

FEA modeling best practice

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Outline

- FEM review
- FE classification
 - Geometry classification
 - Kinematic hypothesis
 - Shape function polynomial basis
 - DOFs per node
 - Node per element
- FE library
 - 3D bar
 - 3D beam
 - 3D shell
 - 3D solid
 - 2D beam
 - 2D shell axisymmetric
 - 2D solid planar stress
 - 2D solid planar strain
 - 2D solid axisymmetric
- Industrial examples

FEM review

Elastostatics equations

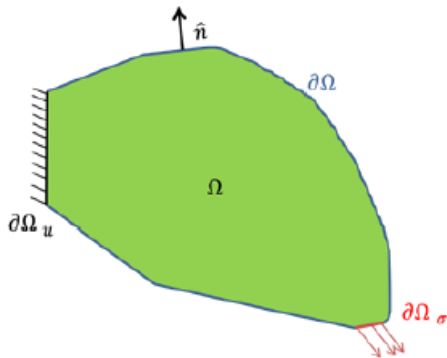


Figure 1.1: linear elastostatics problem definition

Strong formulation

$$\begin{aligned}
 \nabla \cdot [\sigma] + \{b\} &= \{0\} & \forall \{x\} \in \Omega / \partial\Omega \\
 \{u\} &= \{\bar{u}\} & \forall \{x\} \in \partial\Omega_u \\
 [\sigma] \cdot \{\hat{n}\} &= \{\bar{t}\} & \forall \{x\} \in \partial\Omega_\sigma \\
 [\sigma] &= [[E]] : [\varepsilon] & \forall \{x\} \in \Omega
 \end{aligned}$$

Virtual work principle +
Divergence theorem

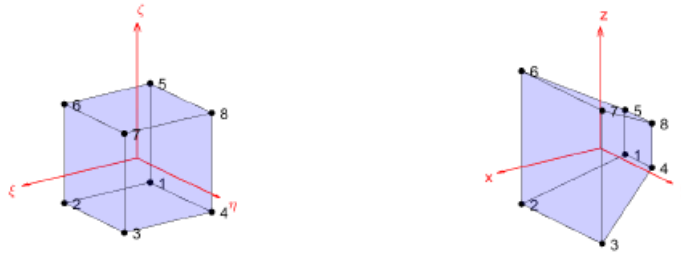
Weak formulation

$$\int_{\partial\Omega_\sigma} \{v\}^T \{\bar{t}\} d\partial\Omega + \int_{\Omega} \{v\}^T \{b\} d\Omega = \int_{\Omega} (\nabla_{sym} \{v\})^T E [D] \nabla_{sym} \{u\} d\Omega \quad \forall \{v\} \in \mathbb{V}$$

FEM review

kinematics

$$\{v\} = [N]^{(h)} \{v\}^{(h)} \quad \{u\} = [N]^{(h)} \{u\}^{(h)}$$



(a) Reference element in the (ξ, η, ζ) space (b) Corresponding mapped element in the (x, y, z) space

Figure 1.2: Classic Mapping in FEA

$$\{X_g\} = \begin{Bmatrix} x \\ y \\ z \end{Bmatrix} = \begin{bmatrix} \{x_n\}^T \\ \{y_n\}^T \\ \{z_n\}^T \end{bmatrix} \{N_n(\xi, \eta, \zeta)\}$$

Local equilibrium

$$[K]^{(h)} \{u\}^{(h)} = \{f\}^{(h)}$$

$$K_{i,j}^{(h)} = \int_{\Omega} ([\nabla_{sym} N_i]^{(h)})^T E [D] [\nabla_{sym} N_j]^{(h)} d\Omega$$

$$f_i^{(h)} = \int_{\partial\Omega_{\sigma}} ([N_i]^{(h)} \cdot \{\bar{t}\}) d\partial\Omega + \int_{\Omega} ([N_i]^{(h)} \cdot \{b\}) d\Omega$$

