

Lecture 8: Algorithm Independent Principles - II

Validation, Regularization, General Issues, Model Selection

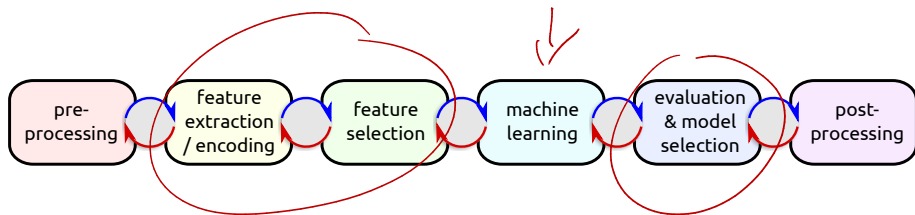
Machine Learning, Summer Term 2019

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University of Freiburg



The Big Picture



Lecture Overview

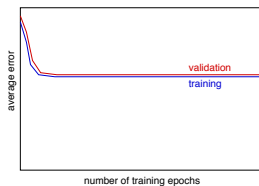
- 1 Validation (cont'd)
- 2 Regularization
- 3 General Considerations
- 4 Model Selection and Feature Selection
- 5 Wrapup

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Recap: Overfitting / Underfitting

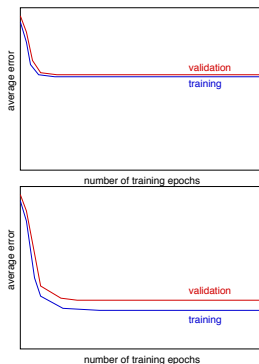
Example of **underfitting**:
validation and training error remain
large



Recap: Overfitting / Underfitting

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Example of **successful learning**:
validation error and training error
monotonically decrease
~> good generalization

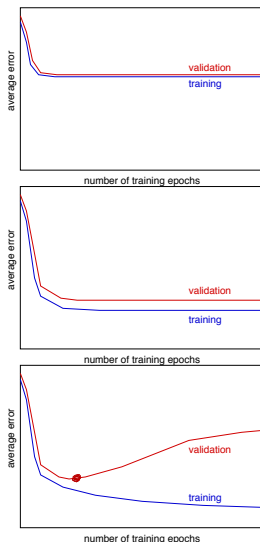


Recap: Overfitting / Underfitting

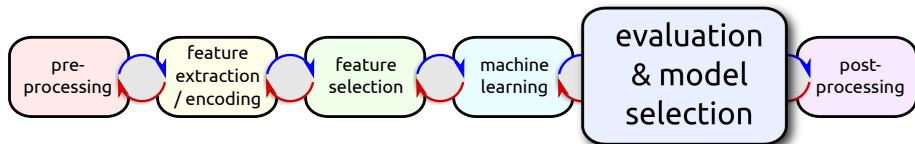
Example of **underfitting**:
validation and training error remain large

Example of **successful learning**:
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Example of **overfitting**:
validation error increases while training error decreases



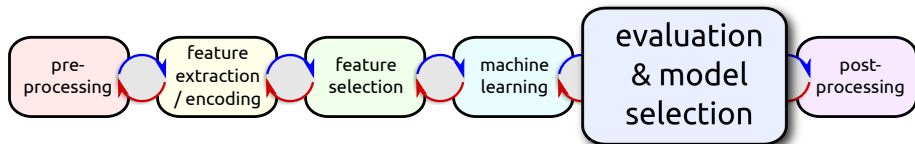
Model Selection 1/2



Evaluation:

- We want our models to **generalize**
 - I.e., perform well on previously unseen data points
- What does it mean to perform well?
 - See metrics covered later today
 - Speed at training time, speed at test time, memory, accuracy, ...

