

Project Number : 4

Project Name : Knight's Tour Problem Solver

Project drive (Shortened URL) : <https://rb.gy/n1eg1o>

Team Members :

Member #	Member ID	Member Name	Member Department
1	20210565	عبدالواحد رجب عبدالواحد حماد	Dept. CS
2	20210531	عبدالرحمن مصطفى حامد محمود	Dept. CS
3	202102505	عبدالرحمن رمضان فتحي محمد	Dept. AI
4	20210261	جوماتا محمد السيد طلبية	Dept. CS
5	20210166	الاء حسن عبدالرحمن عبدالرحمن	Dept. CS
6	20210172	الاء ممدوح احمد عثمان	Dept. CS

Project drive : <https://drive.google.com/drive/u/0/mobile/folders/1ImGLXOc6Z-KDzV1ogpPCNRqLLzr6r2IX>

1. Introduction and Overview

1.1 Project Idea and Overview :

The "Knight's Tour Problem Solver" is a classic chess puzzle that involves finding a sequence of moves for a knight on an $n \times n$ chessboard such that the knight visits every square exactly once. This problem has been studied for centuries and has connections to graph theory and algorithm design. There are various algorithms to solve the Knight's Tour problem, including Warnsdorff's rule, backtracking algorithms and genetic algorithms. The problem has applications in optimization, pathfinding, and puzzle-solving. Additionally, variations of the Knight's Tour problem exist, such as on different board sizes or with different constraints. Visualizing and analyzing the solutions to the Knight's Tour problem can provide insights into the nature of the problem and the effectiveness of different algorithms.

1.2 Problem Overview :

In the Knight's Tour, the knight, a chess piece capable of unique L-shaped moves, must traverse the chessboard, covering each square precisely once. The problem is both combinatorial and algorithmic, requiring strategic exploration to determine a viable sequence of knight moves.

1.3 Approaches Used :

1. Backtracking Search Algorithm: Backtracking involves systematically exploring potential moves while intelligently abandoning paths that lead to dead-ends. This algorithm efficiently navigates the knight through the chessboard, optimizing exploration by discarding unfruitful paths.

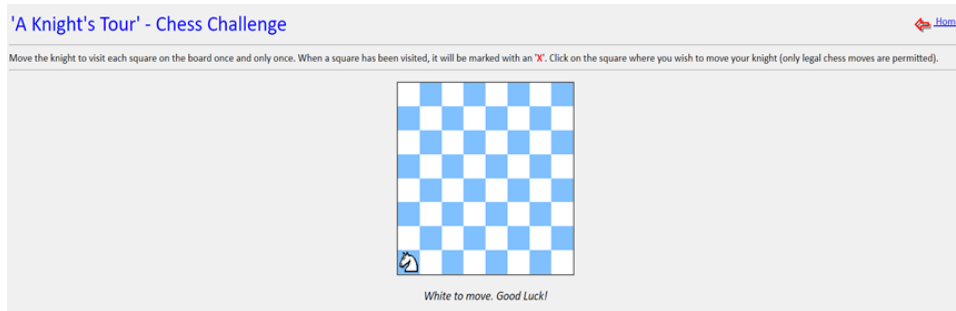
2. Genetic Algorithm: Genetic Algorithms emulate evolutionary processes, employing genetic operations like crossover and mutation to evolve a population of potential solutions. By exploring a diverse set of move sequences and evolving over generations, the algorithm aims to discover effective paths, bringing a stochastic and adaptive approach to solving the Knight's Tour.

1.4 Similar Applications :

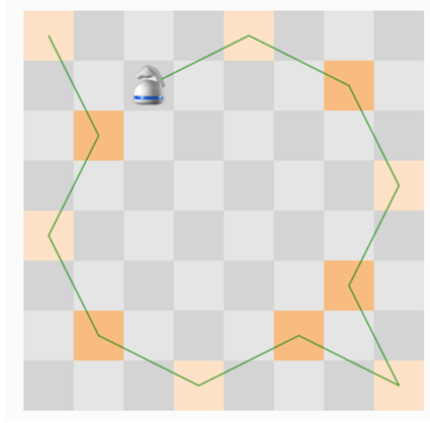
1. First one: <https://www.knightstourpuzzle.com>



2. Second one: <http://www.ee.unb.ca/cgi-bin/tervo/knight.pl?d6e4cc33e0e3b0434cb3>

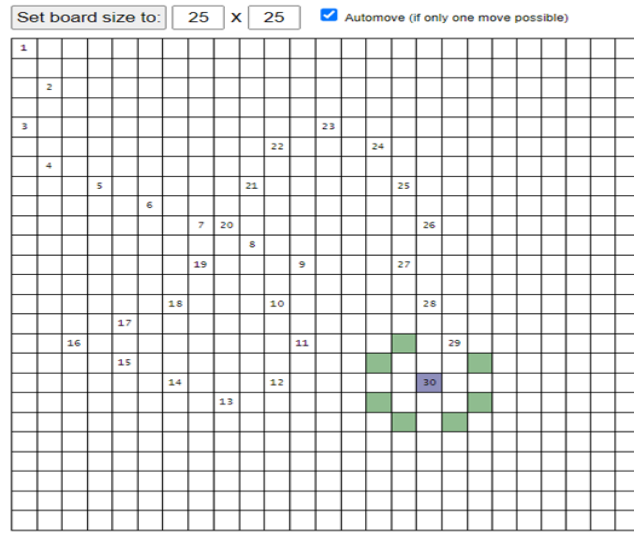


3. Third one : <https://www.flyordie.com/chess/knightstour/>



4. Fourth one: <https://randompearls.com/reference/tools/knight-solution/>

Knight's Tour Challenge



1.5 Literature Review :

We used the papers :

1. First one: Genetic Algorithms with Heuristic Knight's Tour Problem

Link:

https://www.researchgate.net/publication/220862449_Genetic_Algorithms_with_Heuristic_Knight%27s_Tour_Problem

2. Second one: The Knight's Tour - Evolutionary vs. Depth-First Search

Link: <https://ieeexplore.ieee.org/document/1331065>

3. Third one: A simple recursive backtracking algorithm for knight's tours puzzle on standard 8x8 chessboard Link: <https://ieeexplore.ieee.org/document/8126004>

4. Fourth one : Knight's Tours by Ben Hill, Kevin Tostado

Link: http://www.geofhagopain.net/CS007A/assignments/Assignments_F15/ktpaper.pdf

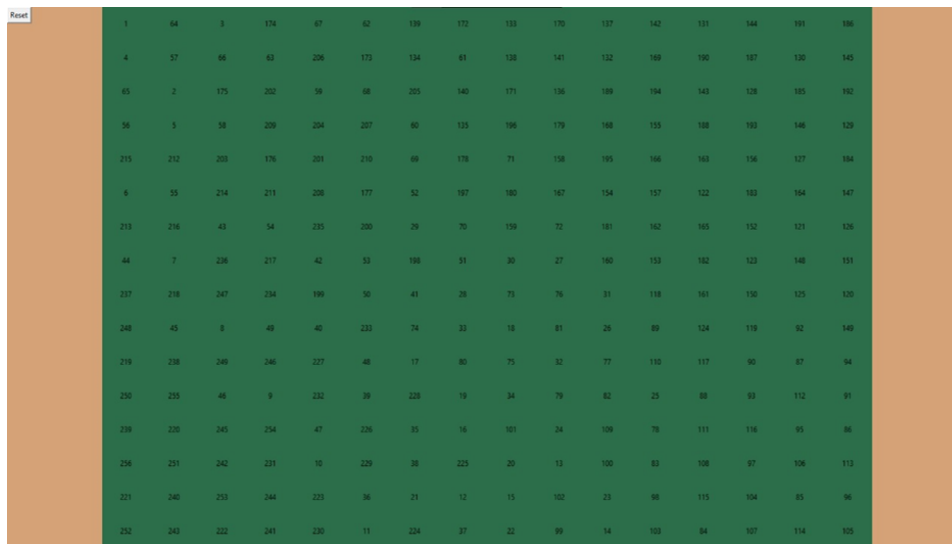
5. Fifth one : A Simple Recursive Backtracking Algorithm for Knight's Tours Puzzle on Standard 8x8 Chessboard , Debajyoti Ghosh Computer Science NIIT University Neemrana, India.

link:https://sites.science.oregonstate.edu/math_reu/proceedings/REU_Proceedings/Proceedings2004/2004Ganzfried.pdf

1.6 Proposed Solution :

The proposed solution for the Knight's Tour problem typically involves using algorithmic approaches such as backtracking and genetic algorithm to find a sequence of moves for the knight on the chessboard. These algorithms aim to systematically explore possible paths and choices to ensure that every square is visited exactly once. Additionally, heuristic methods and optimizations can be applied to enhance the efficiency of finding a solution. The chosen approach depends on factors such as the size of the chessboard, desired performance, and specific constraints or variations of the problem.

For example the user input n = 16 and select GA with heuristic :



1	64	3	174	67	62	139	172	133	170	137	142	131	144	191	186
4	57	66	63	206	173	134	61	138	141	132	169	190	187	135	145
65	2	175	202	58	68	205	140	171	136	189	194	143	138	185	192
36	5	38	209	204	207	60	135	196	179	168	155	188	193	146	129
215	212	203	176	201	210	69	178	71	138	195	166	163	136	127	184
6	55	214	211	208	177	52	197	180	167	154	157	122	183	164	147
213	216	43	54	235	200	29	70	159	72	181	162	165	152	121	138
44	7	236	217	42	53	198	51	30	27	160	153	182	123	148	151
237	218	247	234	199	50	41	28	73	76	31	118	161	130	125	130
248	45	8	49	40	233	74	33	18	81	26	89	124	119	92	149
219	238	249	246	227	48	17	80	75	32	77	110	117	90	87	94
250	255	46	9	232	39	228	19	34	79	82	25	88	93	112	91
239	220	245	254	47	226	35	16	101	24	109	78	111	116	95	86
256	251	242	231	10	229	36	225	20	13	100	83	108	97	106	113
221	240	253	244	223	36	21	12	15	102	23	86	115	104	85	96
252	243	222	241	230	11	224	37	22	89	14	103	84	107	114	105

For example, the user input n =32 and select Backtracking approach:

