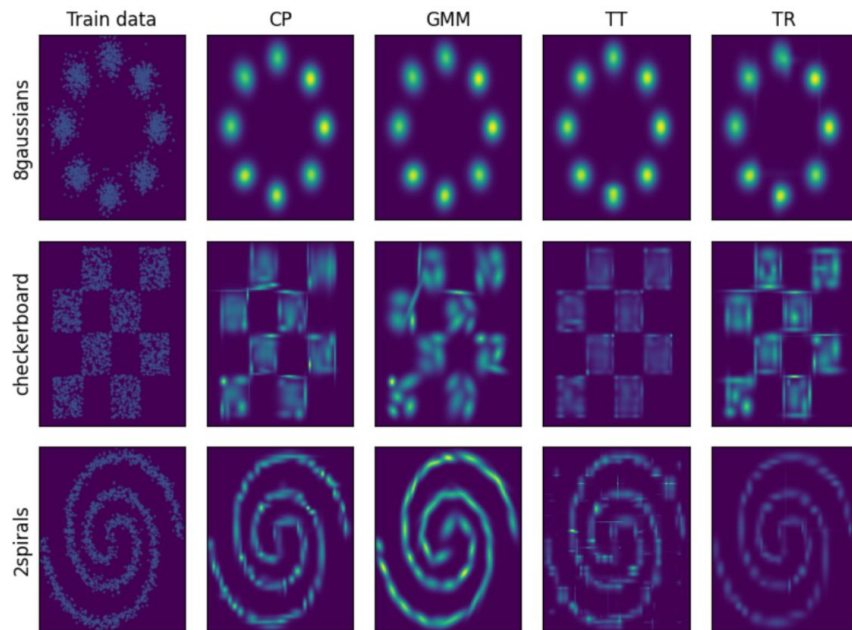


# Tensor Factorized Density Estimation

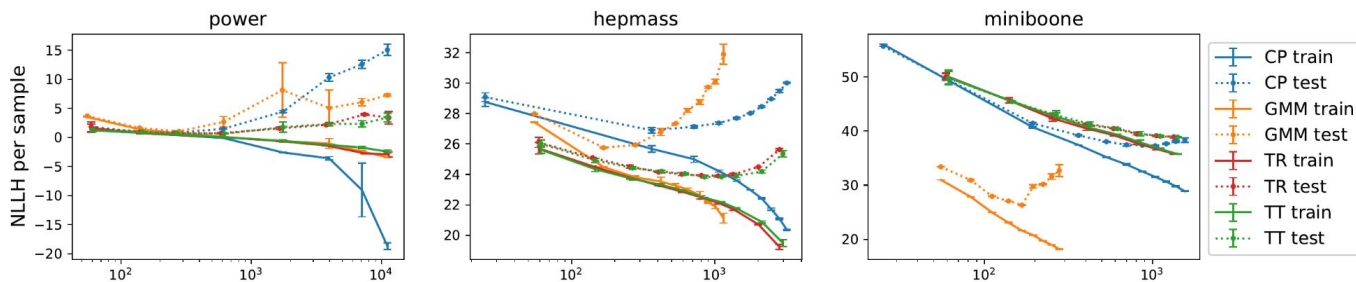
Eskild Børsting Sørensen, Johannes Emme Jørgensen,  
Jonas Vestergaard Jensen, Peter Mørch Groth



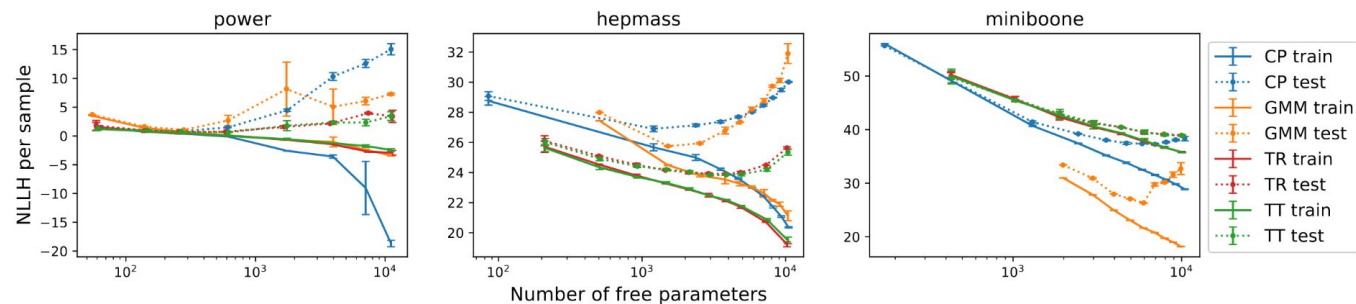
# Correction for Fig. 1. Training and test performance

