
Digital Guitar Effects

Project Report
Group 17gr641

Aalborg University
Electronic Engineering and IT

Copyright © Group 17gr641, Electronic Engineering and IT P6, Aalborg University 2018

This report is compiled in L^AT_EX. Additionally is Mathworks MATLAB, Adobe Illustrator, Inkscape, Lucidcharts.com, Altium Designer, and Xfig used to draw figures and charts.



AALBORG UNIVERSITY
STUDENT REPORT

Electronic Engineering and IT
Aalborg University
<http://www.aau.dk>

Title:

Digital Guitar Effects

Theme:

Signal processing

Project Period:

BSc, 6th Semester 2017

Project Group:

Group 17gr641

Participants:

Mohamed Gabr
Jonas Buchholdt
Sebastian Schiøler

Supervisor:

Sofus Nielsen

Number of Pages: 23

Date of Completion:

26th may 2017

Abstract:

The paper deals with the creation of different sound effects for an electric guitar on the a Digital Signal Processor. Some of these effects are the reverb, the flanger and the equalizer. The report includes a thorough explanation of each of the effects followed by the used design approach. Simulations on MATLAB were done to verify the design. All the effects have been coded in assembly for the DSP implementation. The Assembly code works with the TMS320C5515 DSP from Texas Instruments. In order to make the DSP usable on a variety of electric guitars, a preamplifier was built. All details relating to the design and the implementation of this component are included in the paper as well.

The content of this report is freely available, but publication may only be pursued with reference.

Preface

This report is composed by group 17gr641 during the 6th semester of Electronic Engineering and IT at Aalborg University. The general purpose of the report is the development and implementation of a digital guitar effects which is a part of the overall theme *Signal processing*.

For citations, the report employs the Harvard method. If citations are not present by figures or tables, these have been made by the authors of the report. Units are indicated according to the SI standard.

This project uses the Assembly language for the TMS320C5515 processor, and furthermore, the C programming standard C99.

Aalborg University, February 14, 2018

Mohamed Gabr
<mgabr16@student.aau.dk>

Jonas Buchholdt
<jbuchh13@student.aau.dk>

Sebastian Schiøler
<sschia14@student.aau.dk>

Contents

Preface	v
Glossary	1
1 Introduction	3
1.1 preliminary problem statement	4
I Analysis & Requirements	5
2 Analysis of single source	7
2.1 Single speaker source	7
2.2 The 300 Hertz (Hz)	8
2.3 The dimension limit	8
3 Product Requirements	9
II Design & Construction	11
4 Component Choices	13
III Tests	15
5 Tests of the Stated Requirements	17
IV Discussion and Conclusion	19
V Appendix	21
Bibliography	23

Glossary

Hz Hertz. vi, 7

SPL Sound pressure level. 3

Chapter 1

Introduction

The directivity of sound sources is an issue that has an impact on many situations of our daily lives. This can be illustrated when looking at live music venues. Voluntary listeners, namely the audience, enjoy comparatively high sound pressure levels when gathering around the stage. Involuntary listeners, generally neighbours, tend to perceive the sound emitted by the stage as a disturbing noise. It would be great, if the directivity of the sound sources on the stage could be set up in a way, that emits high sound energy towards the audience, but as little as possible towards the neighbours. There are several effects that make this difficult. First of all, the dampening of sound in the air has significantly less influence on sound towards the lower end of the human hearing range than it has towards the higher end. Secondly, commonly used loudspeaker contraptions for low frequency playback tend to act like omnidirectional sound sources. Also, because of the way most houses are built, low frequency sound penetrates through walls and windows much more than high frequency sound. All of these effects lead to neighbours being disturbed by *the bass* from nearby live music venues.

The difference in the perception of the sound is visualised in Figure 1.1.

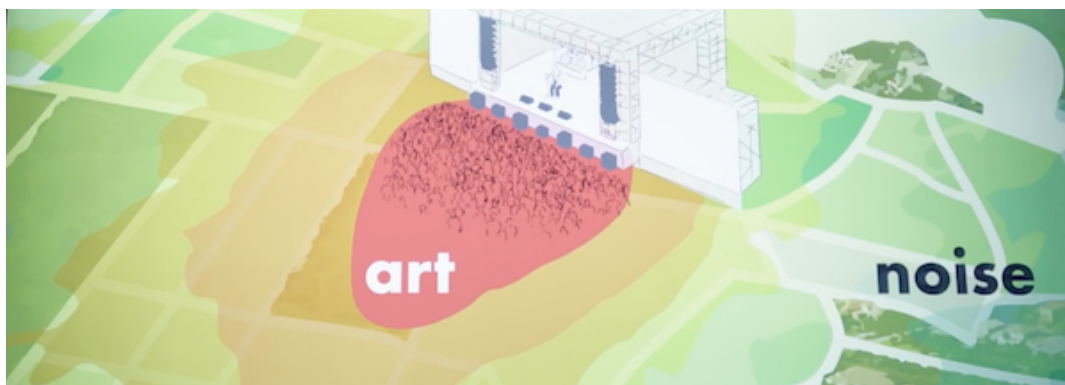


Figure 1.1: Normalized Sound pressure level (SPL) in colour, red is high SPL where blue is low SPL

Figure 1.1 shows the a qualitative drawing of a near-ideal sound pressure distribution in the vicinity of a stage during a concert. High-SPL areas are highlighted by red color. We define the area, in which the voluntary listeners condense, as the **participants' area**. It coincides with the red area in Figure 1.1. The non-voluntary listeners are located in the area around the participants' area, that we define as **the neighbourhood**. While a SPL distribution as depicted in Figure 1.1 is achievable is easier to achieve the higher the frequency gets, towards low frequencies the SPL distribution might look more like depicted in [figure 1.2](#).