Global equilibrium

$$[K]^{(h)} \{u\}^{(h)} = \{f\}^{(h)}$$

$$K_{i,j}^{(h)} = \sum_{el=1}^{n_{el}} E_{el} \int_{\Omega_{el}} ([\nabla_{sym} N_i]^{(h)})^T [D] [\nabla_{sym} N_j]^{(h)} d\Omega_{el}$$

$$f_i^{(h)} = \sum_{el=1}^{n_{el}} \int_{\partial\Omega_{\sigma} \cap \partial\Omega_{el}} ([N_i]^{(h)} \cdot \{\bar{t}\}) d\partial\Omega_{el} + \int_{\Omega_{el}} ([N_i]^{(h)} \cdot \{b\}) d\Omega_{el}$$

Numerical integration

$$K_{i,j}^{(h)} = \sum_{el=1}^{n_{el}} E_{el} \sum_{k=1}^{N_{GP}} ([\nabla_{sym} N_{ik}]^{(h)})^T [D] [\nabla_{sym} N_{jk}]^{(h)} |[J_k]| \omega_k$$

$$f_i^{(h)} = \sum_{el=1}^{n_{el}} \sum_{l=1}^{n_{GP}} ([N_{il}]^{(h)} \cdot \{\bar{t}_l\}) |[J_l]| \omega_l + \sum_{k=1}^{N_{GP}} ([N_{ik}]^{(h)} \cdot \{b_k\}) |[J_k]| \omega_k$$

FEM review

Solution and post processing

$$[\mathbf{K}_{\text{bb}}] \{u_b\} + [\mathbf{K}_{\text{bf}}] \{u_f\} = \{R_b\} + \{F_b\}$$

$$[\mathbf{K}_{\text{fb}}] \{u_b\} + [\mathbf{K}_{\text{ff}}] \{u_f\} = \{R_f\} + \{F_f\}$$

$$\{u_f\} = [\mathbf{K}_{\text{ff}}]^{-1} (-[\mathbf{K}_{\text{fb}}] \{u_b\} + \{F_f\})$$

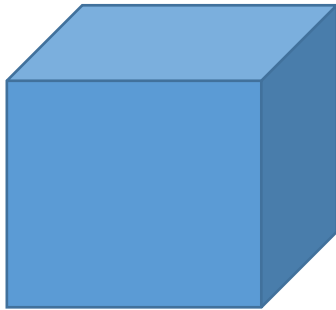
$$\{R_b\} = [\mathbf{K}_{\text{bb}}] \{u_b\} + [\mathbf{K}_{\text{bf}}] \{u_f\} - \{F_b\}$$

$$\{\varepsilon\} = [B_{gp}] \{u_{el}\} \quad \{\sigma\} = [D] [B_{gp}] \{u_{el}\}$$

