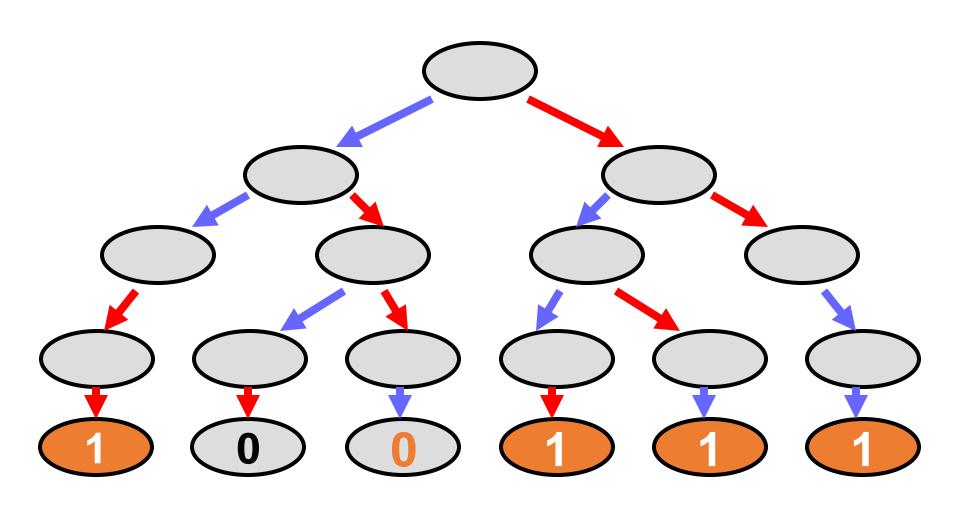


- Either A or B "moves"
- Moving means
  - Register read
  - Register write

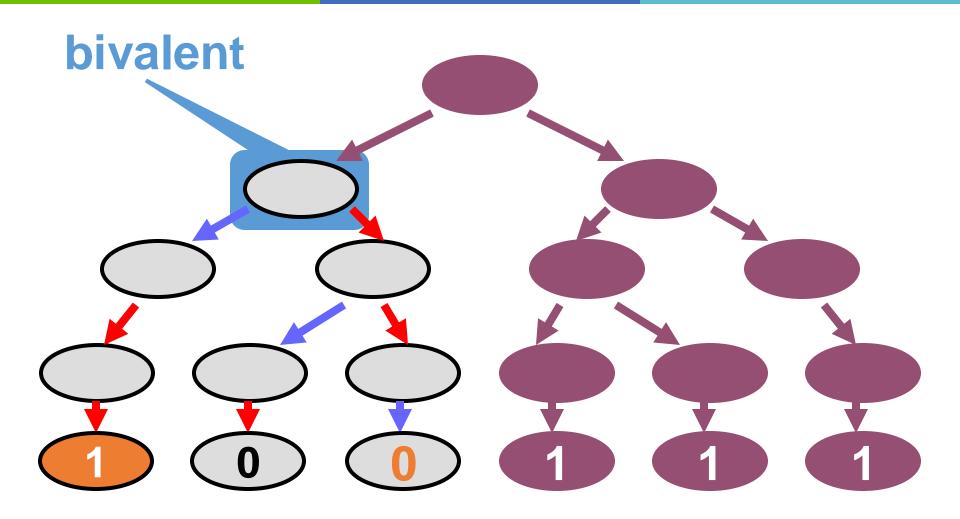
#### The Two-Move Tree



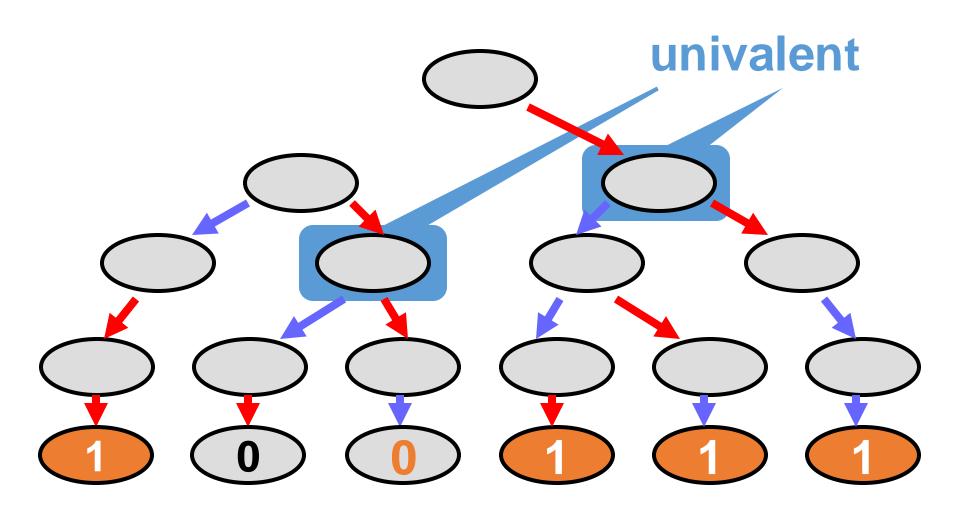
#### **Decision Values**



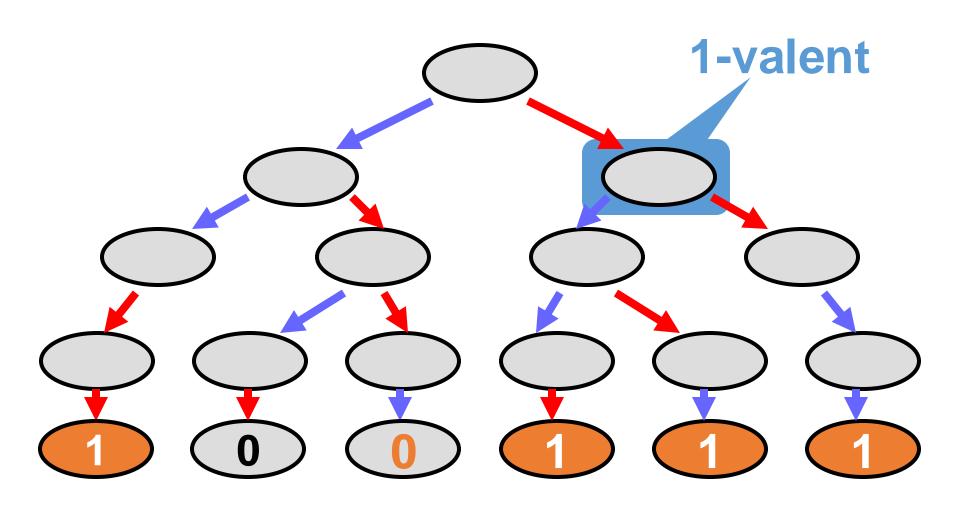
#### Bivalent: Both Possible



### Univalent: Single Value Possible



### x-valent: x Only Possible Decision



Wait-free computation is a tree

- Wait-free computation is a tree
- Bivalent system states
  - Outcome not fixed

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- Univalent states
  - Outcome is fixed
  - May not be "known" yet

- Wait-free computation is a tree
- Bivalent system states
  - Outcome not fixed
- Univalent states
  - Outcome is fixed
  - May not be "known" yet
- 1-Valent and 0-Valent states

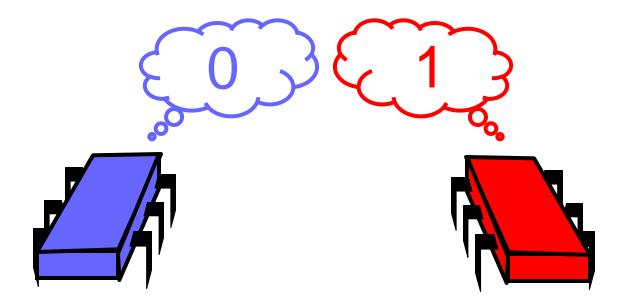
Some initial state is bivalent

- Some initial state is bivalent
- Outcome depends on
  - -Chance
  - -Whim of the scheduler

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- Multicore gods procrastinate ...