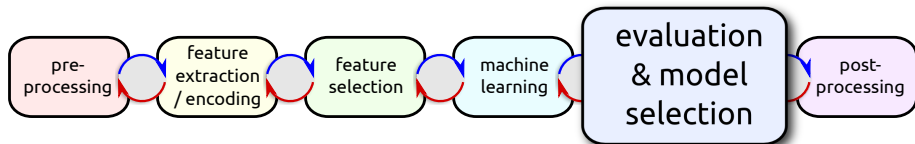
Model Selection 2/2



To obtain estimates of generalization performance using a fixed dataset

- Split dataset into **training set** and **test set**
- **Lock away test set for final assessment**

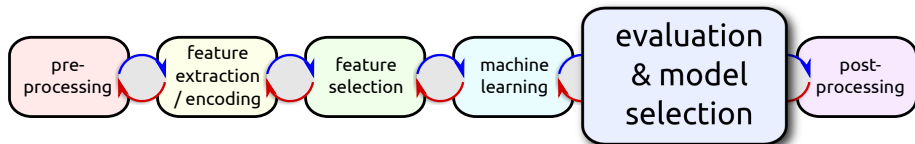
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- E.g., split it further into training and validation
 - Train different models on training set
 - Pick the one with best performance on validation set

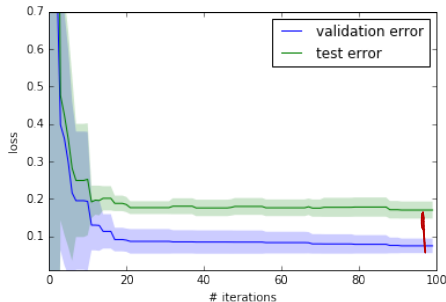
Model Selection 2/2



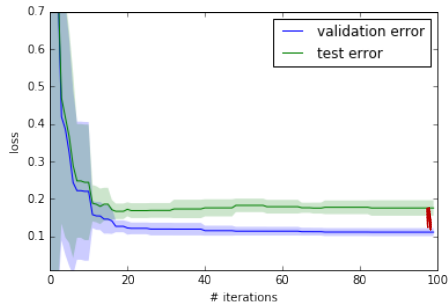
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- E.g., split it further into training and validation
 - Train different models on training set
 - Pick the one with best performance on validation set
- E.g., split it further into cross-validation (CV) folds and pick the model with best CV performance
 - CV performance is not an unbiased estimate of test performance
 - But better estimate than a single split into training/valid

Cross Validation Can Still Overfit 1/2



Single training-validation split (90% - 10%)



10-fold cross-validation

- Validation performance from single training-validation split is **overconfident** (overly optimistic)
- CV performance is still overconfident, but not as much
- In one of the next assignments, you will basically create these plots

Cross Validation Can Still Overfit 2/2

- To overfit least, when and how would you choose between different preprocessors (or feature selectors, data normalizers, etc) when you use k -fold cross-validation?
 - ★ Once: in the beginning, on all data
 - ★ Once: on all the training data
 - ★ k times: on the training split of each CV fold ✓

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 - Normalizes data, drops unimportant features, etc
 - Then builds model on preprocessed data
 - Saves both these data transformations and the model
- Typical method applyModel
 - First apply the transformations, then the model
 - Routine used for both the validation set and the test set alike

Stratified Cross Validation

- E.g., only 10 positive data points, 90 negative ones
- How many positive data points would standard 10-fold cross-validation put into each fold?
 - ★ 1
 - ★ 10
 - ★ Between 0 and 10, depends on the random split into folds ✓

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Stratified cross-validation would put exactly 1 positive and 9 negative data points into each fold

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Regularization

Approaches to improve generalization

Which approaches do you know / can you think of?



