

$$4) \quad \dot{X}_1 = (x_1 x_2 - 1) x_1^3 + (y_1 y_2 + x_3^2 - 1) x_1$$

$$\dot{X}_2 = x_3$$

$$\dot{X}_3 = u$$

$$y = h(x, u) = x_2$$

$$\frac{dh}{dt} = \frac{d}{dt} y_2 = \dot{x}_2 = (x_3) \quad \begin{matrix} \uparrow 1 \\ \downarrow 2 \end{matrix}$$

$$\frac{d^2 h}{dt^2} = \frac{d}{dt} x_3 = \dot{x}_3 = u$$

Relative Degree = 2

2)

$$u = \frac{1}{L_g L_f^{r-1} h(x)} \{ -L_f^r h(x) + v \}$$

$$y = h(x) = x_2$$

$$L_g = \frac{-1}{x_2}$$

$$L_f = \left(1 + 1 \frac{u}{x_2} \right)$$

$$u = \frac{1}{1 + \frac{u}{x_2}} \left\{ -\frac{1}{x_2} + u + v \right\}$$