

# **Logistic Regression**

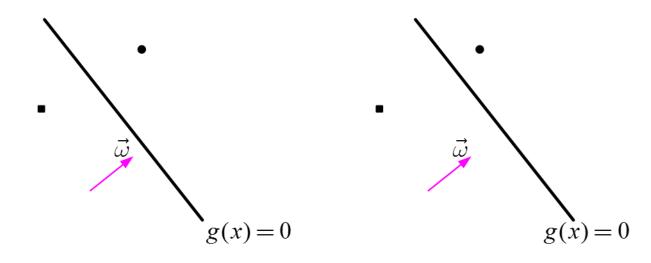
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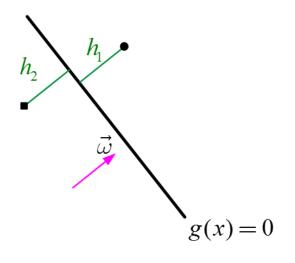
**Prof. Seungchul Lee** 

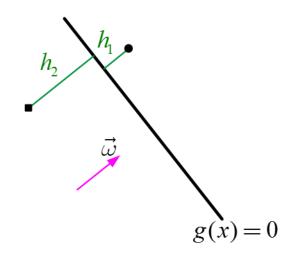


### **Linear Classification: Logistic Regression**

- Logistic regression is a classification algorithm
  - don't be confused
- Perceptron: make use of sign of data
- SVM: make use of margin (minimum distance)
  - Distance from a single data point
- We want to use distance information of all data points
  - logistic regression

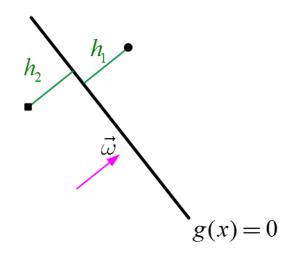


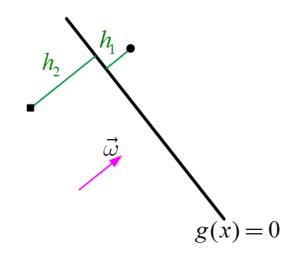




$$|h_1|+|h_2|$$

$$|h_1|+|h_2|$$



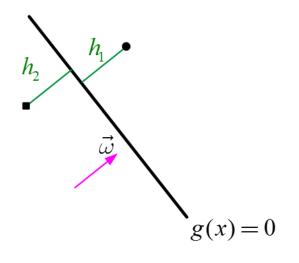


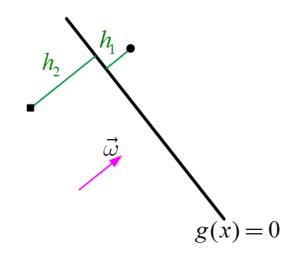
$$|h_1|+|h_2|$$

$$|h_1|\cdot |h_2|$$

$$|h_1|+|h_2|$$

$$|h_1|\cdot |h_2|$$





$$|h_1|+|h_2|$$

$$|h_1|\cdot |h_2|$$

$$|h_1|+|h_2|$$

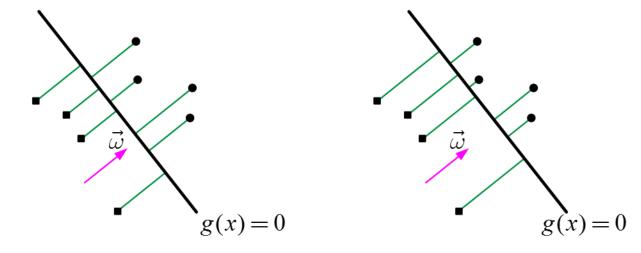
$$|h_1|\cdot |h_2|$$

$$rac{|h_1|+|h_2|}{2} \geq \sqrt{|h_1|\cdot |h_2|} \qquad ext{equal iff} \quad |h_1|=|h_2|$$

equal iff 
$$|h_1| = |h_2|$$

### **Using all Distances**

• basic idea: to find the decision boundary (hyperplane) of  $g(x) = \omega^T x = 0$  such that maximizes  $\prod_i |h_i| \to \text{optimization}$ 