L2 reg.
early stopping
dropout

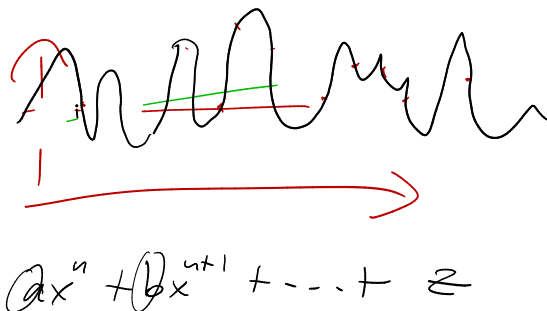
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Regularization - Overview

Approaches to improve generalization

Preference for small parameter values

- Early stopping
- Shrinkage methods



Regularization - Overview

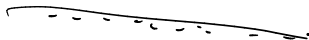
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Better task description

- More training data
- Filter training data
- Use more / less / other input features



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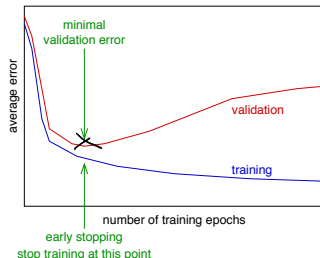
- More training data
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Ensemble techniques

- Bagging

Regularization Techniques - Early Stopping

- Stop learning when error on validation set has reached its minimum
- Often, training is already stopped after a few epochs
 - typically combined with small initial weights
- Simple, popular heuristic
- Needs perpetual observation of the validation error



- Extend the loss function with extra term (penalty) to control overfitting

$$\underline{L(\mathbf{w})} = \underline{L_D(\mathbf{w})} + \underline{\lambda L_W(\mathbf{w})}$$

Regularization Techniques - Shrinkage Methods

- Extend the loss function with extra term (penalty) to control overfitting

$$L(\mathbf{w}) = L_D(\mathbf{w}) + \lambda L_W(\mathbf{w})$$

- Common example: sum-of-squares loss function with L2 regularization

$$L(\mathbf{w}) = \underbrace{\frac{1}{2} \sum_{n=1}^N \{ \underline{y_n} - \underline{\mathbf{w}^T \phi(\mathbf{x}_n)} \}^2}_{L_D(\mathbf{w})} + \underbrace{\frac{\lambda}{2} \mathbf{w}^T \mathbf{w}}_{\lambda L_W(\mathbf{w})}$$

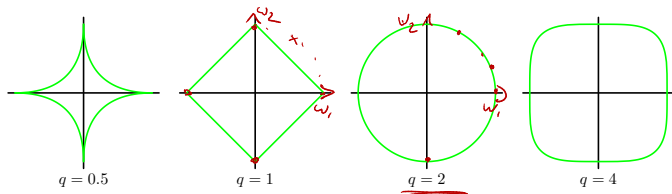
- Allows for closed-form solution: $\mathbf{w} = (\lambda \mathbf{I} + \Phi^T \Phi)^{-1} \Phi^T \mathbf{y}$. This is called **ridge-regression** or **Tikhonov regularization** in the literature.

Regularization Techniques - Shrinkage Methods

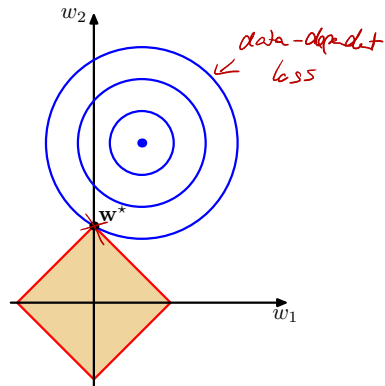
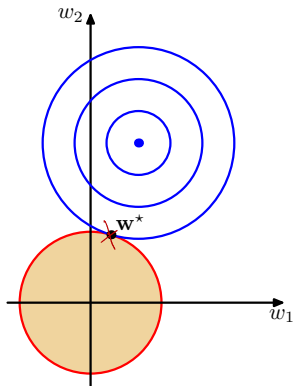
- More general form:

$$L(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \{y_n - \mathbf{w}^T \phi(\mathbf{x}_n)\}^2 + \frac{\lambda}{2} \sum_{j=1}^M |w_j|^q$$

- **Shrinkage**: encourages weights to shrink towards zero
- Case $q = 2$: L2 regularizer as before
- Case $q = 1$: L1 regularizer as before (**lasso** in the literature)
→ sparse solutions



Regularization techniques - Shrinkage Methods



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- Which of these values of q encourages sparsity the most?

