

# Game Theory

## 5. Extensive Games

### 5.1. Extensive Games with Perfect Information

#### 5.1.1. Motivation and Definitions

Albert-Ludwigs-Universität Freiburg



**UNI  
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Summer semester 2020

- **So far:** All players move **simultaneously**, and then the outcome is determined.
- **Often in practice:** Several moves in **sequence** (e. g. in chess).  
     $\rightsquigarrow$  cannot be directly reflected by strategic games.
- **Extensive games** (with perfect information) reflect such situations by modeling games as **game trees**.
- **Idea:** Players have several decision points where they can decide how to play.
- **Strategies:** Mappings from decision points in the game tree to actions to be played.

- **Section 5.1:** extensive games with **perfect information**  
(players know the state of the game and the actions chosen by other players, e. g., chess)
- **Section 5.2:** extensive games with **imperfect information**  
(players may not know the state of the game or the actions chosen by other players, e. g., poker)

## Definition (Extensive game with perfect information)

An **extensive game with perfect information** is a tuple

$\Gamma = \langle N, H, P, (u_i)_{i \in N} \rangle$  that consists of:

- a finite non-empty set  $N$  of **players**,
- a set  $H$  of (finite or infinite) sequences, called **histories**, such that
  - it contains the empty sequence  $\langle \rangle \in H$ ,
  - **$H$  is closed under prefixes**: if  $\langle a^1, \dots, a^k \rangle \in H$  for some  $k \in \mathbb{N} \cup \{\infty\}$ , and  $l < k$ , then also  $\langle a^1, \dots, a^l \rangle \in H$ , and
  - **$H$  is closed under limits**: if for some infinite sequence  $\langle a^i \rangle_{i=1}^\infty$ , we have  $\langle a^i \rangle_{i=1}^k \in H$  for all  $k \in \mathbb{N}$ , then  $\langle a^i \rangle_{i=1}^\infty \in H$ .

All infinite histories and all histories  $\langle a^i \rangle_{i=1}^k \in H$ , for which there is no  $a^{k+1}$  such that  $\langle a^i \rangle_{i=1}^{k+1} \in H$  are called **terminal histories**  $Z$ . Components of a history are called **actions**.

## Definition (Extensive game with perfect information, ctd.)

- a **player function**  $P : H \setminus Z \rightarrow N$  that determines which player's turn it is to move after a given nonterminal history, and
- for each player  $i \in N$ , a **utility function** (or **payoff function**)  $u_i : Z \rightarrow \mathbb{R}$  defined on the set of terminal histories.

The game is called **finite**, if  $H$  is finite. It has a **finite horizon**, if the length of histories is bounded from above.

**Assumption:** All ingredients of  $\Gamma$  are **common knowledge** amongst the players of the game.

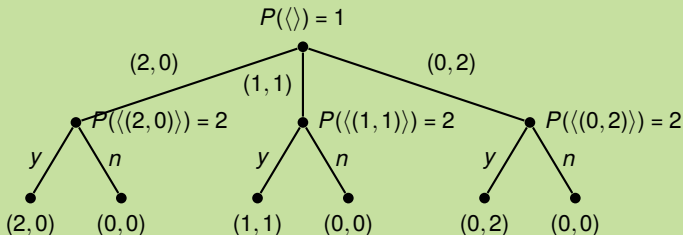
**Terminology:** In the rest of Section 5.1, we will write **extensive games** instead of **extensive games with perfect information**.

## Example (Division game)

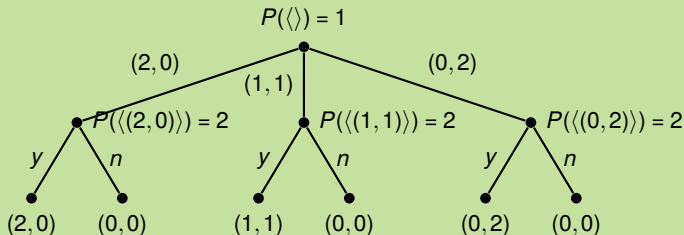
- Two identical objects should be **divided** among two players.
- **Player 1** **proposes** an allocation.
- **Player 2** **agrees** or **rejects**.
  - **on agreement**: allocation as proposed
  - **on rejection**: nobody gets anything

## Example (Division game)

- Two identical objects should be **divided** among two players.
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## Example (Division game, formally)



- $N = \{1, 2\}$
- $H = \{\langle \rangle, \langle (2, 0) \rangle, \langle (1, 1) \rangle, \langle (0, 2) \rangle, \langle (2, 0), y \rangle, \langle (2, 0), n \rangle, \dots\}$
- $P(\langle \rangle) = 1, P(h) = 2$  for all  $h \in H \setminus Z$  with  $h \neq \langle \rangle$
- $u_1(\langle (2, 0), y \rangle) = 2, u_2(\langle (2, 0), y \rangle) = 0$ , etc.



## Notation:

Let  $h = \langle a^1, \dots, a^k \rangle$  be a history, and  $a$  an action.

- Then  $(h, a)$  is the history  $\langle a^1, \dots, a^k, a \rangle$ .
- If  $h' = \langle b^1, \dots, b^\ell \rangle$ , then  $(h, h')$  is the history  $\langle a^1, \dots, a^k, b^1, \dots, b^\ell \rangle$ .
- The set of actions from which player  $P(h)$  can choose after a history  $h \in H \setminus Z$  is written as

$$A(h) = \{a \mid (h, a) \in H\}.$$

**Question:** What is  $A(\langle (2, 0) \rangle)$  in the division game?

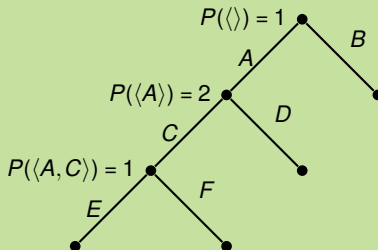
## Definition (Strategy in an extensive game)

A **strategy** of a player  $i$  in an extensive game  $\Gamma = \langle N, H, P, (u_i)_{i \in N} \rangle$  is a function  $s_i$  that assigns to each nonterminal history  $h \in H \setminus Z$  with  $P(h) = i$  an action  $a \in A(h)$ . The set of strategies of player  $i$  is denoted as  $S_i$ .

**Remark:** Strategies require us to assign actions to histories  $h$ , even if it is clear that they will never be played (e. g., because  $h$  will never be reached because of some earlier action).

**Notation (for finite games):** A strategy for a player is written as a string of actions at decision nodes as visited in a breadth-first order.

## Example (Strategies in an extensive game)



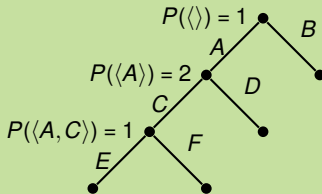
- Strategies for player 1:  $AE$ ,  $AF$ ,  $BE$  and  $BF$
- Strategies for player 2:  $C$  and  $D$ .

## Definition (Outcome)

The **outcome**  $O(s)$  of a strategy profile  $s = (s_i)_{i \in N}$  is the (possibly infinite) terminal history  $h = \langle a^i \rangle_{i=1}^k$ , with  $k \in \mathbb{N} \cup \{\infty\}$ , such that for all  $\ell \in \mathbb{N}$  with  $0 \leq \ell < k$ ,

$$s_{P(\langle a^1, \dots, a^\ell \rangle)}(\langle a^1, \dots, a^\ell \rangle) = a^{\ell+1}.$$

## Example (Outcome)



$$O(AF, C) = \langle A, C, F \rangle$$

$$O(AE, D) = \langle A, D \rangle.$$

- **Extensive games** allow several moves in sequence (cf. game trees).
- Formalized using players, histories, player function, payoff functions for terminal histories.
- **Strategies**: mappings from decision points to actions
- **Outcome**: terminal history resulting from strategy profile

# Game Theory

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### 5.1. Extensive Games with Perfect Information

#### 5.1.2. Solution Concepts

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- So far: definition of extensive games
- Now: solution concepts for extensive games
  - transfer the idea of Nash equilibria
  - identify problems with Nash equilibria
    - ↪ subgame-perfect equilibria

## Definition (Nash equilibrium in an extensive game)

A **Nash equilibrium** in an extensive game  $\Gamma = \langle N, H, P, (u_i)_{i \in N} \rangle$  is a strategy profile  $s^*$  such that for every player  $i \in N$  and for all strategies  $s_i \in S_i$ ,

$$u_i(O(s_{-i}^*, s_i^*)) \geq u_i(O(s_{-i}^*, s_i)).$$



## Definition (Induced strategic game)

The strategic game  $G$  **induced** by an extensive game  $\Gamma = \langle N, H, P, (u_i)_{i \in N} \rangle$  is defined by  $G = \langle N, (A'_i)_{i \in N}, (u'_i)_{i \in N} \rangle$ , where

- $A'_i = S_i$  for all  $i \in N$ , and
- $u'_i(a) = u_i(O(a))$  for all  $i \in N$ .