Reset	1	670	38	606	815	616	91	604	827	622	39	602	789	902	37	580	589	594	35	586	579	582	51	585	597	580	51	585	591	584	48	584	
	64	607	612	617	62	605	626	621	60	603	788	625	58	601	772	583	51	579	580	583	54	587	576	581	52	589	586	579	58	587	581	581	
	615	2	609	614	629	606	619	646	735	628	623	764	799	768	541	600	779	582	585	578	581	574	583	584	547	400	577	570	588	542	545	48	
	608	65	630	639	619	643	664	637	620	763	630	767	624	771	799	769	584	599	774	587	584	577	582	575	582	405	572	589	578	573	570	579	
	3	640	615	644	635	636	647	704	635	706	761	626	621	636	769	768	767	585	585	586	573	584	585	540	401	546	581	578	571	578	41	574	
	64	631	642	655	646	665	684	663	762	623	602	629	779	625	610	633	790	785	796	777	588	597	572	583	406	573	604	577	580	571	574	571	
	641	4	646	634	643	654	703	686	707	762	627	624	611	634	631	616	767	668	791	764	595	776	549	410	543	402	588	574	573	570	577	48	
	632	67	636	633	666	663	662	709	622	605	636	663	628	615	612	608	632	617	782	795	578	571	596	551	388	407	578	403	578	575	572	578	
	1	630	633	652	661	762	679	708	687	758	621	614	635	622	640	628	619	764	607	762	783	550	411	544	409	436	577	586	575	578	45	576	
	64	637	632	667	665	689	680	761	636	637	604	623	672	613	626	621	634	629	616	781	570	779	552	435	414	587	408	578	576	579	574	573	
	651	8	661	660	689	678	709	742	717	625	661	638	625	646	613	644	627	620	791	606	553	526	543	412	437	578	585	584	581	574	578	44	
	638	68	658	677	698	741	750	630	744	607	624	671	680	673	648	639	632	605	600	589	780	419	438	415	434	413	580	575	580	585	580	577	
	7	676	659	690	671	710	743	736	619	684	639	662	647	670	675	638	643	608	605	584	527	542	525	420	579	584	587	582	583	586	43	586	
	70	668	672	675	740	687	616	635	638	617	602	665	674	679	642	648	640	601	580	603	556	438	416	453	416	421	574	588	586	591	578	581	
	675	8	691	670	711	738	755	618	1013	640	663	678	691	666	689	676	657	664	555	528	541	524	421	440	575	588	583	594	587	582	585	42	
	78	71	674	729	696	611	746	641	616	667	1014	693	1002	1000	677	690	641	650	667	602	557	442	529	422	477	422	581	570	585	540	595	592	575
	9	692	79	712	727	754	615	1016	643	1022	1015	694	689	664	687	668	607	558	531	540	523	424	441	572	429	584	541	538	593	584	41	596	
	72	77	736	695	612	747	642	732	1022	1015	696	1003	994	694	690	691	568	687	580	443	530	431	429	425	380	571	582	539	580	589	574	578	
	693	10	713	80	725	614	1017	644	1013	1002	1023	1006	963	688	687	698	559	582	589	522	427	444	539	430	383	542	551	570	603	540	587	40	
	76	74	694	613	748	643	752	1021	1019	1007	962	995	1004	699	692	693	580	581	570	532	430	519	420	355	352	597	588	589	572	573	576	571	
	11	714	75	734	61	1020	671	1010	679	1024	1005	964	933	690	691	562	609	558	521	519	500	354	443	384	543	580	571	582	579	580	58	578	
	74	696	62	749	646	751	678	1019	1008	963	956	961	982	693	688	695	564	511	534	451	520	449	500	353	350	587	544	513	572	577	542	537	
	61	12	715	733	738	679	1009	672	657	689	675	654	699	682	585	680	587	586	517	506	513	452	353	446	540	516	521	576	601	574	579	58	
	488	67	490	647	750	651	752	677	688	673	658	661	662	683	694	687	536	535	532	477	440	507	540	517	536	545	574	578	580	545	536	542	
	11	64	716	716	721	648	669	652	671	676	667	674	685	680	683	538	605	470	505	514	453	534	447	546	515	520	581	580	573	588	57	534	
	66	487	66	461	650	717	722	469	646	653	728	661	664	655	654	479	504	515	454	531	476	547	535	515	582	581	578	587	546	535	544	525	
	63	14	61	718	465	462	649	720	727	466	663	654	659	482	550	656	450	530	475	504	516	514	533	582	577	530	581	572	589	526	533	56	
	64	69	498	503	466	723	480	495	590	729	728	481	502	657	456	629	476	451	520	512	520	512	532	593	578	583	584	571	586	549	532	524	527
	11	68	535	664	493	484	467	724	497	462	501	638	459	628	473	458	521	510	503	500	505	512	515	579	585	580	581	582	578	528	65	532	
	100	61	532	68	504	463	484	481	468	723	460	525	472	457	522	509	502	507	506	511	584	584	584	557	586	583	582	573	548	531	52	525	
	67	16	61	506	463	48	469	508	461	20	471	510	523	22	527	512	507	504	595	514	586	56	567	516	515	58	538	518	521	66	526	54	
	62	503	58	57	69	507	462	49	470	509	524	21	526	511	508	21	586	513	586	25	586	515	536	27	536	517	554	29	530	53	522	51	

2. Implementation and applied Algorithms

2.1 Backtracking Approach :

1. Adaptive Heuristics (Warnsdorff's Rule heuristic):

Warnsdorff's Rule is adaptive because it changes its behavior based on the degree of the nodes in the graph.

It prioritizes moves that lead to squares with the fewest possible future moves, which changes as the search progresses.

However, it's important to note that while Warnsdorff's Rule is adaptive, it doesn't adapt in the same way as some other heuristics. For example,

it doesn't adjust its behavior based on the number of unvisited squares or the number of visited squares.

It simply adjusts its behavior based on the degree of the nodes in the graph

This can significantly reduce the time and computational resources required to find a solution, How can this happens ?

ANS: By prioritizing moves that lead to squares with the fewest possible future moves (in the code we get all accessible squares for every state , sort them in ascendingly and pass the next state that has fewer number of accessible squares first),the algorithm can avoid exploring branches of the search space that are unlikely to lead to a solution.

Backtracking Using Warndorff's rule implementation Analysis:

Initialization: The code initializes necessary variables, sets recursion limit, and defines a class `KnightsTour` to represent the Knight's Tour problem.

Class Methods:

- **`__init__(self, n)`:** The constructor initializes the `KnightsTour` object with the size of the chessboard `n`. It creates an empty chessboard (`self.board`) and defines possible knight moves (`self.moves`) as tuples, `self.solPath` is used to store the path of the solution.

```
8 print("Printing 1 solution for a starting state that is optimized by Warnsdorff's rule ")
9 class KnightsTour:
10     def __init__(self, n): #initilize board , all squares to -1 as unvisited
11         self.n = n
12         self.board = [[-1]*n for _ in range(n)]
13         self.moves = ((-2, -1), (-2, 1), (-1, -2), (-1, 2), (1, -2), (1, 2), (2, -1), (2, 1))
14         self.solPath = []
15
```

- **`is_valid_move(self, x, y)`:** Checks if the given coordinates (`x, y`) are within the chessboard boundaries and the corresponding square is unvisited.

```
15
16     def is_valid_move(self, x, y):
17         return 0 <= x < self.n and 0 <= y < self.n and self.board[x][y] == -1
18
```

- **`get_next_moves(self, x, y)`:** Returns a sorted list of tuples, (the list is sorted in ascending order based on (`count`) of possible next moves from a given position (`x, y`), after checking it's a valid position.

```
9 def get_next_moves(self, x, y):
10     next_moves = []
11     for move in self.moves:
12         next_x, next_y = x + move[0], y + move[1]
13         if self.is_valid_move(next_x, next_y):
14             count = 0
15             for m in self.moves:
16                 if self.is_valid_move(next_x + m[0], next_y + m[1]):
17                     count += 1
18             next_moves.append((next_x, next_y, count))
19     return sorted(next_moves, key=lambda x: x[2])
20
```

- **solve(self, row, col):** it called only one time when passing the initial state , it sets all board positions to 0 as visited , start passing the starting row and col to solve_util function , if it returns False means that there is no solution for this start state, else it prints the solution found.

```
30
31 def solve(self, row, col):
32     self.board[row][col] = 0
33     self.solPath.append((row, col))
34     if not self.solve_util(row, col, 1):
35         print("No solution exists")
36     else:
37         self.print_solution()
38
```

- ② **solve_util(self, x, y, move_num):** A recursive utility function , first it checks if passed move_num = n*n means that board is full and a solution is found so it returns True , else it attempts to find a solution by exploring possible knight moves of a state by getting next accessible moves of that state , if that path lead to a dead end it backtracks and checks rest of moves , if no of move can lead to a solution It backtracks and set initial state to -1 as unvisited and return False as no solution found


```
39
40     def solve_util(self, x, y, move_num):
41         if move_num == self.n**2: #board is full
42             return True
43
44         for next_x, next_y, _ in self.get_next_moves(x, y):
45             self.board[next_x][next_y] = move_num
46             self.solPath.append((next_x, next_y))
47             if self.solve_util(next_x, next_y, move_num+1):
48                 return True
49             self.board[next_x][next_y] = -1
50             self.solPath.pop()
51
52         return False
53     #end of solve_util function
54
```

- **print_solution(self):** Prints the final chessboard configuration and the path taken to reach the solution

```
def print_solution(self):
    for row in self.board:
        print(row)

    print("/")*40
    print(self.solPath)
    print("/")*40
```

2. Randomized heuristic:

This heuristic involves using a depth-first search(backtracking approach) with a randomized order of moves.

The idea is to randomly shuffle the order of the moves for each step, which can help to avoid getting stuck in local optima and explore more of the search space(getting a different solution).

This heuristic can be particularly effective for larger boards where the number of possible moves becomes prohibitively large.

Backtracking Using Randomized heuristic implementation Analysis:

Initialization: The code initializes necessary variables, sets recursion limit, and defines a class KnightsTour to represent the Knight's Tour problem

Class methods:

- **__init__(self, n):** Initializes the board by setting all squares to -1 as unvisited, defines possible moves for the knight, and initializes the solution path.

```
8
9 class KnightsTour:
10     def __init__(self, n):
11         self.n = n
12         self.board = [[-1] * n for _ in range(n)]
13         self.moves = ((-2, -1), (-2, 1), (-1, -2), (-1, 2), (1, -2), (1, 2), (2, -1), (2, 1))
14         self.solPath = []
```

- **is_valid_move:** Checks if a move is valid within the chessboard boundaries.

```
15
16     def is_valid_move(self, x, y):
17         return 0 <= x < self.n and 0 <= y < self.n and self.board[x][y] == -1
18
19
```

- **get_next_moves:** Generates the next possible moves for the passed state(x,y), and prioritizing moves with the fewest possible next moves , sorting all next moves ascendingly after that sets the smallest count(number of accessible moves) from all next_moves of that state to min_next_moves and creates random_moves list that contain all moves from next_moves that has the smallest accessible moves for avoiding dead end paths and call create_random_list function to shuffle that moves for exploring different solutions each run.

```
def get_next_moves(self, x, y):
    next_moves = []
    for move in self.moves:
        next_x, next_y = x + move[0], y + move[1]
        if self.is_valid_move(next_x, next_y):
            count = 0
            for m in self.moves:
                if self.is_valid_move(next_x + m[0], next_y + m[1]):
                    count += 1
            next_moves.append((next_x, next_y, count))

    # Sort the moves based on the number of next moves in ascending order
    next_moves.sort(key=lambda x: x[2])

    # Use Warnsdorff's rule to prioritize moves with the fewest possible next moves
    if len(next_moves) > 0:
        min_next_moves = next_moves[0][2] #contains only 1 element is the smallest count
        random_moves = [move for move in next_moves if move[2] == min_next_moves] #take
        #random moves contain all states that has smallest accessible moves (smallest count)
        if len(random_moves) > 0:
            random_l = self.Create_random_list(random_moves, len(random_moves))
            return random_l
    # If no moves have the fewest possible next moves, return all moves
    return next_moves
```

- **Create_random_list:** Creates a random list of tuples from the available next moves, because it allows the algorithm to explore different sequences of moves that lead to the same square.

```
def Create_random_list(self, next_moves, num_tuples):
    random_list = []
    for _ in range(num_tuples):
        random_tuple = random.choice(next_moves) #No Duplicates
        random_list.append(random_tuple)

    return random_list
```

- **Solve(self, x, y):** it called only one time when passing the initial state, it sets all board positions to 0 as visited, start passing the starting row and col to solve_util function, if it returns False means that there is no solution for this start state, else it prints the solution found.

```
def solve(self, x, y):  
    start_x, start_y = x, y  
    move_num = 0  
    self.board[start_x][start_y] = move_num  
    self.solPath.append((start_x, start_y))  
    if self.solve_util(start_x, start_y, move_num + 1):  
        self.print_solution()  
    else:  
        print("No solution exists")
```

- **solve_util (self, x, y, move_num)**: A recursive utility function, first it checks if passed move_num = n*n means that board is full and a solution is found so it returns True, else it attempts to find a solution by exploring possible knight moves of a state by getting next accessible moves of that state, if that path leads to a dead end it backtracks and checks rest of moves, if no move can lead to a solution it backtracks and sets initial state to -1 as unvisited and returns False as no solution found.

```
def solve_util(self, x, y, move_num):
    if move_num == self.n ** 2:
        return True

    for next_x, next_y, _ in self.get_next_moves(x, y):
        self.board[next_x][next_y] = move_num
        self.solPath.append((next_x, next_y))
        if self.solve_util(next_x, next_y, move_num + 1):
            return True
        self.board[next_x][next_y] = -1
        self.solPath.pop()

    return False
```

- **print_solution(self):** Prints the final board configuration and the solution path.

```
def print_solution(self):
    for row in self.board:
        print(row)

    print("/")*40
    print(self.solPath)
    print("/")*40
```

3. Implementation for Getting all possible solutions for a state

Main functions:

- ❖ **printKnightsTourSolution(chessBoard, n, row, col, upcomingMove, time_flag):**

1. The main function that solve the problem and finds all possible solutions for the initial state Recursively by exploring the Knight's Tour using backtracking.
2. Checking for valid moves and gets the next accessible moves for every state by applying Warndorff's optimization technique as next moves sorted ascendingly and

avoids all paths (moves) that leads to a dead end (for increasing optimization and decreasing time complexity).