Incorrect x-axis values for *hepmass* and *miniboone*:

Before:



After:



**Fig. 1. Training and test performance.** The models are evaluated at various numbers of free parameters at a sample size of 1750 for three datasets with increasing number of dimensions.

# Introduction

- **Prior:** Gaussian Mixture Model (GMM)      $O(KM^2)$
- **Objective:** Density estimator that scales better with high-dimensional data
- **Method:** Tensor decompositions  $\rightarrow$  factorizing joint distribution
- **Evaluation:** Compare with conventional GMM and state-of-the-art neural density estimator

# Tensor decompositions

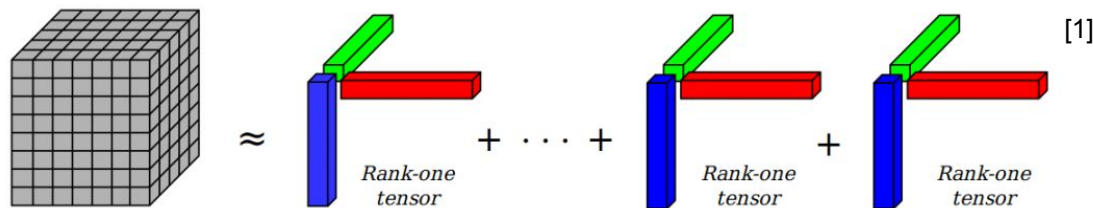
## Canonical polyadic (CP) decomposition

$$A(i_1, i_2, \dots, i_M) = \sum_{\alpha}^r U_1(i_1, \alpha) U_2(i_2, \alpha) \cdots U_M(i_M, \alpha)$$

## Factorization using CP procedure

$$p(x_1, x_2, \dots, x_M) = \sum_{k=1}^K p(k) \prod_{m=1}^M p(x_m | k)$$

$$= \sum_{k=1}^K w_k \prod_{m=1}^M \mathcal{N}(x_m | \mu_{k_m}, \sigma^2_{k_m})$$



Factorization using **Tensor Train** procedure

$$\begin{aligned}
 p(x_1, x_2, \dots, x_M) &= \sum_{k_0, \dots, k_M}^{K_0, \dots, K_M} p(k_0) \prod_{m=1}^M p(x_m, k_m | k_{m-1}) \\
 &= \sum_{k_0, \dots, k_M}^{K_0, \dots, K_M} w_{k_0} \prod_{m=1}^M w_{k_m, k_{m-1}} \mathcal{N}(x_m | \mu_{k_m, k_{m-1}}, \sigma^2_{k_m, k_{m-1}})
 \end{aligned}$$

$$\sim O(K^2 M)$$

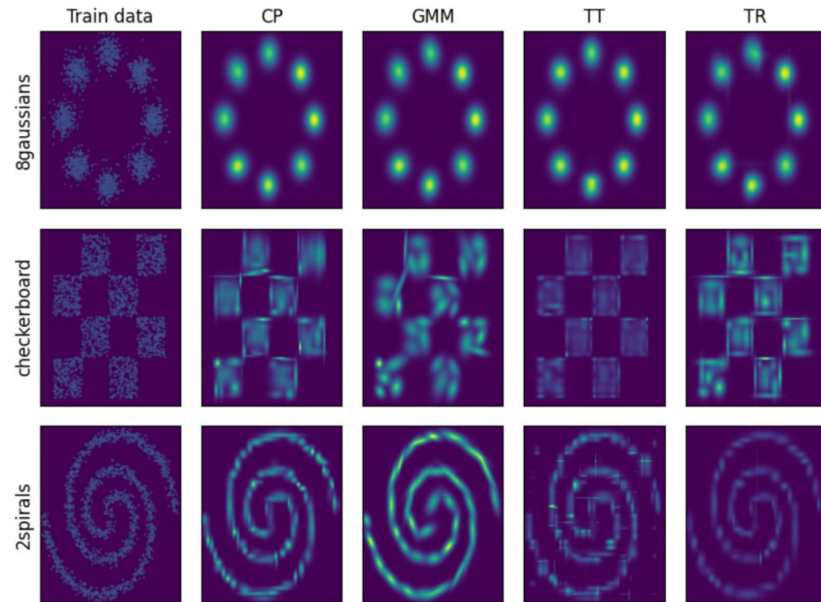
Factorization using **Tensor Ring** procedure

