CS 40: Interfaces, Implementations, and Images (iii)

Check the course calendar for due dates. Your design submission, described in Part E: Designing Function Contracts, is due prior to your code submission.

Please read the entire assignment before starting work.

Contents

1	Purpose	2
2	Preliminaries	2
3	Part A: Two-Dimensional, Polymorphic, Unboxed Arrays	2
	Helper Code	3
	Hints	4
4	Part B: Two-Dimensional Arrays of Bits	5
	Helper Code	5
	Hints	5
5	Part C: Using UArray2 to identify Sudoku solutions	5
	Background: Programs as Predicates	5
	The Problem	6
6	Part D: Using Bit2 to remove black edges	7
	Hints	8
7	Part E: Designing Function Contracts	9
8	Organizing and submitting your solutions	9
	8.1 Submitting your design document	9
	8.2 Submitting your completed code	9

1 Purpose

This assignment has five goals:

- 1. To spur you to think more deeply about programming technique.
- 2. To give you practice designing your own interfaces, not just using interfaces designed by other people.
- 3. To give you practice thinking about what familiar algorithms and data structures you can use to solve new problems.
- 4. To build a set of abstractions that will help you represent and manipulate digital images on this and future assignments.
- 5. To lay a foundation for future assignments. In these future assignments:
 - You will learn about *locality*, its effects on performance, and how to change a program's locality.
 - You will understand how data structures in a high-level language map to machine structures, and how to improve space performance by programming directly with machine structures.
 - You will learn to improve the performance of programs by code tuning.

2 Preliminaries

- In Hanson's *C Interfaces and Implementations*, refresh your memory about exceptions (Section 4.1) and memory management (Section 5.1). Study the Bit abstraction defined in Chapter 13 and the UArray abstraction defined in the Hanson supplemental chapter.
- From wherever you intend to work, issue:

You should now have two .c files and two executables. These are discussed below.

• You should also now have a Makefile that's used in a manner similar to the one we gave you for HW1, but that has targets for the code you will build in this assignment. The style of this Makefile is a little different, but all the key concepts are the same; indeed, this Makefile also introduces a few interesting new features of make.

3 Part A: Two-Dimensional, Polymorphic, Unboxed Arrays

In the Hanson supplemental chapter, Dave Hanson and Norman Ramsey provide an abstraction that implements unboxed one-dimensional arrays. For this part of the assignment, you'll adapt the unboxed-array abstraction to support *two*-dimensional arrays. Your adaptation will be called UArray2 and should define the type UArray2_T. Your adaptation should include the following changes when compared to the original UArray interface:

- Instead of a length, a UArray2_T will have a width and a height.
- Instead of being identified by a single index, an element of a UArray2_T will be identified by two indices: the column or x index measures the distance between the element and the left edge of the array, while the row or y index measures the distance between the element and the top row of the array. Thus the top left element is always indexed by the pair (0, 0).
- Omit the resize and copy operations.
- You must define two analogs of the Bit_map function described on Hanson page 201:
 - UArray2_map_row_major calls an apply function for each element in the array. Column indices vary more rapidly than row indices.

UArray2_map_col_major calls an apply function for each element in the array. Row indices vary
more rapidly than column indices.

The terms "row major" and "column major" may be found in Bryant and O'Halloran as well as on Wikipedia.

As in Hanson's code, an out of bounds reference or a failure to successfully allocate needed memory should result in a checked run-time error. You must also follow Hanson's conventions, e.g., that Hanson's abstract type name (UArray2_T in this case) denotes a pointer.

It is **not acceptable** to clone and modify Hanson's implementation. Your new code should be a *client* of Hanson's existing code, and you should rely on Hanson to do the heavy lifting as much as possible.

For Part A, the problem you are to solve is **define an interface and build an implementation** for UArray2. This file **must be self-contained**, i.e. it must all be contained in **uarray2.c**. Do not create separate files for any helper functions you might create. Richard Townsend's solution to this problem takes about 120 lines of C code (for both the interface and implementation combined).

