

Assignement C4*: Play with a more “complex” FEA code* publish needed on LMS by pair

This **miniproject** addresses how students work with Matlab software to accelerate learning and deepen understanding. The goal of this assignment is to “size” a structure using different criteria and also to compare results with an analytical formulation. The given Matlab code (`Main_Cantilever_Beam.m`) needs to be commented...

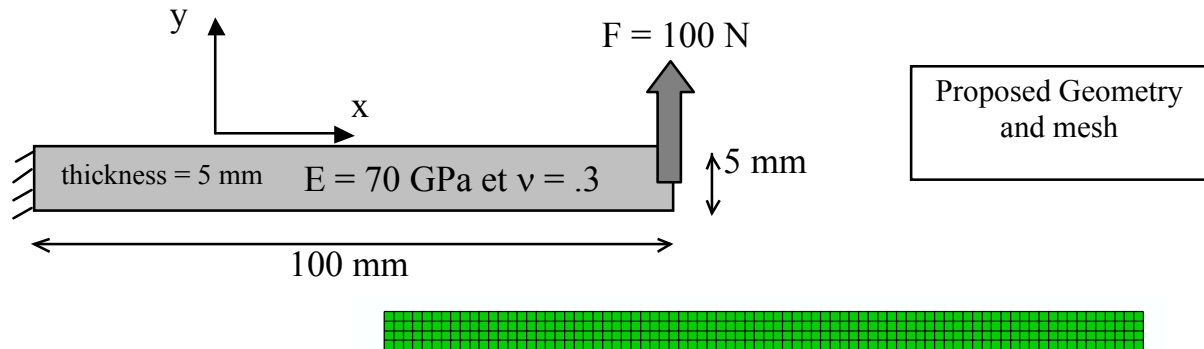


FIGURE 1: CANTILEVER BEAM OF LENGHT L, HEIGHT H, AND THICKNESS T

The instructor provides students with a core version of a MATLAB program containing functions that calculate the x – and y - coordinates of a rectangular grid, the connectivity information, i.e. the four nodes defining each element, the element stiffness matrix, the displacement-to-strain transformation matrix and the elasticity matrix. Students then perform parametric studies varying the finite element mesh density and other structural parameters.

Question 1: The students should program Von Mises/Tresca criteria to conclude on ductile / fragile materials used.

VonMises

$$\bar{\sigma} = \sqrt{\frac{3}{2} \cdot \underline{dev}(\underline{\underline{\sigma}}) : \underline{dev}(\underline{\underline{\sigma}})} = \sqrt{\sigma_x^2 + 3 \cdot \tau_{xy}^2}$$

Tresca

$$Maxi(\sigma_I, \sigma_{II}, \sigma_{III}) < \sigma_r$$

$$\begin{cases} \sigma_I = \frac{\sigma_x}{2} + \sqrt{\left(\frac{\sigma_x}{2}\right)^2 + \tau_{xy}^2} \\ \sigma_{II} = \frac{\sigma_x}{2} - \sqrt{\left(\frac{\sigma_x}{2}\right)^2 + \tau_{xy}^2} \\ \sigma_{III} = 0 \end{cases}$$

Case #1 made of aluminum with characteristics: E = 70GPa; nu = 0.3; sigma_elasticlimit = 250MPa

Case #2 made of glass with characteristics: E = 70GPa; nu = 0.3; sigma_failure = 60MPa

Question 2: Empirically fit with $\sigma_{xx} = K.(L - x).y$ Please. Comment !

Question 3: Add a hole center in L/2, h/2 of size defined from the relationship ($D / H = 0.6$) . Make a convergence study on sigma_max. Compare with standard stress concentration factor abaqus if possible.

NEED SOME HELP Pleaaaaase!!!!!!

In what follows we give a brief overview of key **MATLAB** statements that are used to carry out important computational steps in a finite element analysis.