$$\begin{aligned}
 p(x_1, x_2, \dots, x_M) &= \sum_{k_0, \dots, k_M}^{K_0, \dots, K_M} p(k_0) \left[ \prod_{m=1}^{M-1} p(x_m, k_m | k_{m-1}) \right] p(x_M | k_{M-1}, k_0) \\
 &= \sum_{k_0, \dots, k_M}^{K_0, \dots, K_M} w_{k_0} \left[ \prod_{m=1}^{M-1} w_{k_m, k_{m-1}} \mathcal{N}(x_m | \mu_{k_m, k_{m-1}}, \sigma^2_{k_m, k_{m-1}}) \right] \\
 &\quad \cdot \mathcal{N}(x_M | \mu_{k_M, k_{M-1}}, \sigma^2_{k_M, k_{M-1}})
 \end{aligned}$$

# Performance

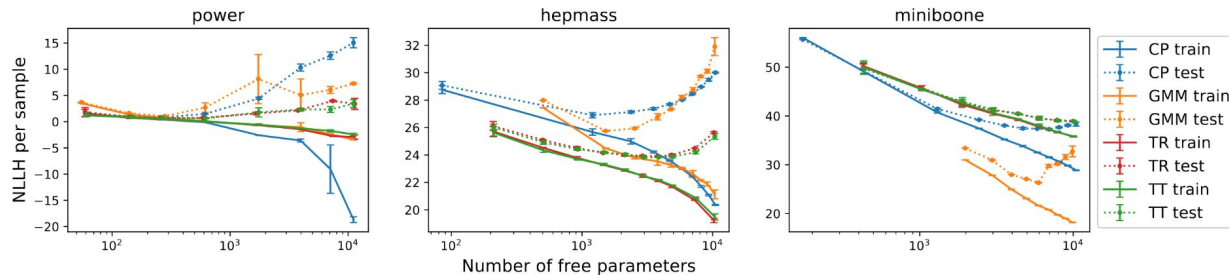
	power	gas	hepmass	miniboone	8gaussians	checkerboard	2spirals
FFJORD	-0.46	-8.59	<b>14.92</b>	<b>10.43</b>			
CP	-0.42	-10.30	22.76	29.23	1.47	2.02	1.85
GMM	-0.43	<b>-13.23</b>	20.78	17.84	1.47	2.04	<b>1.79</b>
TT	-0.47	-5.23	23.07	35.29	1.47	<b>1.93</b>	1.94
TR	<b>-0.53</b>	-5.33	23.06	35.27	1.48	2.01	1.85

