# Unsupervised Learning: Dimension Reduction

Industrial AI Lab.

#### **Dimension Reduction**

- Motivation:
  - Can we describe high-dimensional data in a "simpler" way?
- → Dimension reduction without losing too much information
- →Find a low-dimensional, yet useful representation of the data

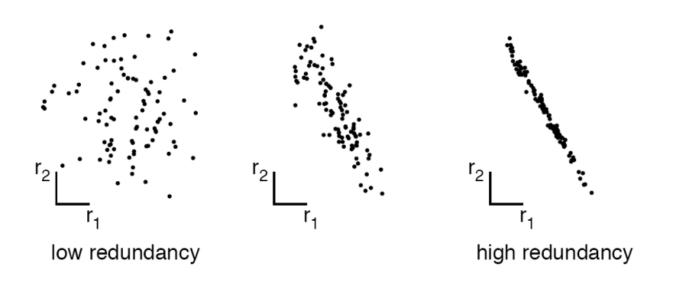
#### **Dimension Reduction**

- Why dimensionality reduction?
  - insights into the low-dimensional structures in the data (visualization)
  - Fewer dimensions  $\Rightarrow$  Less chances of overfitting  $\Rightarrow$  Better generalization
  - Speeding up learning algorithms
    - Most algorithms scale badly with increasing data dimensionality
  - Less storage requirements (data compression)
  - Note: Dimensionality Reduction is different from Feature Selection
    - ... although the goals are kind of the same
  - Dimensionality reduction is more like "Feature Extraction"
    - Constructing a small set of new features from the original features

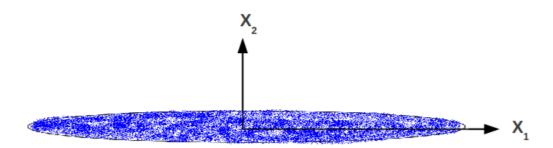
## **Highly Correlated Data**

• How?

idea: highly correlated data contains redundant features

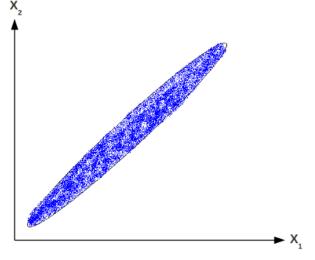


- Each example x has 2 features  $\{x_1, x_2\}$
- Consider ignoring the feature  $x_2$  for each example
- Each 2-dimensional example x now becomes 1-dimensional  $x = \{x_1\}$
- Are we losing much information by throwing away  $x_2$ ?
- No. Most of the data spread is along  $x_1$  (very little variance along  $x_2$ )

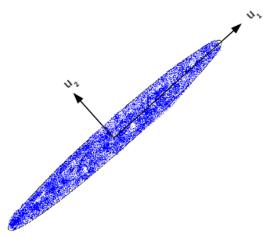


- Each example x has 2 features  $\{x_1, x_2\}$
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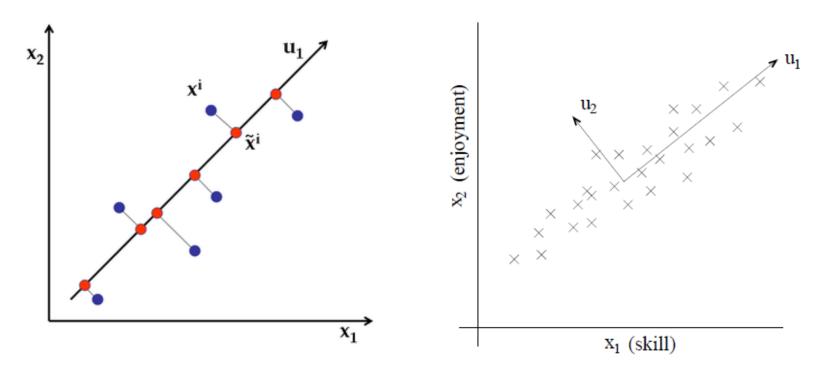
 Yes, the data has substantial variance along both features (i.e., both axes)

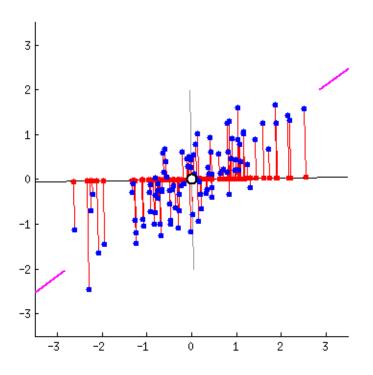


- Now consider a change of axes
- Each example x has 2 features  $\{u_1, u_2\}$
- Consider ignoring the feature  $u_2$  for each example
- Each 2-dimensional example x now become 1-dimensional  $x = \{u_1\}$
- No. Most of the data spread is along  $u_1$  (very little variance along  $u_2$ )