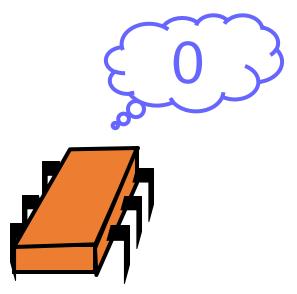
- Some initial state is bivalent
- Outcome depends on
  - -Chance
  - -Whim of the scheduler
- Multicore gods procrastinate ...
- Let's prove it ...

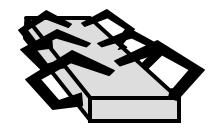
## What if inputs differ?



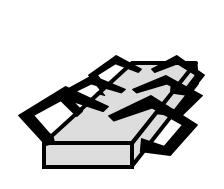
#### Must Decide 0

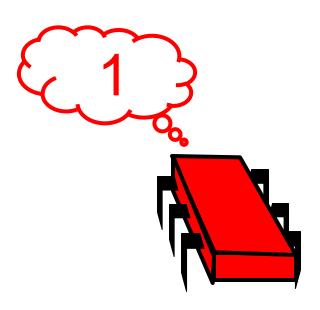
#### In this solo execution by A





#### Must Decide 1

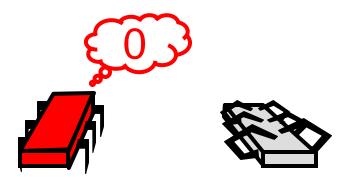




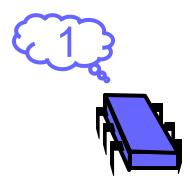
In this solo execution by B

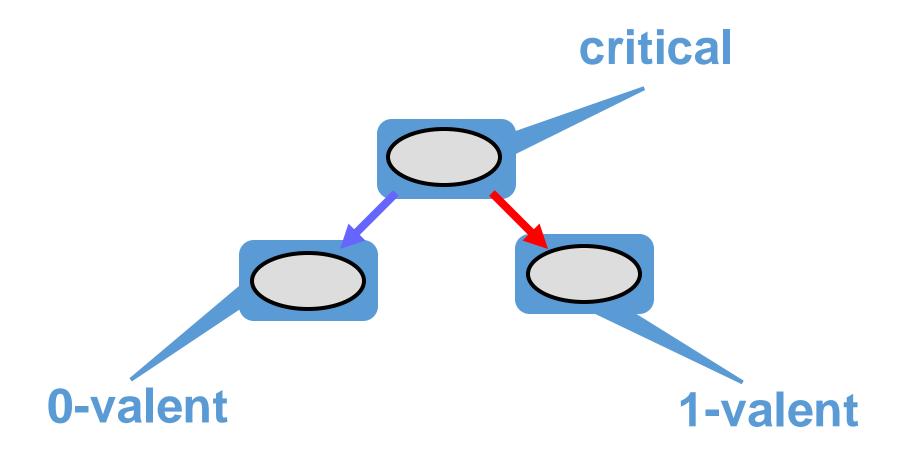
#### Mixed Initial State Bivalent

 Solo execution by A must decide 0  Solo execution by B must decide 1

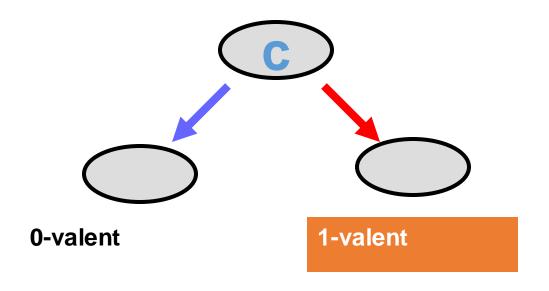








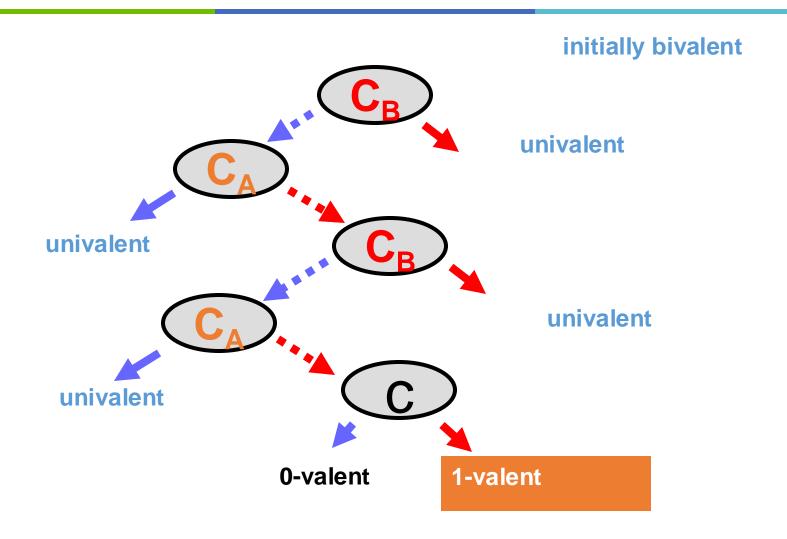
#### From a Critical State



If A goes first, protocol decides 0

If B goes first, protocol decides 1

### Reaching Critical State



• Starting from a bivalent initial state

- Starting from a bivalent initial state
- The protocol must reach a critical state

- Starting from a bivalent initial state
- The protocol must reach a critical state
  - Otherwise we could stay bivalent forever
  - And the protocol is not wait-free

### Model Dependency

- So far, memory-independent!
- True for
  - Registers
  - Message-passing
  - Carrier pigeons
  - Any kind of asynchronous computation

### Atomic Registers & Consensus

Atomic registers have consensus number 1

Start from a critical state

- Start from a critical state
- Each thread fixes outcome by
  - Reading or writing ...
  - Same or different registers

- Start from a critical state
- Each thread fixes outcome by
  - Reading or writing ...
  - Same or different registers
- Leading to a 0 or 1 decision ...

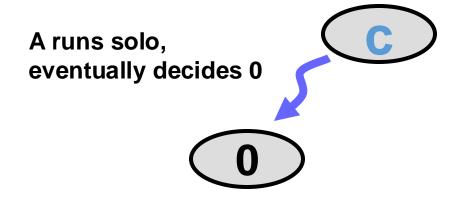
- Start from a critical state
- Each thread fixes outcome by
  - Reading or writing ...
  - Same or different registers
- Leading to a 0 or 1 decision ...
- And a contradiction.

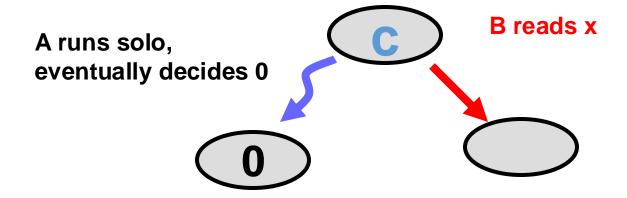
#### Possible Interactions

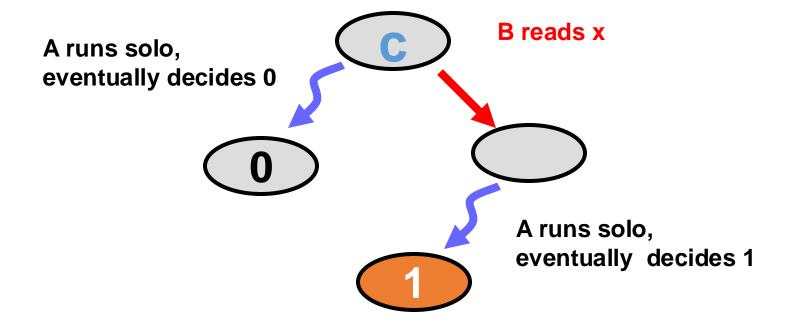
	A reads x			
	x.read()	y.read()	x.write()	A reads y y.write()
x.read()	?	?	?	?
y.read()	?	?	?	?
x.write()	?	?	?	?
y.write()	?	?	?	?

