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https://github.com/julianmak/OCES5303_ML_ocean

The repository principally contains the compiled products rather than the source for size reasons.

- ▶ Associated Python code (as Jupyter notebooks mostly) will be held on the same repository. The source data however might be big, so I am going to be naughty and possibly just refer you to where you might get the data if that is the case (e.g. JRA-55 data). I know I should make properly reproducible binders etc., but I didn't...
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OCES 5303 :
ML methods in Ocean Sciences

Session 8: GANs

Outline

- ▶ Generative Adversarial Networks (GANs)
 - training via generator vs. discriminator
 - issues of mode collapse
 - conditional GAN (cGAN)
 - Deep Convolutional GAN (DCGAN)



Figure: Gans of different varieties.

Oceanic application

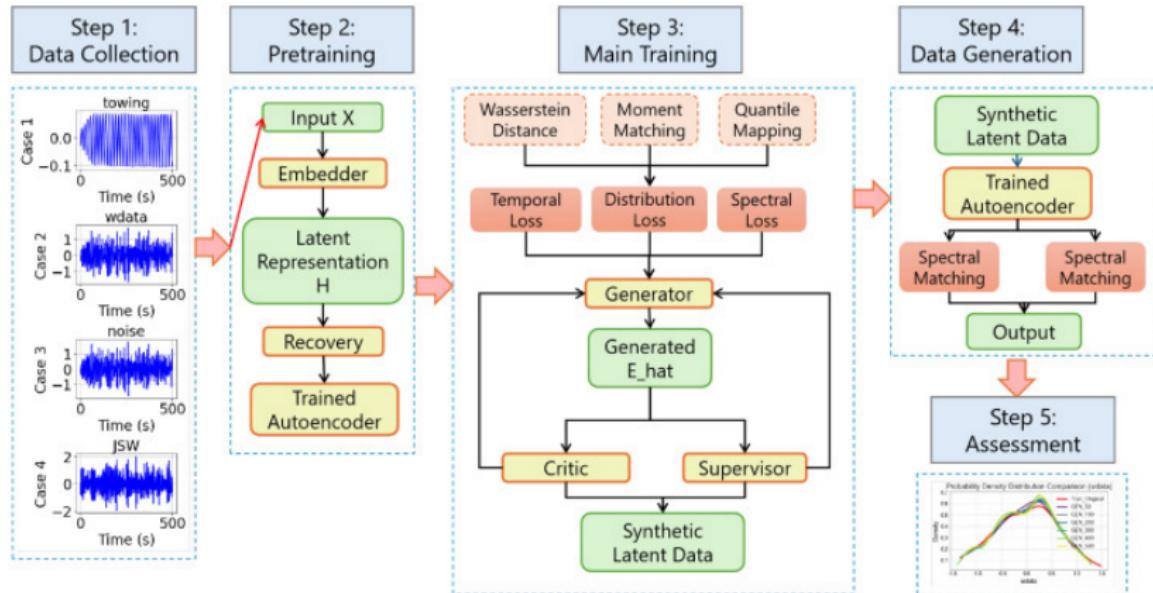


Figure: Schematic for wave reconstruction with a GAN. From Fig. 1 of Chen et al. (2026).

Oceanic application

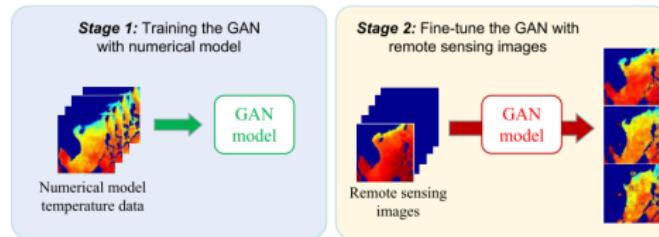


Figure: Reconstruction of satellite images based on GAN trained on numerical data. From Fig. 1 of Meng *et al.* (2023).

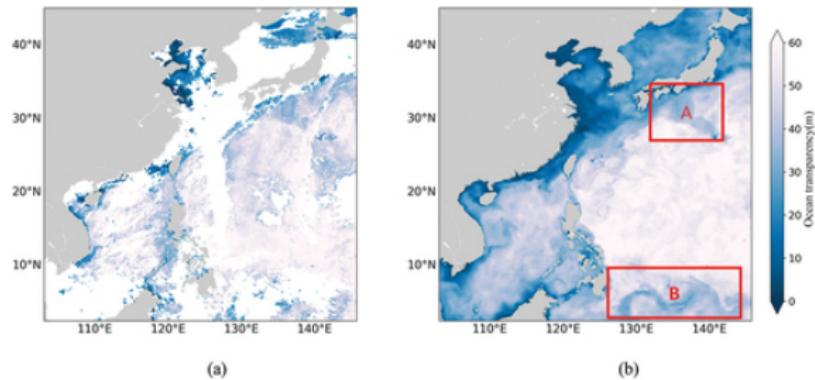


Figure: GAN based filling out of satellite images. From Fig. 11 of Zhou *et al.* (2023).