## Proposition

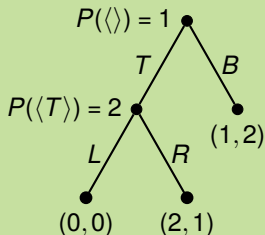
The Nash equilibria of an extensive game  $\Gamma$  are exactly the Nash equilibria of the induced strategic game  $G$  of  $\Gamma$ . □

## Remarks:

- Each extensive game can be transformed into a strategic game, but the resulting game can be exponentially larger.
- The other direction does not work, because in extensive games, we do not have simultaneous actions.

## Example (Empty threat)

Extensive game:



Induced strategic game:

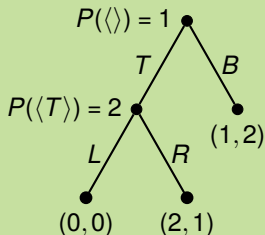
	$L$	$R$
$T$		
$B$		

Strategies:

- Player 1:  $T$  and  $B$
- Player 2:  $L$  and  $R$

## Example (Empty threat)

Extensive game:



Induced strategic game:

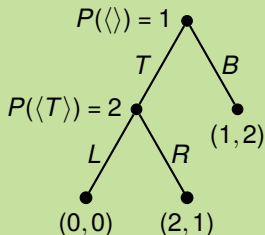
	$L$	$R$
$T$	0, 0	2, 1
$B$	1, 2	1, 2

Strategies:

- Player 1:  $T$  and  $B$
- Player 2:  $L$  and  $R$

## Example (Empty threat)

Extensive game:



Induced strategic game:

	L	R
T	0, 0	2, 1
B	1, 2	1, 2

Nash equilibria:  $(B, L)$  and  $(T, R)$ .

However,  $(B, L)$  is not realistic:

- Player 1 plays  $B$ , “fearing” response  $L$  to  $T$ .
- But player 2 would never play  $L$  against  $T$  in the extensive game.  
 $\rightsquigarrow (B, L)$  involves “empty threat”.

Strategies:

- Player 1:  $T$  and  $B$
- Player 2:  $L$  and  $R$

**Idea:** Exclude empty threats.

**How?** Demand that a strategy profile is not only a Nash equilibrium in the entire game, but also in every subgame.

## Definition (Subgame)

A **subgame** of an extensive game  $\Gamma = \langle N, H, P, (u_i)_{i \in N} \rangle$ , starting after history  $h$ , is the game  $\Gamma(h) = \langle N, H|_h, P|_h, (u_i|_h)_{i \in N} \rangle$ , where

- $H|_h = \{h' \mid (h, h') \in H\}$ ,
- $P|_h(h') = P(h, h')$  for all  $h' \in H|_h$ , and
- $u_i|_h(h') = u_i(h, h')$  for all  $h' \in H|_h$ .

## Definition (Strategy in a subgame)

Let  $\Gamma$  be an extensive game and  $\Gamma(h)$  a subgame of  $\Gamma$  starting after some history  $h$ .

For each strategy  $s_i$  of  $\Gamma$ , let  $s_i|_h$  be the strategy induced by  $s_i$  for  $\Gamma(h)$ . Formally, for all  $h' \in H|_h$ ,

$$s_i|_h(h') = s_i(h, h').$$

The outcome function of  $\Gamma(h)$  is denoted by  $O_h$ .

## Definition (Subgame-perfect equilibrium)

A strategy profile  $s^*$  in an extensive game  $\Gamma = \langle N, H, P, (u_i)_{i \in N} \rangle$  is a **subgame-perfect equilibrium (SPE)** if and only if for every player  $i \in N$  and every nonterminal history  $h \in H \setminus Z$  with  $P(h) = i$ ,

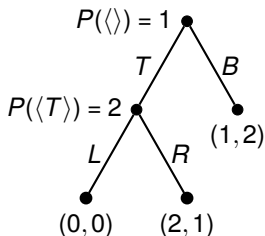
$$u_i|_h(O_h(s_{-i}^*|_h, s_i^*|_h)) \geq u_i|_h(O_h(s_{-i}^*|_h, s_i))$$

for every strategy  $s_i \in S_i$  in subgame  $\Gamma(h)$ .

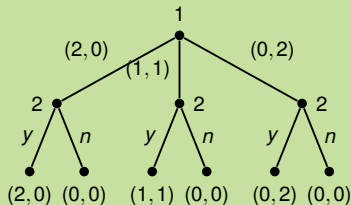


Two Nash equilibria:

- $(T, R)$ : **subgame-perfect**, because:
  - In history  $h = \langle T \rangle$ : subgame-perfect.
  - In history  $h = \langle \rangle$ : player 1 obtains utility 1 when choosing  $B$  and utility of 2 when choosing  $T$ .
- $(B, L)$ : **not subgame-perfect**, since  $L$  does not maximize the utility of player 2 in history  $h = \langle T \rangle$ .



## Example (Subgame-perfect equilibria in division game)



### Equilibria in subgames:

- in  $\Gamma(\langle(2, 0)\rangle)$ :  $y$  and  $n$
- in  $\Gamma(\langle(1, 1)\rangle)$ : only  $y$
- in  $\Gamma(\langle(0, 2)\rangle)$ : only  $y$
- in  $\Gamma(\langle\rangle)$ :  $((2, 0), yyy)$  and  $((1, 1), nyy)$

### Nash equilibria (red: no SPE):

- $((2, 0), yyy)$ ,  $((2, 0), yyn)$ ,  $((2, 0), yny)$ ,  $((2, 0), ynn)$ ,  
 $((2, 0), nny)$ ,  $((2, 0), nnn)$ ,
- $((1, 1), nyy)$ ,  $((1, 1), nyn)$ ,
- $((0, 2), nny)$ .

- **Nash equilibria** in extensive game with perfect information
  - defined directly or
  - defined via induced strategic game
- **Problems with Nash equilibria:**
  - exponentially many strategies to consider
  - **empty threats**
- **Alternative/better solution concept** without empty threats:  
**subgame-perfect equilibria**
  - have to be an equilibrium in every subgame

# Game Theory

## 5. Extensive Games

### 5.1. Extensive Games with Perfect Information

#### 5.1.3. One-Deviation Property

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- So far:
  - definition of extensive games
  - solution concept: subgame-perfect equilibria (SPE)
- Now:
  - Existence:
    - Does every extensive game have a subgame-perfect equilibrium?
    - If not, which extensive games do have a subgame-perfect equilibrium?
  - Computation:
    - If a subgame-perfect equilibrium exists, how to compute it?
    - How complex is that computation?

Positive case (a subgame-perfect equilibrium exists):

- **Step 1:** Show that it suffices to consider **local** deviations from strategies (for finite-horizon games).  
(Section 5.1.3)
- **Step 2:** Show how to **systematically explore such local deviations** to find a subgame-perfect equilibrium (for finite games).  
(Section 5.1.4)

# Step 1: One-Deviation Property



## Definition

Let  $\Gamma$  be a finite-horizon extensive game. Then  $\ell(\Gamma)$  denotes the length of the longest history of  $\Gamma$ .

# Step 1: One-Deviation Property



## Definition (One-deviation property)

A strategy profile  $s^*$  in an extensive game  $\Gamma = \langle N, H, P, (u_i)_{i \in N} \rangle$  **satisfies the one-deviation property** if and only if for every player  $i \in N$  and every nonterminal history  $h \in H \setminus Z$  with  $P(h) = i$ ,

$$u_i|_h(O_h(s^*_{-i}|_h, s^*_i|_h)) \geq u_i|_h(O_h(s^*_{-i}|_h, s_i))$$

for every strategy  $s_i \in S_i$  in subgame  $\Gamma(h)$  **that differs from  $s^*_i|_h$  only in the action it prescribes after the initial history of  $\Gamma(h)$ .**

**Note:** Without the **highlighted part** in the end, this is just the definition of subgame-perfect equilibria!



# Step 1: One-Deviation Property



## Lemma

Let  $\Gamma = \langle N, H, P, (u_i)_{i \in N} \rangle$  be a **finite-horizon** extensive game. Then a strategy profile  $s^*$  is a subgame-perfect equilibrium of  $\Gamma$  if and only if it satisfies the one-deviation property.

## Proof

- $(\Rightarrow)$  Clear.
- $(\Leftarrow)$  By contradiction:

Suppose that  $s^*$  is not a subgame-perfect equilibrium.

Then there is a history  $h$  and a player  $i$  such that  $s_i$  is a profitable deviation for player  $i$  in subgame  $\Gamma(h)$ .

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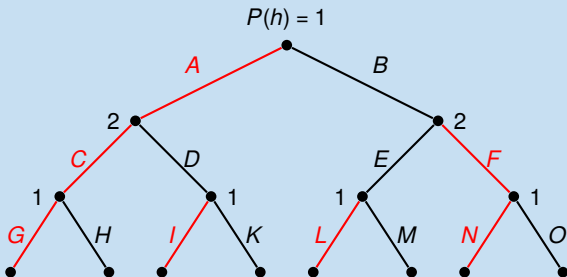
# Step 1: One-Deviation Property



## Proof (ctd.)

- ( $\Leftarrow$ ) ... WLOG, the number of histories  $h'$  with  $s_i(h') \neq s_i^*|_h(h')$  is at most  $\ell(\Gamma(h))$  and hence finite (finite horizon assumption!), since deviations not on resulting outcome path are irrelevant.