3. When a complete tour solution is found , it displays the chessboard configuration , after that it sets the least state(last square visited) to 0 as unvisited to continue exploring its next moves for finding more solutions , this happens to all states for finding all solutions can be found from the start state.

4. Uses multithreading with a timeout to control the search.

```
22 def printKnightsTourSolutions(chessBoard, n, row, col, upcomingMove, timeout_flag):
23     global TotalRuns
24     TotalRuns += 1
25
26     # Checking that passed row and column are valid
27     if row < 0 or col < 0 or row >= n or col >= n or chessBoard[row][col] != 0:
28         return
29
30     if upcomingMove == n * n:
31         chessBoard[row][col] = upcomingMove
32         displayChessBoard(chessBoard)
33         chessBoard[row][col] = 0
34         return
35
36     move_x = [2, 1, -1, -2, -2, -1, 1, 2]
37     move_y = [1, 2, 2, 1, -1, -2, -2, -1]
38
39     chessBoard[row][col] = upcomingMove
40
41     next_moves = []
42     for i in range(8):
43         next_x = row + move_x[i]
44         next_y = col + move_y[i]
45         if next_x >= 0 and next_x < n and next_y >= 0 and next_y < n and chessBoard[next_x][next_y] == 0:
```

```
39 chessBoard[row][col] = upcomingMove
40
41 next_moves = []
42 for i in range(8):
43     next_x = row + move_x[i]
44     next_y = col + move_y[i]
45     if next_x >= 0 and next_x < n and next_y >= 0 and next_y < n and chessBoard[next_x][next_y] == 0:
46         count = 0
47         for j in range(8):
48             if next_x + move_x[j] >= 0 and next_x + move_x[j] < n and next_y + move_y[j] >= 0 and next_y + move_y[j] < n and chessBoard[next_x + move_x[j]][next_y + move_y[j]] == 0:
49                 count += 1
50         next_moves.append((next_x, next_y, count))
51
52 # Sort the next moves based on the number of accessible squares(counts) for this move
53 next_moves.sort(key=lambda x: x[2])
54
55 for move in next_moves:
56     if not timeout_flag.is_set():
57         printKnightsTourSolutions(chessBoard, n, move[0], move[1], upcomingMove + 1, timeout)
58     else:
59         break
60
61 chessBoard[row][col] = 0
62
63 # End of printKnightsTourSolutions function
64
```

❖ displayChessBoard (chessBoard):

Prints the chessboard configuration as a solution is found, incrementing the number_of_solutions count.

```
7
8 def displayChessBoard(chessBoard):
9     print("////////////////////////////////")
10    global number_of_solutions
11    number_of_solutions += 1
12    print("Solution number:", number_of_solutions)
13    # Printing every possible solution
14    for i in range(len(chessBoard)):
15        for j in range(len(chessBoard)):
16            print(chessBoard[i][j], end=" ")
17        print()
18
19    # End of displayChessBoard function
```


2.2 Genetic Approach implementation

1. Encoding

	5		4	
6				3
7				2
	8		1	

The encoding for the Knight's Tour problem involves representing the chessboard as a grid and the knight's moves as combinations of horizontal and vertical steps. Using a coordinate system, each square on the chessboard is assigned a unique identifier. The knight's moves can be encoded using numbers from 1 to 8, representing the eight possible directions the knight can move in. This encoding allows for the creation of algorithms that systematically explore possible move sequences. By representing the knight's moves in this way, it becomes possible to track and analyze the paths taken and ensure that every square is visited exactly once, which is the essence of solving the Knight's Tour problem.

2. Crossover and Mutation

In our approach we used a one-point crossover that is selected randomly, the crossover rate is between 85% and 95% with 0.5% mutation rate


```
4 usages
def crossover(self, parent1, parent2):
    if random.random() > self.crossover_rate:
        return random.choice([parent1, parent2])
    crossover_point = random.randint(a: 1, self.N * self.N - 1)
    offspring = parent1[:crossover_point] + parent2[crossover_point:]
    return offspring
```

The "crossover" function performs a genetic algorithm operation where two parent individuals are combined to create offspring. The crossover point is randomly selected, and the resulting offspring inherits genetic information from both parents. This process simulates genetic recombination and introduces diversity into the population.

```
4 usages
def mutation_flip(self, individual):
    for i in range(len(individual)):
        if random.random() < self.mutation_rate:
            individual[i] = random.randint(a: 1, b: 8)
    return individual
```

The "mutation flip" function introduces random changes to an individual's genetic information. It iterates through the individual's genes and, with a certain probability, replaces each gene with a random value. This operation introduces variability and allows the genetic algorithm to explore a broader search space for potential solutions.

3. Selection

```
2 usages
def select_parents(self, population, use_heuristic=False):
    for i in range(self.population_size):
        self.fitness_values.append(self.evaluate_fitness_matrix(population[i], use_heuristic))
    total_fitness = sum(self.fitness_values)
    probabilities = [fitness / total_fitness for fitness in self.fitness_values]
    parents = random.choices(population, weights=probabilities, k=self.population_size)
    return parents
```

Chromosomes are selected using Russian Roulette wheel selection, where the better chromosomes have a greater chance of being selected. Using this selection method, a maximum of a quarter of the chromosomes (worst chromosomes in generation) are

replaced by better chromosomes in the generation. This gives a greater chance for the best chromosomes to participate in the crossover to produce the next generation and reduces the chances of the worst chromosomes to produce the next generation.

4. Extending partial tours:

We tried to solve this problem using pure genetic algorithms, but this approach did not lead us to the proposed solution and take a lot of time to evaluate the fitness of population, so we determined to make some additional modifications on our approach and using Repair and heuristics.

Gordon and Slocum made a similar argument in their paper, evolutionary VS depth-first search.

```
3 usages
def evaluate_fitness_matrix(self, chromosome, use_heuristic=False):
    self.current_x = self.start_position[0]
    self.current_y = self.start_position[1]
    visited_board = [[False for _ in range(self.N)] for _ in range(self.N)]
    visited_board[self.current_x][self.current_y] = True
    num_legal_moves = 0
    for i in range(0, len(chromosome)):
        legal, chromosome[i] = self.move_matrix(chromosome[i], visited_board, use_heuristic)
        if not legal:
            return num_legal_moves
        else:
            num_legal_moves += 1
            visited_board[self.current_x][self.current_y] = True
    return num_legal_moves
```

This function evaluates a fitness matrix based on a given chromosome and optional heuristic. It initializes the current position and a visited board, then iterates through the chromosome to determine legal moves using a move matrix. If a move is illegal, it returns the number of legal moves encountered so far. Otherwise, it updates the number of legal moves and the visited board. Finally, it returns the total number of legal moves made.

The below function implements a genetic algorithm to find a solution. It initializes a population and iterates through a specified number of generations. During each

generation, it selects parents based on fitness, performs crossover and mutation to create offspring, and updates the population with the new offspring. It then evaluates the fitness of each chromosome in the population and identifies the best fitness value and corresponding chromosome. If the best fitness reaches the maximum possible value, it prints the fittest chromosome, generation, best fitness, and the decoded best chromosome path. Finally, it returns the fittest chromosome, generation, best fitness, and the decoded best chromosome path when the maximum fitness is achieved.

```
7 usages
def run_genetic_algorithm(self, use_heuristic=False):
    # Run the Genetic Algorithm for finding a solution
    population = self.initialize_population()
    for generation in range(self.max_generations):
        self.fitness_values = []
        parents = self.select_parents(population, use_heuristic)
        offspring = []
        for i in range(0, self.population_size, 2):
            parent1 = parents[i]
            parent2 = parents[i + 1]
            child1 = self.crossover(parent1, parent2)
            child2 = self.crossover(parent2, parent1)
            offspring.extend([self.mutation_flip(child1), self.mutation_flip(child2)])
        population = offspring
        self.fitness_values = []

        for chromosome in population:
            value = self.evaluate_fitness_matrix(chromosome, use_heuristic)
            self.fitness_values.append(value)
        best_fitness = max(self.fitness_values)
        max_index = self.fitness_values.index(best_fitness)
        print(f'Fittest Chromosome: {population[max_index]}')
        print(f'Generation {generation + 1}: Best Fitness = {best_fitness}')
        if best_fitness == self.N * self.N - 1:
            return (population[max_index], generation + 1, best_fitness, self.decode_best_chromosome(
                population[max_index]))
```

5. Algorithms Used with Genetic

1. With Repair :

For each partial solution (chromosome in a generation), when a knight jumps off the board or returns to a previously visited square, a modification is applied. We try to replace the move (gene) that represents the illegal move with another move that allows the knight to proceed.

Before every move, we examine the squares that can be reached with legal moves from the current square. Then we try each possible move in an ascending order, then the knight moves according to the first legal move of the possible move. We repeat for each chromosome until a substitution cannot be made, and the evaluation of that chromosome then ends.

for example, the tour contained an illegal move when square 50 was visited twice.

3 - 5 - 6 - 1

(50 - 44 - 27 - 33 - 50)

Therefore, the right-most move (1) would be replaced with another legal move. According to our approach must find the legal moves from the current square (33 in this case) from the other seven possible moves. Which the legal moves are the squares, 43 (through move 1) and 18 (through move number 4) and choose the first legal move we found. Therefore, the move to square 18 is chosen (through move 4) and the gene (move 1) is substituted by move 4.

3 - 5 - 6 - 4

Each chromosome is evaluated when an illegal move is encountered in the same manner until the knight can no longer make a legal move.

2. With Heuristic:

We used the same heuristic approach as used in the first paper we mentioned above, but with different encoding.

For each partial solution (chromosome in a generation), when a knight jumps off the board or returns to a previously visited square, a modification with heuristic is applied. We try to replace the move that represents the illegal move with another move that allows the knight to proceed.

Before every move, we examine the squares that can be reached with legal moves from the current square. Then for each of those possible next squares, we count the number of legal moves at that square. The knight then moves to the square with the lowest number of new choices. We repeat for each chromosome until a substitution cannot be made, and the evaluation of that chromosome then ends. In the earlier example, the tour contained an illegal move when square 50 was visited twice

3 - 5 - 6 - 1 ...

(50 - 44 - 27 - 33 - 50)

Therefore, the right-most move (1) would be replaced with another legal move. According to our approach heuristic must find the legal moves from the current square (33 in this case). Which are the squares, 43 (through move 1) and 18 (through move number 4) and choose the square with the lowest number of legal moves. Square 43 has 7 legal moves, while square 18 has 5 legal moves. Therefore, the move to square 18 is

chosen (move 4) and the (move 1) is substituted by the (move 4). (Moves codes were shown in

3 - 5 - 6 - 4 ...

Each chromosome is evaluated when an illegal move is encountered in the same manner until the knight can no longer make a legal move.