★ $q=0.5$

★ $q=1$

★ $q=2$

★ $q=4$

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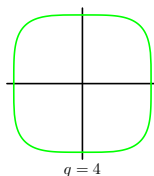
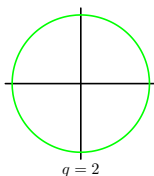
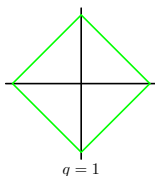
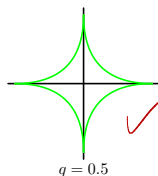
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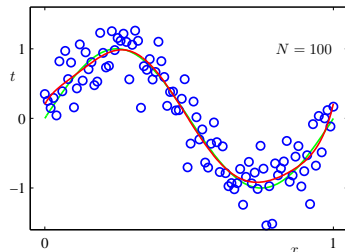
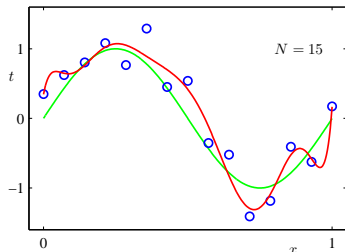
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Regularization Techniques - More Data

- Data analysts' fundamental slogan: *there's no data like more data!*
- Try to get more data; if not possible directly, think about related sources of similar data
- Although trivial, one of the most important techniques to improve ML models



Regularization Techniques - Data Augmentation

- Data augmentation is a common strategy for creating additional training data
- Example: computer vision
 - Translation, Scaling, Reflection, Rotation, Stretching



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 - Often yields very substantial improvements
 - However: 100x augmentation can slow down training 100x
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- Hypothesis learns representation **invariant** to the perturbations
 - Often yields very substantial improvements
 - However: 100x augmentation can slow down training 100x
 - Diminishing returns: rarely more than 100x data augmentation
- What data do we apply these augmentations to?
 - ★ All data ✓
 - ★ Only the test data
 - ★ Only the validation data
 - ★ Only the training data ✓

Regularization Techniques - Data Augmentation

- We only want to be invariant to **certain degrees** of transformations
 - Like the human visual system; not these:



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- **Hyperparameters**: how much of each perturbation to apply?
 - Usually specify a distribution to sample from
 - E.g., zero-mean 5-dimensional Gaussian with degrees of translation, scaling, reflection, rotation, stretching to apply to original data
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- In computer vision, it is not hard to find useful image perturbations
- What could perturbations be in other applications? Domain-specific!
 - Could even lead to domain-specific insights about important invariants

Filtering Training Data

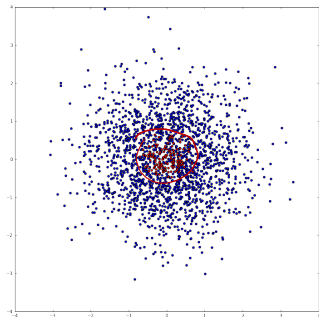
- Some training data points are much more helpful to learn the target concept than others
- **Filtering** means reducing the training set to the really important points that help adjusting the classification boundary/regression curve
- Techniques: oversampling, subsampling, outlier rejection, jittering
- Frequent problem: imbalanced data in classification