Oceanic application

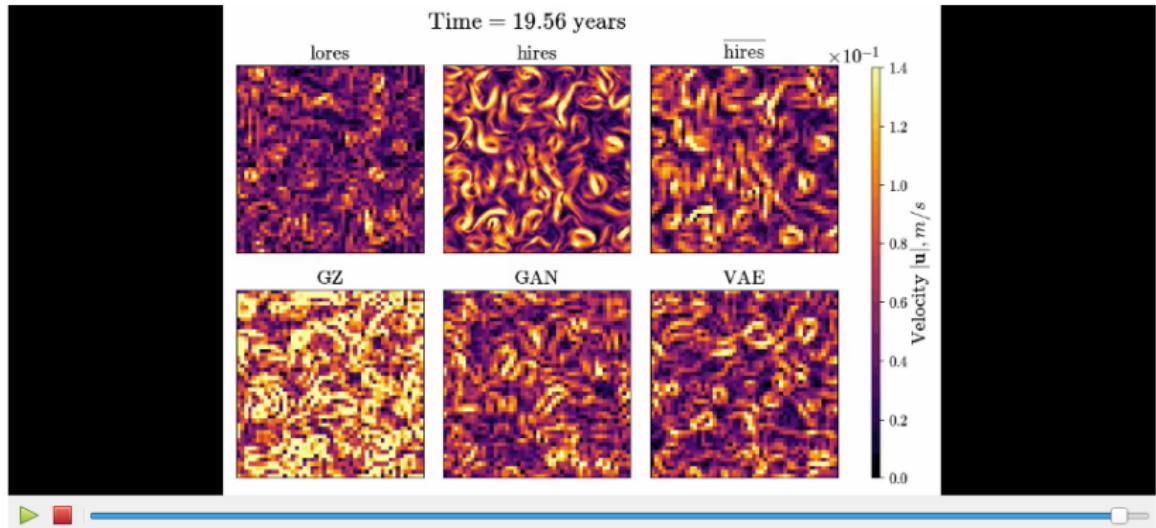


Figure: Visualisation of a low resolution model with parameterised eddies generated based on GAN. From Perezhogin *et al.* (2023).

GANs: tl;dr



Figure: Structure of a GAN in a nutshell.

GANs

1. a **generator** takes input and **generates** “fake” data
 - input is usually some random noise
 - output can be numbers, images, sound, whatever

GANs

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 - input is usually some random noise
 - output can be numbers, images, sound, whatever

2. a **discriminator** takes the data and classifies them as whether they are “real” or “fake”
 - input is the numbers/images/sound/whatever
 - “real” is training data, “fake” is output from **generator**
 - output is a **number** in $[0, 1]$
 - usually $0 = \text{fake}$ and $1 = \text{real}$

GANs

3. **discriminator** tries to maximise the score
→ i.e. being good at telling between “real” and “fake”s
4. **generator** tries to minimise the score
→ i.e. by generating very good “fakes”s

GANs

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 - i.e. being good at telling between “real” and “fake”s
4. **generator** tries to minimise the score
 - i.e. by generating very good “fakes”s
5. results in **minimax** problem, where they “fight” each other and both get “better” in due course
 - cf. **evolutionary arms race** in evolution biology
 - original GAN paper assumes **zero sum games**, and ordering of moves doesn’t matter
 - **zero-sum** = one’s gain is another’s loss
 - universality as generator/discriminator are NN based
 - in practice discriminator moves first

vanilla GAN

- ▶ use penguins data as a quick test
 - aim to generate four numbers for some input noise
 - the species labels are not used for now
- ▶ see notebook for implementation of GAN
 - use PyTorch here (I wasn't comfortable with my Keras implementation, see notebook)
 - generator and discriminator are just MLPs
 - loss uses binary cross entropy
 - optimizer is Adam as usual

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 - optimizer is Adam as usual
- ! subtleties with the training loop
 - did manual batching partly because of that
 - need to be careful with where loss and gradients are computed, and which models are updated where

vanilla GAN

1. the discriminator moves first

- generate outputs from noise, label as 0s, compute loss, train
- take real data, label as 1s, compute loss, train (!!)
- generator is fixed at this substep