3. Experiments & Results

3.1 For backtracking approach :

1. Samples of Applying Warnsdorff's rule

N = 5

```
Printing 1 solution for a starting state that is optimized by Warnsdorff's rule
Enter the size of the chessboard: 5
Enter the starting row: 0
Enter the starting column: 0
[0, 19, 8, 13, 2]
[9, 14, 1, 18, 23]
[15, 10, 5, 24, 17]
[6, 21, 16, 11, 4]
////////////////////
[(0, 0), (1, 2), (0, 4), (2, 3), (4, 4), (3, 2), (4, 0), (2, 1), (0, 2), (1, 0), (3, 1), (4, 3), (2, 4), (0, 3), (1,
1), (3, 0), (4, 2), (3, 4), (1, 3), (0, 1), (2, 0), (4, 1), (2, 2), (1, 4), (3, 3)]
////////////////////
total time : 0.061742305755615234
PS: C:\Users\LEVMQ\OneDrive\Documents\pythonTests\knightTour_Backtracking & C:\Users\LEVMQ\AppData\Local
```

N = 8

```
277 C:\Users\LEVMQ\OneDrive\Documents\pythonTests\knightTour_Backtracking\knightTourBackTracking_Warnsdorff's Rule heuristic.py"
Printing 1 solution for a starting state that is optimized by Warnsdorff's rule
Enter the size of the chessboard: 8
Enter the starting row: 2
Enter the starting column: 2
[22, 1, 18, 33, 40, 37, 16, 35]
[19, 32, 21, 50, 17, 34, 43, 38]
[2, 23, 0, 41, 58, 39, 36, 15]
[31, 20, 49, 28, 51, 42, 57, 44]
[24, 3, 30, 59, 48, 61, 14, 55]
[9, 6, 27, 52, 29, 56, 45, 62]
[4, 25, 8, 11, 60, 47, 54, 13]
[7, 10, 5, 26, 53, 12, 63, 46]
////////////////////
[(2, 2), (0, 1), (2, 0), (4, 1), (6, 0), (7, 2), (5, 1), (7, 0), (6, 2), (5, 0), (7, 1), (6, 3), (7, 5), (6, 7), (4,
6), (2, 7), (0, 6), (1, 4), (0, 2), (1, 0), (3, 1), (1, 2), (0, 0), (2, 1), (4, 0), (6, 1), (7, 3), (5, 2), (3, 3), (
5, 4), (4, 2), (3, 0), (1, 1), (0, 3), (1, 5), (0, 7), (2, 6), (0, 5), (1, 7), (2, 5), (0, 4), (2, 3), (3, 5), (1, 6)
, (3, 7), (5, 6), (7, 7), (6, 5), (4, 4), (3, 2), (1, 3), (3, 4), (5, 3), (7, 4), (6, 6), (4, 7), (5, 5), (3, 6), (2,
4), (4, 3), (6, 4), (4, 5), (5, 7), (7, 6)]
////////////////////
total time : 0.023734569549560547
PS: C:\Users\LEVMQ\OneDrive\Documents\pythonTests\knightTour_Backtracking
```

N = 16

```
knightsTourBackTracking_Warndorff's Rule heuristic.py"
Printing 1 solution for a starting state that is optimized by Warndorff's rule
Enter the size of the chessboard: 16
Enter the starting row: 0
Enter the starting column: 0
[0, 31, 66, 75, 2, 33, 62, 79, 4, 35, 58, 51, 6, 37, 40, 49]
[67, 74, 1, 32, 77, 80, 3, 34, 61, 86, 5, 36, 57, 50, 7, 38]
[30, 65, 76, 81, 108, 63, 78, 85, 100, 59, 92, 87, 52, 39, 48, 41]
[73, 68, 109, 64, 83, 106, 113, 60, 91, 96, 101, 56, 93, 88, 53, 8]
[110, 29, 82, 107, 112, 117, 84, 105, 114, 99, 90, 95, 102, 55, 42, 47]
[69, 72, 111, 118, 145, 142, 115, 160, 97, 104, 163, 186, 89, 94, 9, 54]
[28, 119, 70, 141, 116, 159, 146, 143, 162, 185, 98, 103, 164, 187, 46, 43]
[71, 140, 121, 156, 147, 144, 161, 184, 191, 176, 239, 188, 199, 44, 165, 10]
[120, 27, 148, 179, 158, 155, 192, 177, 240, 189, 198, 175, 244, 167, 200, 45]
[139, 122, 157, 154, 193, 178, 183, 190, 197, 250, 243, 238, 203, 174, 11, 166]
[26, 149, 180, 151, 182, 195, 216, 249, 226, 241, 204, 251, 172, 245, 168, 201]
[123, 138, 153, 194, 215, 220, 225, 196, 253, 248, 237, 242, 231, 202, 173, 12]
[136, 25, 150, 181, 152, 217, 254, 221, 236, 227, 252, 205, 246, 171, 232, 169]
[127, 124, 137, 214, 219, 212, 131, 224, 255, 222, 247, 230, 233, 206, 13, 16]
[24, 135, 126, 129, 22, 133, 218, 211, 20, 235, 228, 209, 18, 15, 170, 207]
[125, 128, 23, 134, 213, 130, 21, 132, 223, 210, 19, 234, 229, 208, 17, 14]
////////////////////////////////
[(0, 0), (1, 2), (0, 4), (1, 6), (0, 8), (1, 10), (0, 12), (1, 14), (3, 15), (5, 14),
```

```
PROBLEMS OUTPUT DEBUG CONSOLE TERMINAL PORTS
////////////////////////////////
[(0, 0), (1, 2), (0, 4), (1, 6), (0, 8), (1, 10), (0, 12), (1, 14), (3, 15), (5, 14), (7, 15), (9, 14), (11, 15), (13,
, 14), (15, 15), (14, 13), (13, 15), (15, 14), (14, 12), (15, 10), (14, 8), (15, 6), (14, 4), (15, 2), (14, 0), (12,
1), (10, 0), (8, 1), (6, 0), (4, 1), (2, 0), (0, 1), (1, 3), (0, 5), (1, 7), (0, 9), (1, 11), (0, 13), (1, 15), (2, 1
3), (0, 14), (2, 15), (4, 14), (6, 15), (7, 13), (8, 15), (6, 14), (4, 15), (2, 14), (0, 15), (1, 13), (0, 11), (2, 1
2), (3, 14), (5, 15), (4, 13), (3, 11), (1, 12), (0, 10), (2, 9), (3, 7), (1, 8), (0, 6), (2, 5), (3, 3), (2, 1), (0,
2), (1, 0), (3, 1), (5, 0), (6, 2), (7, 0), (5, 1), (3, 0), (1, 1), (0, 3), (2, 2), (1, 4), (2, 6), (0, 7), (1, 5),
(2, 3), (4, 2), (3, 4), (4, 6), (2, 7), (1, 9), (2, 11), (3, 13), (5, 12), (4, 10), (3, 8), (2, 10), (3, 12), (5, 13)
, (4, 11), (3, 9), (5, 8), (6, 10), (4, 9), (2, 8), (3, 10), (4, 12), (6, 11), (5, 9), (4, 7), (3, 5), (4, 3), (2, 4)
, (3, 2), (4, 0), (5, 2), (4, 4), (3, 6), (4, 8), (5, 6), (6, 4), (4, 5), (5, 3), (6, 1), (8, 0), (7, 2), (9, 1), (11
, 0), (13, 1), (15, 0), (14, 2), (13, 0), (15, 1), (14, 3), (15, 5), (13, 6), (15, 7), (14, 5), (15, 3), (14, 1), (12
, 0), (13, 2), (11, 1), (9, 0), (7, 1), (6, 3), (5, 5), (6, 7), (7, 5), (5, 4), (6, 6), (7, 4), (8, 2), (10, 1), (12,
2), (10, 3), (12, 4), (11, 2), (9, 3), (8, 5), (7, 3), (9, 2), (8, 4), (6, 5), (5, 7), (7, 6), (6, 8), (5, 10), (6,
12), (7, 14), (9, 15), (8, 13), (10, 14), (12, 15), (14, 14), (12, 13), (10, 12), (11, 14), (9, 13), (8, 11), (7, 9),
(8, 7), (9, 5), (8, 3), (10, 2), (12, 3), (10, 4), (9, 6), (7, 7), (6, 9), (5, 11), (6, 13), (7, 11), (8, 9), (9, 7)
, (7, 8), (8, 6), (9, 4), (11, 3), (10, 5), (11, 7), (9, 8), (8, 10), (7, 12), (8, 14), (10, 15), (11, 13), (9, 12),
(10, 10), (12, 11), (13, 13), (14, 15), (15, 13), (14, 11), (15, 9), (14, 7), (13, 5), (15, 4), (13, 3), (11, 4), (10
, 6), (12, 5), (14, 6), (13, 4), (11, 5), (12, 7), (13, 9), (15, 8), (13, 7), (11, 6), (10, 8), (12, 9), (14, 10), (1
5, 12), (13, 11), (11, 12), (12, 14), (13, 12), (15, 11), (14, 9), (12, 8), (11, 10), (9, 11), (7, 10), (8, 8), (10,
9), (11, 11), (9, 10), (8, 12), (10, 13), (12, 12), (13, 10), (11, 9), (10, 7), (9, 9), (10, 11), (12, 10), (11, 8),
(12, 6), (13, 8)]
////////////////////////////////
total time : 0.04458260536193848
Activate Windows
Go to Settings to activate Windows.
```

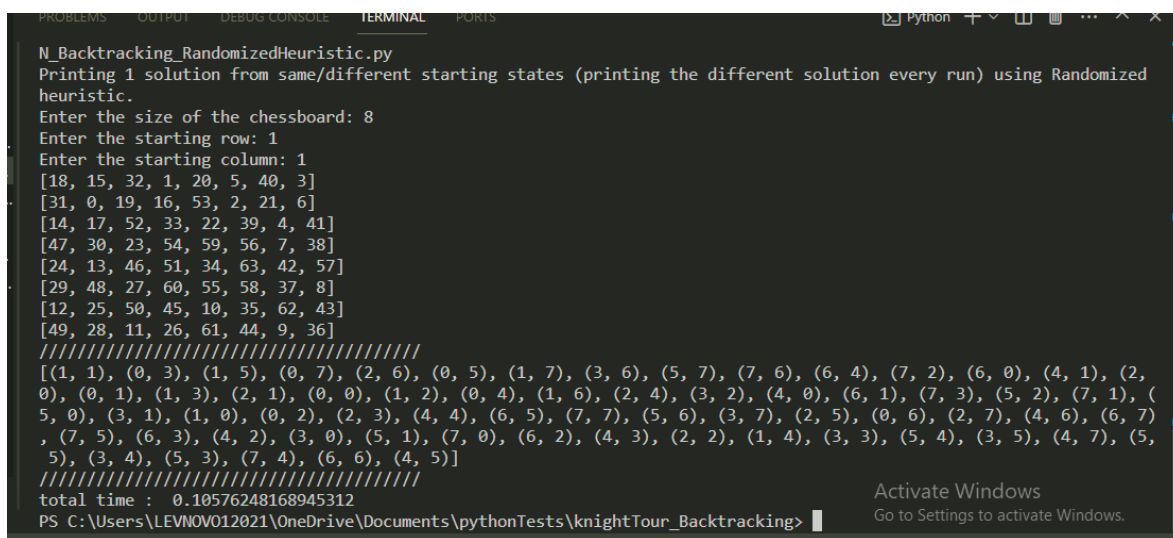
As illustrated in results , by applying Warndorff’s rule it makes the code very
efficient especially for large n boards like n = 16 , it takes 0.044 seconds to get the

optimal solution that decreasing search space and concentrating only on paths (accessible moves) that leads to a solution in shortest time , this achieved by ignoring all paths that leads to a dead end or path that has large accessible moves that takes many time to find optimal solution.