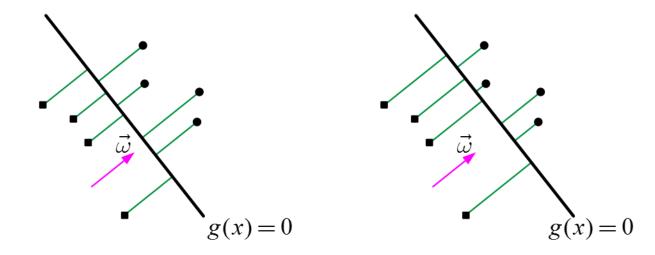


Inequality of arithmetic and geometric means

$$rac{x_1+x_2+\cdots+x_m}{m} \geq \sqrt[m]{x_1\cdot x_2\dots x_m}$$

and that equality holds if and only if  $x_1 = x_2 = \cdots = x_m$ 

### **Using all Distances**

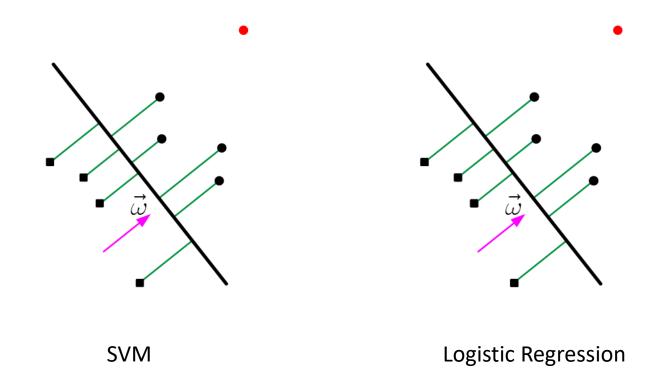


• Roughly speaking, this optimization of  $\max \prod_i |h_i|$  tends to position a hyperplane in the middle of two classes

$$h = rac{g(x)}{\|\omega\|} = rac{\omega^T x}{\|\omega\|} \sim \omega^T x$$

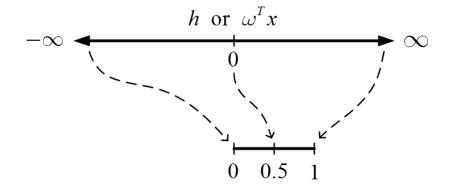
# **Using all Distances with Outliers**

• SVM vs. Logistic Regression

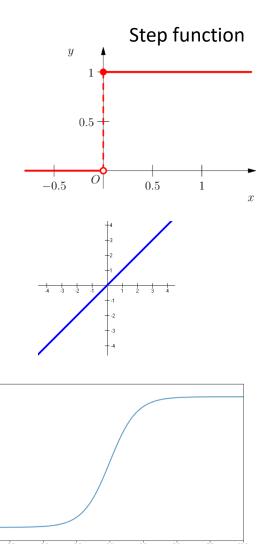


### **Sigmoid Function**

• We link or squeeze  $(-\infty, +\infty)$  to (0, 1) for several reasons:



$$\sigma(z) = rac{1}{1 + e^{-z}} \implies \sigma\left(\omega^T x
ight) = rac{1}{1 + e^{-\omega^T x}}$$



### **Sigmoid Function**

- $\sigma(z)$  is the sigmoid function, or the logistic function
  - Logistic function always generates a value between 0 and 1
  - Crosses 0.5 at the origin, then flattens out

