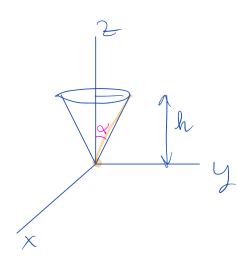
## PROBLEMS LIST 3 - EXERCISES 3,7,8,21,26

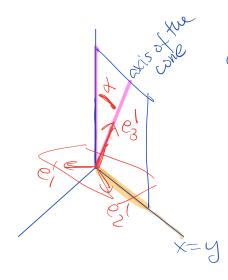
3. Obtain a parametrization of the circular cone of height h, semi-aperture  $\alpha$ , and apex O, located in the first octant, tangent to the coordinate axis Oz along a generatrix, and such that the axis of the cone orthogonally projects onto the plane z = 0 in the line x = y, z = 0.



parametrization:  

$$\begin{cases} x(t,s) = 5 \text{ tgd ast} \\ y(t,s) = 5 \text{ tgd snt}, t \in [0,27] \\ z(t,s) = 5 \end{cases}$$

New reference system:



e3: 
$$\mathcal{W}_{2=0}(e_3) \approx (1,1,0)$$
  
hence:  $e_3 \approx (1,1,0)$   
 $augle((0,0,1),(1,1,0)) = d$   
 $\Rightarrow augle((0,0,1),(1,1,0)) = d$   
 $\Rightarrow augle((1,1,0)) = d$   
 $\Rightarrow aug$ 

$$\begin{pmatrix} x \\ y \\ \frac{2}{1} \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 & 0 \\ e_1 & e_2 & e_3 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x^1 \\ y^1 \\ 2 \\ 1 \end{pmatrix}$$

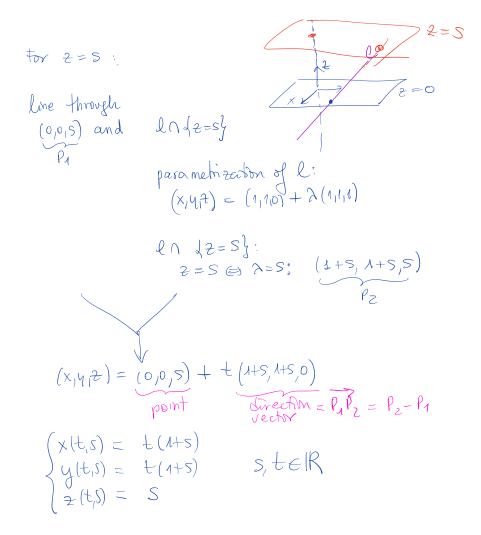
we know;  $(x'(t,s) = S t_3 x) = S t_3 x + t_3$ 

we want.

cone 
$$MS$$

$$\frac{x(t_is)}{y(t_is)} = \left(\frac{a_i}{d_i} + \frac{a_i}{d_i}\right) \left(\frac{s_i}{s_i} + \frac{s_i}{s_i}\right) \left$$

SE [o,h] te[o,211] 7. Obtain a parametrization of the surface that consists of all points belonging to any parallel line to the plane z=0 which intersects axis Oz and the line  $\ell$  defined by the parametric equation  $(x,y,z)=(1,1,0)+\lambda(1,1,1), \lambda \in \mathbb{R}$ .



Which surface is it?
observe that x=y
on fact, it is the plane x=y:

- 8. A helicoid is the trace of a moving line, touching a circular helix and its axis, and parallel to a plane perpendicular to the axis of the helix. Assume, for a start, that the axis of the helix is the coordinate axis Oy and that the helix is right-handed.
  - (a) Give a parametrization of the helicoid.
  - (b) Obtain the implicit equation of the helicoid.
  - (c) Find a parametrization of the helicoid corresponding to a right-handed helix with axis Ox, radius 3 and pitch 2.

