# **Regression and Classification**

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## 1. Regression

- $\hat{y}_i = f(x_i, \theta)$  in general In many cases, a linear model to predict  $y_i$  is assumed

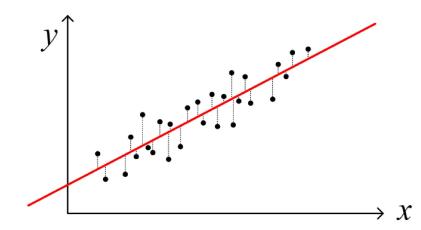
Given 
$$\left\{egin{array}{l} x_i: ext{inputs} \\ y_i: ext{outputs} \end{array}
ight.$$
 , Find  $heta_1$  and  $heta_2$  
$$x=\left[egin{array}{c} x_1 \\ x_2 \\ \vdots \\ x \end{array}\right], \qquad y=\left[egin{array}{c} y_1 \\ y_2 \\ \vdots \\ x \end{array}\right] pprox \hat{y}_i= heta_1x_i+ heta_2$$

- $\hat{y}_i$  : predicted output
- $\theta = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix}$ : Model parameters

$$\hat{y}_i = f(x_i, \theta)$$
 in general

• in many cases, a linear model to predict  $y_i$  used

$${\hat y}_i = heta_1 x_i + heta_2 \; ext{ such that } \min_{ heta_1, heta_2} \sum_{i=1}^m ({\hat y}_i - y_i)^2$$



## Linear Regression as Optimization</fotn>

• How to find model parameters, 
$$heta = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix}$$
  $x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{bmatrix}, \quad y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix} pprox \hat{y}_i = \theta_1 x_i + \theta_2$   $\hat{y}_i = \theta_1 x_i + \theta_2$   $\hat{y}_i = \theta_1 x_i + \theta_2$  such that  $\min_{\theta_1, \theta_2} \sum_{\theta_1, \theta_2}^m (\hat{y}_i - y_i)^2$ 

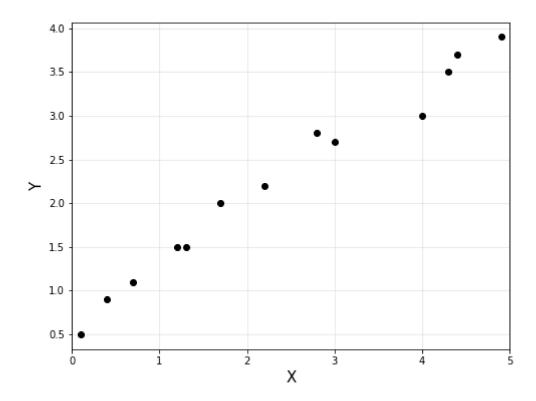
### Regression

#### In [1]:

```
import numpy as np
import matplotlib.pyplot as plt

# data points in column vector [input, output]
x = np.array([0.1, 0.4, 0.7, 1.2, 1.3, 1.7, 2.2, 2.8, 3.0, 4.0, 4.3, 4.4, 4.9]).reshape(-1, 1)
y = np.array([0.5, 0.9, 1.1, 1.5, 1.5, 2.0, 2.2, 2.8, 2.7, 3.0, 3.5, 3.7, 3.9]).reshape(-1, 1)

# to plot
plt.figure(figsize=(10, 6))
plt.plot(x, y, 'ko', label="data")
plt.xlabel('X', fontsize=15)
plt.ylabel('Y', fontsize=15)
plt.axis('scaled')
plt.grid(alpha=0.3)
plt.xlim([0, 5])
plt.show()
```



#### **CVXPY**

- Use CVXPY optimization (least-squared)
  - For convenience, we define a function that maps inputs to feature vectors,  $\phi$

$$egin{aligned} \hat{y}_i &= \left[ egin{aligned} x_i & 1 
ight] \left[ egin{aligned} heta_1 \ 1 \end{array} 
ight]^T \left[ eta_1 \ heta_2 \end{array} 
ight] & ext{feature vector} \phi(x_i) = \left[ egin{aligned} x_i \ 1 \end{array} 
ight] \ &= \phi^T(x_i) heta \end{aligned}$$

$$\Phi = egin{bmatrix} x_1 & 1 \ x_2 & 1 \ dots & dots \ x_m & 1 \end{bmatrix} = egin{bmatrix} \phi^T(x_1) \ \phi^T(x_2) \ dots \ \phi^T(x_m) \end{bmatrix} \quad \Longrightarrow \quad \hat{y} = egin{bmatrix} \hat{y_1} \ \hat{y_2} \ dots \ \hat{y_m} \end{bmatrix} = \Phi heta$$