**Table 1.** Test negative log likelihood per sample for the selected models. Results are averages over 3 runs.

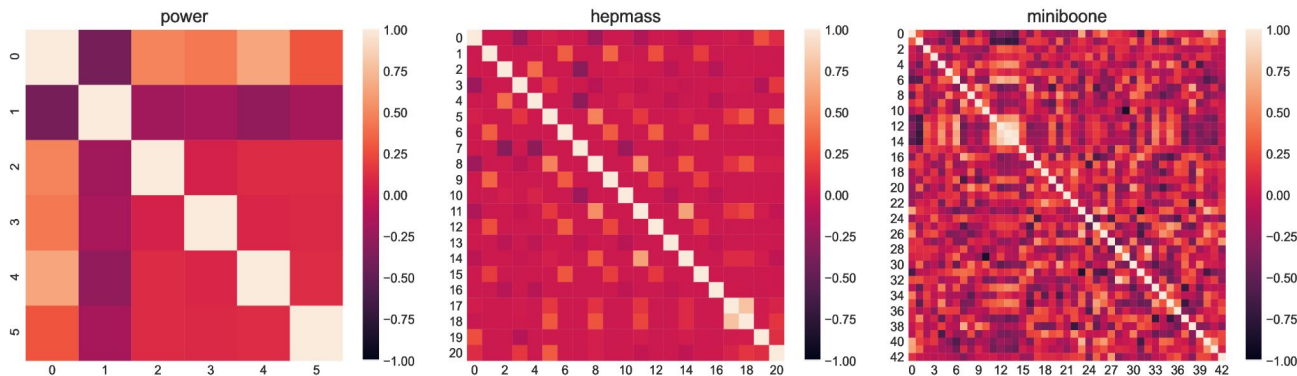


**Fig. A.2. Modelling of synthetic data.** The selected models qualitative performance on the 2D synthetic point data.

# Structural differences in the data

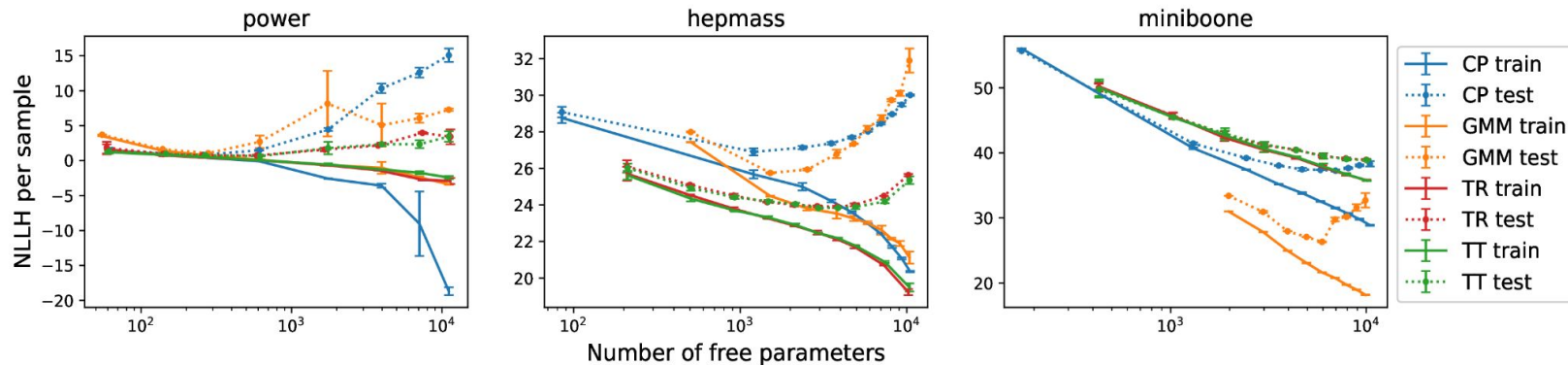


**Fig. 1. Training and test performance.** The models are evaluated at various numbers of free parameters at a sample size of 1750 for three datasets with increasing number of dimensions.



# Regularisation in TT & TR

- **Regularisation properties:** Tensor train & Tensor ring generalizes well when increasing complexity



**Fig. 1. Training and test performance.** The models are evaluated at various numbers of free parameters at a sample size of 1750 for three datasets with increasing number of dimensions.



# Ordering of variables

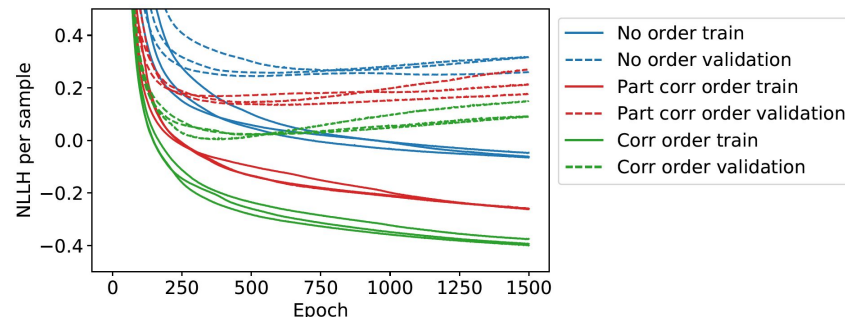
## Ordering by maximizing correlation

- Better performance when doing early stopping.
- More overfitting

## Ordering by maximizing partial correlation

- Worse performance when doing early stopping.
- Less overfitting

Regularization properties by ordering variables.