1. Samples of Applying Randomized heuristics (each run it gets another solution in no time):

N = 8 , start state (1 , 1)

The 1st run :



```
N_Backtracking_RandomizedHeuristic.py
Printing 1 solution from same/different starting states (printing the different solution every run) using Randomized heuristic.
Enter the size of the chessboard: 8
Enter the starting row: 1
Enter the starting column: 1
[18, 15, 32, 1, 20, 5, 40, 3]
[31, 0, 19, 16, 53, 2, 21, 6]
[14, 17, 52, 33, 22, 39, 4, 41]
[47, 30, 23, 54, 59, 56, 7, 38]
[24, 13, 46, 51, 34, 63, 42, 57]
[29, 48, 27, 60, 55, 58, 37, 8]
[12, 25, 50, 45, 10, 35, 62, 43]
[49, 28, 11, 26, 61, 44, 9, 36]
////////////////////////////////////
[(1, 1), (0, 3), (1, 5), (0, 7), (2, 6), (0, 5), (1, 7), (3, 6), (5, 7), (7, 6), (6, 4), (7, 2), (6, 0), (4, 1), (2, 0), (0, 1), (1, 3), (2, 1), (0, 0), (1, 2), (0, 4), (1, 6), (2, 4), (3, 2), (4, 0), (6, 1), (7, 3), (5, 2), (7, 1), (5, 0), (3, 1), (1, 0), (0, 2), (2, 3), (4, 4), (6, 5), (7, 7), (5, 6), (3, 7), (2, 5), (0, 6), (2, 7), (4, 6), (6, 7), (7, 5), (6, 3), (4, 2), (3, 0), (5, 1), (7, 0), (6, 2), (4, 3), (2, 2), (1, 4), (3, 3), (5, 4), (3, 5), (4, 7), (5, 5), (3, 4), (5, 3), (7, 4), (6, 6), (4, 5)]
////////////////////////////////////
total time : 0.10576248168945312
PS C:\Users\LEVN0V012021\OneDrive\Documents\pythonTests\knightTour_Backtracking>
```

The 2nd run :

```
N_Backtracking_RandomizedHeuristic.py
Printing 1 solution from same/different starting states (printing the different solution every run) using Randomized
heuristic.
Enter the size of the chessboard: 8
Enter the starting row: 1
Enter the starting column: 1
[28, 25, 14, 47, 18, 23, 12, 49]
[15, 0, 27, 24, 13, 48, 19, 22]
[26, 29, 52, 17, 46, 21, 50, 11]
[1, 16, 33, 62, 51, 58, 45, 20]
[32, 53, 30, 57, 34, 61, 10, 59]
[5, 2, 39, 54, 63, 56, 35, 44]
[40, 31, 4, 7, 42, 37, 60, 9]
[3, 6, 41, 38, 55, 8, 43, 36]
#####
[(1, 1), (3, 0), (5, 1), (7, 0), (6, 2), (5, 0), (7, 1), (6, 3), (7, 5), (6, 7), (4, 6), (2, 7), (0, 6), (1, 4), (0,
2), (1, 0), (3, 1), (2, 3), (0, 4), (1, 6), (3, 7), (2, 5), (1, 7), (0, 5), (1, 3), (0, 1), (2, 0), (1, 2), (0, 0), (
2, 1), (4, 2), (6, 1), (4, 0), (3, 2), (4, 4), (5, 6), (7, 7), (6, 5), (7, 3), (5, 2), (6, 0), (7, 2), (6, 4), (7, 6)
, (5, 7), (3, 6), (2, 4), (0, 3), (1, 5), (0, 7), (2, 6), (3, 4), (2, 2), (4, 1), (5, 3), (7, 4), (5, 5), (4, 3), (3,
5), (4, 7), (6, 6), (4, 5), (3, 3), (5, 4)]
#####
total time : 0.05066847801208496
PS C:\Users\LEVNVOV12021\OneDrive\Documents\pythonTests\knightTour_Backtracking>
```

AS in the results , it gets two different solutions from the same start state , the both solutions found in no time because the randomized heuristic used is optimized by Warndorff's rule to decrease search space that leads to decreasing time and space complexity .

Now you will see the big difference in time taken for Randomized heuristic with and without optimized code :

With using Warndorff's rule (optimization technique for prioritizing next moves and avoid dead end paths):

```
cuments/pythonTests/.venv/Scripts/python.exe
_Backtracking_RandomizedHeuristic.py
Printing 1 solution from same/different start
using Randomized heuristic.
Enter the size of the chessboard: 5
Enter the starting row: 1
Enter the starting column: 1
[20, 5, 16, 11, 18]
[15, 0, 19, 4, 9]
[6, 21, 10, 17, 12]
[1, 14, 23, 8, 3]
[22, 7, 2, 13, 24]
////////////////////////////////////
[(1, 1), (3, 0), (4, 2), (3, 4), (1, 3), (0,
4), (4, 3), (3, 1), (1, 0), (0, 2), (2, 3),
////////////////////////////////////
total time : 0.04704928398132324
○ (.venv) PS C:\Users\LEVNOVO12021\OneDrive\De
```

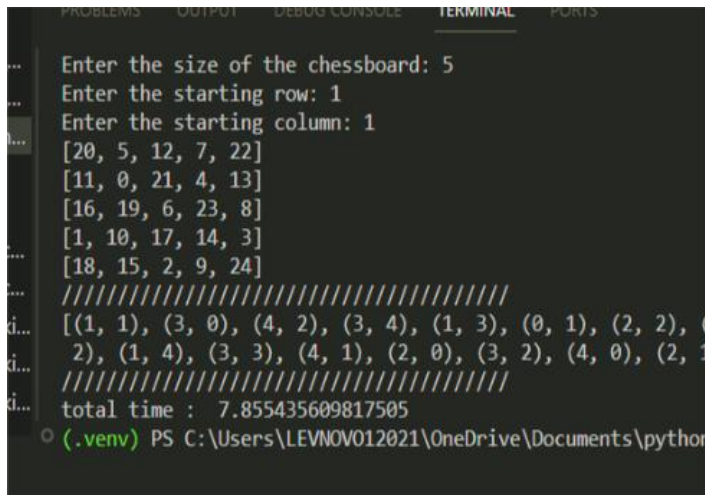


```
cuments/python1ests/.venv/Scripts/python.exe c
_Backtracking_RandomizedHeuristic.py
Printing 1 solution from same/different starti
using Randomized heuristic.
Enter the size of the chessboard: 5
Enter the starting row: 1
Enter the starting column: 1
[24, 15, 6, 1, 18]
[5, 0, 17, 14, 7]
[16, 23, 10, 19, 2]
[11, 4, 21, 8, 13]
[22, 9, 12, 3, 20]
////////////////////////////////////
[(1, 1), (0, 3), (2, 4), (4, 3), (3, 1), (1, 0
2), (3, 4), (1, 3), (0, 1), (2, 0), (1, 2), (
////////////////////////////////////
total time : 0.015612363815307617
(.venv) PS C:\Users\LEVNOV012021\OneDrive\Docu
```

In both runs it gets two different solutions in no time

Without using Warndorff's rule or any optimization technique :

```
PROBLEMS OUTPUT DEBUG CONSOLE TERMINAL POR
using Randomized heuristic.
Enter the size of the chessboard: 5
Enter the starting row: 1
Enter the starting column: 1
[22, 5, 12, 7, 20]
[11, 0, 21, 4, 13]
[16, 23, 6, 19, 8]
[1, 10, 17, 14, 3]
[24, 15, 2, 9, 18]
////////////////////////////////////
[(1, 1), (3, 0), (4, 2), (3, 4), (1, 3), (0, 1)
2), (1, 4), (3, 3), (4, 1), (2, 0), (3, 2), (4
////////////////////////////////////
total time : 5.203878402709961
(.venv) PS C:\Users\LEVNOV012021\OneDrive\Docu
```



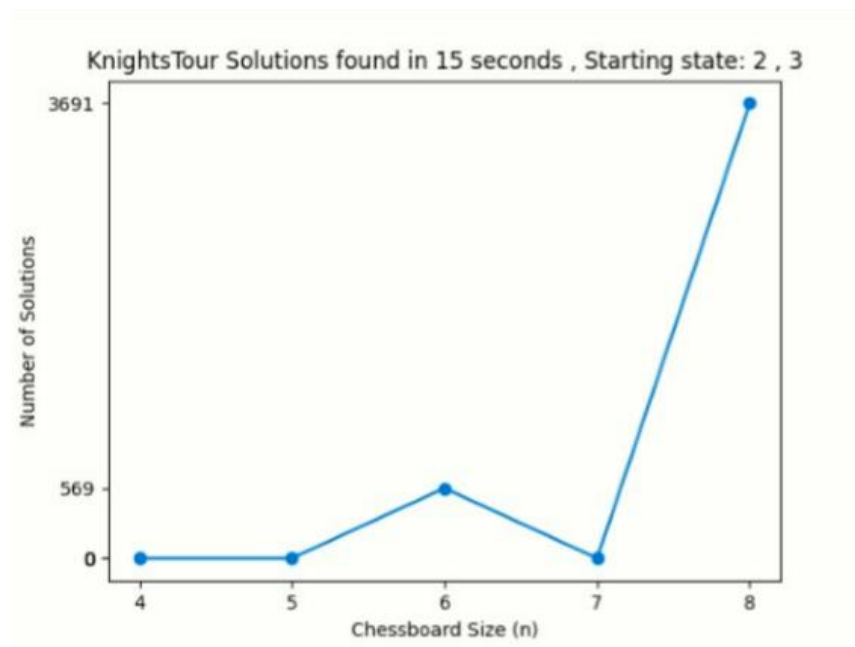
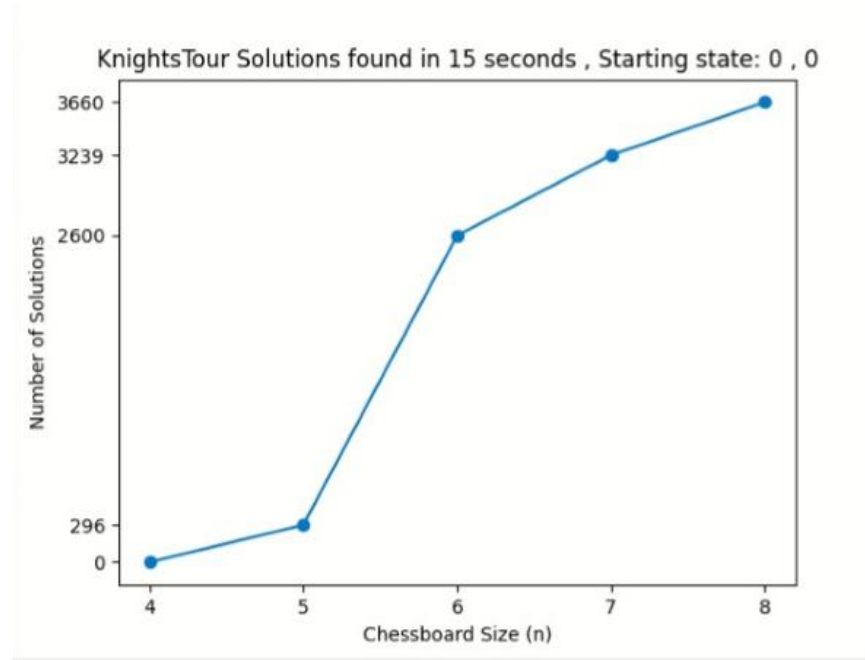
```
... Enter the size of the chessboard: 5
... Enter the starting row: 1
... Enter the starting column: 1
... [20, 5, 12, 7, 22]
... [11, 0, 21, 4, 13]
... [16, 19, 6, 23, 8]
... [1, 10, 17, 14, 3]
... [18, 15, 2, 9, 24]
...
... [1, 1), (3, 0), (4, 2), (3, 4), (1, 3), (0, 1), (2, 2), (
... 2), (1, 4), (3, 3), (4, 1), (2, 0), (3, 2), (4, 0), (2, 1
...
... total time : 7.855435609817505
... (.venv) PS C:\Users\LEVNOV012021\OneDrive\Documents\python
```