Illustration: strategies  $s_1^*|_h = AGILN$  and  $s_2^*|_h = CF$ :

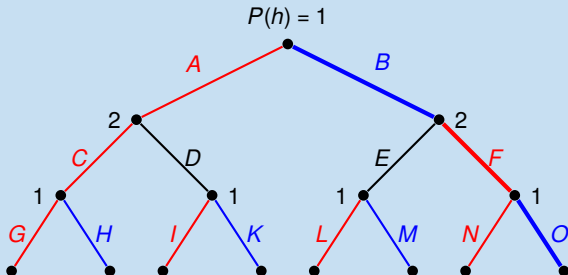


# Step 1: One-Deviation Property



## Proof (ctd.)

- ( $\Leftarrow$ ) ... Illustration for WLOG assumption: Assume  $s_1 = BHKMO$  (blue) profitable deviation:



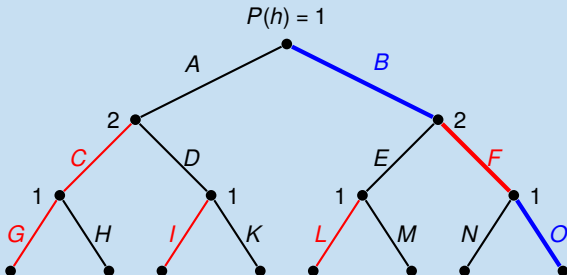
Then only  $B$  and  $O$  really matter.

# Step 1: One-Deviation Property



## Proof (ctd.)

- ( $\Leftarrow$ ) ... Illustration for WLOG assumption: And hence  $\tilde{s}_1 = BGILO$  (blue) also profitable deviation:



# Step 1: One-Deviation Property



## Proof (ctd.)

■ ( $\Leftarrow$ ) ...

Choose profitable deviation  $s_i$  in  $\Gamma(h)$  with minimal number of deviation points (such  $s_i$  must exist).

Let  $h^*$  be the longest history in  $\Gamma(h)$  with  $s_i(h^*) \neq s_i^*|_h(h^*)$ , i.e., “deepest” deviation point for  $s_i$ .

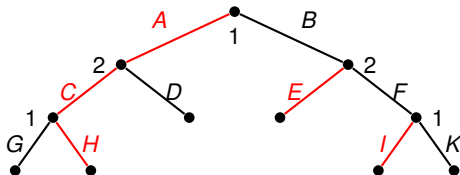
Then in  $\Gamma(h, h^*)$ ,  $s_i|_{h^*}$  differs from  $s_i^*|_{(h, h^*)}$  only in the initial history.

Moreover,  $s_i|_{h^*}$  is a profitable deviation in  $\Gamma(h, h^*)$ , since otherwise fewer deviation points would suffice.

So,  $\Gamma(h, h^*)$  is the desired subgame where a one-step deviation is sufficient to improve utility. □

# Step 1: One-Deviation Property

## Example



To show that  $(AHI, CE)$  is a subgame-perfect equilibrium, it suffices to check these deviating strategies:

### Player 1:

- $G$  in subgame  $\Gamma(\langle A, C \rangle)$
- $K$  in subgame  $\Gamma(\langle B, F \rangle)$
- $BHI$  in  $\Gamma$

### Player 2:

- $D$  in subgame  $\Gamma(\langle A \rangle)$
- $F$  in subgame  $\Gamma(\langle B \rangle)$

In particular, e.g., no need to check if strategy  $BGK$  of player 1 is profitable in  $\Gamma$ .

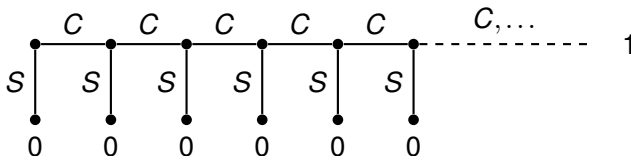
# Step 1: One-Deviation Property

## Remark on Infinite-Horizon Games



The corresponding proposition for infinite-horizon games **does not hold**.

Counterexample (one-player case):



Strategy  $s_i$  with  $s_i(h) = S$  for all  $h \in H \setminus Z$

- satisfies one deviation property, but
- is not a subgame-perfect equilibrium, since it is dominated by  $s_i^*$  with  $s_i^*(h) = C$  for all  $h \in H \setminus Z$ .

- For **finite-horizon extensive games**, it suffices to consider **local deviations** when looking for better strategies.
- This simplifies verifying whether a strategy profile is an SPE (or finding one).
- For infinite-horizon games, this is not true in general.



# Game Theory

## 5. Extensive Games

### 5.1. Extensive Games with Perfect Information

#### 5.1.4. Kuhn's Theorem

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(Section 5.1.3)
- **Step 2:** Show how to **systematically explore such local deviations** to find a subgame-perfect equilibrium (for finite games).  
(Section 5.1.4)

## Step 2: Kuhn's Theorem



### Theorem (Kuhn)

Every **finite** extensive game has a subgame-perfect equilibrium.

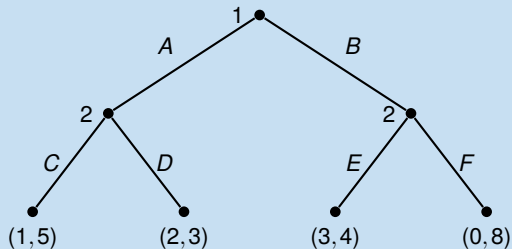
#### Proof idea:

- Proof is **constructive** and builds a subgame-perfect equilibrium bottom-up (aka **backward induction**).
- For those familiar with the Foundations of AI lecture: generalization of Minimax algorithm to general-sum games with possibly more than two players.

## Step 2: Kuhn's Theorem



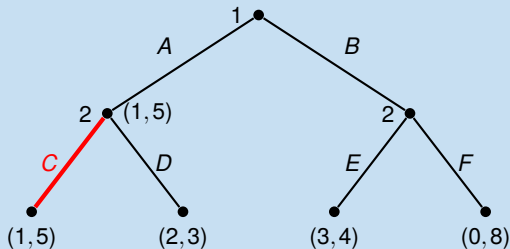
### Example



## Step 2: Kuhn's Theorem



### Example



$$s_2(\langle A \rangle) = C$$

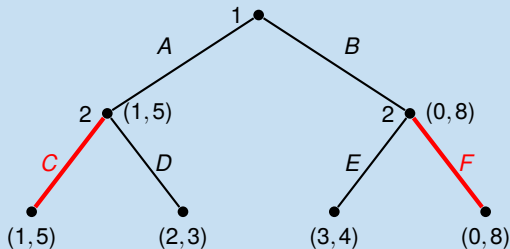
$$t_1(\langle A \rangle) = 1$$

$$t_2(\langle A \rangle) = 5$$

## Step 2: Kuhn's Theorem



### Example



$$s_2(\langle A \rangle) = C$$

$$t_1(\langle A \rangle) = 1$$

$$t_2(\langle A \rangle) = 5$$

$$s_2(\langle B \rangle) = F$$

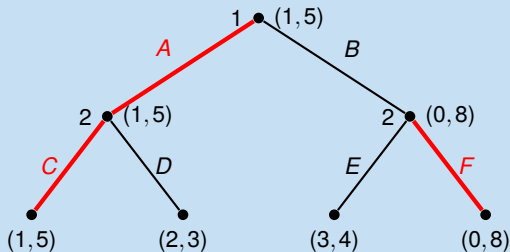
$$t_1(\langle B \rangle) = 0$$

$$t_2(\langle B \rangle) = 8$$

## Step 2: Kuhn's Theorem



### Example



$$s_2(\langle A \rangle) = C$$

$$t_1(\langle A \rangle) = 1$$

$$t_2(\langle A \rangle) = 5$$

$$s_2(\langle B \rangle) = F$$

$$t_1(\langle B \rangle) = 0$$

$$t_2(\langle B \rangle) = 8$$

$$s_1(\langle \rangle) = A$$

$$t_1(\langle \rangle) = 1$$

$$t_2(\langle \rangle) = 5$$



## Step 2: Kuhn's Theorem



A bit more formally:

### Proof

Let  $\Gamma = \langle N, H, P, (u_i)_{i \in N} \rangle$  be a finite extensive game.

Construct a subgame-perfect equilibrium by induction on  $\ell(\Gamma(h))$  for all subgames  $\Gamma(h)$ . In parallel, construct functions  $t_i : H \rightarrow \mathbb{R}$  for all players  $i \in N$  s. t.  $t_i(h)$  is the payoff for player  $i$  in a subgame-perfect equilibrium in subgame  $\Gamma(h)$ .

**Base case:** If  $\ell(\Gamma(h)) = 0$ , then  $t_i(h) = u_i(h)$  for all  $i \in N$ .

...

## Step 2: Kuhn's Theorem



### Proof (ctd.)

**Inductive case:** If  $t_i(h)$  already defined for all  $h \in H$  with  $\ell(\Gamma(h)) \leq k$ , consider  $h^* \in H$  with  $\ell(\Gamma(h^*)) = k + 1$  and  $P(h^*) = i$ .

