ov model = xi(E) = + [ V(Axi(+)) - xi(E)] Dri = Ri-1 - Ri Local stability = va vav rishere v=V(d) - Uniform solu Dak = of Yk - Small perturbe applied only on the follower i oc; (t) = oc; (t) + y(t) = >(:,(t) - d + y(t)

and also Ax; (t)= x;-1(t)-x;(t) = xi-1 (b)-xi(1) uniform translate = d-y(t)

$$x_i(t) = x_i^{ij}(t) + y_i(t)$$

$$x_i(t) = y_i(t)$$

We put this in the model

$$\ddot{y}(t) = \frac{1}{2} \left[ V(d - y(t)) - v - \dot{y}(t) \right]$$

$$= \frac{1}{2} \left[ V(d) - y(t) V'(d) - v - \dot{y}(t) \right]$$

$$= \frac{1}{2} \left[ -y(t) V'(d) - \dot{y}(t) \right]$$

$$= \frac{1}{2} \left[ -y(t) V'(d) - \dot{y}(t) \right]$$

+ ij (E) + j(E) + V'(A) y(E) = 0 characteristic eq:

The solu is non-oscillating if  $\Delta \geq 0$ (=) 1 > 4 = V'(d) => [ =V'(a) < = [ 2 = -1 ± √1-4=V(a) Local linear stability only if fort <0 = alwaystrue for z >0 We have I >0 -1+ VI-4=V(a) <0 V1-42 V (4) < 1 <=> -4=V'(d) <0 <=x V'(a) >0 local linear stability if 1'60 >0 (Tis taken >0) · 2/ 40: (VI= i/4=V'G)-1) the roots can be written as -1 ± 2/4+V/(d)-1 the real part - I is always to - local linear stability. Dut oscillating - snish of collinor

 $\frac{1}{\sqrt{(d)}} = \frac{1}{\sqrt{(d)}} = \frac{1}$