3. Plots analysis Using backtracking:

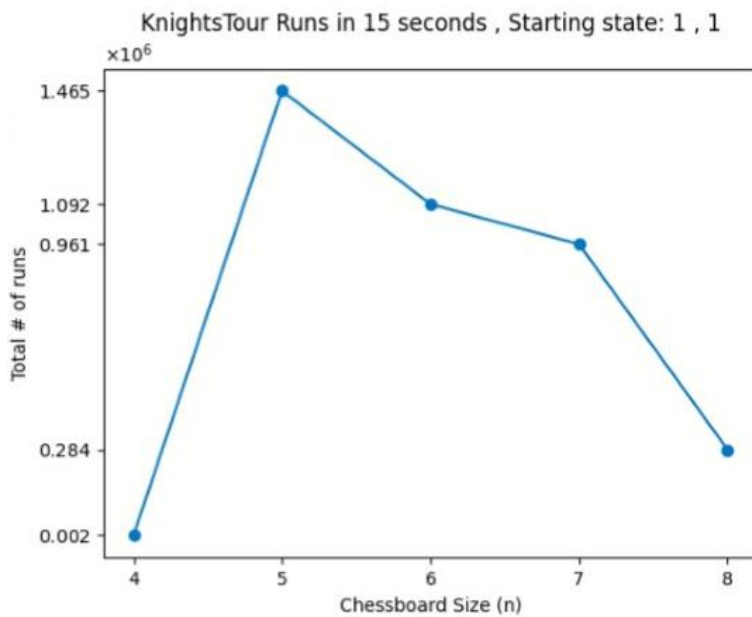
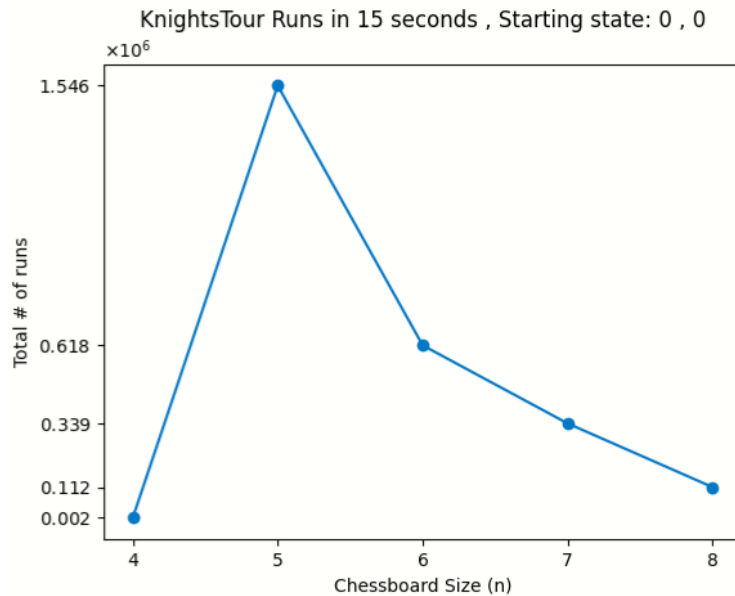
As we want to test the efficiency of algorithms used with backtracking based on (time takes to get the solution for different n sizes and different states and the number of tours (solutions) can get , number of runs for different n sizes and start states too)

1. **Plot Analysis of finding all possible solutions for a specific start state for all $n = \{4, 5, 6, 7, 8\}$**

As the board size increases, the complexity of the search space also increases exponentially. The number of possible moves and paths to explore grows significantly with board size ,
Exploring more solutions increases.

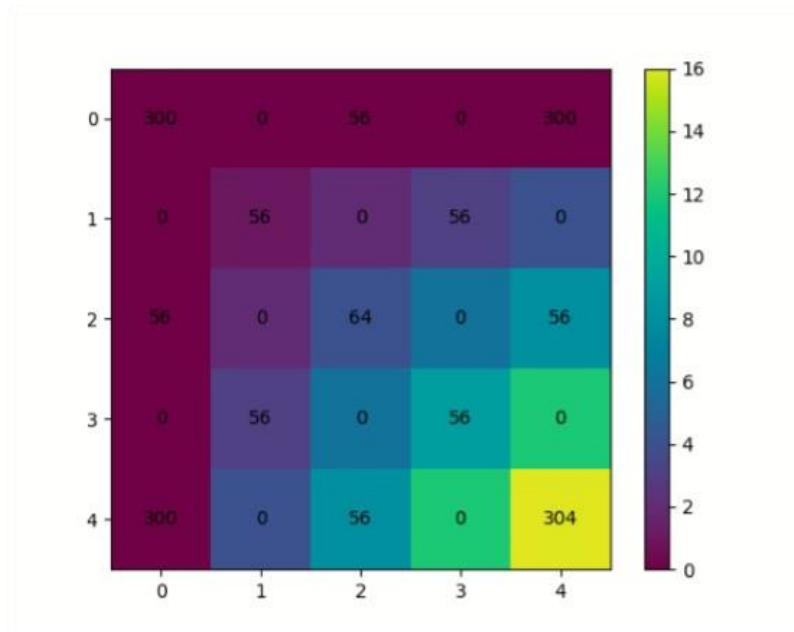


2. Analysis for total number of runs for a specific start state for all n

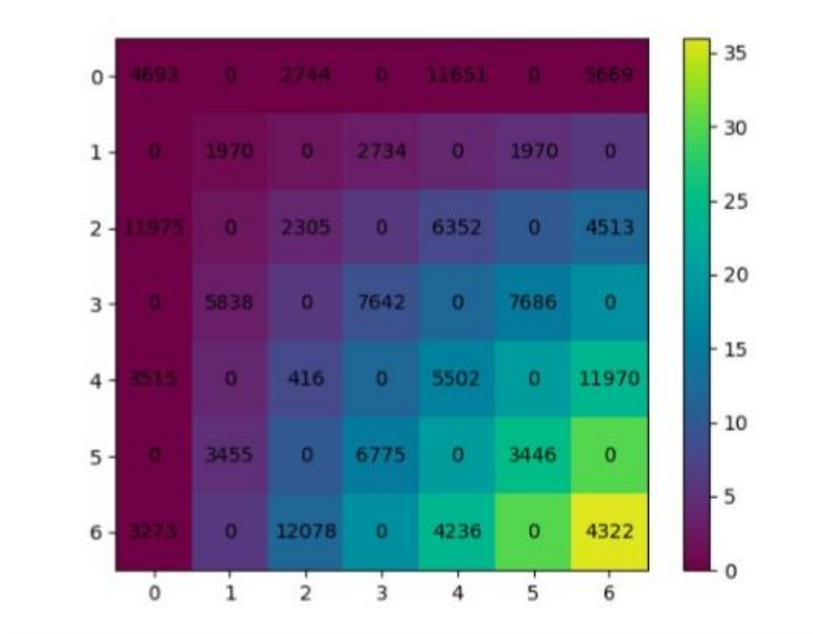


3. Analysis for possible number of solutions can get from (n) in the all states for a time period (15seconds)

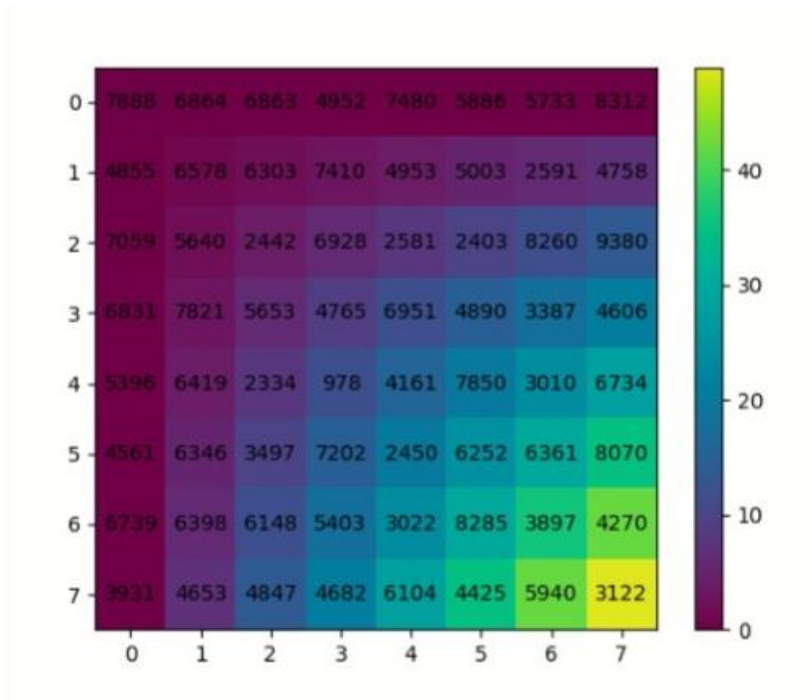
N =5



N = 7

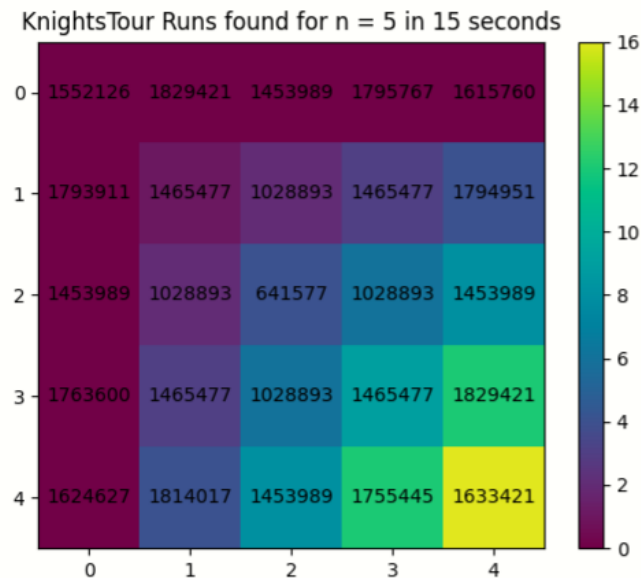


N = 8



4. Analysis for possible number of Runs can get from (n) in the all states for a time period (15seconds)

N = 5



From the two previous analysis of $n = 5$ for both plots (number of solutions and number of runs)you will notice that at state (3,4) the number of solutions = 0 , however the number of runs of the same state is the maximum number compared with all other states , The largest number of runs indicates that the backtracking algorithm attempted various paths or combinations, exploring different possibilities to find a solution, but none of these attempts led to a successful Knight's Tour from the given starting state on a 5x5 chessboard.

4 . Complexity of backtracking approach :

Backtracking is a general algorithmic technique that explores all potential solutions to a computational problem by trying out different choices and undoing those choices when they are found not to lead to a solution.

The time complexity of solving the Knight's Tour problem using a backtracking algorithm is typically high because the search space is quite large.

Let n represent the size of the chessboard (assuming it is an $n \times n$ board). The Knight's Tour problem has an exponential time complexity of approximately $O((n^2)!)^2$ due to the large number of possible move sequences that need to be explored.

But with using optimization techniques as Warndorff's rule that minimized the search space , the complexity become $(k^{(n \times n)})$, as k is the number of accessible moves ,

And there is k number of moves for every state (square) and to find solution must visit all $n \times n$ squares, for that $O(k^{(n \times n)})$ is the complexity after optimization.

3.2 For Genetic Approach :

For testing purposes, the GA parameters were set to common literature values, with a population size of 50, a crossover percentage ranging from 85% to 95%, and a low mutation rate of 0.5%. The GA was run five times for each square, totaling 320 runs for the full board, evaluating 800,000 chromosomes. Results were recorded for each run, and averages were calculated for each square based on the five runs, as well as for all squares based on the 320 runs.

The test results included the total number of distinct tours found and their ratio to the overall tested chromosomes, the maximum and minimum number of tours found in 5 runs of the squares, the average number of tours found per square.

