

MECH 6323 - HW 1

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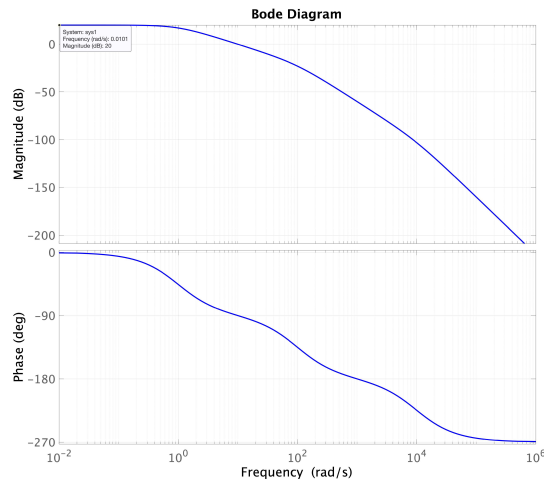
1 Problem 1

2 Problem 3

Problem: For each of the bode plots:

1. Determine the breakpoints and the transfer function.
2. Determine the gain cross-over frequency ω_c and the phase cross-over frequency ω_{180} .

2.1 Bode Plot 1:



2.1.1 Gain, Poles, and Zeros:

1. **Gain:** 20 db = 10
2. **Poles:**
 - (a) $10^0 = 1$ rad/s
 - (b) $10^2 = 100$ rad/s
 - (c) $10^4 = 10,000$ rad/s
3. **Zeros:** (NA)

Transfer Function:

$$H(s) = \frac{10}{\left(1 + \frac{s}{1}\right)\left(1 + \frac{s}{100}\right)\left(1 + \frac{s}{10000}\right)}$$

2.1.2 Cross-over Frequency:

1. $\omega_c = 10^1 = 10$ rad/s
2. $\omega_{180} = 10^3 = 100$ rad/s

2.2 Bode Plot 2:

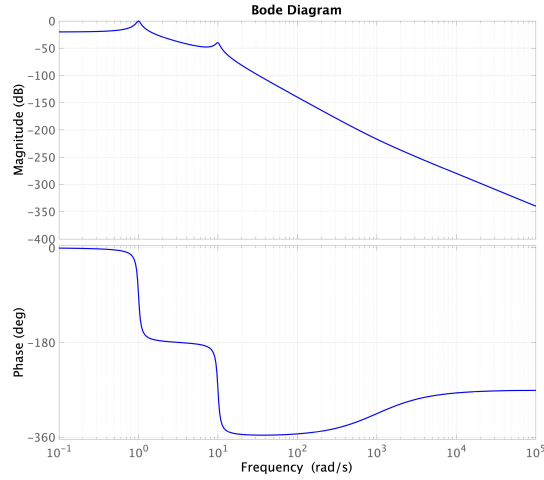


Figure 1: Bode Plot 2

2.2.1 Gain, Poles, and Zeros:

1. **Gain:** $-20 \text{ dB} = \frac{1}{10}$
2. **Poles:**
 - (a) $10^0 = 1 \text{ rad/s}$ (complex)
 - (b) $10^1 = 10 \text{ rad/s}$ (complex)
3. **Zeros:**
 - (a) $10^3 = 1,000 \text{ rad/s}$

2.2.2 Transfer Function:

$$H(s) = \frac{(1 + \frac{s}{1000})}{10(\frac{1}{1}(s^2 + 2(\frac{1}{10})(1)s + (1)^2))(\frac{1}{10}(s^2 + 2(\frac{1}{10})(10)s + (10)^2))} = \frac{(s + 1000)}{(s^2 + 0.2s + 1)(s^2 + 2s + 100)}$$

Assuming a Q-factor of around 10 to get the complex response.

2.2.3 Cross-over Frequency:

1. $\omega_c = 10^0 = 1 \text{ rad/s}$
2. $\omega_{180} = 10^3 = 100 \text{ rad/s}$

3 Problem 4

Consider the interconnection of Problem 1 with the PI controller

$$C(s) = \frac{10(s+3)}{s}$$

and plant

$$P(s) = \frac{-0.5(s^2 - 2000)}{(s-3)(s^2 + 50s + 1000)}$$

3.1 Is the feedback system stable? Why?

$$\begin{aligned} 1 + C(s)P(s) &= 1 + \frac{10(s+3)}{s} \frac{-0.5(s^2 - 2000)}{(s-3)(s^2 + 50s + 1000)} \\ &= \frac{s(s-3)(s^2 + 50s + 1000) + 10(s+3)(-0.5)(s^2 - 2000)}{s(s-3)(s^2 + 50s + 1000)} \\ &\approx \frac{(s^2 + 11.73s + 73.9)(s^2 + 30.27s + 406)}{s(s-3)(s^2 + 50s + 1000)} \end{aligned}$$