The directivity control of mid- and high frequency has a known solution which has been applied for many years. In general, horns are used, which are designed for a particular radiation pattern. Due to the long wave length in the low/mid- and low frequency range, the horns that are required to direct those wavelengths are not feasible for practical applications due to their size and weight. Therefore other, more space saving solutions have been developed and implemented in the last decade. It is possible to achieve a cardioid emission pattern by arranging subwoofers in a particular manner. Two or three subwoofers are pointed towards the participants' area and one subwoofer is pointed the opposite way. The signal for the subwoofer pointing away from the audience is processed to manipulate the phase.

This project aims towards applying a principle that has been put into commercial use in the D& B audiotechnik SL-series, where the low/mid frequency directivity is controlled by signal processing four speaker unit. Two units are arranged in the front of module, pointing towards the participants' area and the other two arranged on each of the sides of the line array module.

1.1 preliminary problem statement

The following questions are made with the intention of gathering the necessary knowledge, to be able to answer a later stated problem statement. The preliminary questions, which will be answered in the analysis, are:

- In which frequency area do the line source speaker behave omnidirectional?
- Which known technique is used to do the speaker cardioid?
- Can a simulation be made which support D&B audiotechnik claim?

Part I

Analysis & Requirements

Chapter 2

Analysis of single source

2.1 Single speaker source

This section aims to introduce and analyse the fundamental for a single source, by analyse the behaviour of a line source shaped as the diaphragm. The pressure around the speaker will be analysed analytically, to determine the radiation of a single speaker from 60 Hz and upwards. The 60 Hz lower limit enable the simulation to be validated by measurement in the AAU anacoid chamber and is a used lower limit for the low/mid driver in some line source array. The analyse shall end out with a limited frequency range, where the directivity have to be controlled.

2.1.1 Pressure analysis around a single source

To characterised the directions properties of a speaker unit, the source will be modulated as three line source shaped as the diaphragm of a speaker. To modulated the diaphragm, a continues line source will be analysed and explained in this section. The analysis of a continues line source built on a thin cylindrical source of length L , and have radius a . The line source is considered as many small sources which vibrate radially, where the vibration speed is complex and modelled as

$$u = \mathcal{U}_0 \cdot \exp(j\omega t) \quad (2.1)$$

Where:

\mathcal{U}_0 is the Amplitude [Ω]

R_F is a resistor in the feedback circuit [Ω]

Figure 2.1 shows the model of the speaker unit.

$$p(r, \theta, t) = \frac{j}{2} * \rho_0 c \mathcal{U}_0 \frac{a}{r} k L \left(\frac{\sin(\frac{1}{2} k L \sin(\theta))}{\frac{1}{2} k L \sin(\theta)} \right) e^{j(\omega t - kr)} \quad (2.2)$$

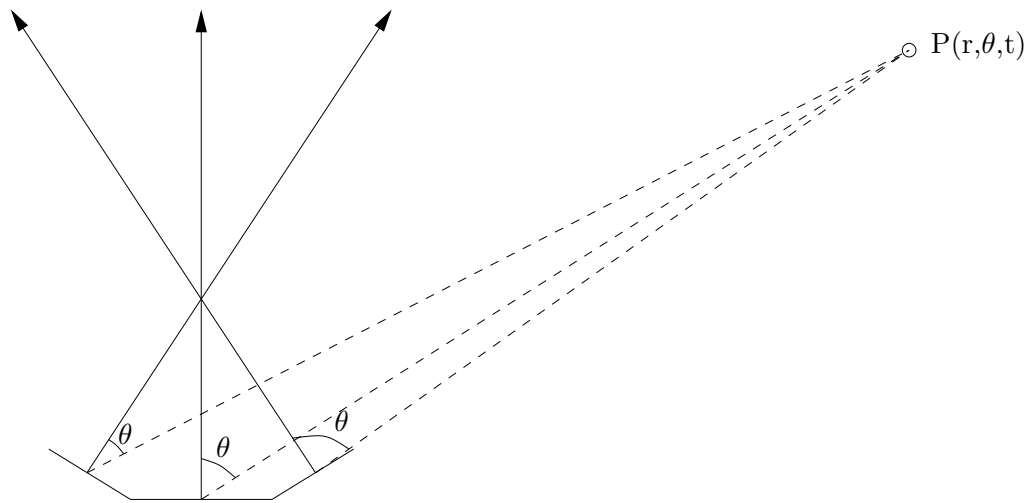


Figure 2.1: The model of a speaker unit

2.2 The 300 Hertz (Hz)

2.3 The dimension limit

Chapter 3

Product Requirements

Part II

Design & Construction

Chapter 4

Component Choices

Part III

Tests

Chapter 5

Tests of the Stated Requirements

Part IV

Discussion and Conclusion

Part V

Appendix

Bibliography