1. GA with Repair

```
The run time was: 127.61244344711304 Sec
[(22, 10), (9, 2), (10, 15), (20, 22), (14, 7), (10, 3), (5, 4), (19, 8)]
[(6, 2), (32, 14), (7, 4), (7, 1), (11, 2), (0, 0), (6, 1), (11, 40)]
[(0, 0), (5, 14), (30, 16), (0, 0), (5, 10), (7, 5), (3, 1), (5, 26)]
[(7, 29), (10, 1), (15, 2), (31, 5), (6, 1), (0, 0), (0, 0), (23, 20)]
[(26, 40), (16, 6), (1, 7), (5, 1), (12, 4), (3, 2), (8, 10), (27, 26)]
[(11, 4), (9, 4), (0, 0), (0, 0), (1, 4), (21, 8), (8, 3), (4, 2)]
[(5, 3), (9, 1), (0, 0), (2, 3), (0, 4), (5, 4), (5, 5), (1, 2)]
[(20, 5), (6, 1), (4, 18), (0, 0), (13, 30), (6, 2), (22, 9), (12, 2)]
```

presents sample results of the GA with repair. Each tuple represents a square, The first value in each tuple represents the average number of generations needed to produce the first tour from that square (average for five runs), while the second value represents the total number of distinct solutions found in the five runs for that square.

```
The number_of_tours: 475
The number_of_evaluation: 800000
Hit Ratio (tours found/evaluated): 0.059375
average # tours found per square: 7
The maximum square: (1, 7) , the number of tours: 40
The minimum square: (1, 5) , the number of tours: 0
```


2 . GA with heuristic

```
The run time was: 224.31919145584106 Sec
[(1, 445), (1, 489), (1, 286), (4, 316), (2, 416), (1, 420), (2, 163), (2, 446)]
[(3, 237), (1, 116), (8, 167), (6, 197), (3, 191), (3, 89), (5, 174), (2, 163)]
[(1, 291), (2, 165), (1, 377), (4, 589), (6, 198), (3, 208), (9, 175), (1, 395)]
[(1, 158), (2, 197), (2, 303), (2, 208), (2, 270), (3, 354), (2, 244), (2, 381)]
[(4, 341), (1, 260), (6, 235), (1, 404), (1, 221), (3, 224), (8, 181), (2, 241)]
[(2, 347), (2, 179), (1, 316), (1, 259), (5, 204), (6, 134), (3, 285), (3, 191)]
[(2, 282), (8, 162), (5, 119), (3, 244), (1, 238), (4, 261), (7, 273), (2, 247)]
[(1, 420), (1, 366), (1, 276), (1, 343), (1, 282), (2, 431), (3, 197), (1, 783)]
```

presents sample results of the GA with heuristic. Each tuple represents a square, The first value in each tuple represents the average number of generations needed to produce the first tour from that square (average for five runs), while the second value represents the total number of distinct solutions found in the five runs for that square.

```
The number_of_tours: 17774
The number_of_evaluation: 800000
Hit Ratio (tours found/evaluated): 2.22175
average # tours found per square: 277
The maximum square: (7, 7) , the number of tours: 783
The minimum square: (1, 5) , the number of tours: 89
```

3. Analysis using N = 16 (Heuristic)

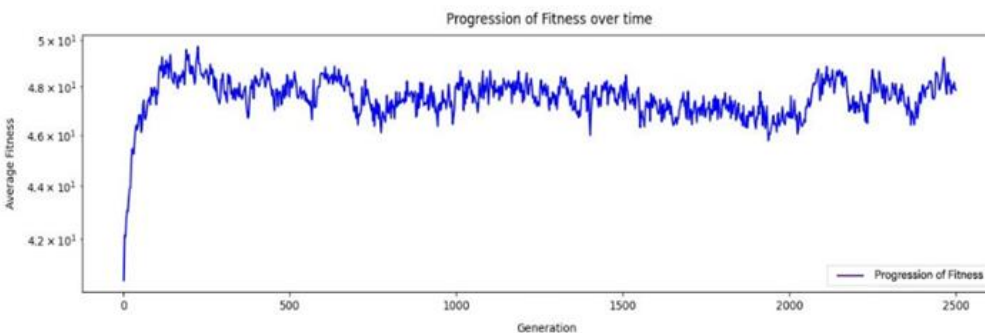
[illegible]

```
The number_of_tours: 8
The number_of_evaluation: 3200000
Hit Ratio (tours found/evaluated): 0.00025
average # tours found per square: 0
The maximum square: (1, 7) , the number of tours: 3
The minimum square: (0, 0) , the number of tours: 0
```

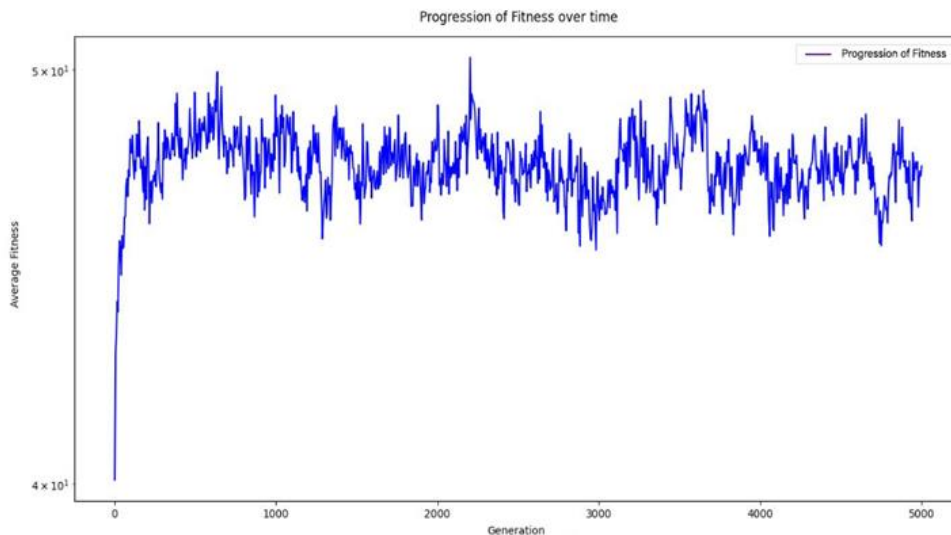
4. Plots for analysis of Genetic algorithm

We need to study the relationship between the fitness values and the number of generation over time , so we made the following plots :

GA with heuristic and N =8 and Generation = 2500 , population size = 1000



GA with heuristic and N =8 and Generation = 5000



Then we assumed that:

The graph displays progressive fitness over time, with a blue line showing the fitness level. The line starts at a lower point, indicating a lower fitness level, and gradually increases over time, indicating an improvement in fitness.

The graph shows a progressive increase in fitness over generations. The convergence of the plot indicates that the organisms are reaching a common optimal point due to natural selection. This suggests that the organisms with higher fitness levels are more likely to survive and reproduce, leading to an overall improvement in fitness levels.

5. Complexity of Genetic approach:

Genetic Algorithms are not chaotic; they are stochastic. The complexity is influenced by the genetic operators, their implementation (which can significantly impact overall complexity), the representation of individuals and the population, and, of course, the fitness function. Using common choices such as point mutation, one-point crossover, and roulette wheel selection, the complexity of a Genetic Algorithm can be expressed as $O(g(nm + nm + n))$, where g is the number of generations, n is the population size, and m is the size of the individuals. Therefore, the complexity is approximately $O(gnm)$. This analysis does not account for the fitness function, which varies based on the specific application.

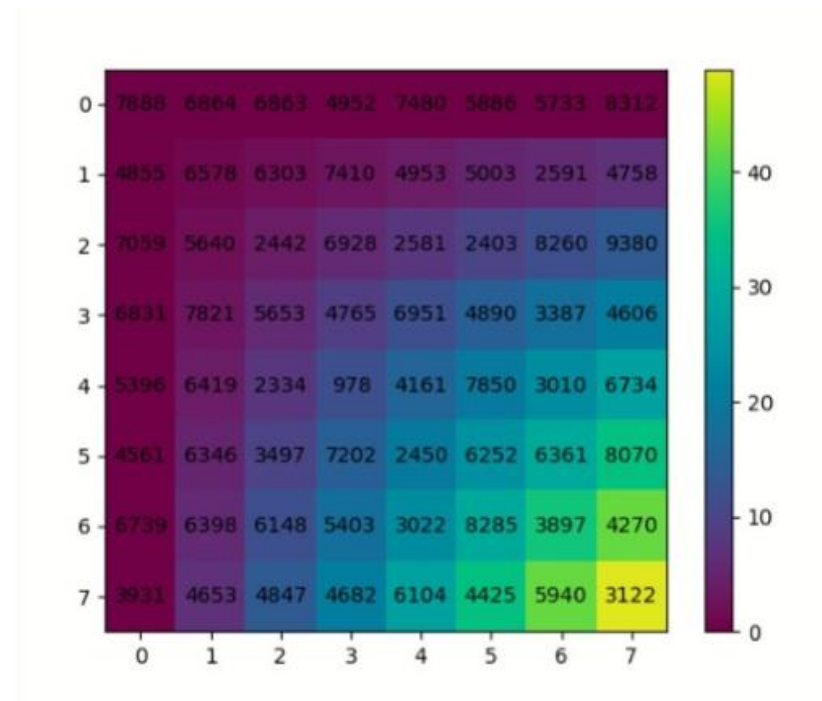
4. Comparison between two used approaches (Backtracking and Genetic)

- Backtracking is suitable for small or moderately sized Knight's Tour problems where complete exploration of the solution space is feasible, Genetic algorithms may be more appropriate for larger Knight's Tour instances.
- If a guaranteed optimal solution is required, backtracking is preferred for the Knight's Tour, Genetic algorithms are suitable when a good heuristic solution is acceptable, and optimality is not strictly necessary.
- Backtracking is effective for the well-defined structure of the Knight's Tour problem with clear decision points, Genetic algorithms are versatile and can handle the complexity of the Knight's Tour problem's solution space.
- Backtracking aims for optimality but may be computationally expensive for larger Knight's Tour instances, Genetic algorithms focus on efficiency and can quickly converge to good solutions for the Knight's Tour but may not guarantee optimality.
- **If we want to see real comparison for both approaches ?**

```
The run time was: 224.31919145584106 Sec
[(1, 445), (1, 489), (1, 286), (4, 316), (2, 416), (1, 420), (2, 163), (2, 446)]
[(3, 237), (1, 116), (8, 167), (6, 197), (3, 191), (3, 89), (5, 174), (2, 163)]
[(1, 291), (2, 165), (1, 377), (4, 589), (6, 198), (3, 208), (9, 175), (1, 395)]
[(1, 158), (2, 197), (2, 303), (2, 208), (2, 270), (3, 354), (2, 244), (2, 381)]
[(4, 341), (1, 260), (6, 235), (1, 404), (1, 221), (3, 224), (8, 181), (2, 241)]
[(2, 347), (2, 179), (1, 316), (1, 259), (5, 204), (6, 134), (3, 285), (3, 191)]
[(2, 282), (8, 162), (5, 119), (3, 244), (1, 238), (4, 261), (7, 273), (2, 247)]
[(1, 420), (1, 366), (1, 276), (1, 343), (1, 282), (2, 431), (3, 197), (1, 783)]
```

This represents the average number of generations needed to produce the first tour from that square (average for five runs), while the second value represents the total number of distinct solutions found in the five runs for that square for 8*8 board

VS



The backtracking approach that represents the number of solutions found for every state(square) in 15 seconds.