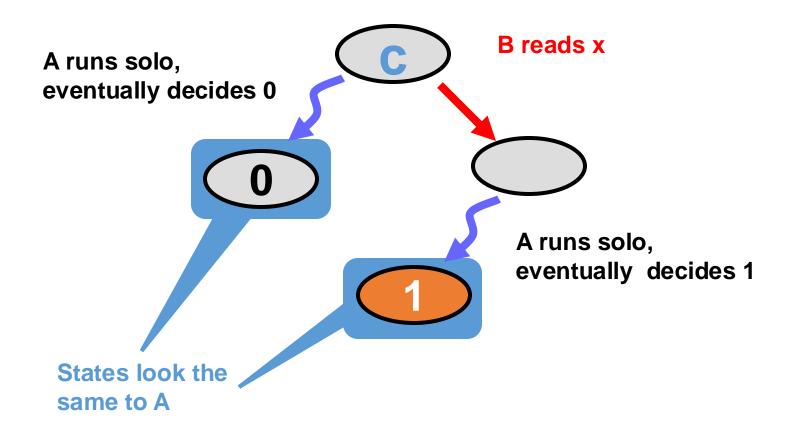
	x.read()	y.read()	x.write()	y.write()
x.read()	?.	?-	?	?
y.read()	?	?	?	?
x.write()	?	?	?	?
y.write()	?	?	?	?

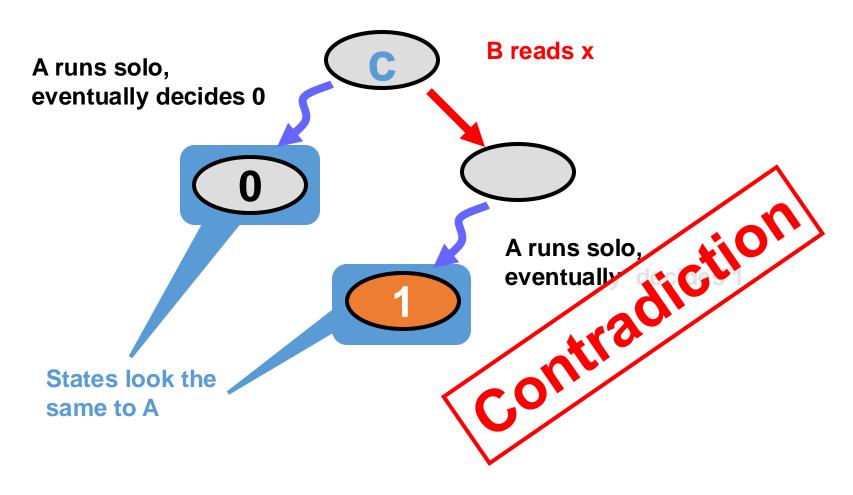










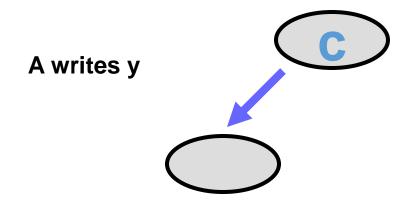


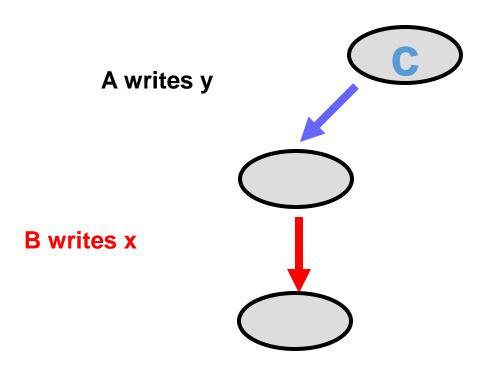
#### Possible Interactions

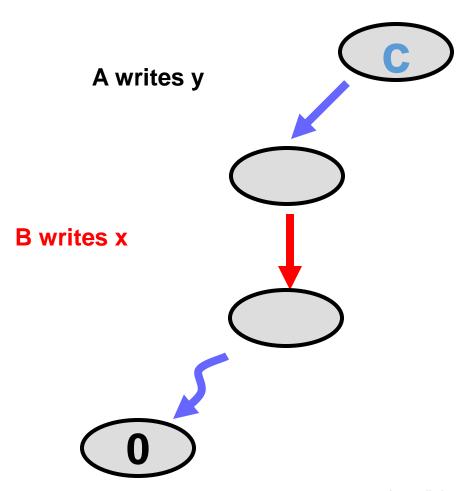
	x.read()	y.read()	x.write()	y.write()
x.read()	no	no	no	no
y.read()	no	no	no	no
x.write()	no	no	?	?
y.write()	no	no	?	?

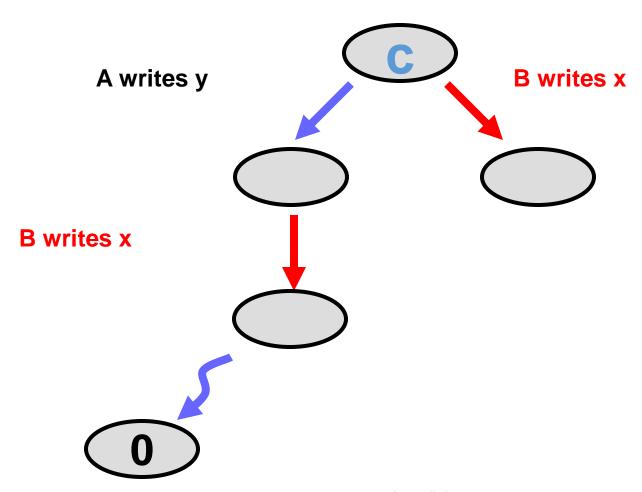
	x.read()	y.read()	x.write()	y.write()
x.read()	no	no	no	no
y.read()	no	no	no	no
x.write()	no	no	?	?
y.write()	no	no	?	?

