1. Let K24, as shown below with the ghan orientation K



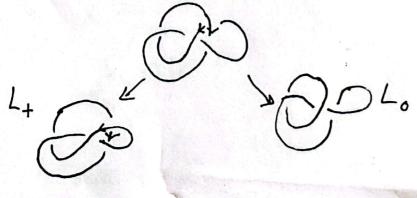
Polynomial DK of K with the relations to compute the Alexander

- · Aturney hoof 21
- three lakes which differ only at one cossing shown as follows

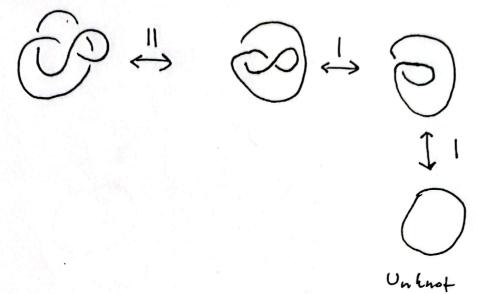
we look at the circled crossing in K:



This crossing is of the L_ form, so we have $K=L_-$



For Lywehave by the following Reviewarster moves, that Ly is the unknot:

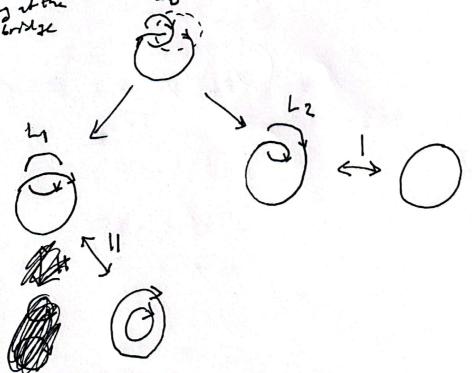


So AL = Dunknot = 1.

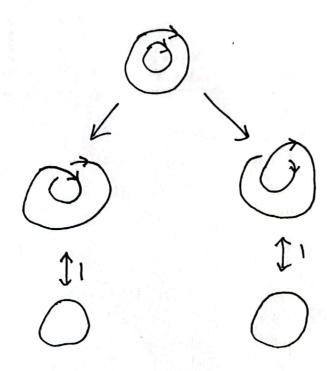
Now, Lo by Reidemenste 1 is the Hopf lank!



By sheet relations, we have that Lo with the following or lestation is a negative crossing at the LO



Now by is the worlder of two components and stree



We have $(t^{\frac{1}{2}}-t^{-\frac{1}{2}})\Delta L_1 = \Delta_{unlinet} - \Delta_{unlenst} = (-1=0=)\Delta L_1=0$ by the shell relations.

we thus have

$$\Delta_{L_0} = \Delta_{L_1} - (t^{\frac{1}{2}} - t^{\frac{1}{2}}) \Delta_{L_2}$$

$$= -(t^{\frac{1}{2}} - t^{\frac{1}{2}})$$

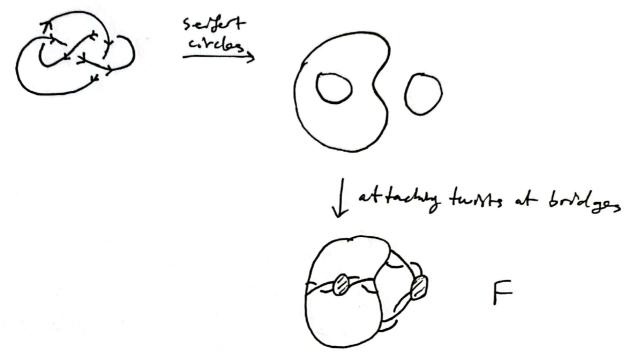
5.
$$\Delta k^2 \Delta L = \Delta L + (t^{\frac{1}{2}} - t^{-\frac{1}{2}}) \Delta L_0$$

$$= 1 - (t^{\frac{1}{2}} - t^{-\frac{1}{2}})^2$$

$$= 1 - t - t^{-1} + 2$$

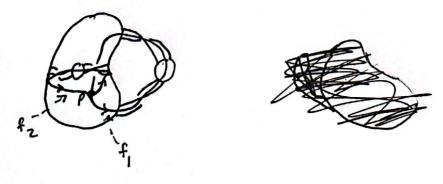
$$= 3 - t - t^{-1}$$

2. To calculate the Alexander polynomed us my the Sevfert forms we sweet find a Sevfort surface for K us, my the Sevfort algorithm, grong:



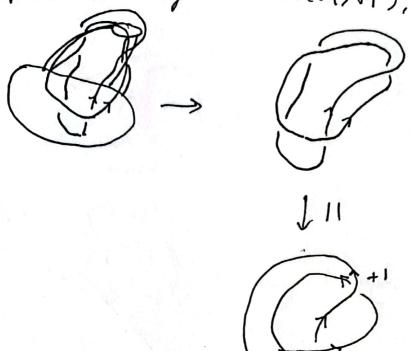
call the surface F. We gove For orventation by considering the shided in smaller discs to have the "upward-facty" side facing us, and the uncolored disc to be facing down, i.e. its "upward direction" is its the

To flad generators for H(F), the first honology group, we take the following two generators for and fz:

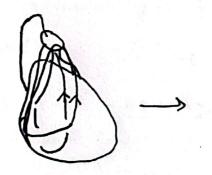


The serfect matrix A is given by Aij = (k (fi, fit), where fit is the pushoff of fig. 100 53-F which runs parallel to fi. but stylith "upward with ornestation" to fi.

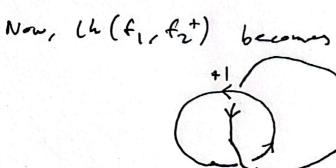
To compute the linking number lh(f, f, t), we look at



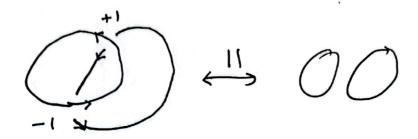
so lh (f1, f1+)=1 Now, lh (f2, f2+) is smilerly



So Ch (fz,fz+)=-1



And lastly the (frifit) is



s. lh (f2, f1+) = 0

Thus
$$A = \begin{pmatrix} 1 & 1 \\ 0 & -1 \end{pmatrix}$$
, Hence $+A - A = \begin{pmatrix} + & + \\ 0 & -+ \end{pmatrix} - \begin{pmatrix} + & 0 \\ 1 & -1 \end{pmatrix}$

$$= \begin{pmatrix} + & -1 & + \\ -1 & 1 - + \end{pmatrix}$$

which has determined $(t-1)(1-t)+t=-(t-1)^2+t$ = $-t^2+2t-1+t$ = $-t^2+3t-1$

which by multiplying by to which is a unit in R[t, to 1]. s associated to 3-t-to 1,50

AK = 3-t-t by page 55 h Lichorsh, which is also what we found in part (a).