(a) Helix: 
$$\begin{cases} x(t) = R \text{ snt} \\ y(t) = bt \\ z(t) = R \text{ cost} \end{cases}$$

$$y = S$$
: like through  $(0, 5, 0) = P_1$ 

$$(R snt, bt, Ruot) = 0$$

(0,5,0)

direction vector:  

$$\vec{P}_1\vec{P}_2 = (R \sin \frac{s}{b}, 0, R \cos \frac{s}{b})$$

$$\Rightarrow \begin{cases} x(t,s) = 0 + t R \sin sb \\ y(t,s) = s + t - 0 \\ 2(t,s) = 0 + t R \cos sb \end{cases}$$
 s, t EIR

(b) Implicit equation:  

$$S = Y \Rightarrow \begin{cases} X = t R 8nn \% \\ 2 = t R wo \% \Rightarrow X \cdot cos \frac{y}{b} = 7 c \ln \frac{y}{b} \end{cases}$$

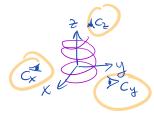
$$(c) \begin{cases} x \in \mathcal{Y} \\ y \in \mathcal{X} \\ z \in \mathcal{X} \\ (c) \in \mathcal{A} \end{cases}$$



Can we express a circular helix as the intersection of two surfaces? Which?

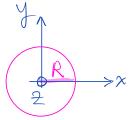
Helix with axis 02: 
$$\begin{cases} x(t) = R \text{ as } t \\ y(t) = R \text{ sin } t \end{cases}$$

$$\begin{cases} x(t) = R \text{ sin } t \\ z(t) = b \end{cases}$$



$$x^{2} + y^{2} = R^{2}$$

straight crular cylinder



$$y = R \sin t = R \sin \left(\frac{2}{b}\right) :$$

$$\times = R \omega s t = R \omega s \left(\frac{2}{5}\right)$$

But: 
$$C_X \cap C_Z$$
 contains point not belonging to the helix: if  $y = R \sin(t)$ ,  $x^2 + y^2 = t^2$ , for  $t = k$  we have  $t = t^2 - y^2$  and only one belongs to the helix.  $C_X \cap C_Y = helix$ :

- Constructing a torus from a circle. Parameterize the circle C intersection of the sphere  $x^2 + y^2 + z^2 = 1$  and the plane x + y = 1. Find the tangent vector to C at a generic point in terms of the parameter used in the previous parametrization. Parameterize now the circle C' of radius r centered at a generic point of C and lying on the plane perpendicular to C that goes through the center of C'.
  - Parametrization of C:  $x^2 + y^2 + z^2 = 1$ x + y = 1Inspecting galinder Cy:  $y = 1 - x \Rightarrow x^2 + (1 - x)^2 + z^2 = 1 \Rightarrow 2x^2 - 2x + z^2 = 0 \Rightarrow 2(x^2 - x) + z^2 = 0 \Rightarrow 2(x^2 - 2\frac{1}{2}x + \frac{1}{4} - \frac{1}{4}) + z^2 = 0 \Rightarrow 2(x - \frac{1}{2})^2 + z^2 = \frac{1}{2} \Rightarrow \frac{(x - \frac{1}{2})^2}{\frac{1}{4}} + \frac{z^2}{\frac{1}{2}} = 1 \Rightarrow \text{dispre} : \begin{cases} x - \frac{1}{2} = \frac{1}{2} \cos t \\ z = \frac{1}{2} \sin t \end{cases}$   $\Rightarrow \begin{cases} xtt = \frac{1}{2} \cot t + \frac{1}{2} \\ z(t) = \frac{1}{2} \sin t \end{cases}$   $\Rightarrow y(t) = 1 - x(t) = -\frac{1}{2} \cot t + \frac{1}{2} \end{cases}$   $\Rightarrow perametrization of C$
  - taugat vector:  $8 \text{ tt} = \left(-\frac{1}{2} \text{ sint}, +\frac{1}{2} \text{ sint}, \frac{1}{\sqrt{2}} \text{ cost}\right)$
  - . New reference system: fix  $t_0 \in [0,27]$  for a generic point  $\delta(t_0)$  of C

Param. of C' M S':