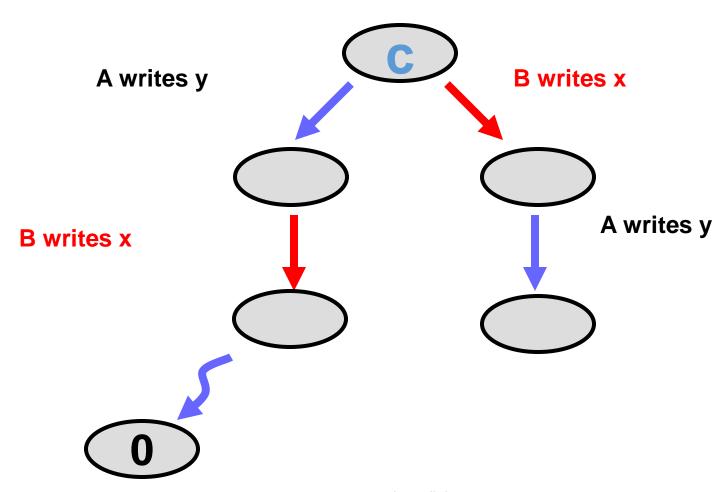


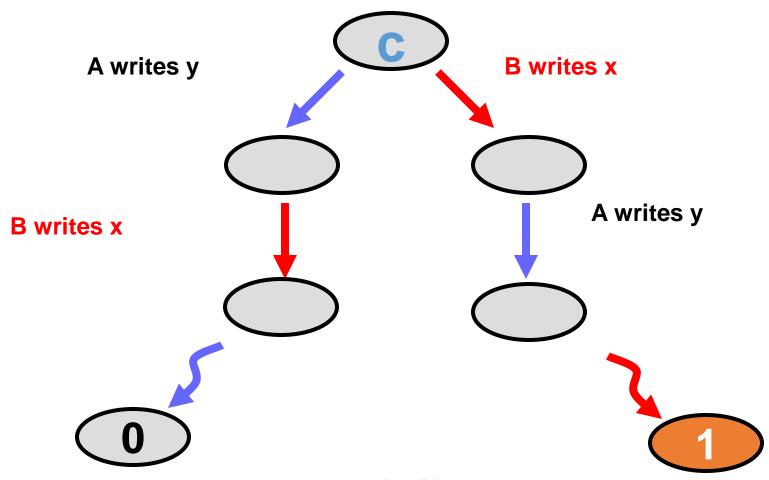


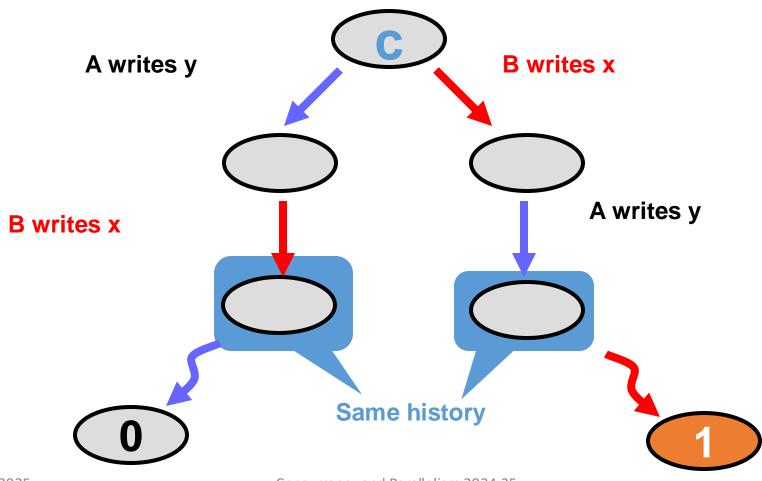


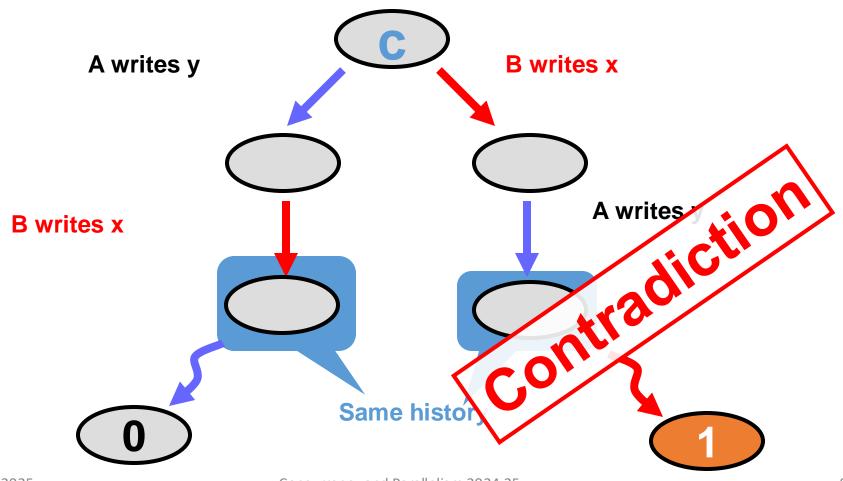












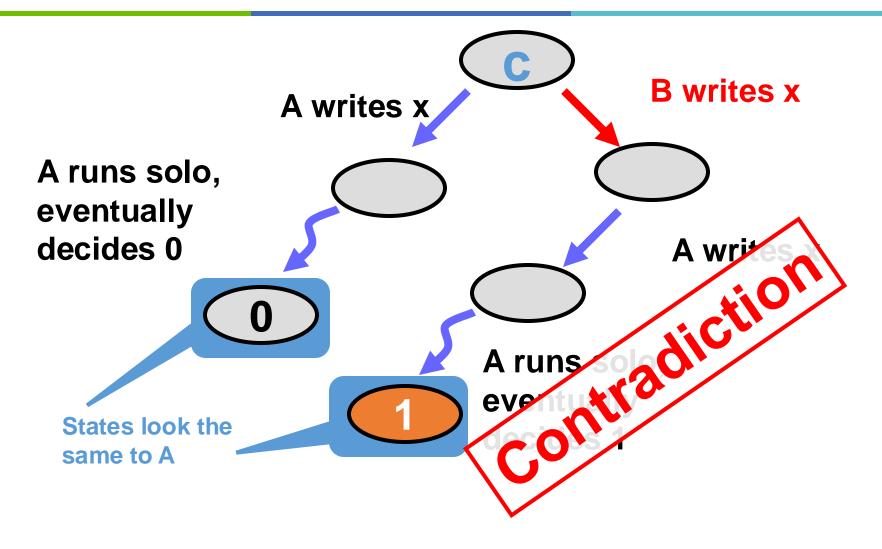
#### Possible Interactions

	x.read()	y.read()	x.write()	y.write()
x.read()	no	no	no	no
y.read()	no	no	no	no
x.write()	no	no	?	no
y.write()	no	no	no	?

## Writing Same Registers

	x.read()	y.read()	x.write()	y.write()
x.read()	no	no	no	no
y.read()	no	no	no	no
x.write()	no	no	?	no
y.write()	no	no	no	?

## Writing Same Registers



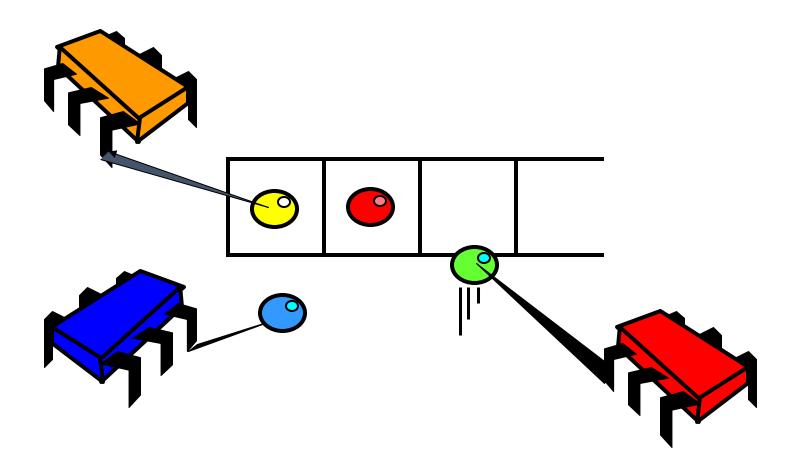
## That's All, Folks!

	x.read()	y.read()	x.write()	y.write()
x.read()	no	no	no	no
y.read()	no	no	no	no
x.write()	no	no	no	no
y.write()	no	no	no <b>O</b>	no

#### Recap: Atomic Registers Can't Do Consensus

- If protocol exists
  - It has a bivalent initial state
  - Leading to a critical state
- What's up with the critical state?
  - Case analysis for each pair of methods
  - As we showed, all lead to a contradiction

# What Does Consensus have to do with Concurrent Objects?



## Consensus Object

```
public interface Consensus<T> {
  T decide(T value);
}
```

## Concurrent Consensus Object

- We consider only one time objects:
  - each thread calls method only once
- Linearizable to sequential consensus object:
  - Winner's call went first

## Java Jargon Watch

- Define Consensus protocol as an abstract class
- We implement some methods
- You do the rest ...

```
abstract class ConsensusProtocol<T>
   implements Consensus<T> {
protected T[] proposed = new T[N];
protected void propose(T value) {
 proposed[ThreadID.get()] = value;
abstract public T decide (T value);
```

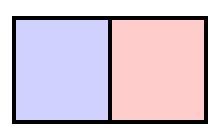
```
abstract class ConsensusProtocol<T>
   implements Consensus<T>
protected T[] proposed = new T[N];
protected void propose(T
  proposed[ThreadID.get
                        Each thread's
abstract public T dec
                        proposed value
```

```
abstract class ConsensusProtocol<T>
   implements Consensus<T> {
protected T[] proposed = new T[N];
protected void propose(T value) {
 proposed[ThreadID.get()] = value;
abstract public T decida/m
                      Propose a value
```

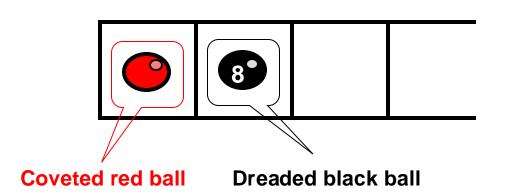
```
abstract class ConsensusProtocol<T>
   implements Consensus {
 protected T[] proposed = new T[N];
  Decide a value: abstract method means subclass
  does the real work
                  propose(T value) {
               readID.get()] = value;
abstract public T decide(T value);
```