#### parameter Estimation

Model parameter estimation

$$\min_{ heta} \|\hat{y} - y\|_2 = \min_{ heta} \|A heta - y\|_2$$

In [2]:

```
import cvxpy as cvx

m = y.shape[0]
#A = np.hstack([x, np.ones([m, 1])])
A = np.hstack([x, x**0])
A = np.asmatrix(A)

theta2 = cvx.Variable(2, 1)
obj = cvx.Minimize(cvx.norm(A*theta2-y, 2))
cvx.Problem(obj,[]).solve()

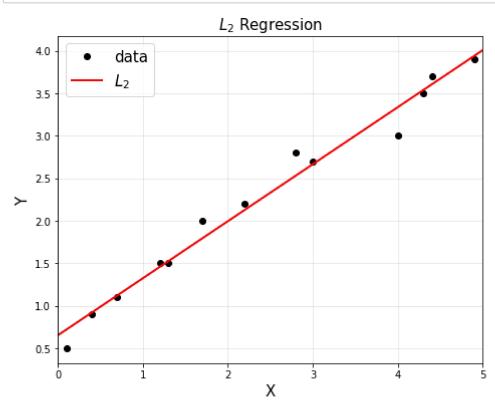
print('theta:\n', theta2.value)
```

theta:

```
[[0.67129519]
[0.65306531]]
```

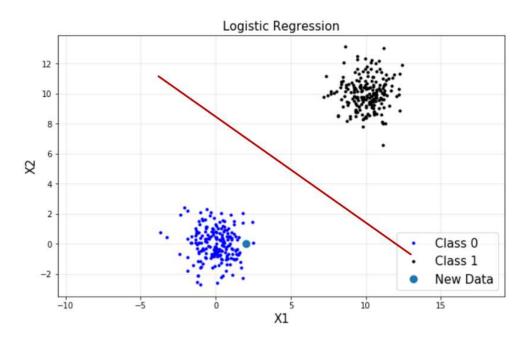
#### In [3]:

```
# to plot
plt.figure(figsize=(10, 6))
plt.title('$L_2$ Regression', fontsize=15)
plt.xlabel('X', fontsize=15)
plt.ylabel('Y', fontsize=15)
plt.plot(x, y, 'ko', label="data")
# to plot a straight line (fitted line)
xp = np.arange(0, 5, 0.01).reshape(-1, 1)
theta2 = theta2.value
yp = theta2[0,0]*xp + theta2[1,0]
plt.plot(xp, yp, 'r', linewidth=2, label="$L_2$")
plt.legend(fontsize=15)
plt.axis('scaled')
plt.grid(alpha=0.3)
plt.xlim([0, 5])
plt.show()
```



## 2. Classification

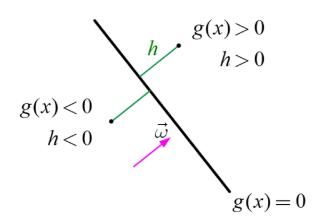
- · Perceptron: make use of sign of data
  - discuss it later
- · Logistic regression is a classification algorithm
  - don't be confused
- To find a classification boundary



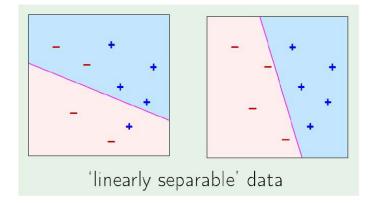
## Sign

• Sign with respect to a line

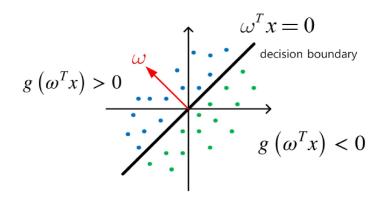
$$\omega = egin{bmatrix} \omega_1 \ \omega_2 \end{bmatrix}, \quad \omega = egin{bmatrix} \omega_1 \ \omega_2 \end{bmatrix} \implies g(x) = \omega_1 x_1 + \omega_2 x_2 + \omega_0 = \omega^T x + \omega_0 \ \omega = egin{bmatrix} \omega_0 \ \omega_1 \ \omega_2 \end{bmatrix}, \quad \omega = egin{bmatrix} 1 \ \omega_1 \ \omega_2 \end{bmatrix} \implies g(x) = \omega_0 + \omega_1 x_1 + \omega_2 x_2 = \omega^T x \end{aligned}$$