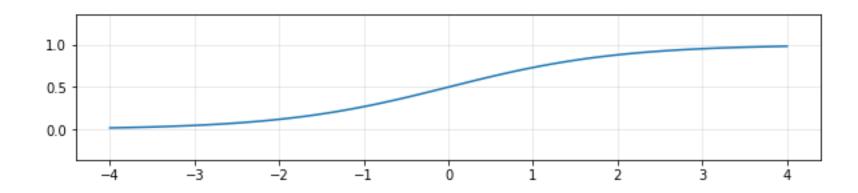
```
# plot a sigmoid function

import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline

z = np.linspace(-4,4,100)
s = 1/(1 + np.exp(-z))

plt.figure(figsize=(10,2))
plt.plot(z, s)
plt.xlim([-4, 4])
plt.axis('equal')
plt.grid(alpha = 0.3)
plt.show()
```

$$\sigma(z) = rac{1}{1 + e^{-z}} \implies \sigma(\omega^T x) = rac{1}{1 + e^{-\omega^T x}}$$



# **Sigmoid Function**

- Benefit of mapping via the logistic function
  - Monotonic: same or similar optimization solution
  - Continuous and differentiable: good for gradient descent optimization
  - Probability or confidence: can be considered as probability

$$P\left(y=+1\mid x,\omega
ight)=rac{1}{1+e^{-\omega^{T}x}}\;\;\in\;\left[0,1
ight]$$

- Probability that the label is +1

$$P(y = +1 \mid x; \omega)$$

Probability that the label is 0

$$P\left(y=0\mid x\,;\omega
ight)=1-P\left(y=+1\mid x\,;\omega
ight)$$

### Goal: We Need to Fit $\omega$ to Data

• For a single data point (x,y) with parameters  $\omega$ 

$$egin{aligned} P\left(y=+1\mid x\,;\omega
ight) &= h_{\omega}(x) = \sigma\left(\omega^T x
ight) \ P\left(y=0\mid x\,;\omega
ight) &= 1-h_{\omega}(x) = 1-\sigma\left(\omega^T x
ight) \end{aligned}$$

It can be compactly written as

$$P(y \mid x; \omega) = (h_{\omega}(x))^{y} (1 - h_{\omega}(x))^{1-y}$$

• For m training data points, the likelihood function of the parameters:

$$egin{aligned} \mathscr{L}(\omega) &= P\left(y^{(1)}, \cdots, y^{(m)} \mid x^{(1)}, \cdots, x^{(m)} ; \omega
ight) \ &= \prod_{i=1}^m P\left(y^{(i)} \mid x^{(i)} ; \omega
ight) \ &= \prod_{i=1}^m \left(h_\omega\left(x^{(i)}
ight)
ight)^{y^{(i)}} \left(1 - h_\omega\left(x^{(i)}
ight)
ight)^{1-y^{(i)}} \qquad \left(\sim \prod_i \lvert h_i 
vert 
ight) \end{aligned}$$

# Goal: We Need to Fit $\omega$ to Data

$$egin{aligned} \mathscr{L}(\omega) &= P\left(y^{(1)}, \cdots, y^{(m)} \mid x^{(1)}, \cdots, x^{(m)} \; ; \omega
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ight)
ight)^{y^{(i)}} \left(1 - h_\omega\left(x^{(i)}
ight)
ight)^{1-y^{(i)}} \qquad \left(\sim \prod_i \lvert h_i 
vert 
ight) \end{aligned}$$

It would be easier to work on the log likelihood.

$$\ell(\omega) = \log \mathscr{L}(\omega) = \sum_{i=1}^m y^{(i)} \log h_\omega \left(x^{(i)}
ight) + \left(1 - y^{(i)}
ight) \log \left(1 - h_\omega \left(x^{(i)}
ight)
ight)$$

• The logistic regression problem can be solved as a (convex) optimization problem:

$$\hat{\omega} = rg \max_{\omega} \ell(\omega)$$

• Again, it is an optimization problem

# **Logistic Regression using GD**



# **Gradient Descent**

• To use the gradient descent method, we need to find the derivative of it

$$abla \ell(\omega) = \left[egin{array}{c} rac{\partial \ell(\omega)}{\partial \omega_1} \ dots \ rac{\partial \ell(\omega)}{\partial \omega_n} \end{array}
ight]$$