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- generate outputs from noise, label as 1s
- let the discriminator do its thing
- compute loss based on discriminator output, train
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3. above is one epoch, repeat as necessary

!!! otherwise possible to have loss reduction simply by having a weak discriminator (because of zero-sum game nature)

vanilla GAN

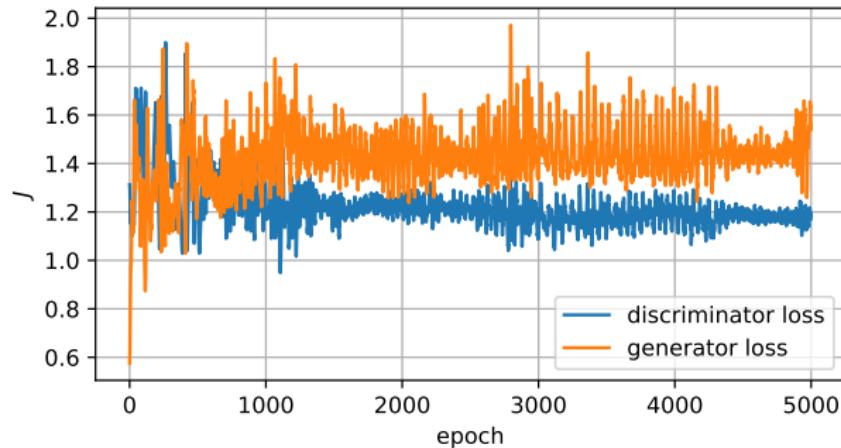


Figure: Generator and discriminator loss as a function of epochs for the penguins data.

- ▶ note the loss values are not small
 - not an issue as such
- ▶ quite a bit of fluctuation
 - competition between generator and discriminator via minimax/zero-sum game

GAN: mode collapse

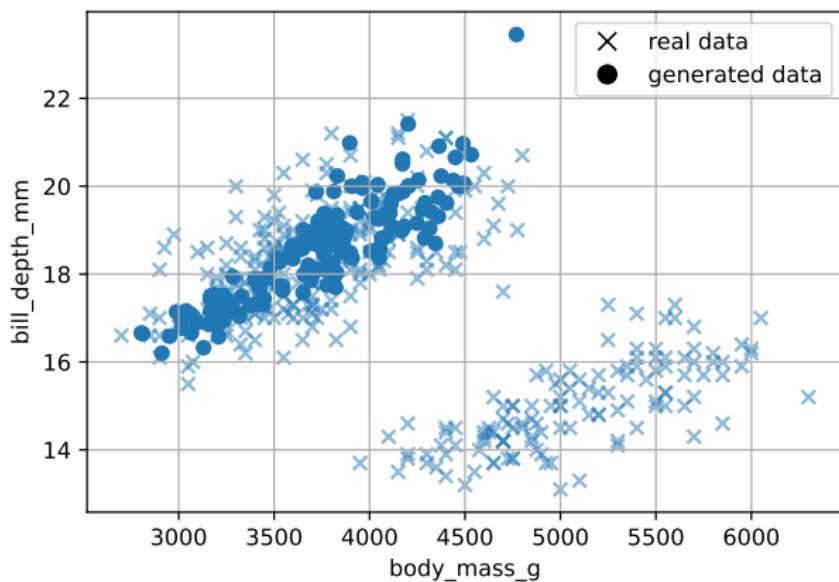


Figure: Outputs from the generator for the vanilla GAN.

- ▶ model exposed to Gentoo data but none being generated?