Helper Code

We want you to have the experience of creating and implementing an interface, but we want to be sure the interface you create is at least reasonably close to what we're expecting. To help you get this right, we are giving you some tools to help you understand what's expected and to do some simple testing of your results.

When you pull the starter code (as instructed in Section 2) you will get two files relating to UArray2s:

- 1. useuarray2.c: this is the source to a C program that uses a UArray2 implementation. Specifically, it does a #include "uarray2.h" and calls most of the methods in the interface.
- 2. correct_useuarray2: this is an executable program that is built from the .c program, but it's linked with our "correct" implementation of Uarray2. So, you can see what a correct implementation of Uarray2 does.

You can do some interesting things with the the .c source. The key is that when you build *your* uarray2.h and uarray2.c, link them with the .o resulting from useuarray2.c, and run the result *you should produce* the same output as correct_useuarray2. Knowing that, here are some things to consider doing:

- Carefully read and figure out what useuarray2.c is doing. It's not an otherwise useful or sensible program, but it's designed to make clear certain characteristics required of your Uarray2 interface and implementation. The code is intentionally not heavily commented, as figuring things out from the code itself is part of the exercise. Of course, you'll want to compare the source with the output.
- When you think you've got a good uarray2.h, use the Makefile to try compiling useuarray2.c with your .h file to produce a .o file. If the compile doesn't work, your .h file has a problem.
- After you build your own uarray2.c (which is your implementation of the 2D array), use the Makefile to build my_useuarray2. You can do this by issuing the command:

make my_useuarray2

This will take the .o file you got in the step above and link it with *your* uarray2.o to produce an executable. If your code needs additional modules to run then you will need to modify the Makefile, but if you just need uarray2.o what we supply should work.

• Now, run your executable. If the output doesn't exactly match what's produced by correct_useuarray2 then you surely have a problem in your implementation. Hint: use file redirection and the Linux diff command for this. Use the man command to find out about diff if you need a refresher.

Note: useuarray2.c is *not* designed as a comprehensive test program, though it does some very helpful limited testing. Writing good test code is your job. You are welcome to make a copy of useuarray2.c and hack it up to make better test programs. Indeed, one of the reasons the actual logic in that source looks a little odd and arbitrary is that we did not want to hand you a complete test framework. So, it includes just enough to highlight some features of the interface.

The my_useuarray2 program should compile and run properly before you submit your work.

Hints

• The key to this problem is to set up an implementation in which the elements of your two-dimensional array are in one-to-one correspondence with elements of one or more one-dimensional UArray_T's. The key question to answer is

How do you relate each element in a two-dimensional array to a corresponding element in some one-dimensional array?

Having a precise answer to this question will set you up for success. If your answer is not precise, it's easy to get lost chasing pointers.

- Representation is the essence of programming! Your major design decision will be how to represent a UArray2_T (and a Bit2_T, which is described in the following section). Two obvious alternatives, both of which are acceptable, are:
 - To represent a UArray2_T as an array of UArray_T's.
 - To represent a UArray2_T as a single UArray_T.
- The indices into a two-dimensional array, regardless of how you name them (e.g., "x and y" or "column and row" or anything else), are always both integers. When passing them in the wrong order to a function, however, the compiler will not catch the error. A common mistake is to use different orderings in different parts of your code. Choose **one ordering** and use it *consistently* in all your code. Consistent use of the names "row" and "col" will also tend to reduce mistakes compared to use of single-letter names. It will also make your program clearer to your readers/graders.
- Don't worry about performance; aim for simplicity. If you feel compelled to worry about performance, you may make simple code improvements provided you *justify* them. Don't try anything radical; premature optimization is the root of much evil.
- Think carefully about what should be the prototype for the apply function passed to the functions UArray2_map_col_major and UArray2_map_row_major.
- The pixels in a portable gray map are stored in row-major order, so one way to test your UArray2 mapping functions is to write a simple program that reads and writes a graymap by calling the UArray2_map_row_major function with an argument that calls Pnmrdr_get from the Pnmrdr interface. If you compare results with diff -bu you should be able to get the same output as pnmtopnm -plain. If you read with UArray2_map_col_major and write with UArray2_map_row_major, you should be able to duplicate the effect of pamflip -transpose.
- Think about other ways of putting data into your array that will make it easy to tell whether your implementation is working as intended. Sometimes, putting in some temporary debugging output can be helpful too.
- When working with void pointers, it's easy to get confused about the correct number of levels of indirection. **Draw diagrams**.