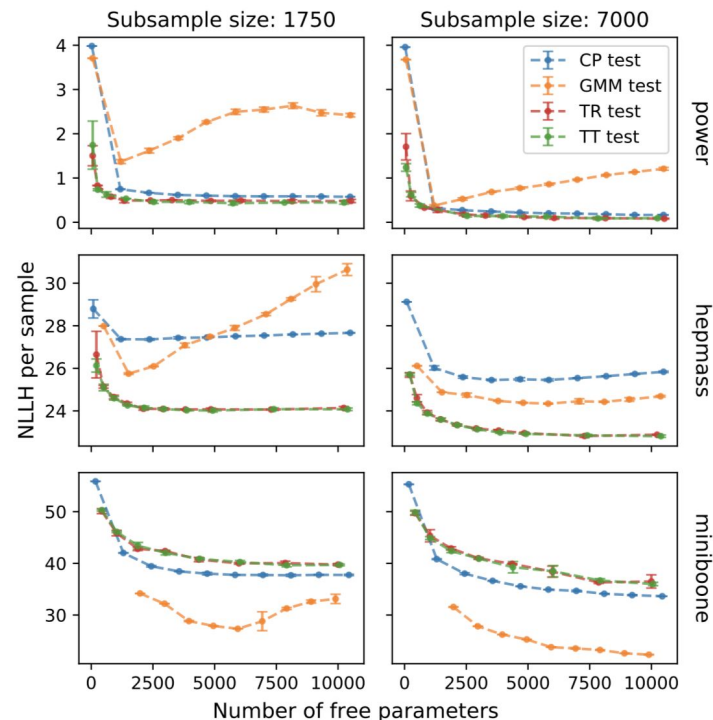


**Fig. 3. Performance of TT and TR by ordering variables.**  
The experiments were trained on the *power* dataset with 1750 subsamples and  $k=12$ .

# Performance continued

	power	gas	hepmass	miniboone	8gaussians	checkerboard	2spirals
FFJORD	-0.46	-8.59	<b>14.92</b>	<b>10.43</b>			
CP	-0.42	-10.30	22.76	29.23	1.47	2.02	1.85
GMM	-0.43	<b>-13.23</b>	20.78	17.84	1.47	2.04	<b>1.79</b>
TT	-0.47	-5.23	23.07	35.29	1.47	<b>1.93</b>	1.94
TR	<b>-0.53</b>	-5.33	23.06	35.27	1.48	2.01	1.85

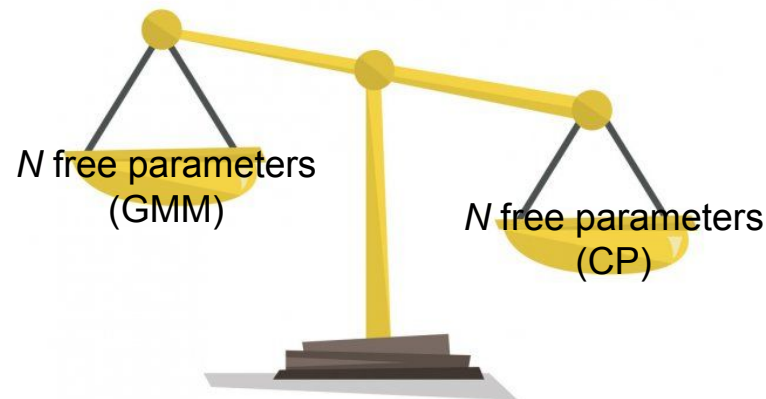
**Table 1.** Test negative log likelihood per sample for the selected models. Results are averages over 3 runs.



**Fig. 2. Test performance.** Comparison at various levels of model complexities.

# Improvements

- **Means of comparison**
- **High-dimensional synthetic data**
- **Initialisations for TT and TR**



# Conclusion

- **Tensor factorized density estimators are viable for density estimation**
- **Performance depends on dataset structure and ordering**
- **Robust when little data is available**