- Data  $\rightarrow$  projection onto unit vector  $\hat{u}_1$ 
  - PCA is used when we want projections capturing maximum variance directions
  - Principal Components (PC): directions of maximum variability in the data
  - Roughly speaking, PCA does a change of axes that can represent the data in a succinct manner





- HOW?
  - 1. Maximize variance (most separable)
  - 2. Minimize the sum-of-squares (minimum squared error)

#### **PCA Algorithm: Pre-processing**

Given data

$$x^{(i)} = egin{bmatrix} x_1^{(i)} \ dots \ x_n^{(i)} \end{bmatrix}, \qquad X = egin{bmatrix} \cdots & (x^{(1)})^T & \cdots \ \cdots & (x^{(2)})^T & \cdots \ dots \ dots \ \ddots & (x^{(m)})^T & \cdots \end{bmatrix}$$

- Shifting (zero mean) and rescaling (unit variance)
  - 1. Shift to zero mean

$$egin{aligned} \mu &= rac{1}{m} \sum_{i=1}^m x^{(i)} \ x^{(i)} \leftarrow x^{(i)} - \mu \quad ext{(zero mean)} \end{aligned}$$

2. [optional] Rescaling (unit variance)

$$egin{align} \sigma_j^2 &= rac{1}{m-1} \sum_{i=1} m \Big( x_j^{(i)} \Big)^2 \ x_j^{(i)} &\leftarrow rac{x_j^{(i)}}{\sigma_j} \end{aligned}$$

#### **PCA Algorithm: Maximize Variance**

• Find unit vector u such that maximizes variance of projections Note:  $m \approx m-1$  for big data

variance of projected data 
$$= \frac{1}{m} \sum_{i=1}^{m} \left( u^T x^{(i)} \right)^2 = \frac{1}{m} \sum_{i=1}^{m} \left( x^{(i)^T} u \right)^2$$

$$= \frac{1}{m} \sum_{i=1}^{m} \left( x^{(i)^T} u \right)^T \left( x^{(i)^T} u \right) = \frac{1}{m} \sum_{i=1}^{m} u^T x^{(i)} x^{(i)^T} u$$

$$= u^T \left( \frac{1}{m} \sum_{i=1}^{m} x^{(i)} x^{(i)^T} \right) u$$

$$= u^T S u \qquad (S = \frac{1}{m} X^T X : \text{ sample covariance matrix})$$

#### **Maximize Variance**

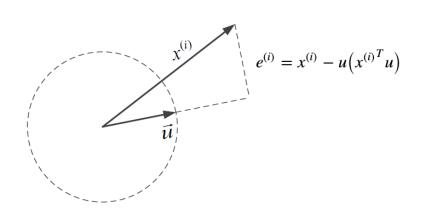
• In an optimization form

$$egin{array}{ll} ext{maximize} & u^T S u \ ext{subject to} & u^T u = 1 \end{array}$$

$$u^T S u = u^T \lambda u = \lambda u^T u = \lambda$$
 (Eigen analysis:  $S u = \lambda u$ )

- $\implies$  pick the largest eigenvalue  $\lambda_1$  of covariance matrix S
- $\implies u = u_1$  is the  $\lambda'_1 s$  corresponding eigenvector
- $\implies u_1$  is the first principal component (direction of highest variance in the data)

## Minimize the Sum-of-Squared Error



$$||e^{(i)}||^2 = ||x^{(i)}||^2 - (x^{(i)^T}u)^2$$

$$= ||x^{(i)}||^2 - (x^{(i)^T}u)^T (x^{(i)^T}u)$$

$$= ||x^{(i)}||^2 - u^T x^{(i)} x^{(i)^T}u$$

$$\frac{1}{m} \sum_{i=1}^{m} ||e^{(i)}||^2 = \frac{1}{m} \sum_{i=1}^{m} ||x^{(i)}||^2 - \frac{1}{m} \sum_{i=1}^{m} u^T x^{(i)} x^{(i)T} u$$

$$= \frac{1}{m} \sum_{i=1}^{m} ||x^{(i)}||^2 - u^T \left(\frac{1}{m} \sum_{i=1}^{m} x^{(i)} x^{(i)T}\right) u$$