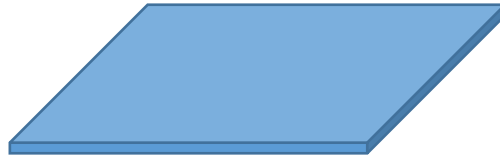
FE classification

Geometry classification

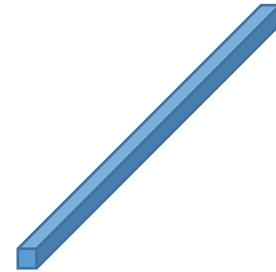
No main dimension



2 main dimensions

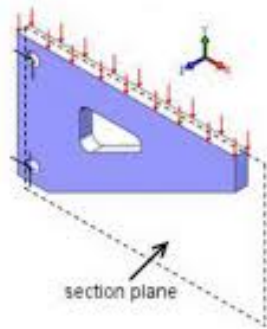


1 main dimensions

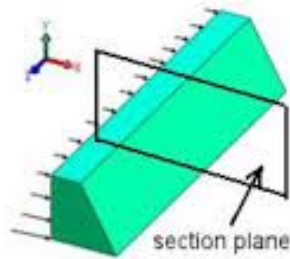


FE classification

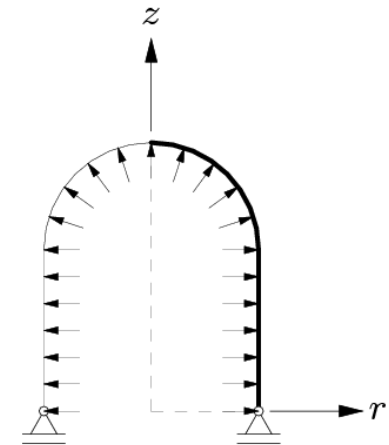
Kinematic hypothesis



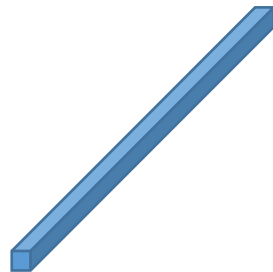
Plane Stress



Plane Strain



Axial symmetry



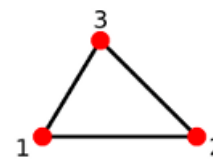
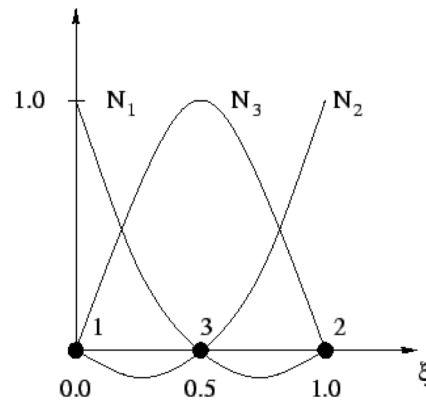
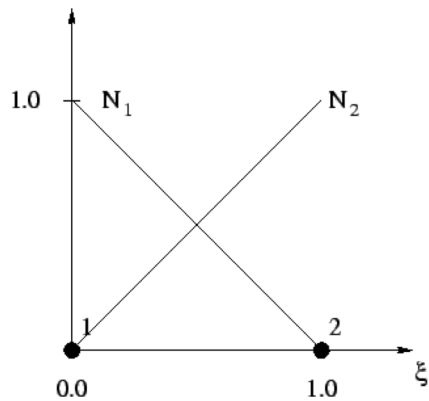
Rigid section



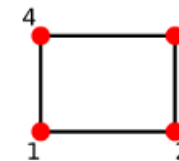
Rigid thickness

FE classification

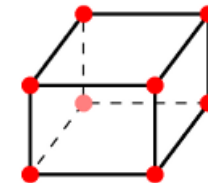
Shape function polynomial basis



Triangle element
with 3 and 6 nodes



Rectangle element
with 4 and 8 nodes



Box element (for 3D)
with 8 and 20 nodes

Sample of some simple element shapes and standard node placement. By convention nodes are numbered anti-clockwise.

FE classification

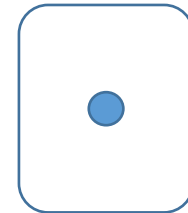
DOFs per node



Solid point:
Material point kinematics
 (u, v, w)



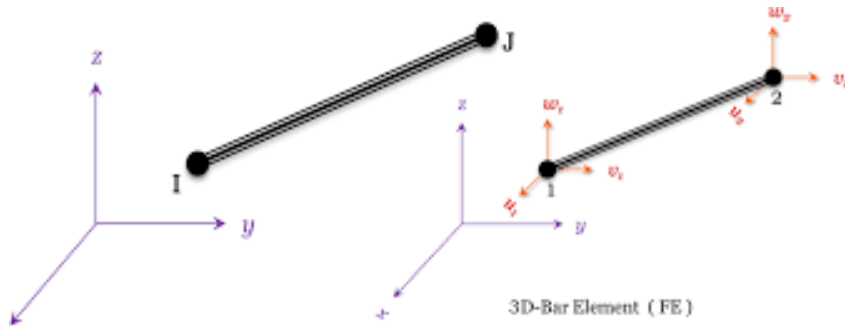
Shell thickness:
Rigid thickness kinematics
 $(u, v, w, \phi_x, \phi_y)$



