

Medical Image Segmentation

and other things I do at Rice University

Jonas Actor

Rice University

21 February 2020



jonasactor@rice.edu

Medical Image Segmentation



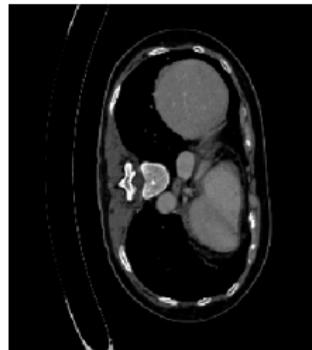
(a) abdominal CT scan



(b) segmentation of liver

Goal.

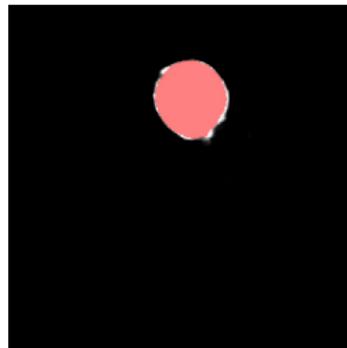
use **mathematics** to **improve clinician trust** in deep learning methods for image segmentation



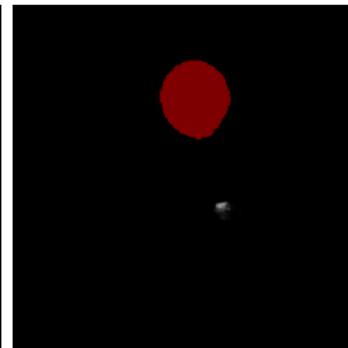
(a) image



(b) noisy image



(c) original prediction



(d) noisy prediction

Convolutions

$$K = \begin{bmatrix} k_{-1,-1} & k_{-1,0} & k_{-1,1} \\ k_{0,-1} & k_{0,0} & k_{0,1} \\ k_{1,-1} & k_{1,0} & k_{1,1} \end{bmatrix}$$

$$u_{i,j} \longmapsto \sum_{p=-1}^1 \sum_{q=-1}^1 K_{p,q} u_{i+p, j+q}$$

$$u \longmapsto K * u$$

$$\vec{u} \longmapsto A_{[K]} \vec{u}$$

Stability of Convolutional Layers

Stability \sim small $\|A_{[K]}\|_2$ (largest singular value)

Reducing $\|A_{[K]}\|_2$ requires computing $\|A_{[K]}\|_2$

Convolution Linear Operators

$$T_i = \begin{bmatrix} k_{i,0} & k_{i,1} & & & \\ k_{i,-1} & \ddots & \ddots & & \\ & \ddots & \ddots & \ddots & \\ & & \ddots & \ddots & k_{i,1} \\ & & & k_{i,-1} & k_{i,0} \end{bmatrix}$$

$$A_{[K]} = \begin{bmatrix} T_0 & T_1 & & & \\ T_{-1} & \ddots & \ddots & & \\ & \ddots & \ddots & \ddots & \\ & & \ddots & \ddots & T_1 \\ & & & T_{-1} & T_0 \end{bmatrix}$$

Problem...

$A_{[K]}$ is very very **big**:

current DCNNs $\sim A_{[K]}$ are $100M \times 100M$

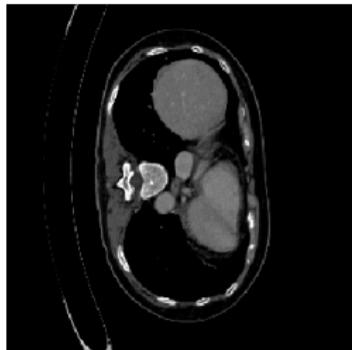
Approach: Hölder's Inequality

Bound $\|A_{[K]}\|_2$ instead of computing directly:

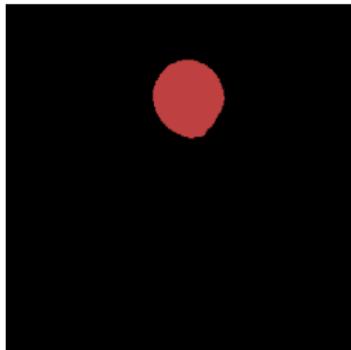
$$\|A_{[K]}\|_2 \leq \|A_{[K]}\|_1 \|A_{[K]}\|_\infty \leq \|K\|_{1,ent}$$

Train for robustness

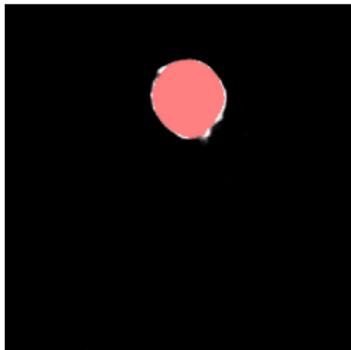
- incorporate ℓ_1 regularization on kernels to training
- implement via proximal gradient algorithm → learn sparse kernels
- fast → linear in number of entries in K
- provable + empirical decrease in Lipschitz constant of DCNNs



(a) image



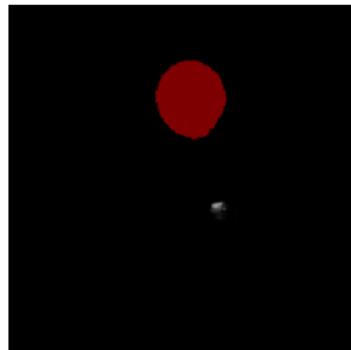
(b) true segmentation



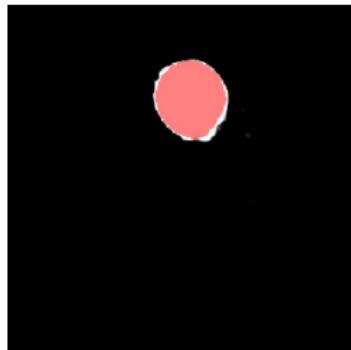
(c) original prediction



(d) noisy image



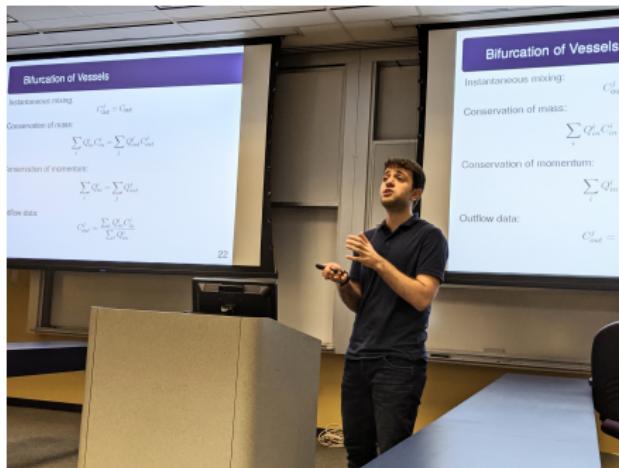
(e) noisy prediction

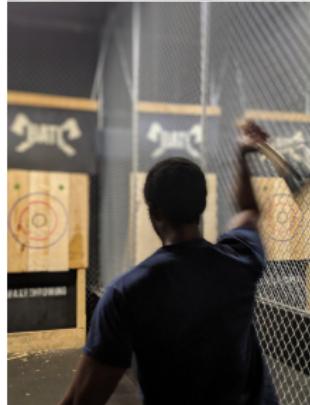


(f) stable prediction



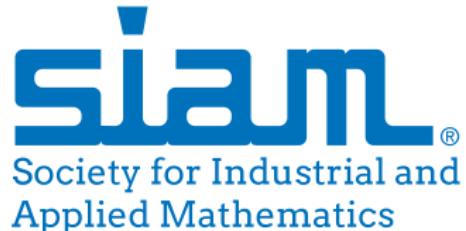
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