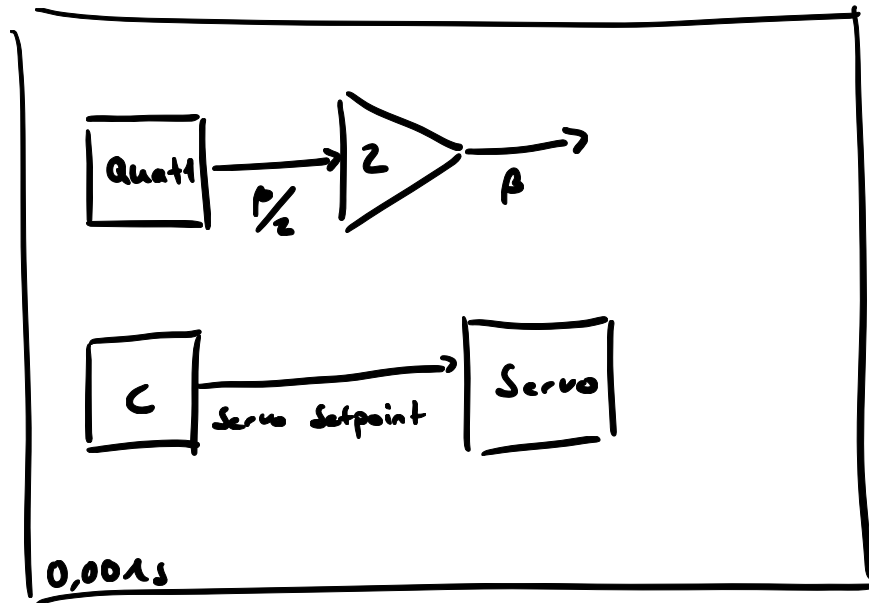


Control System

In our CS we have to get the orientation of the Beaglebone blue and set the position of the servo. To get the orientation we can use once more the IMU. For the setpoint of the servo we can use a constant and modify its value later on in the sequence.



Sequence