GAN: mode collapse

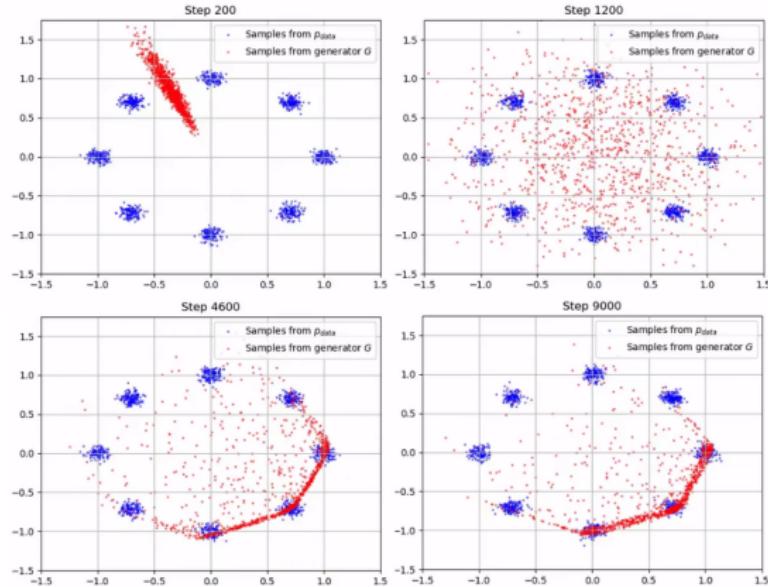


Figure: Visualisation of mode collapse via generator output as a function of training epoch. From Christoph Reich's GitHub page.

GAN: mode collapse

- ▶ mode collapse refers to generator specialising too early
 - reduces diversity of resulting output
 - generator “plays it too safe”
- ▶ one way to avoid is to use a different loss such as the Wasserstein metric
 - amount of “work” to move one pdf to another, measures distances between pdfs
 - deviation from data pdf is then penalised
 - not standard loss in PyTorch at the time of writing
- ▶ other methods (e.g. unrolling) is possible, but going to do something easier...

conditional GAN (cGAN)

- ▶ we could just make the GAN use the label information
 - GAN **conditioned** on the label information
 - e.g. a **prompt** when you get AI to generate an image
- ▶ side-steps but does not avoid mode collapse
 - produced samples could still be lacking in diversity

conditional GAN (cGAN)

- ▶ we could just make the GAN use the label information
 - GAN **conditioned** on the label information
 - e.g. a **prompt** when you get AI to generate an image
- ▶ side-steps but does not avoid mode collapse
 - produced samples could still be lacking in diversity
- ▶ setting basically exactly the same, just need some trickery
 - (!!!) to merge the label information in
 - label information usually in **one-hot form**, i.e.
(Adelie, Chinstrap, Gentoo) → ([1, 0, 0], [0, 1, 0], [0, 0, 1])
 - bulk up input dimension by three here

conditional GAN (cGAN)

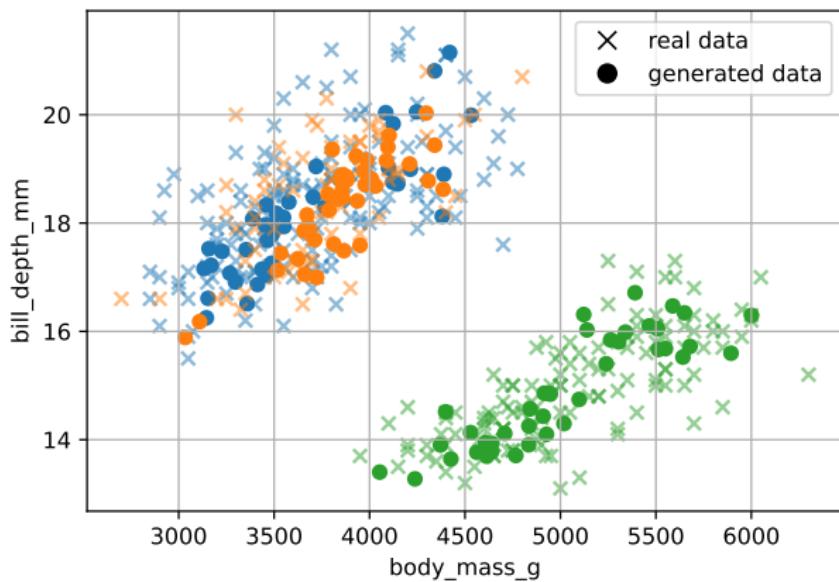


Figure: Outputs from the generator for the cGAN.

- still some hints of mode collapse within specie?

convolutional GAN (DCGAN)

- ▶ example on the Mercator eddy data (see notebook 05)
→ already processed and standardised, just using SST images of cyclonic eddies here