Your life will be much easier if you follow the programming idioms for Hanson's UArray_Ts, which deal with most of these issues.

4 Part B: Two-Dimensional Arrays of Bits

In some cases, particularly for documents scanned at high resolution, it can be useful to represent an image as an array of bits. To save space, it is useful to have a *packed* representation of such images. The pbm format provides this style of representation but (ANNOYINGLY) takes the "opposite" approach to the pgm format you experienced in HW1: in pgm, black is represented as 0 and white is some maximum value; in pbm (which is what you'll be using in Section 6), black is represented as 1 and white is represented as 0.

For this part of the assignment, you'll design Bit2: an interface to support two-dimensional arrays of bits.

Helper Code

We supply helper code for Bit2 that's equivalent in function and intent to what you used above for UArray2. Adapt the instructions in the obvious way.

Hints

- Your interface should be very, very similar to your UArray2 interface, with one possible exception: because it is not possible to create a pointer to a single bit, you cannot use the at idea; your only option is an interface like the Bit interface, which exports put and get.
- Your interface should include row-major and column-major mapping operations.
- Your interface should not contain anything analogous to the set operations in Chapter 13. These operations are quite useful when considering a one-dimensional bit vector as a set, but it is rare to require set operations over integer pairs. Indeed, the most useful transformations and computations over two-dimensional bitmaps involve an operator called "bit blit." Google and Wikipedia are fine sources for this operator, but if you are curious you will find a marvelous collection of simple transformations in a classic article by Guibas and Stolfi (Note that Tufts students have free access to ACM articles). There is no need to implement any of these transformations.
- You should provide for checked runtime errors in the cases equivalent to those allowed for UArray2.

For part B, the problem you are to solve is **define an interface and build an implementation** for Bit2. Similar to UArray2, Bit2 must be self-contained. Richard Townsend's solution to this problem takes about 110 lines of C code.

5 Part C: Using UArray2 to identify Sudoku solutions

Background: Programs as Predicates

You have seen that C (and C++) programs produce a value, i.e., they return a value to the operating system either by returning from main or by calling exit. (Either method of terminating the program will be considered "exiting the program.") A value of 0 indicates success (think "no problem"). Any other value is considered an error indication. Programs can use non-zero return codes, aka exit codes, to indicate what went wrong.

Happy families are all alike; every unhappy family is unhappy in its own way.

—Leo Tolstoy, Anna Karenina

Fun fact: You can find out the return code of the last program you ran in the shell by typing echo \$?

You've seen that C provides the names EXIT_SUCCESS and EXIT_FAILURE (via stdlib.h), defined to be 0 and 1, respectively, to be used as a clearer indication of the intent of the exit codes.

Thus, we can write entire programs that function as *predicates*; they result in a true or false indication. A program that *succeeds* (exits with a code of EXIT_SUCCESS, aka 0) is treated as *true*; a program that *fails* (exits a non-zero code like EXIT_FAILURE) is treated as *false*. That's right — 0 means true!