Balancing Data

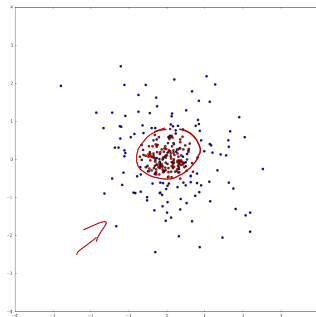
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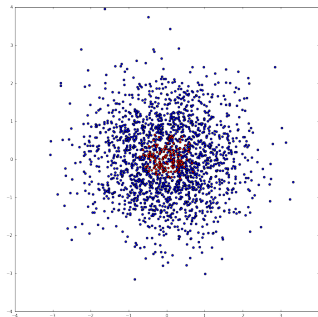
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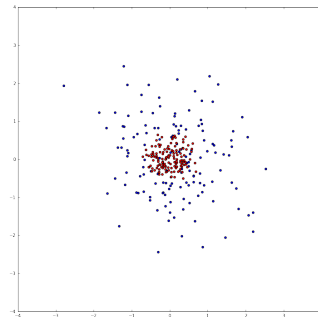
Subsampled majority class

Balancing Data

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Subsampled majority class

- Solution 1: If your classifier supports it, weight your data
- Solution 2: Subsample the majority class
- Solution 3: Generate new data points of minority class

Regularization Techniques - Input Features

- Removing features may reduce overfitting by helping the model avoid fitting pseudo relationships
 - Extreme: think of a feature that is just random noise
- Dimensionality reduction is related: PCA, ICA

Regularization Techniques - Input Features

- Removing features may reduce overfitting by helping the model avoid fitting pseudo relationships
 - Extreme: think of a feature that is just random noise
- Dimensionality reduction is related: PCA, ICA
- Of course, adding features can also help improve performance
 - If they are related to the desired output
 - Very often, domain experts can come up with useful additional features
 - Can also add non-linear transformations of features

Regularization Techniques - Committee / Ensemble Approaches

- If you ask one expert, the expert may fail
- Ask a committee of experts: the majority has a better chance to be right

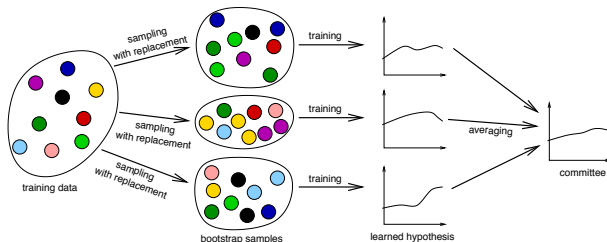
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- Premise: experts are experienced and diverse



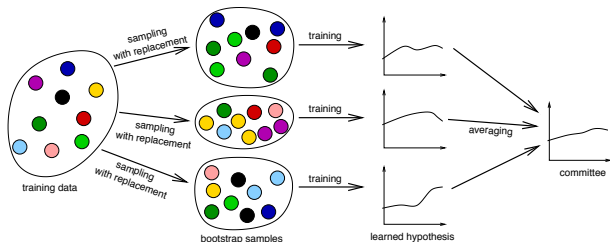
Committees - Bagging [Breimann, 1996]

- Train several models on bootstrap samples of the training data
 - Data is drawn randomly with replacements \Rightarrow some data points may occur twice or more, others don't occur at all
- Average the output of all trained models



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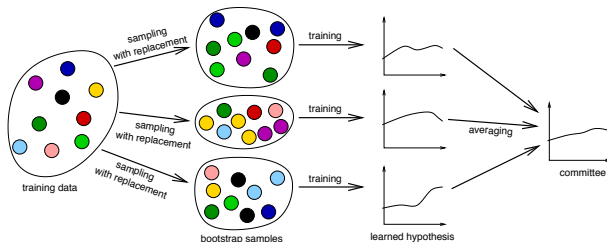
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- We'll cover committee methods / ensemble methods in more detail in the module on tree-based methods

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Metrics of Success 1/3

- In different applications, different metrics of success apply
- Example metrics for classification
 - E.g., 0/1 loss, higher loss for false positives than false negatives, etc
 - E.g., AUC, F1, precision/recall, ... (see next slide)