For all  $a \in A(h^*)$ ,  $\ell(\Gamma(h^*, a)) \leq k$ , let

$$s_i(h^*) := \operatorname{argmax}_{a \in A(h^*)} t_i(h^*, a) \quad \text{and}$$

$$t_j(h^*) := t_j(h^*, s_i(h^*)) \quad \text{for all players } j \in N.$$

Inductively, we obtain a strategy profile  $s$  that satisfies the one-deviation property.

With the one-deviation property lemma it follows that  $s$  is a subgame-perfect equilibrium. □

## Step 2: Kuhn's Theorem



- **In principle:** sample subgame-perfect equilibrium effectively computable using the technique from the above proof.
- **In practice:** often game trees not enumerated in advance, hence unavailable for backward induction.
- E.g., for branching factor  $b$  and depth  $m$ , procedure needs time  $O(b^m)$ .

# Step 2: Kuhn's Theorem

## Remark on Infinite Games



Corresponding proposition for infinite games **does not hold**.

Counterexamples (both for one-player case):

A) finite horizon, infinite branching factor:

Infinitely many actions  $a \in A = [0, 1)$  with payoffs  $u_1(\langle a \rangle) = a$  for all  $a \in A$ .

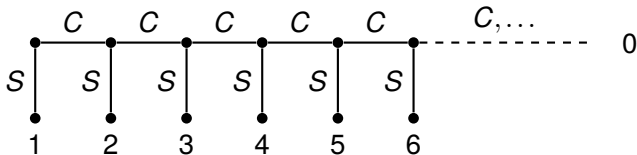
There exists no subgame-perfect equilibrium in this game.

# Step 2: Kuhn's Theorem

## Remark on Infinite Games



B) infinite horizon, finite branching factor:



$$u_1(CCC\dots) = 0 \text{ and } u_1(\underbrace{CC\dots C}_n S) = n + 1.$$

No subgame-perfect equilibrium.

## Step 2: Kuhn's Theorem



### Uniqueness:

Kuhn's theorem tells us nothing about uniqueness of subgame-perfect equilibria. However, if no two histories get the same evaluation by any player, then the subgame-perfect equilibrium is unique.

# Extended Example: Pirate Game



- 1 There are five **rational** pirates,  $A, B, C, D$  and  $E$ . They find 100 gold coins. They must decide how to distribute them.
- 2 The pirates have a strict order of **seniority**:  $A$  is senior to  $B$ , who is senior to  $C$ , who is senior to  $D$ , who is senior to  $E$ .
- 3 The pirate world's rules of distribution say that the most senior pirate first **proposes** a distribution of coins. The pirates, including the proposer, then **vote** on whether to accept this distribution (in order from most junior to senior). In case of a tie vote, the proposer has the casting vote. If the distribution is accepted, the coins are disbursed and the **game ends**. If not, the proposer is thrown overboard from the pirate ship and dies, and the next most senior pirate makes a new proposal to apply the method again.

- 4 The pirates do not trust each other, and will neither make nor honor any promises between pirates apart from a proposed distribution plan that gives a whole number of gold coins to each pirate.
- 5 Pirates base their decisions on three factors. First of all, each pirate wants to **survive**. Second, everything being equal, each pirate wants to **maximize the number of gold coins** each receives. Third, each pirate would prefer to **throw another overboard**, if all other results would otherwise be equal.



- Players  $N = \{A, B, C, D, E\}$ ;
- actions are:
  - proposals by a pirate:  $\langle A : x_A, B : x_B, C : x_C, D : x_D, E : x_E \rangle$ ,  
with  $\sum_{i \in \{A, B, C, D, E\}} x_i = 100$ ;
  - votings:  $y$  for accepting,  $n$  for rejecting;
- histories are sequences of a proposal, followed by votings of the alive pirates;
- utilities:
  - for pirates who are alive: utilities are according to the accepted proposal plus  $x/100$ ,  $x$  being the number of dead pirates;
  - for dead pirates:  $-100$ .

**Remark:** Very large game tree!



- 1 Assume only  $D$  and  $E$  are still alive.  $D$  can propose  $\langle A : 0, B : 0, C : 0, D : 100, E : 0 \rangle$ , because  $D$  has the casting vote!

# Pirates: Analysis by Backward Induction



- 1 Assume only  $D$  and  $E$  are still alive.  $D$  can propose  $\langle A : 0, B : 0, C : 0, D : 100, E : 0 \rangle$ , because  $D$  has the casting vote!
- 2 Assume  $C$ ,  $D$ , and  $E$  are alive. For  $C$  it is enough to offer 1 coin to  $E$  to get his vote:  $\langle A : 0, B : 0, C : 99, D : 0, E : 1 \rangle$ .

- 1 Assume only  $D$  and  $E$  are still alive.  $D$  can propose  $\langle A : 0, B : 0, C : 0, D : 100, E : 0 \rangle$ , because  $D$  has the casting vote!
- 2 Assume  $C$ ,  $D$ , and  $E$  are alive. For  $C$  it is enough to offer 1 coin to  $E$  to get his vote:  $\langle A : 0, B : 0, C : 99, D : 0, E : 1 \rangle$ .
- 3 Assume  $B$ ,  $C$ ,  $D$ , and  $E$  are alive.  $B$  offering  $D$  one coin is enough because of the casting vote:  
 $\langle A : 0, B : 99, C : 0, D : 1, E : 0 \rangle$ .

- 1 Assume only  $D$  and  $E$  are still alive.  $D$  can propose  $\langle A : 0, B : 0, C : 0, D : 100, E : 0 \rangle$ , because  $D$  has the casting vote!
- 2 Assume  $C$ ,  $D$ , and  $E$  are alive. For  $C$  it is enough to offer 1 coin to  $E$  to get his vote:  $\langle A : 0, B : 0, C : 99, D : 0, E : 1 \rangle$ .
- 3 Assume  $B$ ,  $C$ ,  $D$ , and  $E$  are alive.  $B$  offering  $D$  one coin is enough because of the casting vote:  
 $\langle A : 0, B : 99, C : 0, D : 1, E : 0 \rangle$ .
- 4 Assume  $A$ ,  $B$ ,  $C$ ,  $D$ , and  $E$  are alive.  $A$  offering  $C$  and  $E$  each one coin is enough:  $\langle A : 98, B : 0, C : 1, D : 0, E : 1 \rangle$   
(note that giving 1 to  $D$  instead to  $E$  does not help).

- Every **finite extensive game** has a **subgame-perfect equilibrium**.
- This does not generally hold for infinite games, no matter if the game is infinite due to infinite branching factor or infinitely long histories (or both).
- Subgame-perfect equilibria in finite extensive game can be identified using **backward induction**.

# Game Theory

## 5. Extensive Games

### 5.1. Extensive Games with Perfect Information

#### 5.1.5 Simultaneous Moves and Chance Moves

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Summer semester 2020

- So far:
  - Finite-horizon extensive games with perfect information: one-deviation property
  - Finite extensive games with perfect information: Kuhn's theorem
- Now: what about those results if we allow
  - simultaneous moves or
  - chance moves?



## Definition

An **extensive game with simultaneous moves** is a tuple

$\Gamma = \langle N, H, P, (u_i)_{i \in N} \rangle$ , where

- $N, H, P$  and  $(u_i)$  are defined as before, and
- $P : H \setminus Z \rightarrow 2^N$  assigns to each nonterminal history a **set** of players to move; for all  $h \in H \setminus Z$ , there exists a family  $(A_i(h))_{i \in P(h)}$  such that

$$A(h) = \{a \mid (h, a) \in H\} = \prod_{i \in P(h)} A_i(h).$$



- **Intended meaning of simultaneous moves:** all players from  $P(h)$  move simultaneously
- **Strategies:** functions  $s_i : h \mapsto a_i$  with  $a_i \in A_i(h)$
- **Histories:** sequences of vectors of actions
- **Outcome:** terminal history reached when tracing strategy profile
- **Payoffs:** utilities at outcome history

### Observations:

- The **one-deviation property still holds** for extensive games with perfect information and simultaneous moves.
- **Kuhn's theorem does not hold** for extensive game with simultaneous moves.

**Example:** MATCHING PENNIES can be viewed as extensive game with simultaneous moves. No Nash equilibrium/subgame-perfect equilibrium.

		player 2	
		<i>H</i>	<i>T</i>
player 1	<i>H</i>	1, -1	-1, 1
	<i>T</i>	-1, 1	1, -1

⇒ Need more sophisticated solution concepts (cf. mixed strategies). Not covered in this course.

# Simultaneous Moves

## Example: Three-Person Cake Splitting Game



### Setting:

- Three players have to split a cake fairly.
- Player 1 suggest split: shares  $x_1, x_2, x_3 \in [0, 1]$  s.t.  
 $x_1 + x_2 + x_3 = 1$ .
- Then players 2 and 3 **simultaneously** and **independently** decide whether to accept (“y”) or reject (“n”) the suggested splitting.
- If both accept, each player  $i$  gets their allotted share (utility  $x_i$ ). Otherwise, no player gets anything (utility 0).