Criteria	Genetic algorithm	Backtracking algorithm
----------	-------------------	------------------------

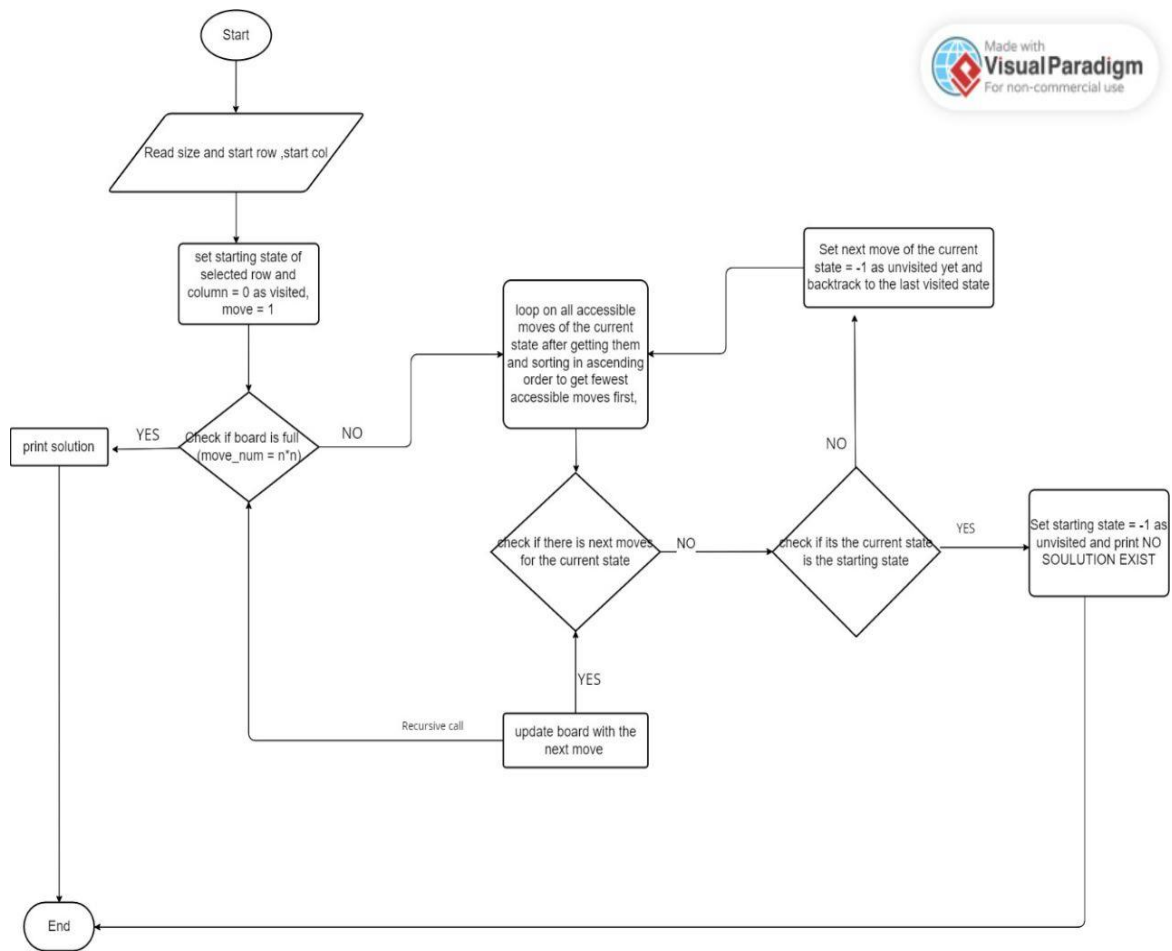
Quality of solution (n = 8)	Good	Optimal
Time to find first solution	longer	shorter
Number of solutions found	multiple	single

Conclusion : as illustrated how backtracking represents larger number of solutions for each state than genetic in short time , for optimal solutions in a short running time backtracking is recommended , while if you focus on efficiency and algorithm that can quickly converge to good solutions so Genetic algorithm is your choice .

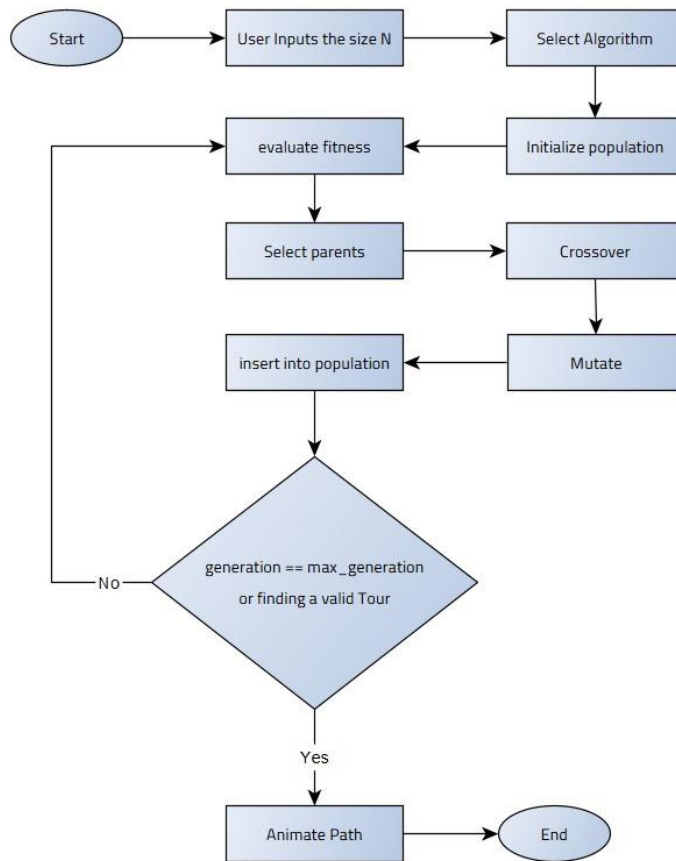
5 . Diagrams

1. Flowcharts

Backtracking

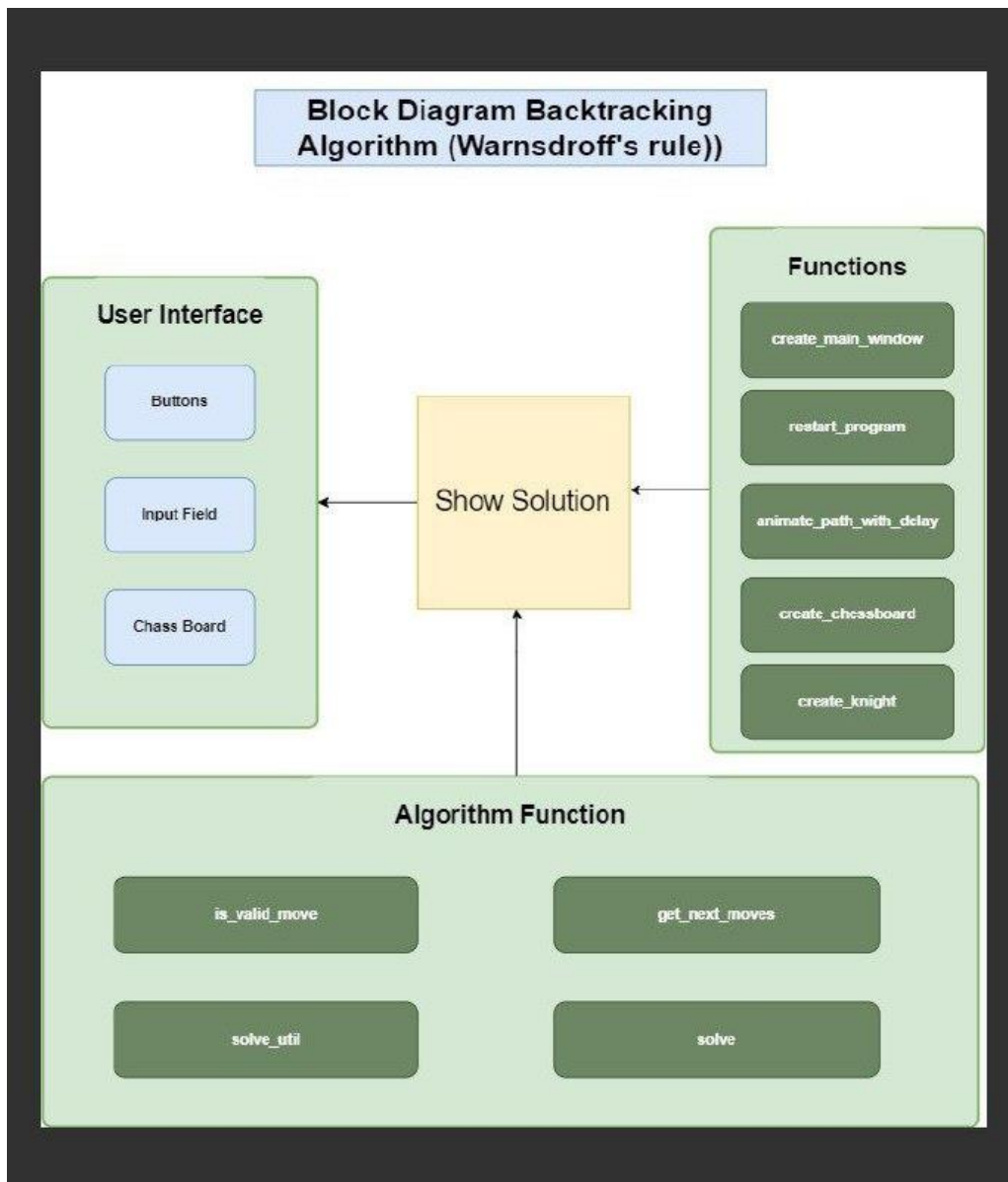


Genetic flowchart :

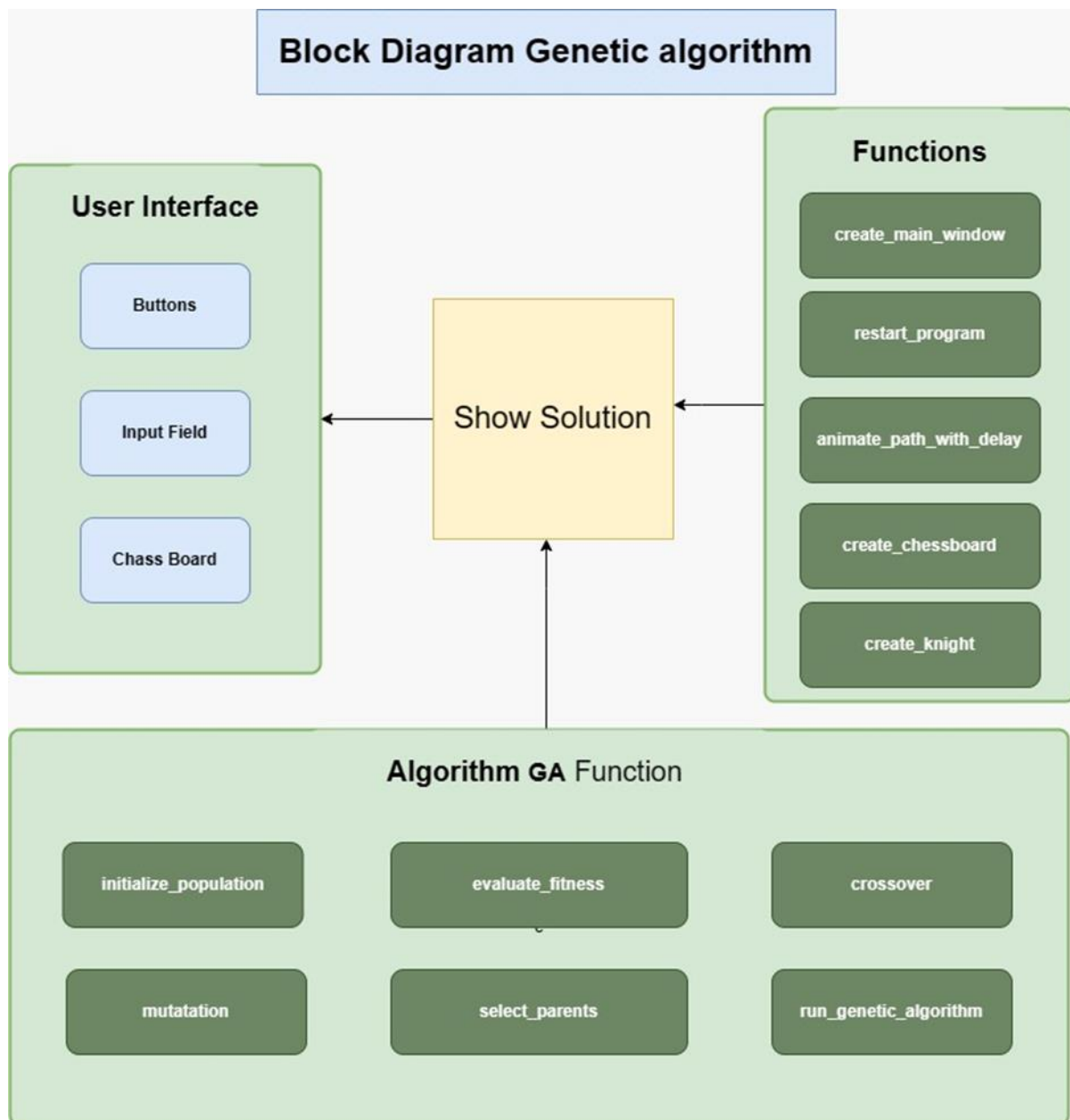


2.Block diagram

Backtracking :



Block diagram Genetic:



3. Use case diagram