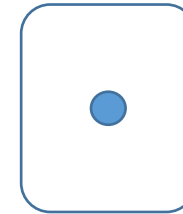
Beam cross section:
Rigid section
 $(u, v, w, \phi_x, \phi_y, \phi_z)$

FE library

3D bar element



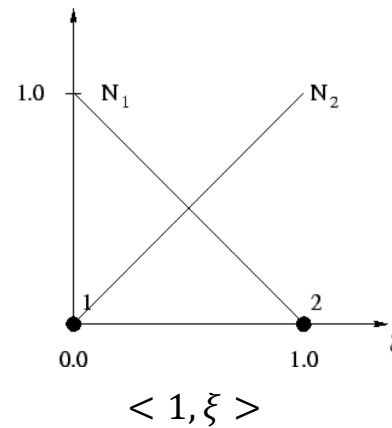
Source: ANSYS (2007)



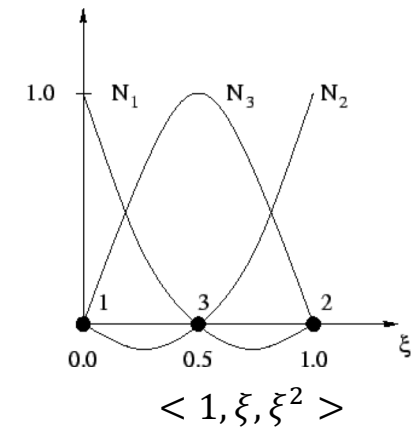
Rod cross section:
Rigid section
(u, v, w)

Shape functions

Linear 2 node element

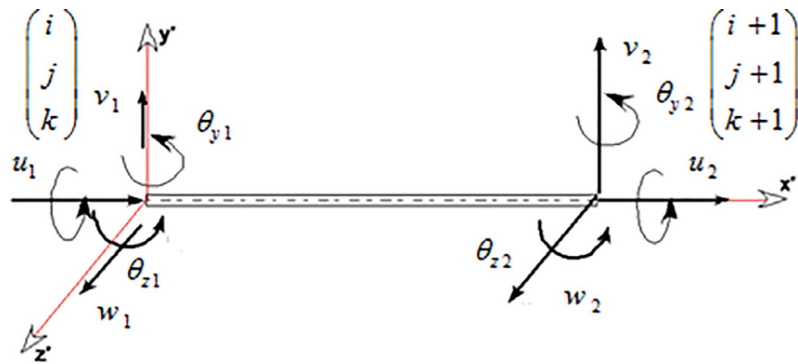


Quadratic 3 node element

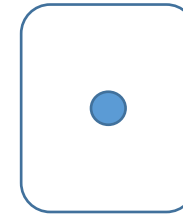


FE library

3D beam element



2 node element



Beam cross section:
Rigid section
($u, v, w, \phi_x, \phi_y, \phi_z$)

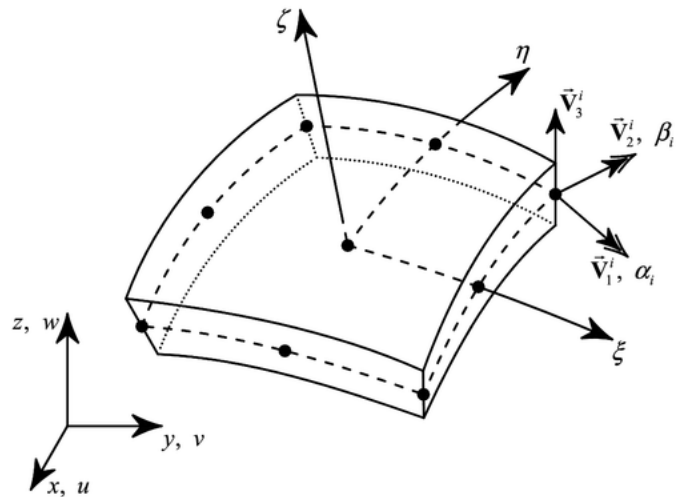
Shape functions

Traction, Torsion $\langle 1, \xi \rangle$

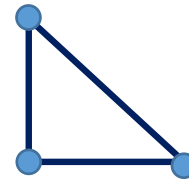
Bending $\langle 1, \xi, \xi^2, \xi^3 \rangle$