#### Minimize the Sum-of-Squared Error

In an optimization form

$$\underbrace{\frac{1}{m} \sum_{i=1}^{m} \|x^{(i)}\|^2}_{\text{constant given } x_i} - \underbrace{u^T \left(\frac{1}{m} \sum_{i=1}^{m} x^{(i)} x^{(i)^T}\right) u}_{\text{maximize}}$$

$$\implies$$
 maximize  $u^T \left( \frac{1}{m} \sum_{i=1}^m x^{(i)} x^{(i)^T} \right) u = \max \ u^T S u$ 

 $\therefore$  minimize  $error^2 = \text{maximize } variance$ 

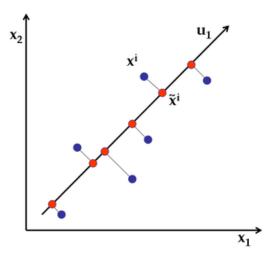
#### Dimension Reduction Method $(n \rightarrow k)$

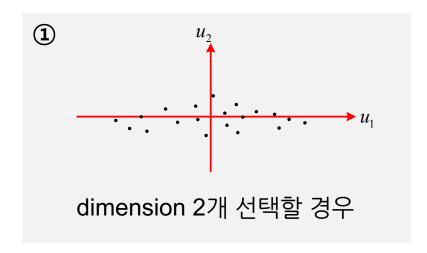
- 1. Choose top k (orthonormal) eigenvectors,  $U = [u_1, u_2, \dots, u_k]$
- 2. Project  $x_i$  onto span  $\{u_1, u_2, \dots, u_k\}$

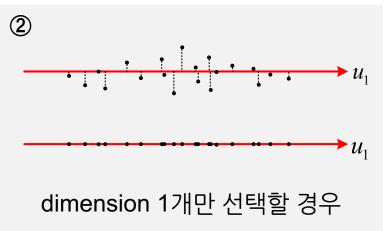
$$z^{(i)} = egin{bmatrix} u_1^T x^{(i)} \ u_2^T x^{(i)} \ dots \ u_k^T x^{(i)} \end{bmatrix} ext{ or } z = U^T x$$

•  $x^{(i)} \rightarrow \text{projection onto unit vector } u \Longrightarrow u^T x^{(i)} = \text{distance from the origin along } u$ 

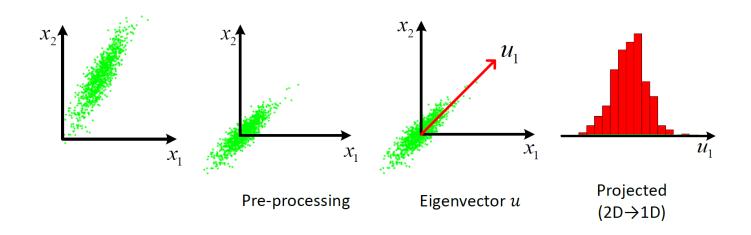
• Data  $\rightarrow$  projection onto unit vector u







# **Pictorial Summary of PCA**



```
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import axes3d
%matplotlib inline
```

```
# data generation
m = 5000
mu = np.array([0, 0])
sigma = np.array([[3, 1.5],
                   [1.5, 1]]
X = np.random.multivariate normal(mu, sigma, m)
X = np.asmatrix(X)
fig = plt.figure(figsize=(10, 6))
plt.plot(X[:,0], X[:,1], 'k.')
plt.axis('equal')
plt.show()
                                        -1
                                        -2
                                        -3
```

```
S = 1/(m-1)*X.T*X
S = np.asmatrix(S)

D, V = np.linalg.eig(S)

idx = np.argsort(-D)
D = D[idx]
V = V[:,idx]

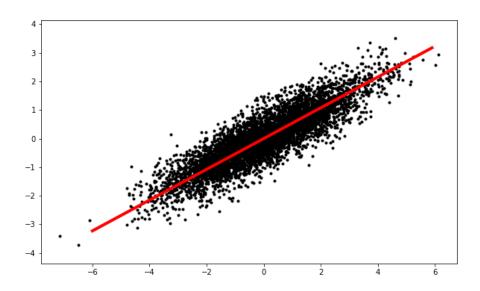
print(D)
print(V)

[ 3.78868797  0.19209281]
[[ 0.88056479 -0.47392579]
```

[ 0.47392579 0.88056479]]