## **Perceptron**

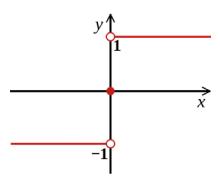


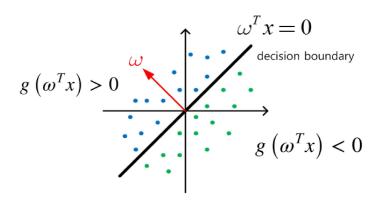
- Hyperplane
  - Separates a D-dimensional space into two half-spaces
  - Defined by an outward pointing normal vector
  - ullet  $\omega$  is orthogonal to any vector lying on the hyperplane



## How to Find $\omega$

- All data in class 1
  - $g(\omega^T x) > 0$
- All data in class 0
  - $g(\omega^T x) < 0$





#### **Perceptron Algorithm**

• The perceptron implements

$$h(x) = \mathrm{sign}\left(\omega^T x\right)$$

Given the training set

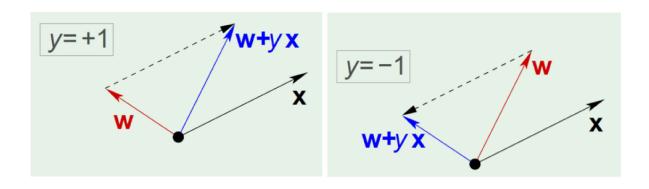
$$(x_1,y_1),(x_2,y_2),\cdots,(x_N,y_N) \quad ext{where } y_i \in \{-1,1\}$$

1) pick a misclassified point

$$\text{sign}\left(\omega^T x_n\right) \neq y_n$$

2) and update the weight vector

$$\omega \leftarrow \omega + y_n x_n$$



- Why perceptron updates work?
- Let's look at a misclassified positive example  $(y_n=+1)$  
   perceptron (wrongly) thinks  $\omega_{old}^T x_n < 0$
- updates would be

$$\omega_{new} = \omega_{old} + y_n x_n = \omega_{old} + x_n$$

$$\omega_{new}^T x_n = (\omega_{old} + x_n)^T x_n = \omega_{old}^T x_n + x_n^T x_n$$

- Thus  $\omega_{new}^T x_n$  is less negative than  $\omega_{old}^T x_n$ 

## **Python Example**

```
In [9]:
```

```
import numpy as np
import matplotlib.pyplot as plt
% matplotlib inline
```

#### In [10]:

```
#training data gerneration

m = 100

x1 = 8*np.random.rand(m, 1)

x2 = 7*np.random.rand(m, 1) - 4

g0 = 0.8*x1 + x2 - 3

g1 = g0 - 1

g2 = g0 + 1
```

#### In [11]:

```
C1 = np.where(g1 >= 0)
C2 = np.where(g2 < 0)
print(C1)
```

#### In [12]:

```
C1 = np.where(g1 >= 0)[0]
C2 = np.where(g2 < 0)[0]
print(C1.shape)
print(C2.shape)</pre>
```

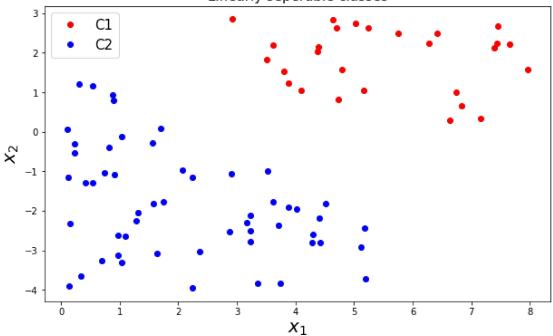
(27,)

(54,)

#### In [13]:

```
plt.figure(figsize=(10, 6))
plt.plot(x1[C1], x2[C1], 'ro', label='C1')
plt.plot(x1[C2], x2[C2], 'bo', label='C2')
plt.title('Linearly seperable classes', fontsize=15)
plt.legend(loc='upper left', fontsize=15)
plt.xlabel(r'$x_1$', fontsize=20)
plt.ylabel(r'$x_2$', fontsize=20)
plt.show()
```

### Linearly seperable classes



In [15]:

```
X1 = np.hstack([np.ones([C1.shape[0],1]), x1[C1], x2[C1]])
X2 = np.hstack([np.ones([C2.shape[0],1]), x1[C2], x2[C2]])
X = np.vstack([X1, X2])

y = np.vstack([np.ones([C1.shape[0],1]), -np.ones([C2.shape[0],1])])

X = np.asmatrix(X)
y = np.asmatrix(y)
```

$$\omega = egin{bmatrix} \omega_1 \ \omega_2 \ \omega_3 \end{bmatrix} \ \omega \leftarrow \omega + yx$$

where (x,y) is a misclassified training point

In [16]:

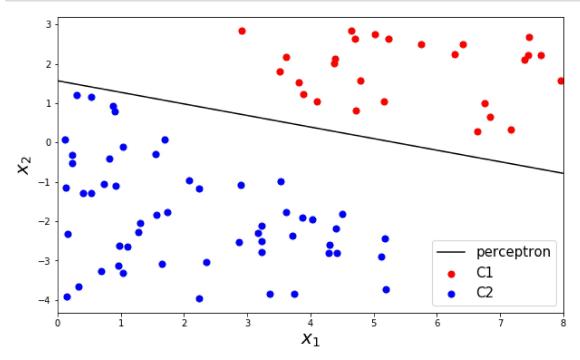
```
[[-11. ]
[ 2.05983422]
[ 7.00620838]]
```

$$egin{aligned} g(x) &= \omega^T x + \omega_0 = \omega_1 x_1 + \omega_2 x_2 + \omega_0 = 0 \ \Longrightarrow \ x_2 &= -rac{\omega_1}{\omega_2} x_1 - rac{\omega_0}{\omega_2} \end{aligned}$$

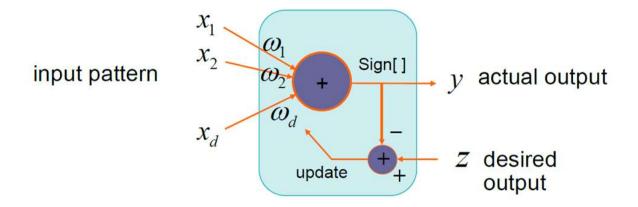
#### In [17]:

```
x1p = np.linspace(0,8,100).reshape(-1,1)
x2p = - w[1,0]/w[2,0]*x1p - w[0,0]/w[2,0]

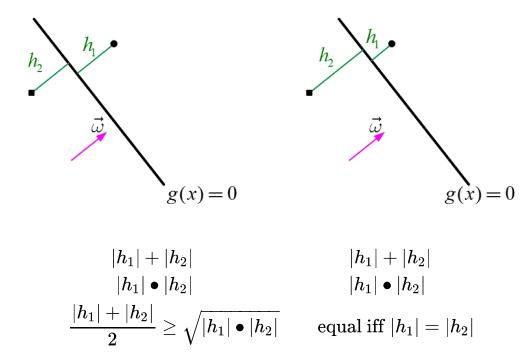
plt.figure(figsize=(10, 6))
plt.scatter(x1[C1], x2[C1], c='r', s=50, label='C1')
plt.scatter(x1[C2], x2[C2], c='b', s=50, label='C2')
plt.plot(x1p, x2p, c='k', label='perceptron')
plt.xlim([0,8])
plt.xlabel('$x_1$', fontsize = 20)
plt.ylabel('$x_2$', fontsize = 20)
plt.legend(loc = 4, fontsize = 15)
plt.show()
```



#### Perceptron

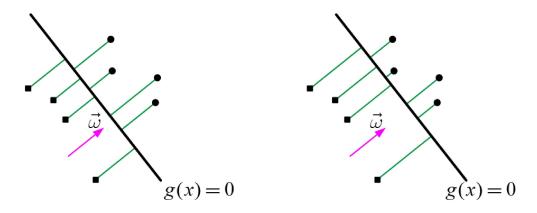


#### **Using Distances**



## **Using all Distances**

• basic idea: to find the decision boundary (hyperplane) of  $g(x)=\omega^Tx=0$  such that maximizes  $\prod_i |h_i| o ext{optimization}$ 



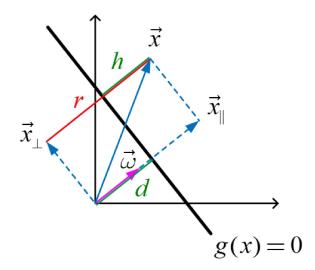
Inequality of arithmetic and geometric means

and that equality holds if and only if 
$$x_1=x_2=\cdots=x_m$$

• Roughly speaking, this optimization of  $\max \prod_i |h_i|$  tends to position a hyperplane in the middle of two classes