FE library

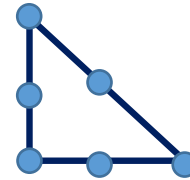
3D shell element



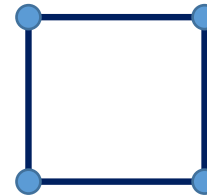
Shell thickness:
Rigid thickness kinematics
(u, v, w, ϕ_x, ϕ_y)



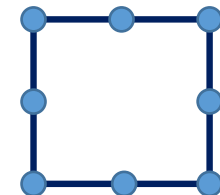
3-node Triangular
 $< 1, \xi, \eta >$



6-node Triangular
 $< 1, \xi, \eta, \xi^2, \xi\eta, \eta^2 >$



4-node Quadrilateral
 $< 1, \xi, \eta, \xi\eta >$



8-node Quadrilateral
 $< 1, \xi, \eta, \xi\eta, \xi^2, \eta^2, \xi^2\eta, \xi\eta^2 >$

FE library

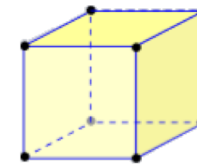
3D solid element



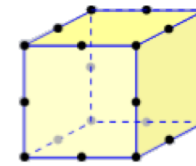
Solid point:
Material point kinematics
(u, v, w)

Hexahedral

$\langle 1, \xi, \eta, \zeta, \xi\eta, \xi\zeta, \eta\zeta, \xi\eta\zeta \rangle$



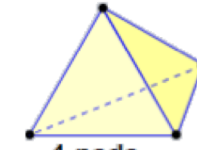
8-node



20-node

Tetrahedral

$\langle 1, \xi, \eta, \zeta \rangle$



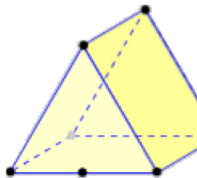
4-node



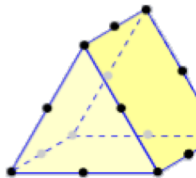
10-node

Pentahedral

$\langle 1, \xi, \eta, \zeta, \xi\zeta, \eta\zeta \rangle$



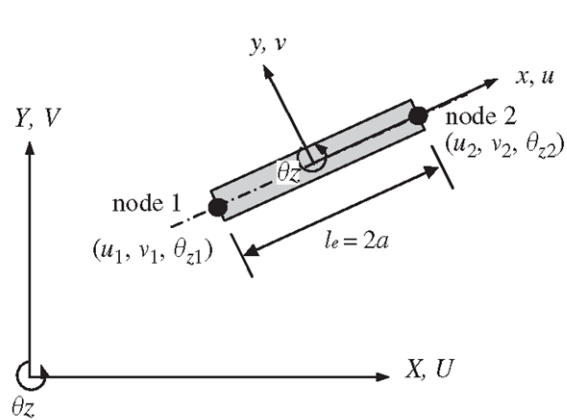
6-node



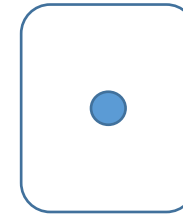
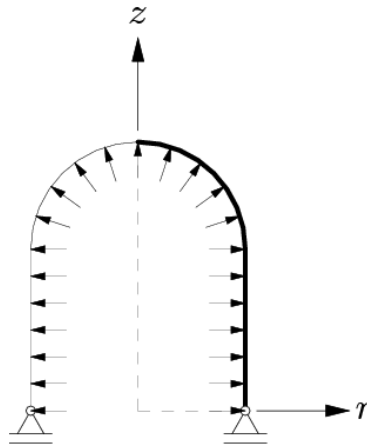
15-node

