## MECH 6300-HW3

$$\mathcal{L}_{1} = \alpha \begin{pmatrix} \frac{1}{10} \\ \frac{1}{5} \\ \frac{1}{3} \end{pmatrix} \qquad \mathcal{L}_{3} = \alpha \begin{pmatrix} 0 \\ 0 \\ \frac{1}{5} \\ \frac{1}{3} \end{pmatrix} \qquad \mathcal{L}_{3} = \alpha \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$Q = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ -1 & 0 & 0 \\ \frac{5}{3} & -\frac{5}{3} & 1 \end{bmatrix}$$