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 - E.g., AUC, F1, precision/recall, ... (see next slide) *cross entropy*
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 - E.g., RMSE (root mean squared error)
 - E.g., MAE (mean absolute error)
 - Log-likelihood: $\log(P(\text{observations} \mid \text{model}))$

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- Example metrics for regression
 - E.g., RMSE (root mean squared error)
 - E.g., MAE (mean absolute error)
 - Log-likelihood: $\log(P(\text{observations} \mid \text{model}))$
- Internal loss function being optimized often differs from external metric of success
 - E.g., internally, to fit the model, we may need a differentiable surrogate loss function, such as cross entropy
 - E.g., 0/1 loss is not differentiable

- Binary classification: detecting a signal (e.g., disease)
 - True positive rate, sensitivity or recall:
percentage of positive data points that are classified as positive
→ want this to be high

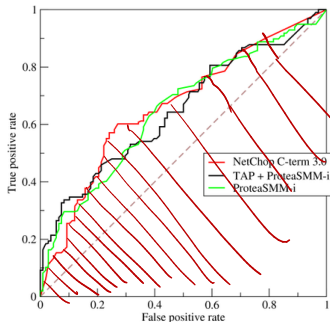
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 - F-measure or F_1 score: $F = 2 \cdot (\text{precision} \cdot \text{recall}) / \underline{(\text{precision} + \text{recall})}$

Metrics of Success 3/3

- Receiver operating characteristic (ROC curve)
 - Plots true positive rate vs. false positive rate
 - At various threshold settings of a classifier
 - Single number for a classifier: Area Under the ROC Curve (AUC)

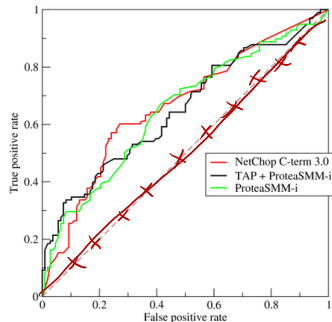


ROC curve of three predictors of peptide cleaving in the proteasome.

Source: https://en.wikipedia.org/wiki/Receiver_operating_characteristic

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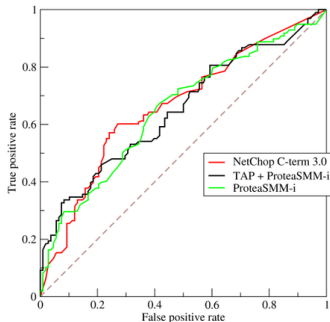
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- With which algorithm can you trivially achieve the diagonal? 🙌🙌
- Another, similar type of curve: precision-recall curve

Metrics of Success: Take Home Message

- There are several metrics of success
- The correct metric depends on your application
- For example, for spam classification you should not only consider accuracy
 - The predictor should not classify an important message as spam
 - similar cases in medicine

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- There are several metrics of success
- The correct metric depends on your application
- For example, for spam classification you should not only consider accuracy
 - The predictor should not classify an important message as spam
 - similar cases in medicine
- In case of doubt, you should consider several metrics

The i.i.d. Assumption

- So far, we've assumed an underlying distribution $p(\mathbf{x}, y)$
- More precisely, we made the **standard assumption in supervised learning**: data points $p(\mathbf{x}, y)$ are **independently** and **identically distributed** (i.i.d.)

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 - **Independent**: learning the label A of one data point doesn't tell you anything about the label B of another data point:
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- In practice, especially independence can be broken in many ways
- Example: weather prediction: one data point per day
 - ★ Data points from consecutive days are independent.
 - ★ Data points from consecutive days are dependent. ✓

Validation for the Non-i.i.d. Setting

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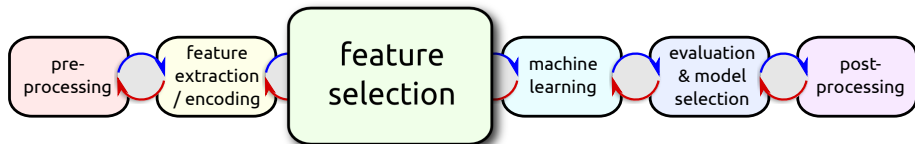
Validation for the Non-i.i.d. Setting