• We need to compute  $\frac{\partial \ell(\omega)}{\partial \omega_j}$ 

$$\ell(\omega) = \log \mathscr{L}(\omega) = \sum_{i=1}^m y^{(i)} \log h_\omega \left(x^{(i)}
ight) + \left(1 - y^{(i)}
ight) \log \left(1 - h_\omega \left(x^{(i)}
ight)
ight)$$

### **Gradient Descent**

$$\ell(\omega) = \log \mathscr{L}(\omega) = \sum_{i=1}^m y^{(i)} \log h_\omega \left(x^{(i)}
ight) + \left(1 - y^{(i)}
ight) \log \left(1 - h_\omega \left(x^{(i)}
ight)
ight)$$

• Think about a single data point with a single parameter  $\omega$  for the simplicity.

$$\frac{\partial}{\partial \omega} [y \log(\sigma) + (1 - y) \log(1 - \sigma)]$$

$$= y \frac{\sigma'}{\sigma} + (1 - y) \frac{-\sigma}{1 - \sigma}$$

$$= \left(\frac{y}{\sigma} - \frac{1 - y}{1 - \sigma}\right) \sigma'$$

$$= \frac{y - \sigma}{\sigma(1 - \sigma)} \sigma'$$

$$= \frac{y - \sigma}{\sigma(1 - \sigma)} \sigma(1 - \sigma)x$$

$$= (y - \sigma)x$$

• For m training data points with parameters  $\omega$ 

$$\frac{\partial \ell(\omega)}{\partial \omega_{i}} = \sum_{i=1}^{m} \left( y^{(i)} - h_{\omega} \left( x^{(i)} \right) \right) x_{j}^{(i)} \quad \overset{\text{vectorization}}{=} \quad \left( y - h_{\omega}(x) \right)^{T} x_{j} = x_{j}^{T} \left( y - h_{\omega}(x) \right)$$

# **Gradient Descent for Logistic Regression**

$$\omega = \left[egin{array}{c} \omega_0 \ \omega_1 \ \omega_2 \end{array}
ight], \qquad x = \left[egin{array}{c} 1 \ x_1 \ x_2 \end{array}
ight]$$

$$X = egin{bmatrix} \left(x^{(1)}
ight)^T \ \left(x^{(2)}
ight)^T \ \left(x^{(3)}
ight)^T \end{bmatrix} = egin{bmatrix} 1 & x_1^{(1)} & x_2^{(1)} \ 1 & x_1^{(2)} & x_2^{(2)} \ 1 & x_1^{(3)} & x_2^{(3)} \ dots & dots & dots \end{bmatrix}$$

$$y = egin{bmatrix} y^{(1)} \ y^{(2)} \ y^{(3)} \ dots \end{bmatrix}$$

- Maximization problem
- Be careful on matrix shape

$$rac{\partial \ell(\omega)}{\partial \omega_j} = \sum_{i=1}^m \left( y^{(i)} - h_\omega \left( x^{(i)} 
ight) 
ight) x_j^{(i)}$$

$$\stackrel{\text{vectorization}}{=} \quad \left(y - h_{\omega}(x)\right)^{T} x_{j} = x_{j}^{T} \left(y - h_{\omega}(x)\right)$$

$$abla \ell(\omega) = egin{bmatrix} rac{\partial \ell(\omega)}{\partial \omega_0} \ rac{\partial \ell(\omega)}{\partial \omega_1} \ rac{\partial \ell(\omega)}{\partial \omega_2} \end{bmatrix} = X^T \left( y - h_\omega(x) 
ight) = X^T \left( y - \sigma(X\omega) 
ight)$$