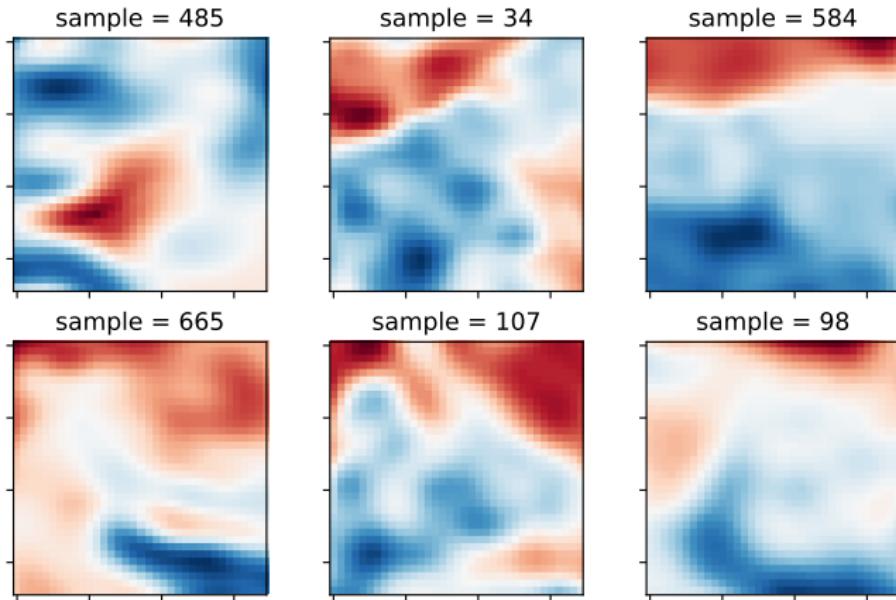


Figure: Some samples of the SSTs of cyclonic eddies from the Mercator eddy dataset.

convolutional GAN

- ▶ see notebook for the network structure
 - Conv2d and ConvTranspose2d again but in PyTorch
- ▶ some care is needed to make sure the dimensions at each stage are correct and intended
 - would suggest doing the **discriminator** first
 - possibly easier to figure how to go from

$$(\text{channel}, \text{height}, \text{width}) \rightarrow (1, 1, 1)$$

via Conv2d layers than the other way round

→ once you have **discriminator**, could mirror the ordering of operations, swap out Conv2d for ConvTranspose2d, which then does

$$(\text{noise}, 1, 1) \rightarrow (\text{channel}, \text{height}, \text{width})$$

convolutional GAN

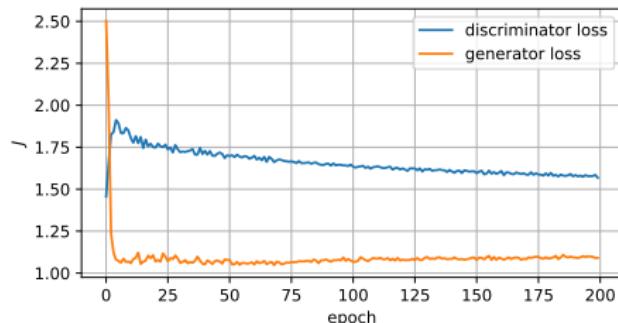


Figure: Generator and discriminator loss as function of epoch.

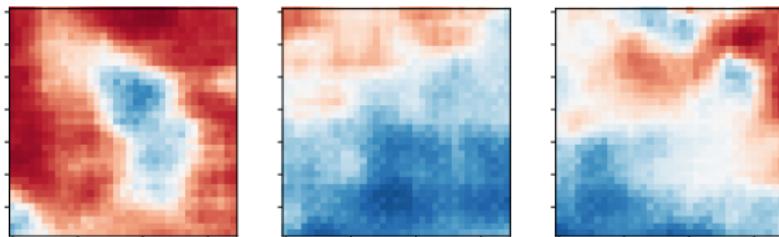


Figure: Visualisation of samples of generator output.

convolutional GAN

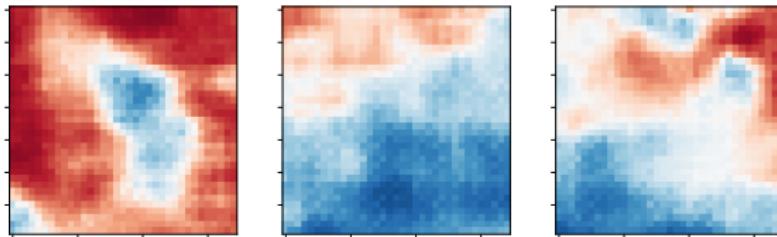


Figure: Visualisation of samples of generator output.

- ▶ is the above “good”?
 - some guiding principles to judge?
 - probably need to look into the full dataset quite a bit more
 - compute some statistics to be quantitative about it

Demonstration



Figure: Generated image from '*HKUST with sun setting over the sea*', from <https://visualgpt.io/>. Spot any issues here?

- ▶ some varieties of GANs
 - basics in constructing generator and discriminator
 - deal with issues of **mode collapse?**
 - how to judge whether something is “good” quantitatively?
 - Keras implementation?

(see notebook)

Moving to a Jupyter notebook →