

# UC Berkeley Math 228B, Spring 2019: Problem Set 4

Due March 21

1. Consider the boundary value problem

$$u''''(x) = f(x) \equiv 480x - 120, \quad \text{for } x \in (0, 1) \quad (1)$$

$$u(0) = u'(0) = u(1) = u'(1) = 0 \quad (2)$$

- (a) Derive the following Galerkin formulation for the problem (1)-(2) on some appropriate function space  $V_h$ : Find  $u_h \in V_h$  such that

$$\int_0^1 u_h''(x)v''(x) dx = \int_0^1 f(x)v(x) dx, \quad \forall v \in V_h. \quad (3)$$

- (b) Define the triangulation  $T_h = \{K_1, K_2\}$ , where  $K_1 = [0, \frac{1}{2}]$  and  $K_2 = [\frac{1}{2}, 1]$ , and the function space

$$V_h = \{v \in C^1([0, 1]) : v|_{K_1} \in \mathbb{P}_3(K_1) \ \forall K \in T_h, \ v(0) = v'(0) = v(1) = v'(1) = 0\}. \quad (4)$$

Find a basis  $\{\varphi_i\}$  for  $V_h$ . Hint: Consider Hermite polynomials on each element.

- (c) Solve the Galerkin problem (3) using your basis functions. Plot the numerical solution  $u_h(x)$  and the true solution  $u(x)$ .

2. Implement a Julia function with the syntax

```
u = fempoi(p, t, e)
```

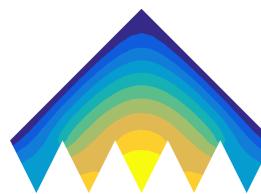
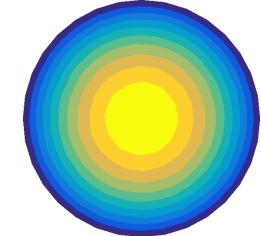
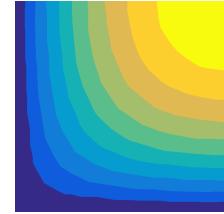
that solves Poissons's equation  $-\nabla^2 u(x, y) = 1$  on the domain described by the unstructured triangular mesh  $p, t$ . The boundary conditions are homogeneous Neumann ( $n \cdot \nabla u = 0$ ) except for the nodes in the array  $e$  which are homogeneous Dirichlet ( $u = 0$ ).

Here are a few examples for testing the function:

```
# Square, Dirichlet left/bottom
pv = Float64[0 0; 1 0; 1 1; 0 1; 0 0]
p, t, e = pmesh(pv, 0.15, 0)
e = e[0..(p[e,1] < 1e-6) | (p[e,2] < 1e-6)]
u = fempoi(p, t, e)
tplot(p, t, u)

# Circle, all Dirichlet
n = 32; phi = 2pi*(0:n)/n
pv = [cos.(phi) sin.(phi)]
p, t, e = pmesh(pv, 2pi/n, 0)
u = fempoi(p, t, e)
tplot(p, t, u)

# Generic polygon geometry, mixed Dirichlet/Neumann
x = 0:.1:1
y = 0.1*(-1).^(0:10)
pv = [x y; .5 .6; 0 .1]
p, t, e = pmesh(pv, 0.04, 0)
e = e[0..p[e,2] > (.6 - abs(p[e,1] - 0.5) - 1e-6)]
u = fempoi(p, t, e)
tplot(p, t, u)
```



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3. Implement a Julia function with the syntax

```
errors = poiconv(pv, hmax, nrefmax)
```

that solves the all-Dirichlet Poisson problem for the polygon `pv`, using the mesh parameters `hmax` and `nref = 0, 1, ..., nrefmax`. Consider the solution on the finest mesh the exact solution, and compute the max-norm of the errors at the nodes for all the other solutions (note that this is easy given how the meshes were refined – the common nodes appear first in each mesh). The output `errors` is a vector of length `nrefmax` containing all the errors.

Test the function using the commands below, which makes a convergence plot and estimates the rates:

```
hmax = 0.15
pv_square = Float64[0 0; 1 0; 1 1; 0 1; 0 0]
pv_polygon = Float64[0 0; 1 0; .5 .5; 1 1; 0 1; 0 0]

errors_square = poiconv(pv_square, hmax, 3)
errors_polygon = poiconv(pv_polygon, hmax, 3)
errors = [errors_square errors_polygon]

clf()
loglog(hmax ./ [1,2,4], errors)
rates = @. log2(errors[end-1,:]) - log2(errors[end,:])
```

**Code Submission:** Submit a zip-file on bCourses which contains a Julia file named `fempoi.jl` where all requested functions are defined (that is, `fempoi` and `poiconv`), and any other supporting functions. Alternatively, submit a Jupyter notebook which will define these functions when executed.