# Can a FIFO Queue Implement Consensus?

#### FIFO Consensus

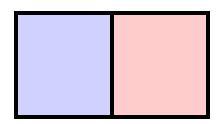


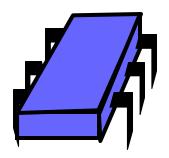
#### proposed array

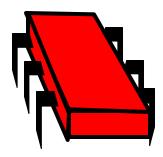


# FIFO Queue with red and black balls

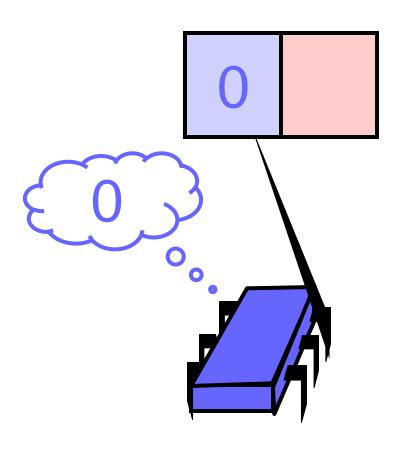
## Protocol: Write Value to Array

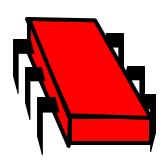




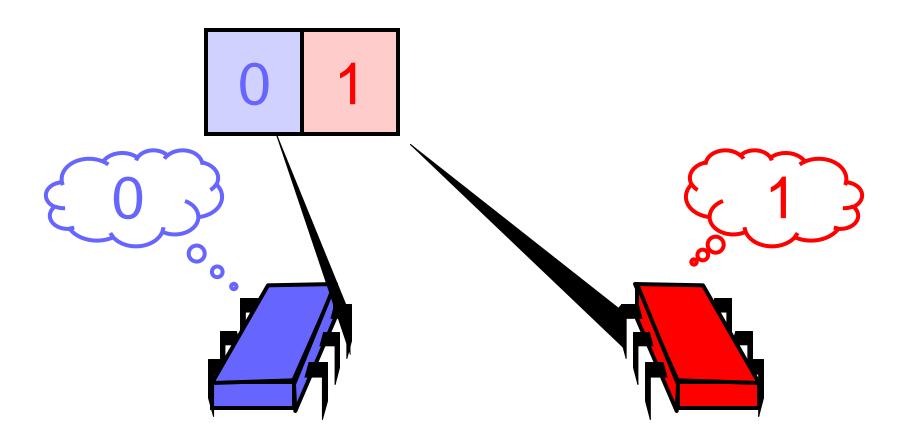


## Protocol: Write Value to Array

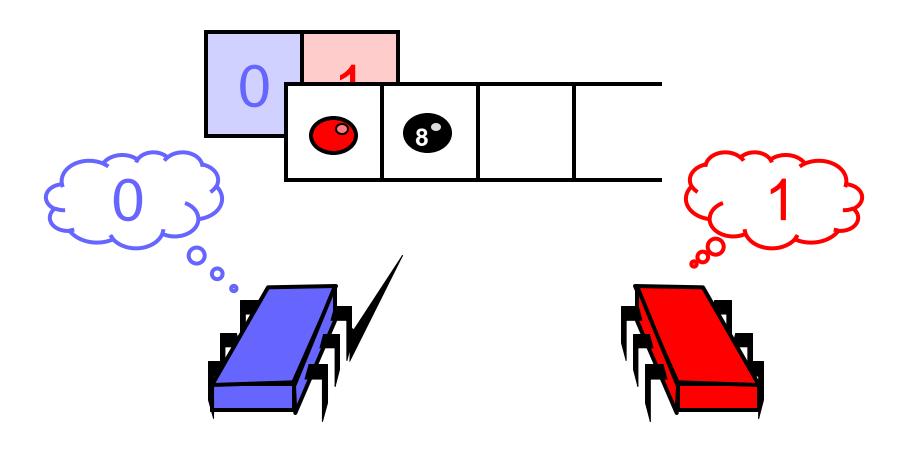




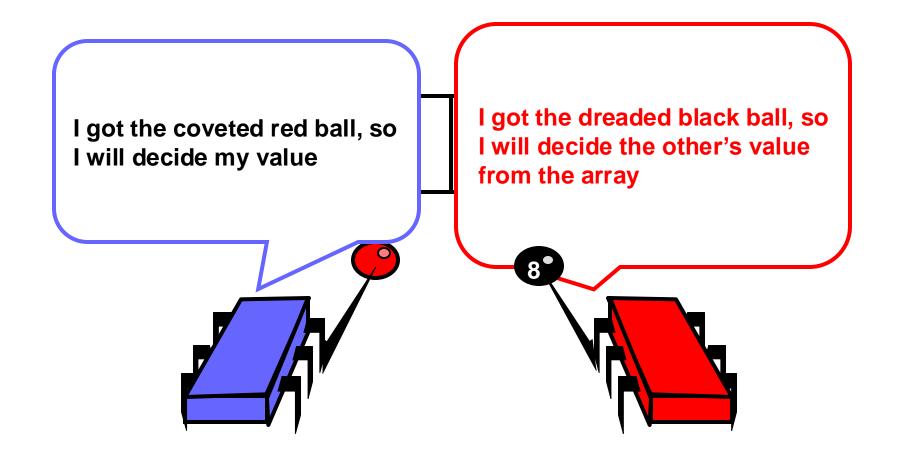
## Protocol: Write Value to Array



## Protocol: Take Next Item from Queue



## Protocol: Take Next Item from Queue



### Consensus Using FIFO Queue

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
 public QueueConsensus() {
  queue = new Queue();
  queue.enq(Ball.RED);
  queue.enq(Ball.BLACK);
```

## Initialize Queue

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
 public QueueConsensus() {
  queue = new Queue();
  queue.enq(Ball.RED);
  queue.enq(Ball.BLACK);
```

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
 public T decide(T value) {
  propose(value);
  Ball ball = queue.deq();
  if (ball == Ball.RED)
   return proposed[i];
  else
   return proposed[1-i];
```

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
 public T decide(T value) {
  propose (value) :
 Ball ball = queue.deq();
  if (ball == Ball RED)
   return proposed[i]
  else
   return proposed[1-i];
                          Race to dequeue
                          first queue item
```

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue;
 public T decide(T value) {
  propose(value);
  Ball ball = queue.deq();
  if (ball == Ball.RED)
   return proposed[i];
  else
   return proposed[1-i],
                        I win if I was first
```