FE library

2D beam element \ 2D shell axisymmetric



2 node element



Beam cross section:
Rigid section
 (u, v, ϕ_z)

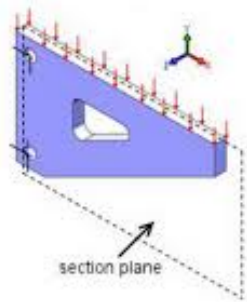
Shape functions

Traction $< 1, \xi >$

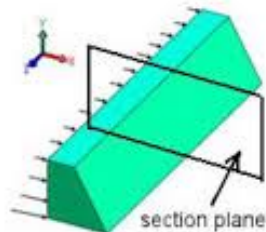
Bending $< 1, \xi, \xi^2, \xi^3 >$

FE library

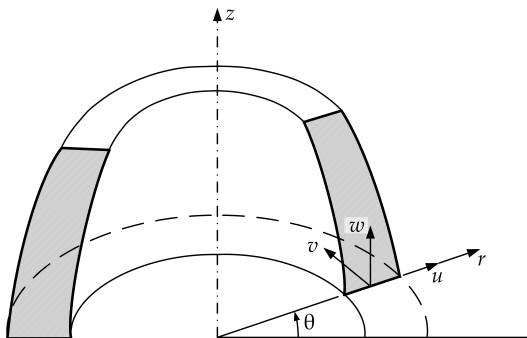
2D solid plane stress\ 2D solid plane strain\ 2D solid axisymmetric



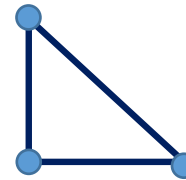
Plane Stress



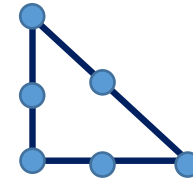
Plane Strain



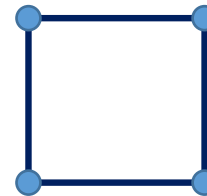
- Solid point:
Material point kinematics
(u, v)



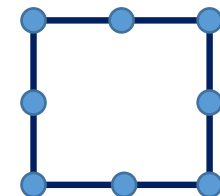
3-node Triangular
< $1, \xi, \eta$ >



6-node Triangular
< $1, \xi, \eta, \xi^2, \xi\eta, \eta^2$ >



< $1, \xi, \eta, \xi\eta$ >



< $1, \xi, \eta, \xi\eta, \xi^2, \eta^2, \xi^2\eta, \xi\eta^2$ >

Industrial Examples



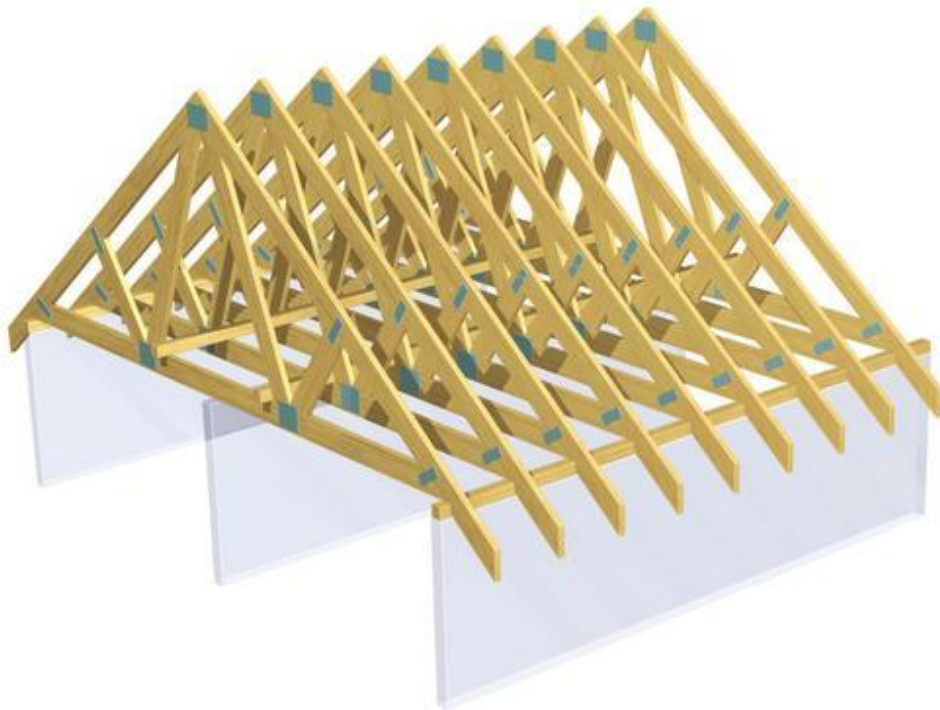
Bridge piers
What kind of FE can you use?