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 - To predict tomorrow's weather, we cannot use data from the future
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- Example: 50 data points measured for each of 100 patients
- What would the right 10-fold cross-validation protocol be to get an unbiased estimate of how well we'll predict on a new patient?
 - ★ Split data randomly into 10 folds of 500 data points each
 - ★ In each fold: use 5 data points of each of the 100 patients 500
 - ★ In each fold: use all 50 data points of 10 patients each ✓ 500

Lecture Overview

- 1 Validation (cont'd)
- 2 Regularization
- 3 General Considerations
- 4 Model Selection and Feature Selection**
- 5 Wrapup

Feature Selection



- Feature selection: pick a subset of features that performs best
- Exactly the same problem of generalization as for model selection
- Special mechanisms exist to evaluate feature importance, etc
 - Here a quick preview

Feature Selection: Forward Selection

Forward Selection

- Build up your feature set step by step
- Iterate:
 - 1 Evaluate the predictor performance by adding each of the unused features
 - 2 Add the feature with the highest performance improvements

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↪ we could also consider to stop after the second iteration, if the improvement by adding f_1 is considered too small.

Backward Elimination

- Reduce your feature set step by step
 - Iterate:
 - 1 Evaluate the predictor performance by removing each of the considered features
 - 2 Remove the feature with the smallest performance loss
- ~> "larger" feature set, but dependencies between features are preserved

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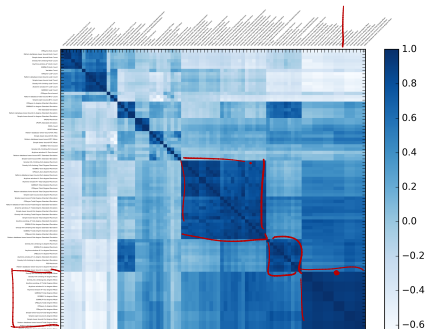
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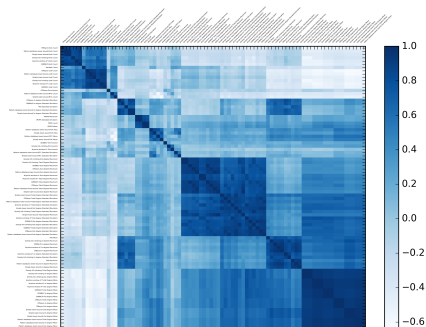
↪ Forward selection and backward elimination often do not recover the same set of features.

Feature Selection: Correlation Analysis



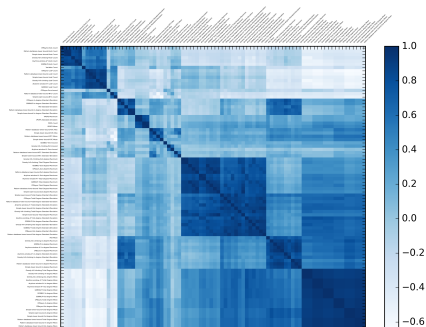
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- highly correlated features often hurt the training process more than they help
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 - a PCA is implicitly doing something similar
- Pearson correlation coefficient

$$\rho_{X,Y} = \frac{\text{cov}(X,Y)}{\sigma_X \sigma_Y}$$

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Summary by learning goals

Having heard this lecture, you can now ...

- Explain how to check performance using **cross-validation**
- Identify **over- and underfitting** based on learning curves
- Explain different **regularization approaches**
- **Select features** (using basic approaches)
- Explain the **i.i.d. assumption** and where it can break down
- Handle **imbalanced data**
- Choose the right **metric of success** for a new application
- Explain the **appropriate cross-validation splits** for several settings