# Simultaneous Moves

## Example: Three-Person Cake Splitting Game



Formally:

$$N = \{1, 2, 3\}$$

$$X = \{(x_1, x_2, x_3) \in [0, 1]^3 \mid x_1 + x_2 + x_3 = 1\}$$

$$H = \{\langle \rangle\} \cup \{\langle x \rangle \mid x \in X\} \cup \{\langle x, z \rangle \mid x \in X, z \in \{y, n\} \times \{y, n\}\}$$

$$P(\langle \rangle) = \{1\}$$

$$P(\langle x \rangle) = \{2, 3\} \text{ for all } x \in X$$

$$u_i(\langle x, z \rangle) = \begin{cases} 0 & \text{if } z \in \{(y, n), (n, y), (n, n)\} \\ x_i & \text{if } z = (y, y). \end{cases} \text{ for all } i \in N$$

Simultaneous  
Moves

Chance  
Moves

# Simultaneous Moves

Example: Three-Person Cake Splitting Game



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Simultaneous  
Moves

Chance  
Moves

Subgame-perfect equilibria:

- **Subgames after legal split**  $(x_1, x_2, x_3)$  by player 1:
  - NE  $(y, y)$  (both accept)
  - NE  $(n, n)$  (neither accepts)
  - If  $x_2 = 0$ , NE  $(n, y)$  (only player 3 accepts)
  - If  $x_3 = 0$ , NE  $(y, n)$  (only player 2 accepts)

### Subgame-perfect equilibria (ctd.):

#### ■ Entire game:

Let  $s_2$  and  $s_3$  be any two strategies of players 2 and 3 such that for all splits  $x \in X$  the profile  $(s_2(\langle x \rangle), s_3(\langle x \rangle))$  is one of the NEs from above.

Let  $X_y = \{x \in X \mid s_2(\langle x \rangle) = s_3(\langle x \rangle) = y\}$  be the set of splits accepted under  $s_2$  and  $s_3$ . Distinguish three cases:

- $X_y = \emptyset$  or  $x_1 = 0$  for all  $x \in X_y$ . Then  $(s_1, s_2, s_3)$  is a subgame-perfect equilibrium for any possible  $s_1$ .
- $X_y \neq \emptyset$  and there are splits  $x_{\max} = (x_1, x_2, x_3) \in X_y$  that maximize  $x_1 > 0$ . Then  $(s_1, s_2, s_3)$  is a subgame-perfect equilibrium if and only if  $s_1(\langle \rangle)$  is such a split  $x_{\max}$ .
- $X_y \neq \emptyset$  and there are no splits  $(x_1, x_2, x_3) \in X_y$  that maximize  $x_1$ . Then there is no subgame-perfect equilibrium, in which player 2 follows strategy  $s_2$  and player 3 follows strategy  $s_3$ .

## Definition

An **extensive game with chance moves** is a tuple

$\Gamma = \langle N, H, P, f_c, (u_i)_{i \in N} \rangle$ , where

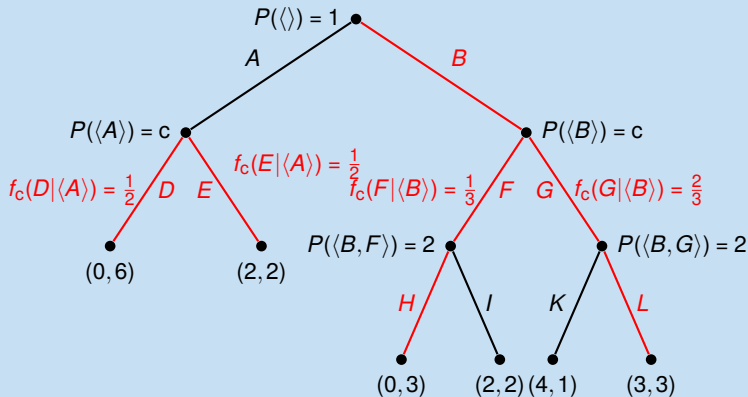
- $N, A, H$  and  $u_i$  are defined as before,
- the player function  $P : H \setminus Z \rightarrow N \cup \{c\}$  can also take the value **c** for a **chance node**, and
- for each  $h \in H \setminus Z$  with  $P(h) = c$ , the function  $f_c(\cdot|h)$  is a probability distribution on  $A(h)$  such that the probability distributions for all  $h \in H \setminus Z$  with  $P(h) = c$  are independent of each other.



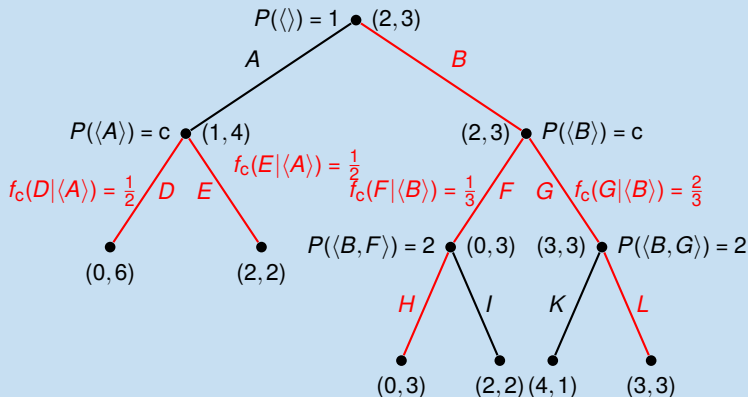


- **Intended meaning of chance moves:** in chance node, an applicable action is chosen randomly with probability according to  $f_c$
- **Strategies:** as before
- **Outcome:** for a given strategy profile, the outcome is a probability distribution on the set of terminal histories
- **Payoffs:** for player  $i$ ,  $U_i$  is the expected payoff (with weights according to outcome probabilities)

## Example



## Example





### Remark:

The one-deviation property and Kuhn's theorem still hold in the presence of chance moves. When proving Kuhn's theorem, **expected** utilities have to be used.

- With **simultaneous moves**:
  - ✓ One-deviation property still holds.
  - ✗ Kuhn's theorem no longer holds.
  
- With **chance moves**:
  - ✓ One-deviation property still holds.
  - ✓ Kuhn's theorem still holds.

# Game Theory

## 5. Extensive Games

### 5.2. Extensive Games with Imperfect Information

#### 5.2.1. Motivation and Definitions

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- **So far:** All state information is common knowledge among all players
- **Often in practice:** Only partial knowledge (e. g. in card games)
- Extensive games **with imperfect information** model such situations using **information sets** of indistinguishable histories.

- Decision points are now such information sets.
- Strategies:
  - **Pure:** InfoSets  $\rightarrow$  Actions
  - **Mixed:** (InfoSets  $\rightarrow$  Actions)  $\rightarrow$  Probabilities  
(randomization over pure strategies)
  - **Behavioral:** InfoSets  $\rightarrow$  (Actions  $\rightarrow$  Probabilities)  
(collections of independent randomized decisions for each information set)
- Different from **incomplete** information games, in which there is uncertainty about the utility functions of the other players.



## Definition (Extensive game)

An **extensive game** is a tuple  $\Gamma = \langle N, H, P, f_c, (\mathcal{I}_i)_{i \in N}, (u_i)_{i \in N} \rangle$  that consists of:

- a finite non-empty set  $N$  of **players**,
- a set  $H$  of (finite or infinite) sequences, called **histories**, such that
  - it contains the empty sequence  $\langle \rangle \in H$ ,
  - $H$  is **closed under prefixes**: if  $\langle a^1, \dots, a^k \rangle \in H$  for some  $k \in \mathbb{N} \cup \{\infty\}$ , and  $l < k$ , then also  $\langle a^1, \dots, a^l \rangle \in H$ , and
  - $H$  is **closed under limits**: if for some infinite sequence  $\langle a^i \rangle_{i=1}^\infty$ , we have  $\langle a^i \rangle_{i=1}^k \in H$  for all  $k \in \mathbb{N}$ , then  $\langle a^i \rangle_{i=1}^\infty \in H$ .

All infinite histories and all histories  $\langle a^i \rangle_{i=1}^k \in H$ , for which there is no  $a^{k+1}$  such that  $\langle a^i \rangle_{i=1}^{k+1} \in H$  are called **terminal histories**. Components of a history are called **actions**.

## Definition (Extensive game, ctd.)

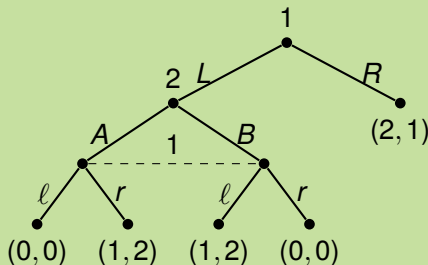
- a **player function**  $P : H \setminus Z \rightarrow N \cup \{c\}$  that determines which player's turn it is to move after a given nonterminal history,  $c$  signifying a **chance move**,
- a probability distribution  $f_c(\cdot|h)$  over  $A(h)$ ,
- an **information partition**  $\mathcal{I}_i$  for player  $i$  of  $\{h \in H | P(h) = i\}$  with the property that  $A(h) = A(h')$  whenever  $h$  and  $h'$  are in the same member  $I_i \in \mathcal{I}_i$  of the partition (notation:  $A(I_i)$ ,  $P(I_i)$ ; members  $I_i$  of the partition are called **information sets**), and
- for each player  $i \in N$ , a **utility function** (or **payoff function**)  $u_i : Z \rightarrow \mathbb{R}$  defined on the set of terminal histories.