```
public class QueueConsensus<T>
  extends ConsensusProtocol<T> {
 private Queue queue; Other thread wins
                       if I was second
 public T decide(T valua)
  propose(value);
  Ball ball = queue ded();
  if (ball == Ball.RED
   return proposed[i]/;
  else
   return proposed[1-i];
```

### Why does this Work?

- If one thread gets the red ball
- Then the other gets the black ball
- Winner decides her own value
- Loser can find winner's value in array
  - Because threads write array
  - Before dequeueing from queue

#### Theorem

- We can solve 2-thread consensus using only
  - A two-dequeuer queue, and
  - Some atomic registers

### Implications

- Given
  - A consensus protocol from queue and registers
- Assume there exists
  - A queue implementation from atomic registers
- Substitution yields:
  - A wait-free consensus protocol from at registers

### Corollary

- It is impossible to implement
  - a two-dequeuer wait-free FIFO queue
  - from read/write memory.

#### Consensus Numbers

- An object X has consensus number n
  - If it can be used to solve n-thread consensus
    - Take any number of instances of X
    - together with atomic read/write registers
    - and implement n-thread consensus
  - But not (n+1)-thread consensus

#### Consensus Numbers

- Theorem
  - Atomic read/write registers have consensus number 1
- Theorem
  - Multi-dequeuer FIFO queues have consensus number at least 2

### Consensus Numbers Measure Synchronization Power

#### Theorem

- If you can implement X from Y
- And X has consensus number c
- Then Y has consensus number at least c

### Synchronization Speed Limit

- Conversely

  - Theoretical Caveat: If X has consensus number desceptions
    And Y has consensus number desceptions
    is no way to construct a missist
- This theorem will be very useful
  - Unforeseen practical implications!

### Earlier Grand Challenge

- Snapshot means
  - Write any array element
  - Read multiple array elements atomically
- What about
  - Write multiple array elements atomically
  - Scan any array elements
- Call this problem multiple assignment

### Multiple Assignment Theorem

- Atomic registers cannot implement multiple assignment
- Weird or what?
  - Single write/multi read OK
  - Multi write/multi read impossible

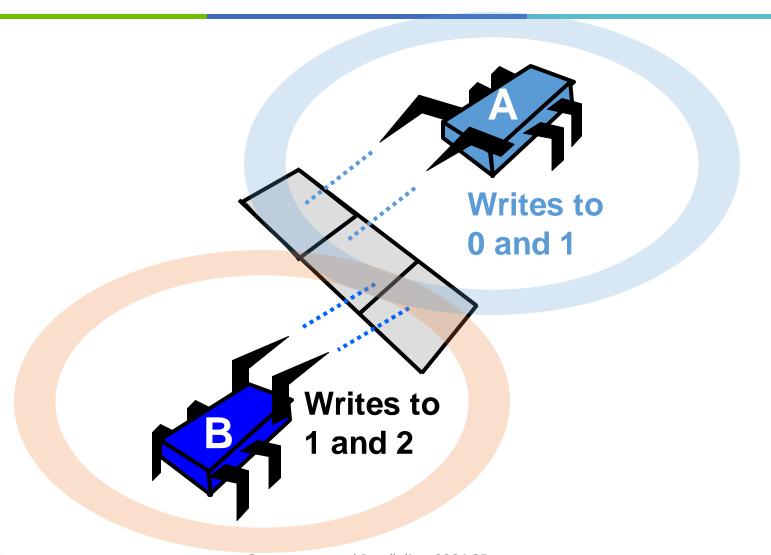
### **Proof Strategy**

- If we can write to 2/3 array elements
  - We can solve 2-consensus
  - Impossible with atomic registers
- Therefore
  - Cannot implement multiple assignment with atomic registers

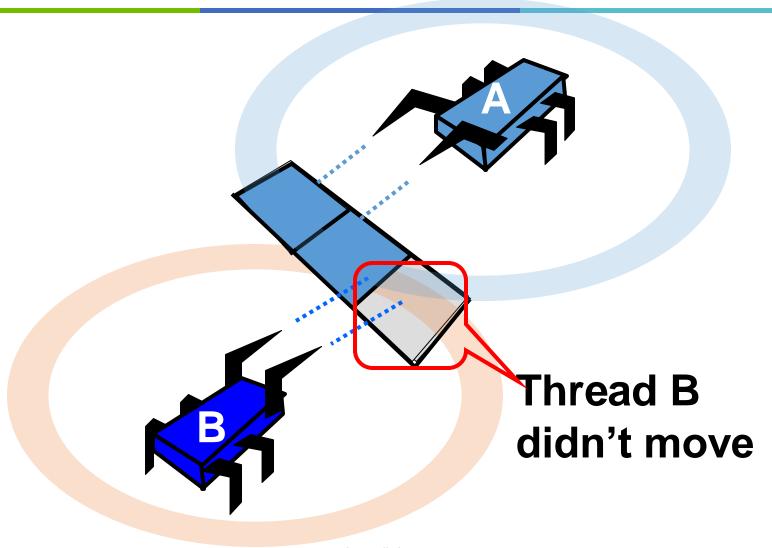
### **Proof Strategy**

- Take a 3-element array
  - A writes atomically to slots 0 and 1
  - B writes atomically to slots 1 and 2
  - Any thread can scan any set of locations

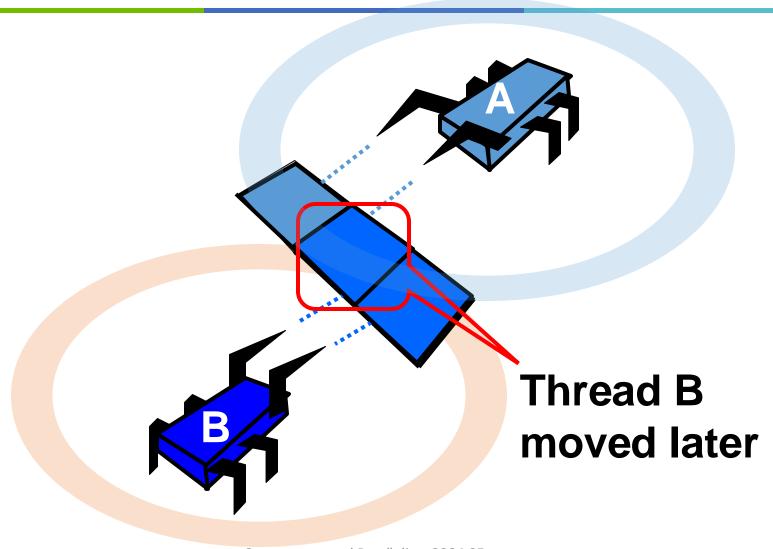
### Initially



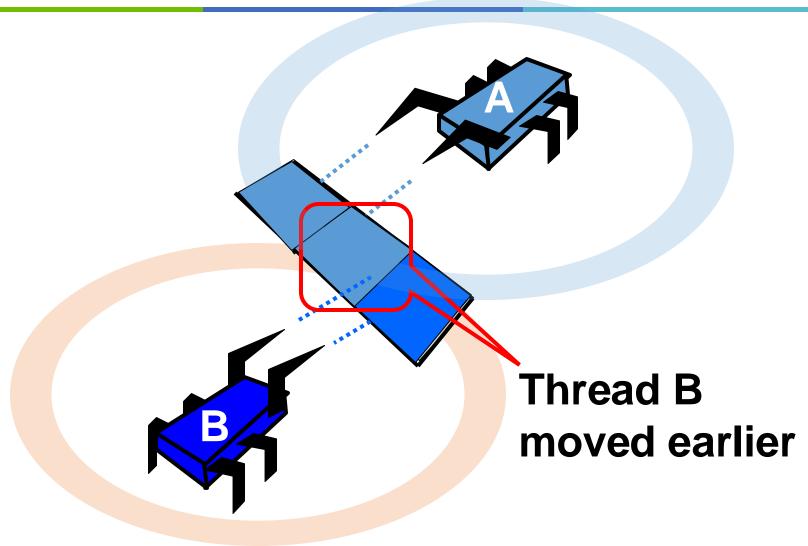
#### Thread A wins if



#### Thread A wins if



#### Thread A loses if



```
class MultiConsensus extends ...{
Assign2 a = new Assign2(3, EMPTY);
public T decide(T value) {
  a.assign(i, i, i+1, i);
  int other = a.read((i+2) % 3);
  if (other==EMPTY||other==a.read(1))
   return proposed[i];
  else
   return proposed[j];
  } }
```

```
class MultiConsensus extends ...{
Assign2 a = new Assign2(3, EMPTY);
public T decide(T value) {
  a.assign(i, i, i+1, i);
  int other = a.read((i+2) % 3);
  if (other==EMPTY||other==a.read(1))
   return proposed[i];
  else
   return proposed[j];
  } }
```

# Extends ConsensusProtocol Decide sets j=i-1 and proposes value

```
class MultiConsensus extends ... {
Assign2 a = new Assign2(3, EMPTY);
public T decide(T value) {
  a.assign(i, i, i+1, i
  int other = a.read((i+2))
  if (other==EMPTY||other==a.read(1))
   return proposed[i];
  else
                             Three slots
   return proposed[j];
                             initialized to
  } }
                             EMPTY
```

```
class MultiConsensus extends ... {
Assign2 a = new Assign2(3, EMPTY);
public T decide(T value) {
 a.assign(i, i, i+1, i);
  int other = a.xead((i+2) % 3);
  if (other==EMPTY) (other==a.read(1))
   return proposed[i];
  else
   return proposed[jAssign ID 0 to entries 0,1
                     (or ID 1 to entries 1,2)
  }}
```

```
class MultiConsensus extends ... {
Assign2 a = new Assign2(3, EMPTY);
public T decide(T value) {
  a.assiqn(i, i, i+1, i);
 int other = a.read((i+2) % 3);
  if (other==EMPTY||other==a read(1))
   return proposed[i];
  else
   return proposed[j];
                        Read the register my
  }}
                        thread didn't assign
```

```
class MultiConsensus extends
Assign2 a = new Assign2(3,
public T decide(T value)
  a.assign(i, i, i+1, i);
  int_other = a.read((i+2)
  if (other==EMPTY | other==a.read(1))
   return proposed[i];
  else
                          Other thread didn't
   return proposed[j];
                          move, so I win
  } }
```