The following bash shell program prints Hurray! if, for example, foo.c contains the word "struct" and Aww... otherwise:

```
if grep struct *.c >& /dev/null
then
    echo 'Hurray!'
else
    echo 'Aww...'
fi
```

The command grep struct *.c >& /dev/null succeeds (with an exit code of 0) if it finds the string "struct" in any of the C source files in the current directory. grep fails (returns a non-zero code) if it doesn't find the string. (There are different codes depending on whether it was actually able to search the file or not; the file may not exist or the permissions may not permit grep to read the contents.) The output redirection throws away both standard output and standard error because, in this example, we don't want to see the result; we just want to know whether the string is there.

The Problem

Write the test program sudoku, which functions as a predicate. The syntax of the sudoku command is:

```
./sudoku [ filename ]
```

where filename is the (optional) name of an input graymap file; if there is no filename argument, input data is on standard input.

We define *correct* input as a single portable graymap (i.e., pgm) file. If the input is not *correct*, your program should terminate with a checked run-time error (any one will do). Otherwise, if the input is *correct*, your program must not print anything, but:

- If the graymap file represents a solved sudoku puzzle, your program must exit with EXIT_SUCCESS (i. e., a code of 0).
- Otherwise it must exit with EXIT_FAILURE (i. e., a code of 1).

(You may define your own constants for the values 0 and 1 if you have clearer names for them.)

A solved sudoku puzzle is a nine-by-nine graymap with these properties:

- The maximum pixel intensity (aka the denominator for scaled integers) is nine.
- No pixel has zero intensity.
- In each row, no two pixels have the same intensity.
- In each column, no two pixels have the same intensity.
- If the nine-by-nine graymap is divided into nine three-by-three submaps (like a tic-tac-toe board), in each three-by-three submap, no two pixels have the same intensity.

Here's an example (which you can also view as an image):

```
P2
9 9
# portable graymap representing a sudoku solution
1 2 3
        4 5 6
                 7 8 9
4 5 6
        7 8 9
                 1 2 3
7 8 9
        1 2 3
                 4 5 6
2 3 4
        5 6 7
                 8 9 1
5 6 7
                 2 3 4
        8 9 1
8 9 1
        2 3 4
                 5 6 7
                 9 1 2
3 4 5
        6 7 8
6 7 8
        9 1 2
                 3 4 5
9 1 2
        3 4 5
                 6 7 8
```

Norman Ramsey's solution to this problem takes about 120 lines of C code. There is a significant opportunity for abstraction; a Very Good solution will identify such opportunities and use them to avoid repeating code.

6 Part D: Using Bit2 to remove black edges

Write the program unblackedges, which removes black edges from a scanned image. The program takes at most one argument:

- If an argument is given, it should be the name of a portable bitmap file (in pbm format; remember the difference from pgm discussed in Section 4?).
- If no argument is given, unblackedges reads from standard input, which should contain a portable bitmap.
- If more than one argument is given, or if a portable bitmap is promised but not delivered, or if the supplied bitmap has a width and/or height of 0, unblackedges should either raise a Checked Runtime Error (using Hanson assertions or a Hanson Exception) OR halt with some sort of error message (on stderr) and terminate with a return value of EXIT_FAILURE.

The program unblackedges should print, on standard output, a plain (P1) format portable bitmap file which has width, height and pixel values identical to the original file except that all *black edge pixels* are changed to white. You may note that PBM allows a comment field on the line after the P1 code; feel free to put a comment of your choice into the comment field of the output file if you like.

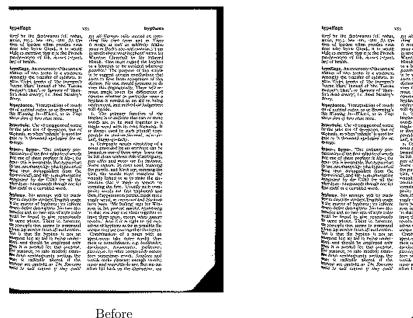
You can find some sample images in /comp/40/bin/images/bitonal. Try, for example,

```
pngtopnm /comp/40/bin/images/bitonal/hyphen.png | ./unblackedges | display -
```

Here's an example of removing black edges from a scanned image:

For a bitmap of size w by h, a black edge pixel is defined inductively as follows:

- A pixel is a black edge pixel if it is black and if it appears in column 0, in row 0, in column w 1, or in row h 1.
- A pixel that appears in column c, row r is a black edge pixel if it is black, if c > 0 and c < w 1, if r > 0 and r < h 1, and any neighboring pixel is a black edge pixel.