$$\omega \leftarrow \omega - \eta \left( -\nabla \ell(\omega) \right)$$

### **Python Implementation**

```
# datat generation

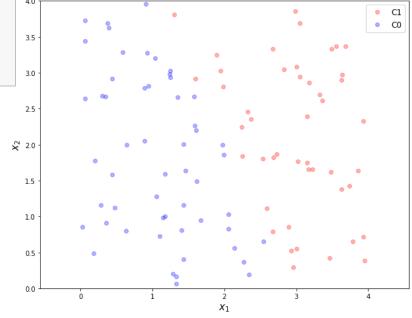
m = 100
w = np.array([[-6], [2], [1]])
X = np.hstack([np.ones([m,1]), 4*np.random.rand(m,1), 4*np.random.rand(m,1)])

w = np.asmatrix(w)
X = np.asmatrix(X)

y = 1/(1 + np.exp(-X*w)) > 0.5

C1 = np.where(y == True)[0]
C0 = np.where(y == False)[0]

y = np.empty([m,1])
y[C1] = 1
y[C0] = 0
```





### **Python Implementation**

```
# be careful with matrix shape

def h(x,w):
    return 1/(1 + np.exp(-x*w))
```

```
alpha = 0.0001
w = np.zeros([3,1])

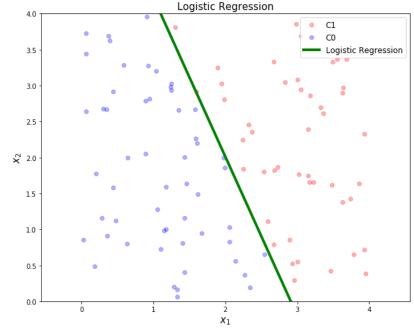
for i in range(1000):
    df = -X.T*(y - h(X,w))
    w = w - alpha*df

print(w)
```

$$h_{\omega}(x) = h(x\,;\omega) = \sigma\left(\omega^T x
ight) = rac{1}{1 + e^{-\omega^T x}}$$

$$abla \ell(\omega) = egin{bmatrix} rac{\partial \ell(\omega)}{\partial \omega_0} \ rac{\partial \ell(\omega)}{\partial \omega_1} \ rac{\partial \ell(\omega)}{\partial \omega_2} \end{bmatrix} = X^T \left( y - h_\omega(x) 
ight) = X^T \left( y - \sigma(X\omega) 
ight)$$

$$\omega \leftarrow \omega - \eta \left( -\nabla \ell(\omega) \right)$$



# **Logistic Regression using CVXPY**



# **Probabilistic Approach (or MLE)**

• Consider a random variable  $y \in \{0, 1\}$ 

$$P(y=+1) = p, \quad P(y=0) = 1-p$$

where  $p \in [0, 1]$ , and is assumed to depend on a vector of explanatory variables  $x \in \mathbb{R}^n$ 

• Then, the logistic model has the form

$$p=rac{1}{1+e^{-\omega^Tx}}=rac{e^{\omega^Tx}}{e^{\omega^Tx}+1} \ 1-p=rac{1}{e^{\omega^Tx}+1}$$

- We can re-order the training data so
  - for  $x_1, \dots, x_q$ , the outcome is y = +1, and
  - for  $x_{q+1}, \dots, x_m$ , the outcome is y = 0

## **Probabilistic Approach (or MLE)**

Likelihood function

$$\mathscr{L} = \prod_{i=1}^q p_i \prod_{i=q+1}^m \left(1-p_i
ight) \qquad \left(\sim \prod_i \lvert h_i 
vert
ight)$$

Log likelihood function

$$egin{aligned} \ell(\omega) &= \log \mathscr{L} = \sum_{i=1}^q \log p_i + \sum_{i=q+1}^m \log(1-p_i) \ &= \sum_{i=1}^q \log rac{\exp\left(\omega^T x_i
ight)}{1+\exp(\omega^T x_i)} + \sum_{i=q+1}^m \log rac{1}{1+\exp(\omega^T x_i)} \ &= \sum_{i=1}^q \left(\omega^T x_i
ight) - \sum_{i=1}^m \log (1+\exp\left(\omega^T x_i
ight)) \end{aligned}$$