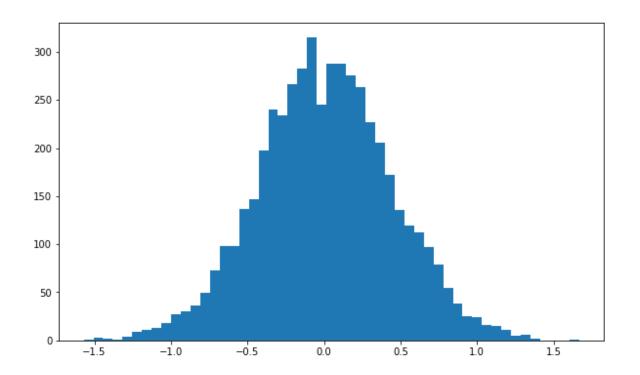
```
h = V[1,0]/V[0,0]
xp = np.arange(-6, 6, 0.1)
yp = h*xp

fig = plt.figure(figsize=(10, 6))
plt.plot(X[:,0], X[:,1], 'k.')
plt.plot(xp, yp, 'r', linewidth=4.0)
plt.axis('equal')
plt.show()
```

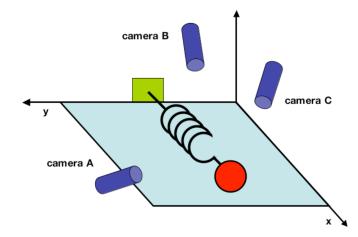


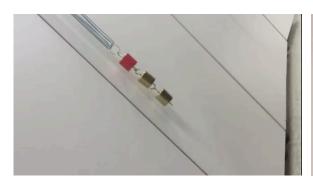
```
Z = X*V[:,1]

plt.figure(figsize=(10, 6))
plt.hist(Z, 51)
plt.show()
```

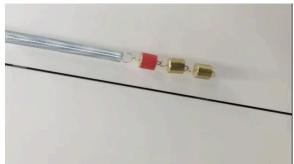


- Multiple video camera records of spring and mass system
- Optimal data representation
  - Find the most informative point of view



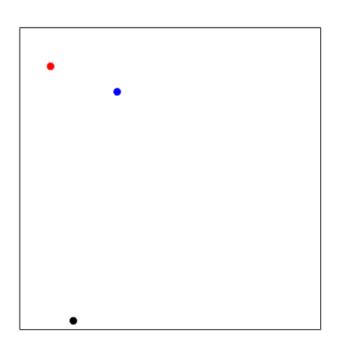






- source:
  - https://www.cs.princeton.edu/picasso/mats/PCA-Tutorial-Intuition\_jp.pdf