After

- The neighboring pixels of the pixel in column c, row r are
 - The pixel in column c 1, row r
 - The pixel in column c + 1, row r
 - The pixel in column c, row r 1
 - The pixel in column c, row r + 1

Norman Ramsey's solution to this problem takes about 110 lines of C code for the main problem, plus about 40 lines of code that could be reused for other problems. John Dias suggested an even simpler solution that requires less than 70 lines of code for the main part, and John's solution runs 30% faster.

Hints

- Your solution is expected to scale to images of reasonably large size and complexity. However, the Halligan servers impose a strict and unusually low limit on the size of the stack allotted to any given program. Think carefully about perfectly reasonable strategies that this limit might preclude.
- You may find it useful to define auxiliary functions with these prototypes:

```
Bit2_T pbmread (FILE *inputfp);
       pbmwrite(FILE *outputfp, Bit2_T bitmap);
```

You can read or write pixels using an explicit loop or a row-major mapping function. To learn the correct output format for a PBM file, run

```
man 5 pbm
```

and look for the "plain" format described at the bottom of the page. NOTE: programs like display may be forgiving of some errors when displaying PBM files, but your output is required to be correct per the man page. Make sure that your output conforms to all the rules or you may lose credit for all of your results.

- There is at least one opportunity to exploit one of your map functions.
- If you find yourself in difficulty, try writing a simpler program that merely inverts the image in a bitmap (change white to black and vice versa).

7 Part E: Designing Function Contracts

Your filesofpix design process focused on architecture, implementation, and testing. These are still important elements to consider in this assignment. For example, if you seek help from a TA, you must be able to clearly describe the representation you are using for your 2-dimensional array and your testing plan. However, your design *submission* for iii will focus on a new aspect of design: function contracts.

A good function contract is comprised of two parts. The first is a brief (1–2 sentence) description of what your function does. For example, the **readaline** function in your **filesofpix** submission might be described as: "Reads one line of text from the file specified in the first parameter into the character buffer supplied by the second parameter."

The second part of your function contract lists the logical expectations of your function's input and output. These are expectations that the compiler cannot verify, and thus you must ensure that they are met. Often, each of these expectations will translate into an assert statement in your code. For example, one of the expectations of readaline is that the first parameter, inputfd, is non-null. This would translate to the following assert statement:

```
assert(inputfd != NULL);
```

For this design submission, you will submit your two interfaces, uarray2.h and bit2.h (that is, the text from these two files should be copied, as is, into your design document). The uarray2.h interface you submit should specify function contracts for *every* function in that interface; the bit2.h interface does not need to provide them.

8 Organizing and submitting your solutions

8.1 Submitting your design document

Your document should be a pdf file named design.pdf. You will submit your document via Gradescope. Again, the submission process will be comprised of two steps:

- Choose the assignment "iii" and upload your document
- Indicate the partner that you worked with

8.2 Submitting your completed code

- In your final submission, don't forget to include a README file which:
 - Identifies you and your programming partner by name
 - Acknowledges help you may have received from or collaborative work you may have undertaken with classmates, programming partners, course staff, or others
 - Identifies what has been correctly implemented and what has not
 - Says approximately how many hours you have spent completing the assignment
- Your submission should include at least these files:

README Makefile uarray2.h uarray2.c bit2.h
bit2.c
sudoku.c
unblackedges.c

• When you get everything working, cd into the directory contianing your submission and type submit40-iii to submit your work.