

4. [20 points] Consider the following set of models:

$$\mathcal{I} := \left\{ \frac{G(s)}{1 + w(s)\Delta(s)} \mid \Delta \text{ stable, } \|\Delta\|_{\infty} < 1 \right\}$$

$G(s)$  is SISO and  $w(s)$  is a stable, proper rational transfer function.

- (a) Draw a block diagram showing the structure of any  $G_p \in \mathcal{I}$ . Your diagram should only include blocks for  $G$ ,  $w$ , and  $\Delta$ .
- (b) Consider the feedback diagram show in Figure 4. Assume the controller  $K$  stabilizes the nominal system  $G$ . Find a necessary and sufficient condition for  $K$  to stabilize all  $G_p \in \mathcal{I}$ . Provide a proof of sufficiency, i.e., prove that  $K$  achieves robust stability if your condition is satisfied. You do not need to prove necessity.

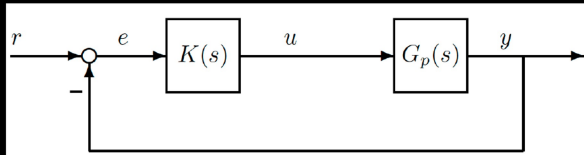


Fig. 4: Feedback loop



b)

$$\frac{K G}{1 + w(s)\Delta(s)} \quad \text{stable } \forall w$$

Proof:

This can be proven w/ Nyquist criteria...

(don't have time to write out specifics, but essentially that it must just remain