$\Gamma$  is **finite**, if  $H$  is finite; **finite horizon**, if histories are bounded.

# Extensive Games with Imperfect Information



## Example



After player 1 chooses  $L$ , player 2 makes a move ( $A$  or  $B$ ) that player 1 cannot observe. Formally:

$$\mathcal{I}_1 = \{I_{11}, I_{12}\} \quad \text{with} \quad I_{11} = \{\langle \rangle\} \text{ and } I_{12} = \{\langle L, A \rangle, \langle L, B \rangle\}$$

$$\mathcal{I}_2 = \{I_{21}\} \quad \text{with} \quad I_{21} = \{\langle L \rangle\}$$

- **Question:** We already have chance moves, but could/should we extend the model with **simultaneous moves** as well?
- **Answer:** We could, but we don't need to. Actually, we can already **model** them somehow.
- In the example game after the history  $\langle L \rangle$ , we have essentially a simultaneous move of players 1 and 2:
  - When player 2 moves, he does not know what player 1 will do.
  - After player 2 has made his move, player 1 does not know whether  $A$  or  $B$  was chosen.
  - Only after both players have acted, they are presented with the outcome.

- **Consequence:** We will need **randomized strategies** as part of a reasonable solution concept, since:
  - already for **strategic games**, we need **randomized strategies** to guarantee equilibrium existence (in the finite case),
  - **strategic games** are a **special case** of extensive games with perfect information and **simultaneous moves**, and
  - extensive games with perfect information and **simultaneous moves** are a **special case** of extensive games with **imperfect information**.

- Extensive games with **imperfect information** can model situations in which the players know only part of the world.
- Modeled by **information sets**, which are the histories an agent cannot distinguish.
- In the model, we allow chance moves (explicitly) and simultaneous moves (implicitly).

# Game Theory

## 5. Extensive Games

### 5.2. Extensive Games with Imperfect Information

#### 5.2.2. Perfect Recall

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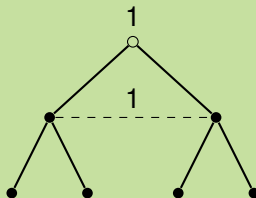
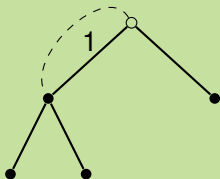
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Information sets can be arbitrary. However, often we want to assume that agents always remember what they have learned before and which actions they have performed: **perfect recall**.

## Example (Imperfect recall)



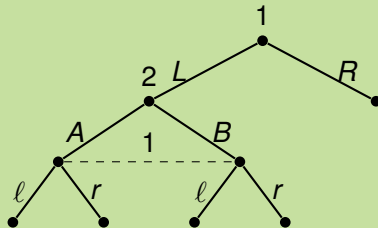
- **Left:** player 1 forgets that he made a move!
- **Right:** player 1 cannot remember what his last move was.



## Definition (Experience record)

Given a history  $h$  of an extensive game,  $X_i(h)$  is the sequence consisting of information sets that player  $i$  encounters in  $h$  and the actions that player  $i$  takes at them.  $X_i$  is called the **experience record** of player  $i$  in  $h$ .

## Example



Player 1 encounters two information sets in the history  $h = \langle L, A \rangle$ , namely  $I_{11} = \{\langle \rangle\}$  and  $I_{12} = \{\langle L, A \rangle, \langle L, B \rangle\}$ . In the first information set, he chooses L.

Hence,  $X_1(h) = \langle I_{11}, L, I_{12} \rangle$ .

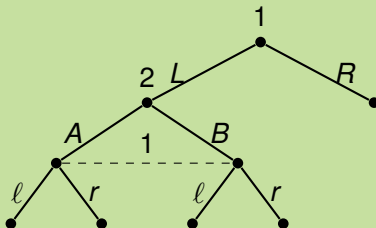
## Definition (Perfect recall)

An extensive game has **perfect recall** if for each player  $i$ , we have  $X_i(h) = X_i(h')$  whenever the histories  $h$  and  $h'$  are in the same information set of player  $i$ .

Conversely, whenever an agent has made different experiences (own actions, observations) when arriving at  $h$  and  $h'$ , he can distinguish between them.

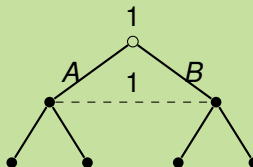
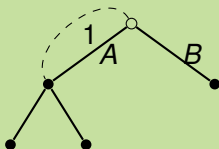
In most cases, our games will have perfect recall.

## Example



This game has perfect recall: the only  $h \neq h'$  in the same information set of some player are  $h = \langle L, A \rangle$  and  $h' = \langle L, B \rangle$  in information set  $I_{12} = \{h, h'\}$ . They satisfy the condition, since  $X_1(h) = X_1(h') = \langle I_{11}, L, I_{12} \rangle$ .

## Example



No perfect recall:

- **Left:** player 1 cannot distinguish between  $h = \langle \rangle$  and  $h' = \langle A \rangle$ , although  $X_1(h) = \langle \{h, h'\} \rangle \neq \langle \{h, h'\}, A, \{h, h'\} \rangle = X_1(h')$ .
- **Right:** player 1 cannot distinguish between  $h = \langle A \rangle$  and  $h' = \langle B \rangle$ , although  $X_1(h) = \langle \{ \langle \rangle \}, A, \{h, h'\} \rangle \neq \langle \{ \langle \rangle \}, B, \{h, h'\} \rangle = X_1(h')$ .

- **Perfect recall** requires that agents remember what they have done and learned.
- Formalized using **experience records**.
- For perfect recall, different experience records must be sufficient for a player to be able to distinguish between two histories.

# Game Theory

## 5. Extensive Games

### 5.2. Extensive Games with Imperfect Information

#### 5.2.3. Strategies and Outcomes

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- Decision points are **information sets**.
- Types of **strategies**:
  - **Pure**: InfoSets  $\rightarrow$  Actions
  - **Mixed**: (InfoSets  $\rightarrow$  Actions)  $\rightarrow$  Probabilities  
(randomization over pure strategies)
  - **Behavioral**: InfoSets  $\rightarrow$  (Actions  $\rightarrow$  Probabilities)  
(collections of independent randomized decisions for each information set)



## Definition (Pure strategy in an extensive game)

A **pure strategy** of a player  $i$  in an extensive game  $\Gamma = \langle N, H, P, f_c, (\mathcal{I}_i)_{i \in N}, (u_i)_{i \in N} \rangle$  is a function  $s_i$  that assigns an action from  $A(I_i)$  to each information set  $I_i$ .

**Remark:** Note that the outcome of a strategy profile  $s$  is now a probability distribution (because of the chance moves).

**Remark:** Because of the chance moves and because of the imperfect information, it probably makes more sense to consider randomized strategies.

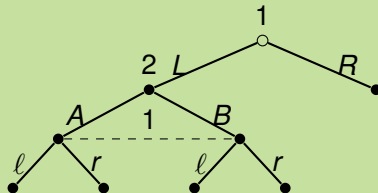
## Definition (Mixed and behavioral strategies)

A **mixed strategy**  $\sigma_i$  of a player  $i$  in an extensive game  $\Gamma = \langle N, H, P, f_C, (\mathcal{I}_i)_{i \in N}, (u_i)_{i \in N} \rangle$  is a probability distribution over the set of player  $i$ 's pure strategies.

A **behavioral strategy** of player  $i$  is a collection  $(\beta_i(I_i))_{I_i \in \mathcal{I}_i}$  of independent probability distributions, where  $\beta_i(I_i)$  is a probability distribution over  $A(I_i)$ .

For any history  $h \in I_i \in \mathcal{I}_i$  and action  $a \in A(h)$ , we denote by  $\beta_i(h)(a)$  the probability  $\beta_i(I_i)(a)$  assigned by  $\beta_i(I_i)$  to action  $a$ .

## Example

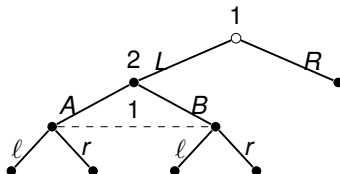


- Player 1 has four **pure strategies** (two information sets, two actions at each):  $L\ell$ ,  $Lr$ ,  $R\ell$ ,  $Rr$ .
- A **mixed strategy** is a probability distribution over those.
- A **behavioral strategy** is a pair of probability distributions, one over  $\{L, R\}$  for  $\{\langle \rangle\}$ , and one over  $\{\ell, r\}$  for  $\{\langle L, A \rangle, \langle L, B \rangle\}$ .