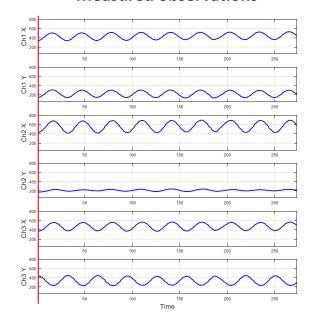
#### **Multivariate Time Series**



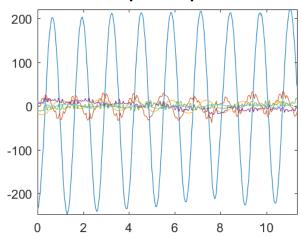
#### System order from

- Laws of physics or
- Data

#### **Measured observations**



#### **Principal components**



```
x^{(i)} = \begin{bmatrix} x \text{ in camera 1} \\ y \text{ in camera 1} \\ x \text{ in camera 2} \\ y \text{ in camera 2} \\ x \text{ in camera 3} \\ y \text{ in camera 3} \end{bmatrix}, \qquad X = \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ (x^{(1)}) & (x^{(2)}) & \cdots & (x^{(m)}) \\ \vdots & \vdots & & \vdots \end{bmatrix}
```

```
from six.moves import cPickle

X = cPickle.load(open('./data_files/pca_spring.pkl','rb'))
X = np.asmatrix(X.T)

print(X.shape)
m = X.shape[0]

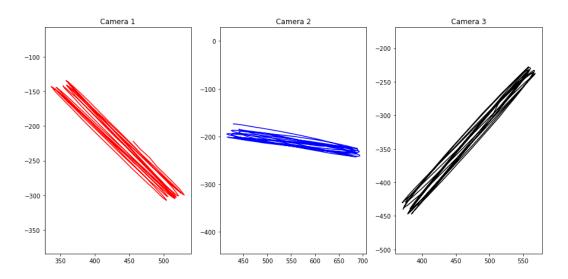
(273, 6)
```

```
plt.figure(figsize=(15, 7))
plt.subplot(131)
plt.plot(X[:,0], -X[:,1],'r')
plt.axis('equal')
plt.title('Camera 1')

plt.subplot(132)
plt.plot(X[:,2], -X[:,3],'b')
plt.axis('equal')
plt.title('Camera 2')

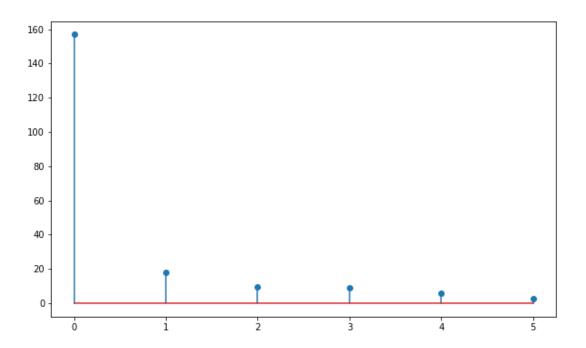
plt.subplot(133)
plt.plot(X[:,4], -X[:,5],'k')
plt.axis('equal')
plt.title('Camera 3')

plt.title('Camera 3')
```



```
X = X - np.mean(X,axis=0)
S = 1/(m-1)*X.T*X
S = np.asmatrix(S)
D, V = np.linalq.eiq(S)
idx = np.argsort(-D)
D = D[idx]
V = V[:,idx]
print(D)
print(V)
                                   8.73851124e+01
                                                   8.19527660e+01
[ 2.46033089e+04
                 3.22747042e+02
                 7.42861585e+001
   3.19467195e+01
0.59881765 -0.40143215 0.087340451
 [ 0.35632379  0.57286174  0.132303
 [0.58419477 - 0.22610057 - 0.20325551 - 0.47751523 - 0.58153918 0.00857804]
 [0.08652315 - 0.02671281 \quad 0.75692234 - 0.14177391 - 0.06010869 - 0.62861422]
 [0.4159798 -0.29900638 \ 0.49374948 \ 0.05637591 \ 0.32442517 \ 0.62075559]
 [-0.46389987 \quad 0.37746931 \quad 0.32963322 \quad -0.45633202 \quad -0.34660023 \quad 0.45308403]
```

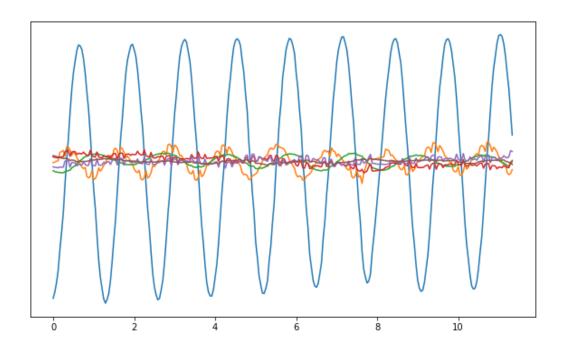
```
plt.figure(figsize=(10,6))
plt.stem(np.sqrt(D))
plt.show()
```



```
# relative magnitutes of the principal components

Z = X*V
xp = np.arange(0,m)/24

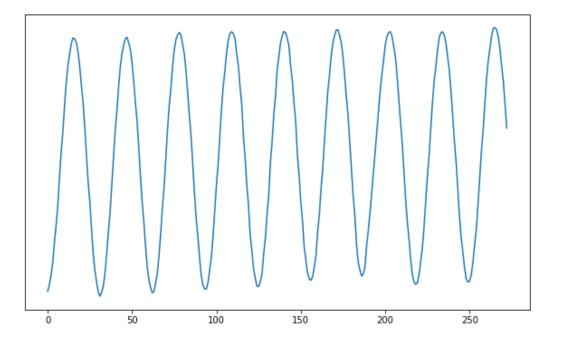
plt.figure(figsize=(10, 6))
plt.plot(xp, Z)
plt.yticks([])
plt.show()
```



```
## projected onto the first principal component
# 6 dim -> 1 dim (dim reduction)
# relative magnitute of the first principal component

Z = X*V[:,0]

plt.figure(figsize=(10, 6))
plt.plot(Z)
plt.yticks([])
plt.show()
```



Reference: John P Cunningham & Byron M Yu, Dimensionality reduction for large-scale neural recordings, Nature Neuroscience 17, 1500–1509 (2014)