• Since  $\ell$  is a concave function of  $\omega$ , the logistic regression problem can be solved as a convex optimization problem

$$\hat{\omega} = rg \max_{\omega} \ell(\omega)$$

### **CVXPY Implementation**

$$egin{aligned} \ell(\omega) &= \log \mathscr{L} = \sum_{i=1}^q \log p_i + \sum_{i=q+1}^m \log(1-p_i) \ &= \sum_{i=1}^q \log rac{\exp\left(\omega^T x_i
ight)}{1+\exp(\omega^T x_i)} + \sum_{i=q+1}^m \log rac{1}{1+\exp(\omega^T x_i)} \ &= \sum_{i=1}^q \left(\omega^T x_i
ight) - \sum_{i=1}^m \logig(1+\expig(\omega^T x_iig)ig) \end{aligned}$$

```
w = cvx.Variable([3, 1])
obj = cvx.Maximize(y.T*X*w - cvx.sum(cvx.logistic(X*w)))
prob = cvx.Problem(obj).solve()

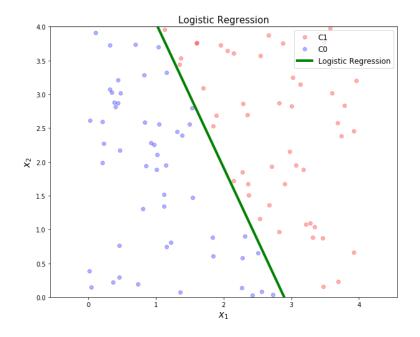
w = w.value

xp = np.linspace(0,4,100).reshape(-1,1)
yp = - w[1,0]/w[2,0]*xp - w[0,0]/w[2,0]
```

cvx.sum(x) = 
$$\sum_{ij} x_{ij}$$
 cvx.logistic(x) =  $\log(1+e^x)$ 

$$\omega = egin{bmatrix} \omega_0 \ \omega_1 \ \omega_2 \end{bmatrix}, \qquad x = egin{bmatrix} 1 \ x_1 \ x_2 \end{bmatrix}$$

$$X = egin{bmatrix} egin{pmatrix} egin{pmatrix}$$



### In a More Compact Form

- Change  $y \in \{0, +1\} \rightarrow y \in \{-1, +1\}$  for computational convenience
  - Consider the following function

$$P(y=+1) = p = \sigma(\omega^T x), \quad P(y=-1) = 1 - p = 1 - \sigma(\omega^T x) = \sigma(-\omega^T x) \ P\left(y \mid x, \omega
ight) = \sigma\left(y\omega^T x
ight) = rac{1}{1 + \exp(-y\omega^T x)} \in [0, 1]$$

Log-likelihood

$$egin{aligned} \ell(\omega) &= \log \mathscr{L} = \log P\left(y \mid x, \omega
ight) = \log \prod_{n=1}^m P\left(y_n \mid x_n, \omega
ight) \ &= \sum_{n=1}^m \log P\left(y_n \mid x_n, \omega
ight) \ &= \sum_{n=1}^m \log rac{1}{1 + \exp(-y_n \omega^T x_n)} \ &= \sum_{n=1}^m - \log (1 + \exp(-y_n \omega^T x_n)) \end{aligned}$$

### **CVXPY Implementation**

$$egin{aligned} \hat{\omega} &= rg \max_{\omega} \sum_{n=1}^m -\logig(1 + \expig(-y_n \omega^T x_nig)ig) \ &= rg \min_{\omega} \sum_{n=1}^m \logig(1 + \expig(-y_n \omega^T x_nig)ig) \end{aligned}$$

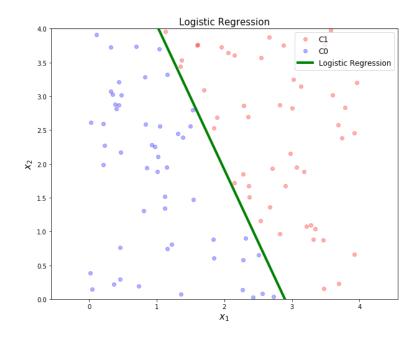
```
y = np.empty([m,1])
y[C1] = 1
y[C0] = -1
y = np.asmatrix(y)

w = cvx.Variable([3, 1])

obj = cvx.Minimize(cvx.sum(cvx.logistic(-cvx.multiply(y,X*w))))
prob = cvx.Problem(obj).solve()

w = w.value

xp = np.linspace(0,4,100).reshape(-1,1)
yp = - w[1,0]/w[2,0]*xp - w[0,0]/w[2,0]
```