The outcome of a (mixed or behavioral) strategy profile  $\sigma$  is a probability distribution over histories  $O(\sigma)$ , resulting from following the individual strategies:

- For any history  $h = \langle a^1, \dots, a^k \rangle$ , define a **pure strategy  $s_i$  of  $i$  to be consistent with  $h$**  if for any prefix  $h' = \langle a^1, \dots, a^\ell \rangle$  of  $h$  with  $P(h') = i$ , we have  $s_i(h') = a^{\ell+1}$ .
- For any history  $h$ , let  $\pi_i(h)$  be the sum of probabilities of pure strategies  $s_i$  from  $\sigma_i$  that are consistent with  $h$ .
- Then for any mixed profile  $\sigma$ , the probability that  $O(\sigma)$  assigns to a terminal history  $h$  is:  $\prod_{i \in N \cup \{c\}} \pi_i(h)$   
(where  $\pi_c(h)$  is the product of the  $f_c(\cdot|\cdot)$  values along  $h$ ).
- For any behavioral profile  $\beta$ , the probability that  $O(\beta)$  assigns to  $h = \langle a^1, \dots, a^k \rangle$  is:  
$$\prod_{k=0}^{K-1} \beta_{P(\langle a^1, \dots, a^k \rangle)}(\langle a^1, \dots, a^k \rangle)(a^{k+1}).$$

# Outcomes: Mixed Strategies – Example



Assume  $\sigma_1 = \{L\ell \mapsto 28/70, Lr \mapsto 21/70, R\ell \mapsto 12/70, Rr \mapsto 9/70\}$ ,  
 $\sigma_2 = \{A \mapsto 1/2, B \mapsto 1/2\}$ , and  $\sigma = (\sigma_1, \sigma_2)$ .

Then, e. g.,  $s_{13} = R\ell$ ,  $s_{14} = Rr$ ,  $s_{21} = A$ , and  $s_{22} = B$  all  
 consistent with  $h = \langle R \rangle$ , but  $s_{11} = L\ell$  and  $s_{12} = Lr$  not.

$$\pi_1(\langle R \rangle) = \sigma_1(R\ell) + \sigma_1(Rr) = 12/70 + 9/70 = 3/10,$$

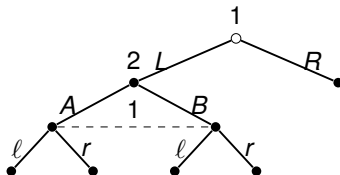
$$\pi_2(\langle R \rangle) = \sigma_2(A) + \sigma_2(B) = 1/2 + 1/2 = 1, \text{ and}$$

$$O(\sigma)(\langle R \rangle) = \pi_1(\langle R \rangle) \cdot \pi_2(\langle R \rangle) = 3/10 \cdot 1 = 3/10.$$

Similarly,

$$O(\sigma)(\langle L, A, \ell \rangle) = \pi_1(\langle L, A, \ell \rangle) \cdot \pi_2(\langle L, A, \ell \rangle) = 28/70 \cdot 1/2 = 2/10.$$

# Outcomes: Behavioral Strategies – Example



Assume  $\beta_1(\{\langle \rangle\}) = \{L \mapsto 7/10, R \mapsto 3/10\}$ ,  
 $\beta_1(\{\langle L, A \rangle, \langle L, B \rangle\}) = \{\ell \mapsto 4/7, r \mapsto 3/7\}$ ,  
 $\beta_2(\{\langle L \rangle\}) = \{A \mapsto 1/2, B \mapsto 1/2\}$ , and  $\beta = (\beta_1, \beta_2)$ .

Then, e. g.,  $O(\beta)(\langle R \rangle) = \beta_1(\{\langle \rangle\})(R) = 3/10$ .

Similarly,  $O(\beta)(\langle L, A, \ell \rangle) = \beta_1(\{\langle \rangle\})(L) \cdot \beta_2(\{\langle L \rangle\})(A) \cdot$   
 $\beta_1(\{\langle L, A \rangle, \langle L, B \rangle\})(\ell) = 7/10 \cdot 1/2 \cdot 4/7 = 2/10$ .

## Definition

Two (mixed or behavioral) strategies of a player  $i$  are called **outcome-equivalent** if for every partial profile of pure strategies of the other players, the two strategies induce the same outcome.

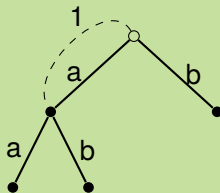
**Question:** Can we find outcome-equivalent mixed strategies for behavioral strategies and vice versa?

**Partial answer:** Sometimes.

# Counterexample (1)



## Example (Behavioral strategy without a mixed strategy)



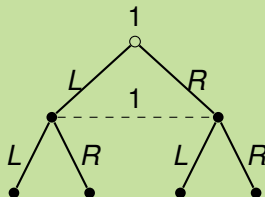
- A behavioral strategy assigning non-zero probability to  $a$  and  $b$  generates outcomes  $\langle a, a \rangle$ ,  $\langle a, b \rangle$ , and  $\langle b \rangle$  with non-zero probabilities.
- Since there are only the pure strategies of playing  $a$  or  $b$ , no mixed strategy can produce  $\langle a, b \rangle$ .



# Counterexample (2)



## Example (Mixed strategy without a behavioral strategy)



- Mix the two pure strategies  $LL$  and  $RR$  equally, resulting in the distribution  $(1/2, 0, 0, 1/2)$  over the terminal histories.
- No behavioral strategy can accomplish this.

If we restrict ourselves to games with perfect recall, however, everything works.

## Theorem (Equivalence of mixed and behavioral strategies (Kuhn))

*In a game of perfect recall, any mixed strategy of a given agent can be replaced by an outcome-equivalent behavioral strategy, and any behavioral strategy can be replaced by an outcome-equivalent mixed strategy.*

- Types of strategies:
  - Pure: InfoSets  $\rightarrow$  Actions
  - Mixed: (InfoSets  $\rightarrow$  Actions)  $\rightarrow$  Probabilities  
(randomization over pure strategies)
  - Behavioral: InfoSets  $\rightarrow$  (Actions  $\rightarrow$  Probabilities)  
(collections of independent randomized decisions for each information set)
- Mixed and behavioral are equivalent (induce same outcome probabilities) in the case of perfect recall.
- Otherwise not.

# Game Theory

## 5. Extensive Games

### 5.2. Extensive Games with Imperfect Information

#### 5.2.4. Solution Concepts

Albert-Ludwigs-Universität Freiburg



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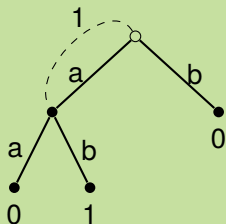
Bernhard Nebel and Robert Mattmüller

Summer semester 2020

Similar to the case of mixed strategies for strategic games, we define the utility for mixed and behavioral strategies as expected utility, summing over all terminal histories:

$$U_i(\sigma) = \sum_{h \in Z} u_i(h) \cdot O(\sigma)(h)$$

## Example



- Mixed strategy (mixing  $a$  and  $b$ )  $\sigma$ :  
 $U_1(\sigma) = 0$ .
- Behavioral strategy  $\beta$  with  $p = 1/2$  for  $a$ :  $U_1(\beta) = 1/4$ .

## Definition (Nash equilibrium in mixed strategies)

A **Nash equilibrium in mixed strategies** is a profile  $\sigma^*$  of mixed strategies with the property that for every player  $i$ :

$$U_i(\sigma_{-i}^*, \sigma_i^*) \geq U_i(\sigma_{-i}^*, \sigma_i) \text{ for every mixed strategy } \sigma_i \text{ of } i.$$

**Note:** Support lemma applies here as well.

## Definition (Nash equilibrium in behavioral strategies)

A **Nash equilibrium in behavioral strategies** is a profile  $\beta^*$  of behavioral strategies with the property that for every player  $i$ :

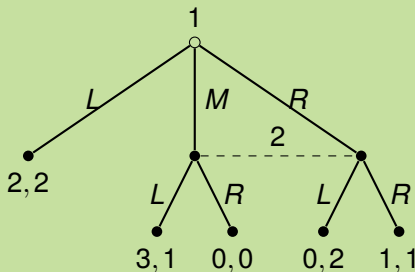
$$U_i(\beta_{-i}^*, \beta_i^*) \geq U_i(\beta_{-i}^*, \beta_i) \text{ for every behavioral strategy } \beta_i \text{ of } i.$$

**Remark:** Equivalent, provided we have perfect recall.

# Eliminating Imperfect Equilibria



## Example



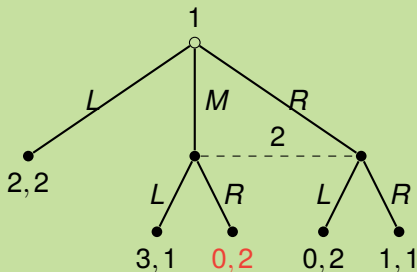
Nash equilibria:  $(M, L)$  and  $(L, R)$ .

Unreasonable ones:  $(L, R)$ , because in the information set of player 2,  $L$  dominates  $R$  (cf. empty threats).

# How have we got here?



## Example



Nash equilibria:  $(L, R)$ .

What should player 2 do in his information set?

This depends on his **belief**: if the probability that  $M$  has been played is  $\geq 1/2$ , then  $R$  is optimal, otherwise  $L$ .