```
class MultiComensus extends ... {
               ew Assign2(3, EMPTY);
Assign2
          decide (T value) {
  a.assiq
               i, i+1, i);
        her = a.read((i+2) % 3)
        cher==EMPTY | other==a.read(1))
   return proposed[i];
  else
                         Other thread moved
   return proposed[j]; later so | win
  } }
```

```
class MultiConsensus extends ... {
Assign2 a = new Assign2(3, EMPTY);
public T decide(T value) {
  a.assign(i, i, i+1, i);
  int other = a.read((i+2) % 3);
  if (other==EMPTY||other==a.read(1))
  return proposed[i];
  else
   return proposed[j];
                      OK, I win.
  } }
```

```
class MultiConsensus extends ... {
Assign2 a = new Assign2(3,
public T decide (T value)
  a.assign(i, i, i+1,
  int other = a.read((i+2))
  if (other==EMPTY||other=a.read(1))
   return proposed[i];
  else
                         Other thread moved
   return proposed[j];
                         first, so I lose
```

### Summary

- If a thread can assign atomically to 2 out of 3 array locations
- Then we can solve 2-consensus
- Therefore
  - No wait-free multi-assignment
  - From read/write registers

### Read-Modify-Write Objects

- Method call
  - Returns object's prior value **x**
  - Replaces x with mumble(x)

```
public abstract class RMWRegister {
private int value;
 public int synchronized
  getAndMumble() {
    int prior = value;
    value = mumble(value);
    return prior;
```

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
  getAndMumble()
    int prior = value;
    value = mumble(value);
    return prior;
                Save prior value to return later
```

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
  getAndMumble() {
    int prior = value;
    value = mumble(value);
    return prior;
                  Apply function to current value
```

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
  getAndMumble() {
    int prior = value;
    value = mumble(value);
    return prior;
                       Return prior value
```

### RMW Everywhere!

- Most synchronization instructions
  - are RMW methods
- The rest
  - Can be trivially transformed into RMW methods

### Example: Read

```
public abstract class RMWRegister {
  private int value;
  public int synchronized read() {
    int prior = value;
    value = value;
    return prior;
```

### Example: Read

```
public abstract class RMWRegister {
  private int value;
  public int synchronized read() {
    int prior = value;
   value = value;
    return prior
            apply f(x)=x, the
            identity function
```

## Example: getAndSet (swap)

```
public abstract class RMWRegister {
private int value;
 public int synchronized
   getAndSet(int v) {
  int prior = value;
  value = v;
  return prior;
```

## Example: getAndSet (swap)

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
   getAndSet(int v) {
  int prior = value;
  value = v;
  return prior;
     f(x)=v is constant
```

## getAndIncrement

```
public abstract class RMWRegister {
private int value;
 public int synchronized
   getAndIncrement() {
  int prior = value;
  value = value + 1;
  return prior;
```

## getAndIncrement

```
public abstract class RMWRegister {
private int value;
 public int synchronized
   getAndIncrement() {
  int prior = value;
 value = value + 1;
  return prior;
          f(x) = x+1
```

## getAndAdd

```
public abstract class RMWRegister {
private int value;
 public int synchronized
   getAndAdd(int a) {
  int prior = value;
  value = value + a;
  return prior;
```

## Example: getAndAdd

```
public abstract class RMWRegister {
private int value;
 public int synchronized
   getAndAdd(int a) {
  int prior = value;
 value = value + a;
  return prior;
        f(x) = x+a
```

```
public abstract class CASObject {
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
                  int update) {
  if (value==expected) {
   value = update; return true;
  return false;
  } ... }
```

```
public abstract class CASObject {
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
                   int update)
     (value==expected)
   value = update; return true;
  return false;
  } ... }
                      If value is as expected, ...
```

```
public abstract class CASObject {
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
                  int update)
  if (value==expected)
  value = update; return true;
  return false;
                       ... replace it
  } ... }
```

```
public abstract class CASObject {
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
                  int update) {
  if (value==expected)
   value = update; return true;
  return false;
  } ... }
                      Report success
```

```
public abstract class CASObject {
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
                  int update) {
  if (value==expected) {
   value = update; return true;
                       Otherwise report failure
  return false;
```

## Read-Modify-Write

```
public abstract class RMWRegister {
 private int value;
 public int synchronized
  getAndMumble() {
    int prior = value;
    value = mumble(value);
    return prior;
         Let's characterize f(x)...
```

#### Definition

- A RMW method
  - -With function mumble(x)
  - is non-trivial if there exists a value v
  - -such that v ≠ mumble(v)

## Par Example

- Identity (x) = x
  - is trivial
- getAndIncrement(x) = x+1
  - is non-trivial

#### Theorem

- Any non-trivial RMW object has consensus number at least 2
- No wait-free implementation of RMW registers from atomic registers
- Hardware RMW instructions not just a convenience

#### Reminder

- Subclasses of consensus have
  - propose (x) method
    - which just stores x into proposed[i]
    - built-in method
  - decide (object value) method
    - which determines winning value
    - customized, class-specific method

```
public class RMWConsensus
     extends ConsensusProtocol {
 private RMWRegister r = v;
 public T decide(T value) {
  propose(value);
  if (r.getAndMumble() == v)
   return proposed[i];
  else
   return proposed[j];
}}
```

```
public class RMWConsensus
     extends ConsensusProtocol {
private RMWRegister r = v;
 public T decide (T value)
  propose(value);
  if (r.getAndMumble()
   return proposed[i];
                          Initialized to v
  else
   return proposed[j];
} }
```

```
public class RMWConsensus
     extends ConsensusProtocol {
                                  Am I first?
 private RMWRegister r = v;
 public T decide (T value)
  propose(value);
  if (r.getAndMumble() == v)
   return proposed[i];
  else
   return proposed[j];
} }
```

```
public class RMWConsensus
     extends ConsensusProtocol {
 private RMWRegister r = v;
 public T decide(T value)
                            Yes, return my input
  propose(value);
  if (r.getAndMumble()
   return proposed[i];
  else
   return proposed[j];
} }
```