Industrial Examples



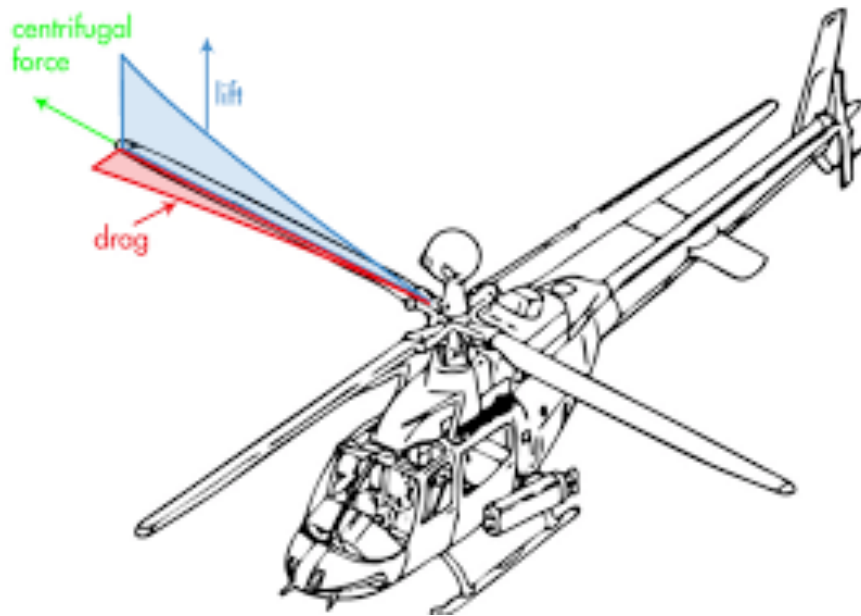
Bridge cables
What kind of FE can you use?

Industrial Examples



Roof frames
What kind of FE can you use?

Industrial Examples



Helicopter blades
What kind of FE can you use?

Industrial examples



Wing box
What kind of FE can you use?

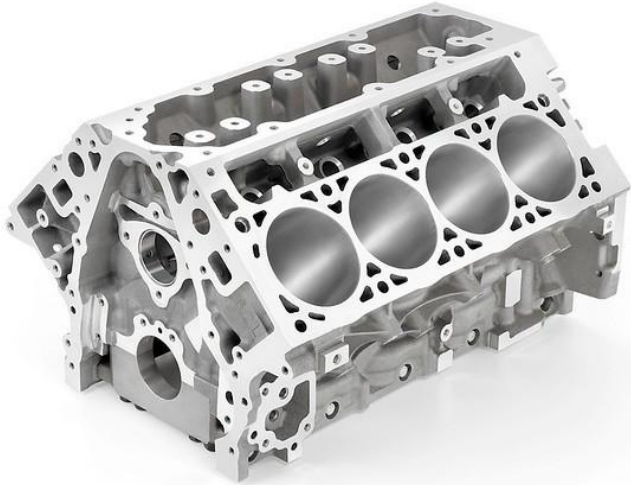
Industrial examples



Dam

What kind of FE can you use?

Industrial examples



Engine block
What kind of FE can you use?

Industrial examples



Rocket Fairings
What kind of FE can you use?

Industrial Examples



Water reservoir
What kind of FE can you use?