Let us take the beliefs about what has been played into account when defining an equilibrium.

## Definition (Assessment)

An **assessment** in an extensive game is a pair  $(\beta, \mu)$ , where  $\beta$  is a profile of behavioral strategies and  $\mu$  is a function that assigns to every information set a probability distribution on the set of histories in the information set.

$\mu(I)(h)$  is the probability that player  $P(I)$  assigns to the history  $h \in I$ , given that  $I$  is reached.

We have to modify the **outcome** function. Let  $h^* = \langle a^1, \dots, a^K \rangle$  be a terminal history. Then:

- $O(\beta, \mu | I)(h^*) = 0$ , if there is no subhistory of  $h^*$  in  $I$  (i. e.,  $h^*$  is unreachable from  $I$ ), and
- $O(\beta, \mu | I)(h^*) = \mu(I)(h) \cdot \prod_{k=L}^{K-1} \beta_{P(\langle a^1, \dots, a^k \rangle)}(\langle a^1, \dots, a^k \rangle)(a^{k+1})$ , if a subhistory  $h = \langle a^1, \dots, a^L \rangle$  of  $h^*$  with  $L \leq K$  is in  $I$ .

**Remark 1:** This is well-defined, since the subhistory  $h = \langle a^1, \dots, a^L \rangle$  in the second case is unique if the game has perfect recall.

**Remark 2:** For the initial history, we have  $O(\beta, \mu | \langle \rangle)(h^*) = O(h^*)$ .

Similar to the outcome function, we generalize the expected utility functions:

$$U_i(\beta, \mu | I_i) = \sum_{h \in Z} u_i(h) \cdot O(\beta, \mu | I_i)(h)$$

## Definition (Sequential rationality)

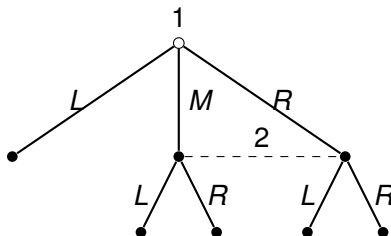
Let  $\Gamma$  be an extensive game with perfect recall. An assessment  $(\beta, \mu)$  is **sequentially rational** if for every player  $i$  and every information set  $I_i \in \mathcal{I}_i$ , we have

$$U_i(\beta, \mu | I_i) \geq U_i((\beta_{-i}, \beta'_i), \mu | I_i) \quad \text{for every strategy } \beta'_i \text{ of player } i.$$

**Note:** restrictions on  $\mu$  still missing!

We would at least require that the beliefs  $\mu$  are consistent with the strategies, meaning they should be derived from the strategies using Bayes' rule.

In our earlier example, player 2's belief should be derived from the behavioral strategy of player 1.



E.g., the probability that  $M$  has been played should be:

$$\mu(\{\langle M \rangle, \langle R \rangle\})(\langle M \rangle) = \frac{\beta_1(\langle \rangle)(M)}{\beta_1(\langle \rangle)(M) + \beta_1(\langle \rangle)(R)}.$$

However, what to do when the denominator is 0? (I. e., in this example, if player 1 only plays  $L$ , i. e., if  $\beta_1(\langle \rangle)(L) = 1$ .)

By viewing an assessment as a limit of a sequence of **completely mixed** strategy profiles (all strategies are in the support), one can enforce the Bayes condition also on information set that are not reached by an equilibrium profile.

## Definition (Consistency)

Let  $\Gamma$  be a finite extensive game with perfect recall. An assessment  $(\beta, \mu)$  is **consistent** if there is a sequence  $((\beta^n, \mu^n))_{n=1}^{\infty}$  of assessments that converges to  $(\beta, \mu)$  in Euclidian space and has the properties that each strategy profile  $\beta^n$  is completely mixed and that each belief system  $\mu^n$  is derived from  $\beta^n$  using Bayes' rule.

**Note:** Kreps (1990) wrote: “a lot of bodies are buried in this definition.”

## Definition (Sequential equilibrium)

An assessment is a **sequential equilibrium** of a finite extensive game with perfect recall if it is sequentially rational and consistent.

## Theorem (Kreps and Wilson, 1982)

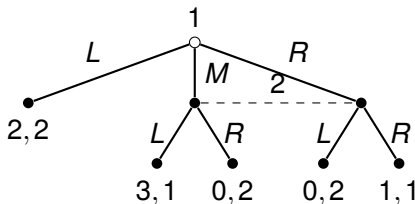
*Every finite extensive game with perfect recall has a sequential equilibrium.* ☐

## Theorem (Kreps and Wilson, 1982)

*Sequential equilibria generalize subgame-perfect equilibria.* ☐

# Sequential Equilibria

## Example 1: Introductory Example

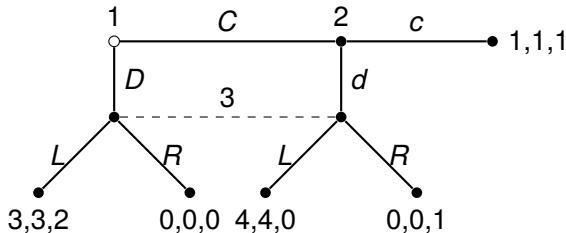


- Let  $(\beta, \mu)$  be as follows:  $\beta_1(L) = 1$ ,  $\beta_2(R) = 1$ ,  $\mu(\{\langle M \rangle, \langle R \rangle\})(\langle M \rangle) = \alpha$  with  $0 \leq \alpha \leq 1$ .
- Then  $(\beta, \mu)$  is consistent since  $\beta_1^n = (1 - \varepsilon, \alpha\varepsilon, (1 - \alpha)\varepsilon)$ ,  $\beta_2^n = (\varepsilon, 1 - \varepsilon)$ , for  $\varepsilon = 1/n$ , and  $\mu^n(\{\langle M \rangle, \langle R \rangle\})(\langle M \rangle) = \alpha$  converges to  $(\beta, \mu)$  for  $n \rightarrow \infty$ .
- For  $\alpha \geq 1/2$ ,  $(\beta, \mu)$  is sequentially rational.



# Sequential Equilibria

## Example 2: Selten's Horse



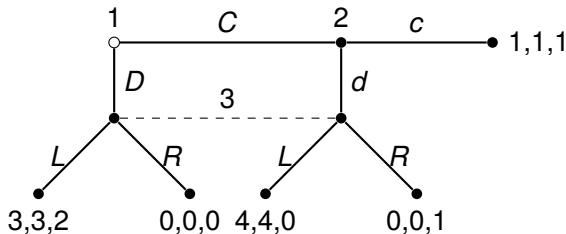
Two types of NE (for  $I = \{\langle D \rangle, \langle C, d \rangle\}$ ):

- 1  $\beta_1(\langle \rangle)(D) = 1, \frac{1}{3} \leq \beta_2(\langle C \rangle)(c) \leq 1, \beta_3(I)(L) = 1$
- 2  $\beta_1(\langle \rangle)(C) = 1, \beta_2(\langle C \rangle)(c) = 1, \frac{3}{4} \leq \beta_3(I)(R) \leq 1$

Are these also sequential equilibria?

# Sequential Equilibria

## Selten's Horse: Type 1 Nash Equilibrium

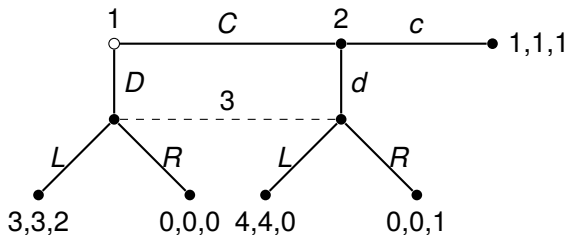


1  $\beta_1(\langle \rangle)(D) = 1, \frac{1}{3} \leq \beta_2(\langle C \rangle)(c) \leq 1, \beta_3(I)(L) = 1:$

violates sequential rationality for player 2!

# Sequential Equilibria

## Selten's Horse: Type 2 Nash Equilibrium



2  $\beta_1(\langle \rangle)(C) = 1, \beta_2(\langle C \rangle)(c) = 1, \frac{3}{4} \leq \beta_3(I)(R) \leq 1$ :

for each NE of this form, there exists a sequential equilibrium  $(\beta, \mu)$  with  $\mu(I)(D) = 1/3$ .

For consistency consider:  $\beta_1^n(\langle \rangle)(D) = \varepsilon, \beta_2^n(\langle C \rangle)(d) = 2\varepsilon/1-\varepsilon,$   
 $\beta_3^n(I)(R) = \beta_3(I)(R) - \varepsilon \quad (\varepsilon = 1/n).$

**Note:**  $\beta_1^n(\langle \rangle)(D) + (\beta_1^n(\langle \rangle)(C) \cdot \beta_2^n(\langle C \rangle)(d)) = 3\varepsilon.$

- Nash equilibria can be defined for extensive games, however, similar to perfect information games, are not always reasonable.
- **Sequential equilibria** are the refinement, which is based on **assessments** (behavioral strategies + beliefs).
- Beliefs should be consistent with strategies.
- Strategies should be best responses in each information set, given beliefs.