cvx.sum(x) = 
$$\sum_{ij} x_{ij}$$
 cvx.logistic(x) =  $\log(1+e^x)$ 

# Logistic Regression using Scikit-Learn



### **Logistic Regression using Scikit-Learn**

```
X = X[:,1:3]
X.shape
```

```
from sklearn import linear_model

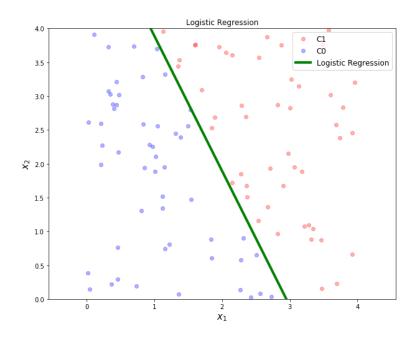
clf = linear_model.LogisticRegression(solver='lbfgs')
clf.fit(X,np.ravel(y))
```

```
w0 = clf.intercept_[0]
w1 = clf.coef_[0,0]
w2 = clf.coef_[0,1]

xp = np.linspace(0,4,100).reshape(-1,1)
yp = - w1/w2*xp - w0/w2
```

$$\omega = \left[egin{array}{c} \omega_1 \ \omega_2 \end{array}
ight], \qquad \omega_0, \qquad x = \left[egin{array}{c} x_1 \ x_2 \end{array}
ight]$$

$$X = egin{bmatrix} egin{pmatrix} egin{pmatrix}$$





### **Multiclass Classification**



### **Multiclass Classification**

- Generalization to more than 2 classes is straightforward
  - one vs. all (one vs. rest)
  - one vs. one
- Using the softmax function instead of the logistic function
  - (refer to <u>UFLDL Tutorial</u>)
  - see them as probability

$$P\left(y=k\mid x,\omega
ight)=rac{\exp\left(\omega_{k}^{T}x
ight)}{\sum_{k}\exp\left(\omega_{k}^{T}x
ight)}\in\left[0,1
ight]$$

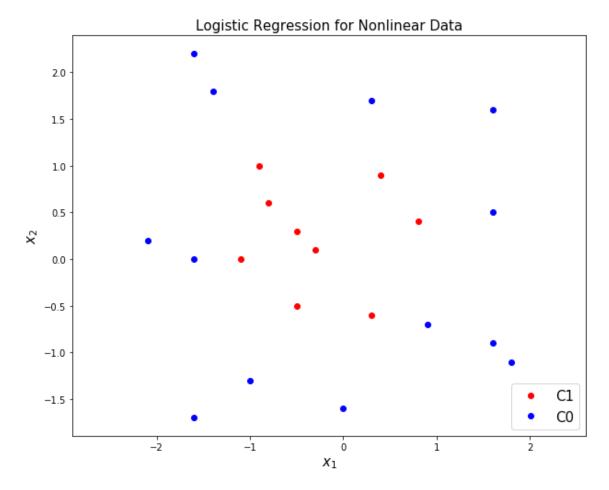
• We maintain a separator weight vector  $\omega_k$  for each class k

## **Non-linear Classification**



### **Non-linear Classification**

- Same idea as non-linear regression: non-linear features
  - Explicit or implicit Kernel





#### **Explicit Kernel**

$$x=egin{bmatrix} x_1 \ x_2 \end{bmatrix} \quad \Longrightarrow \quad z=\phi(x)=egin{bmatrix} rac{\sqrt{2}x_1}{\sqrt{2}x_2} \ x_1^2 \ \sqrt{2}x_1x_2 \ x_2^2 \end{bmatrix}$$



#### **Non-linear Classification**