```
public class RMWConsensus
     extends ConsensusProtocol {
 private RMWRegister r = v;
 public T decide(T value) {
  propose(value);
  if (r.getAndMumble() == v)
                           No, return other's input
   return proposed[i];
  else
   return proposed[j];
```

- We have displayed
  - A two-thread consensus protocol
  - Using any non-trivial RMW object

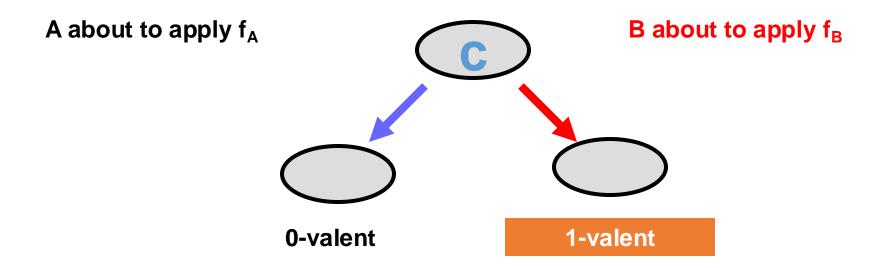
## Interfering RMW

- Let F be a set of functions such that for all  $f_i$  and  $f_{i,j}$  either
  - Commute:  $f_i(f_i(v)) = f_i(f_i(v))$
  - Overwrite:  $f_i(f_i(v)) = f_i(v)$
- Claim: Any set of RMW objects that commutes or overwrites has consensus number exactly 2

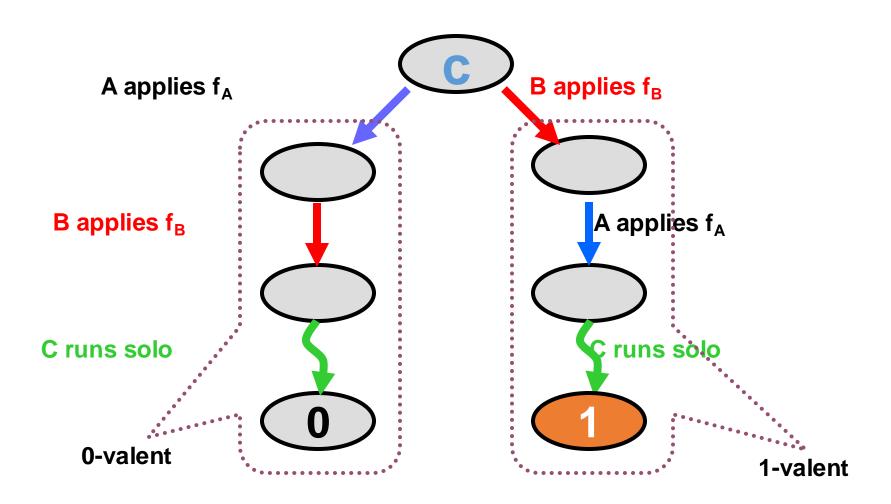
## Examples

- "test-and-set" getAndSet(1) f(v)=1
   Overwrite f<sub>i</sub>(f<sub>i</sub>(v))=f<sub>i</sub>(v)
- "swap" getAndSet(x) f(v,x)=xOverwrite  $f_i(f_i(v))=f_i(v)$
- "fetch-and-inc" getAndIncrement() f(v)=v+1
   Commute f<sub>i</sub>(f<sub>i</sub>(v))= f<sub>i</sub>(f<sub>i</sub>(v))

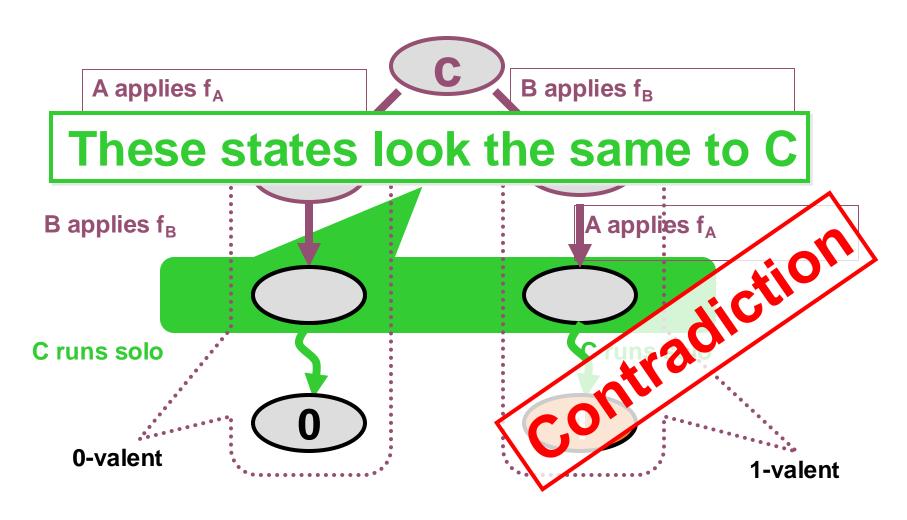
# Meanwhile Back at the Critical State



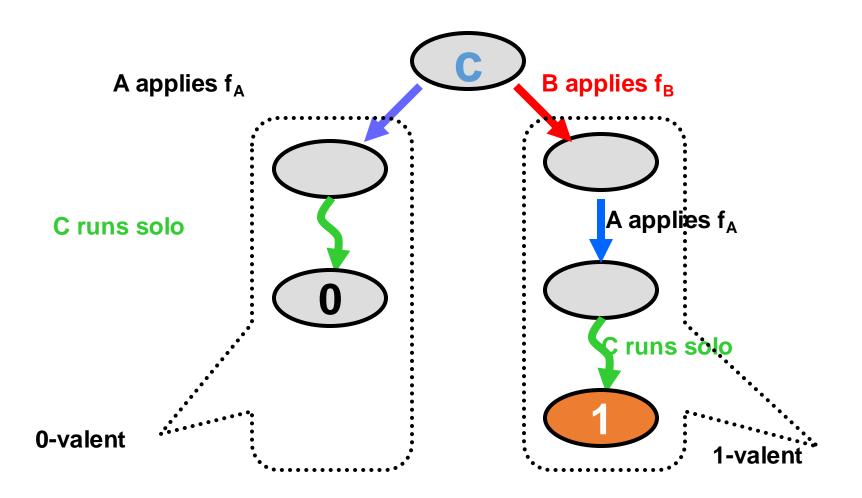
#### Maybe the Functions Commute



#### Maybe the Functions Commute

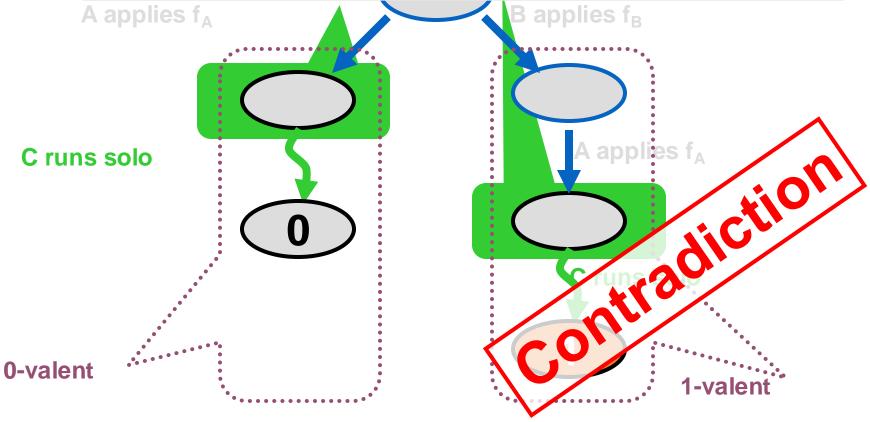


### Maybe the Functions Overwrite



#### Maybe the Functions Overwrite

## These states look the same to C



## Impact

- Many early machines provided only these "weak" RMW instructions
  - Test-and-set (IBM 360)
  - Fetch-and-add (NYU Ultracomputer)
  - Swap (Original SPARCs)
- We now understand their limitations
  - But why do we want consensus anyway?

```
public abstract class RMWRegister {
private int value;
 public boolean synchronized
   compareAndSet(int expected,
                  int update) {
  int prior = value;
  if (value==expected) {
   value = update; return true;
  return false;
  } ... }
```

```
public abstract class RMWRegister {
 private int value;
 public boolean synchronized
   compareAndSet(int expected,
                   int update)
  int prior = value;
  if (value==expected) {
   value = update; return true;
  return false;
                  replace value if it's what we expected, ...
  } ... }
```

```
public class RMWConsensus
     extends ConsensusProtocol {
 private AtomicInteger r =
   new AtomicInteger(-1);
 public T decide(T value) {
  propose(value);
  r.compareAndSet(-1,i);
  return proposed[r.get()];
```

```
public class RMWConsensus
     extends ConsensusProtocol {
private AtomicInteger r =
   new AtomicInteger(-1);
 public T decide (T value)
  propose (value);
  r.compareAndSet(-1)i
  return proposed[r.get
                      Initialized to -1
```

```
public class RMWConsensus
     extends ConsensusProtocol {
 private AtomicInteger r =
                             Try to swap in my id
   new AtomicInteger(-1);
 public T decide (T value
  propose (value)
 r.compareAndSet(-1,i);
  return proposed[r.get()];
```

```
public class RMWConsensus
     extends ConsensusProtocol {
 private AtomicInteger r =
   new AtomicInteger (-1); Decide winner's preference
 public T decide (T value)
  propose (value) ;
  r.compareAndSet 1
  return proposed[r.get()];
```

## The Consensus Hierarchy

1 Read/Write Registers, Snapshots
2 getAndSet, getAndIncrement,
•
-
•
∞ compareAndSet,

#### Lock-Freedom

- Lock-free:
  - in an infinite execution
  - infinitely often some method call finishes
- Pragmatic approach
- Implies no mutual exclusion



#### Lock-Free vs. Wait-free

 Wait-Free: each method call takes a finite number of steps to finish

 Lock-free: infinitely often some method call finishes



#### Lock-Freedom

- Any wait-free implementation is lock-free.
- Lock-free is the same as wait-free if the execution is finite.



## Lock-Free Implementations

- Lock-free consensus is as impossible as waitfree consensus
- All these results hold for lock-free algorithms also.

## There is More: Universality

- Consensus is universal
- From n-thread consensus
  - Wait-free/Lock-free
  - Linearizable
  - n-threaded
  - Implementation
  - Of any sequentially specified



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