(x'(s) = r coss
y'(s) = r sms, se [0,21)
2'(s) = 0

Param. of C' in S:
$$\begin{pmatrix}
x(s) \\
y(s) \\
\frac{2}{1}
\end{pmatrix} = \begin{pmatrix}
7 & 1 & 1 \\
e_1 & e_2 & e_3 \\
\hline
0 & 0 & 0 \\
\end{bmatrix}$$

$$\begin{pmatrix}
x & (s) \\
y & (s) \\
\hline
0 & 0 & 0 \\
\end{bmatrix}$$

$$\begin{pmatrix}
x & (s) \\
y & (s) \\
\hline
0 & 0 & 0 \\
\end{bmatrix}$$

$$\begin{pmatrix}
x & (s) \\
y & (s) \\
\hline
0 & 1
\end{pmatrix}$$

$$\begin{pmatrix}
x & (s) \\
y & (s) \\
y & (s) \\
\hline
0 & 1
\end{pmatrix}$$

$$\begin{pmatrix}
x & (s) \\
y & (s) \\
y & (s) \\
\hline
0 & 1
\end{pmatrix}$$

$$\begin{pmatrix}
x & (s) \\
y & (s) \\
y & (s) \\
\hline
0 & 1
\end{pmatrix}$$

$$\begin{pmatrix}
x & (s) \\
y & (s) \\
y & (s) \\
0 & 1
\end{pmatrix}$$

$$\begin{pmatrix}
x & (s) \\
y & (s) \\
y & (s) \\
0 & 1
\end{pmatrix}$$

$$\begin{pmatrix}
x & (s) \\
y & (s) \\
y & (s) \\
0 & 1
\end{pmatrix}$$

$$\begin{pmatrix}
x & (s) \\
y & (s) \\
y & (s) \\
0 & 1
\end{pmatrix}$$

$$\begin{pmatrix}
x & (s) \\
y & (s) \\
y & (s) \\
y & (s) \\
0 & 1
\end{pmatrix}$$

$$\begin{pmatrix}
x & (s) \\
y &$$

Parametrization of torus:

replace to with t  $\begin{pmatrix}
x(t,s) \\
y(t,s)
\\
z(t,s)
\end{pmatrix} = \begin{pmatrix}
7 & 7 & 7 \\
e_1 & e_2 & e_3 \\
t & t & t
\end{pmatrix}$   $\begin{pmatrix}
r \cos s \\
r \sin s \\
0
\end{pmatrix}, s \in [0,27), t \in [0,27]$ 

Y'(to)

[Question: which is the projecting cylinder  $C_2$  of  $C_7$ ]

It is the plane x+y=1 and the circle can be paramercized as:  $\begin{cases} x=t \\ y=1-t \end{cases} = C_2$ ,  $t \in [0,1]$ 

With this parametrization, the tangent vector does not exist for (0,1,0), (4,0,0):

$$\begin{cases} x' = A \\ y' = -1 \\ \frac{2}{2} = \pm \frac{2(1-2t)}{2\sqrt{2t(1-t)}} = \pm \frac{1-2t}{\sqrt{2t(1-t)}} \end{cases} \Rightarrow \vec{1} \vec{1} \vec{1} \vec{1} = \vec{1}$$

HINTS FOR LAB EXERCISE CONSTRUCTING A "TUBULAR" SURFACE FROM A CURVE

3D curve, M: 8H) = (xH), yH), zH), teI

TUBULAR SURFACE:



IDEA: Fix a point of T, &(to):

S! 
$$o'=\delta(t_0)$$
  
 $(e'_3 \approx \delta'(t_0))$  for example,  
 $e'_1 \perp e'_3$  fue truet timedian!  
 $e'_2 = e'_3 \times e'_1$  for example,  
 $e'_1 \perp e'_3$  fue truet timedian!

Parametrization of 
$$C$$
 in  $S'$ :
$$\begin{cases} x'(s) = R \cos s \\ y'(s) = R \sin s \end{cases}, \quad S \in [0,27]$$

Parametrization of 
$$C$$
 in  $S$ :
$$\begin{pmatrix}
X(S) \\
y(S) \\
\frac{z(S)}{1}
\end{pmatrix} = \begin{pmatrix}
1 & 1 & 1 & | & x(t_0) \\
0 & 0 & 0 & 1
\end{pmatrix}
\begin{pmatrix}
R \cos \\
R \sin S \\
0 \\
1
\end{pmatrix}, SE[0,2T]$$

Parametrization of the tubular surface:

$$\begin{pmatrix} x(t_1s) \\ y(t_1s) \\ \frac{2}{3}(t_1s) \end{pmatrix} = \begin{pmatrix} \begin{pmatrix} x(t) \\ e_1 & e_2 & e_3 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x(t) \\ y(t) \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} R(\omega s) \\ R(sin s) \\ 0 \\ 1 \end{pmatrix}, se[0,27], t \in T$$