#### Distance from a Line: h

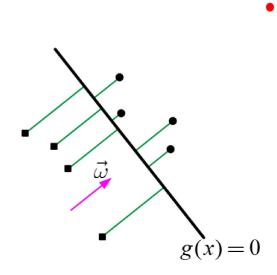
ullet for any vector of x



$$\therefore \quad h = rac{g(x)}{\|\omega\|} \implies ext{orthogonal distance from the line} \ h = rac{g(x)}{\|\omega\|} = rac{\omega^T x}{\|\omega\|} \sim \omega^T x$$

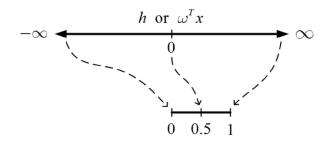
# **Using all Distances with Outliers**

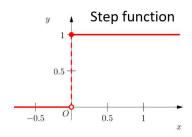
• Logistic Regression

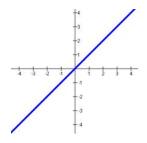


## **Sigmoid Function**

• We link or squeeze  $(-\infty,+\infty)$  to (0, 1) for several reasons:



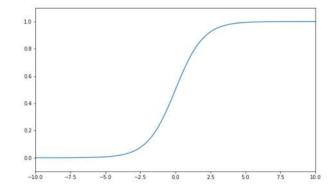




 $\sigma(z)$  is the sigmoid function, or the logistic function

- logistic function always generates a value between 0 and 1
- Crosses 0.5 at the origin, then flattens out

$$\sigma(z) = rac{1}{1 + e^{-z}} \implies \sigma(\omega^T x) = rac{1}{1 + e^{-\omega^T x}}$$



- Benefit of mapping via the logistic function
  - monotonic: same or similar optimziation solution
  - continuous and differentiable: good for gradient descent optimization
  - probability or confidence: can be considered as probability

$$P\left(y=+1\mid x,\omega
ight)=rac{1}{1+e^{-\omega^{T}x}}~\in~\left[0,1
ight]$$

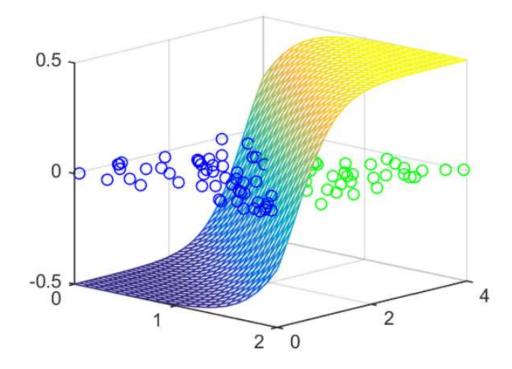
• Goal: we need to fit  $\omega$  to our data

$$\max \prod_i |h_i|$$

• Again, it is an optimization problem

# **Logistic Regression**

· Classified based on probability



## 3.1. Multiclass Classification: Softmax

- · Generalization to more than 2 classes is straightforward
  - one vs. all (one vs. rest)
  - one vs. one
- Using the soft-max function instead of the logistic function (refer to <u>UFLDL Tutorial</u> (<a href="http://ufldl.stanford.edu/tutorial/supervised/SoftmaxRegression/">http://ufldl.stanford.edu/tutorial/supervised/SoftmaxRegression/</a>))
  - see them as probability

$$P\left(y=k\mid x,\omega
ight)=rac{\exp\left(\omega_{k}^{T}x
ight)}{\sum_{k}\exp\left(\omega_{k}^{T}x
ight)}\in\left[0,1
ight]$$

- We maintain a separator weight vector  $\omega_k$  for each class k
- Note: sigmoid function

$$P(y = +1 \mid x, \omega) = rac{1}{1 + e^{-\omega^T x}} \in [0, 1]$$

# 4. Summary

From parameter estimation of machine learning to optimization problems

| Machine learning | Optimization  |
|------------------|---|
|                  | Loss (or objective functions)   |
| Regression       | $\min_{	heta_1,	heta_2} \sum_{i=1}^m ({\hat y}_i - y_i)^2$  |
| Classification   | $egin{aligned} \ell(\omega) &= \log \mathscr{L} = \log P\left(y \mid x, \omega ight) = \log \prod_{n=1}^{m} P\left(y_{n} \mid x_{n}, \omega ight) \ &= \sum_{n=1}^{m} \log P\left(y_{n} \mid x_{n}, \omega ight) \end{aligned}$ |

#### In [1]:

%%javascript

\$.getScript('https://kmahelona.github.io/ipython\_notebook\_goodies/ipython\_notebook\_toc.js')