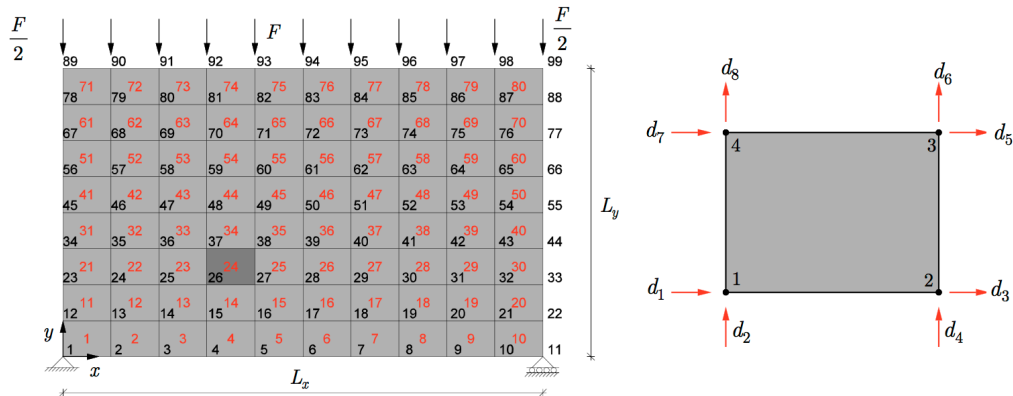


FIGURE 2: SAMPLE FINITE ELEMENT MESH AND FOUR-NODE ELEMENT WITH EIGHT DEGREES-OF-FREEDOM

Let us consider the simple finite element mesh above consisting of 80 four-node elements and 99 nodes. We use the standard four-node element with two degrees-of-freedom per node (eight degrees-of-freedom total), the displacements in the horizontal and vertical directions. The structure thus has 198 degrees-of-freedom. For the sake of argument, we place the 8x8 element stiffness matrix k of element 24 (the element highlighted above) into the 198x198 structure stiffness matrix K . Since element 24 has nodes 26, 27, 38 and 37, the proper location of the element stiffness matrix in the structure stiffness matrix is defined by the eight-component "location" vector

$$\text{loc} = [2 \cdot 26 - 1 \ 2 \cdot 27 - 1 \ 2 \cdot 27 \ 2 \cdot 38 - 1 \ 2 \cdot 38 \ 2 \cdot 37 - 1 \ 2 \cdot 37] = [51 \ 52 \ 53 \ 54 \ 75 \ 76 \ 73 \ 74]$$

The location vector is the fundamental piece of information required in the **assembly loop** that calculates the structure stiffness matrix K (see following statements).

```
K = sparse(dim,dim);      %dim = 198
```

```
for element = 1:numele    %numele = 80
```

```
%calculate element stiffness matrix
```

```
    kele = elastiffness()
```

```
%calculate location vector
```

```
    loc = ....
```

```
    K(loc,loc) = K(loc,loc) + kele
```

```
end
```

Students usually struggle for some time before they grasp the important statement above, which is one of the key statements in a finite element analysis. Understanding begins, once the student recognizes MATLAB's submatrix capabilities, i.e. that the location vector `loc` temporarily reduces the 198x198 structure stiffness matrix to a 8x8 submatrix to which the element stiffness matrix is added.

For simplicity, each of the six nodes of the eight-element structure is assumed to have only one degree-of-freedom. Each quartet of x-symbols thus represents the 2x2 element stiffness matrix. An empty box stands for a zero entry in the structure stiffness matrix. We observe that a matrix element k_{ij} is non-zero only if the corresponding nodes i and j are directly connected by an element. Figure 2 schematically depicts the state of the 6x6 structure stiffness matrix each time one of the eight elements, re- presented by their 2x2 element stiffness matrix, is added to it. Several x-symbols in one box indicate that the corresponding numerical values should be added.

To efficiently incorporate the displacement **boundary conditions** into MATLAB (we consider only homogeneous boundary conditions here), we use the `find` command to locate the fixed degrees-of-freedom (see Fig. 1).

```
%boundary condition at pin connection
```

```
fixnode = find(x==0 & y==0)
```

```
fixdof = [2*fixnode-1 2*fixnode];
```

```
%boundary condition at roller connection
```

```
fixnode = find(x==Lx & y==0)
```

```
fixdof = [fixdof 2*fixnode];
```

In order to eliminate the fixed degrees-of-freedom from the stiffness matrix it is practical to specify the complementary set, **the free degrees-of-freedom**, which are obtained from the fixed degrees-of-freedom by the operations

```
dof = zeros(1,dim) %dim= number of dofs (fixed and free combined)
```

```
dof(fixdof)=1;
```

```
free = find(dof==0);
```

We reduce the structure force vector F and the structure stiffness matrix K to form the corresponding quantities F_{Free} and K_{free} , solve the set of linear equations for the vector q_{free} of structure displacements and finally add the prescribed zero displacements to the solution vector using the following statements.

```
%initialize displacement vector
```

```
q = zeros(dim,1);
```

%reduce stiffness matrix (eliminate rows and columns representing fixed dofs)

```
Kfree = K(free,free);
```

%reduce force vector

```
Ffree = F(free);
```

%solve equations

```
qfree = Kfree \ Ffree;
```

%include fixed degrees of freedom in displacement vector

```
q(free) = qfree;
```

Similarly to the statement

$$K(\text{loc},\text{loc}) = K(\text{loc},\text{loc}) + k_{\text{ele}}$$

discussed before, which adds the element stiffness matrix to the structure stiffness matrix, students need time to understand the sequence of commands above involving sub-matrix and sub-vector operations.

We **apply the load** to the model (see Fig. 1) by using the find command again.

%distributed load in vertical direction (2nd degree of freedom at loaded %nodes)

```
loadnode = find(y==Ly); %find all nodes on top of beam
```

```
F(2*loadnode) = F;
```

%load at corner points

```
loadnode = find(y==Ly & (x==0 | x==Lx));
```

```
F(2*loadnode) = F/2;
```