

CENTRALITY

degree

eigenvector

katz

PageRank

Hubs + Authorities

betweenness

closeness

SYSM 6302

CLASS 7

Closeness Centrality

Let d_{ij} = length of the shortest path from i to j

\Rightarrow Recall diameter = $\max_{i,j} d_{ij}$

Mean distance of other nodes from i : $l_i = \frac{1}{n} \sum_{j=1}^n d_{ij}$

small is
more
important

Closeness centrality: $C_i = \frac{1}{l_i} = \frac{n}{\sum d_{ij}}$

for unweighted networks
the range of l_i is not
very broad

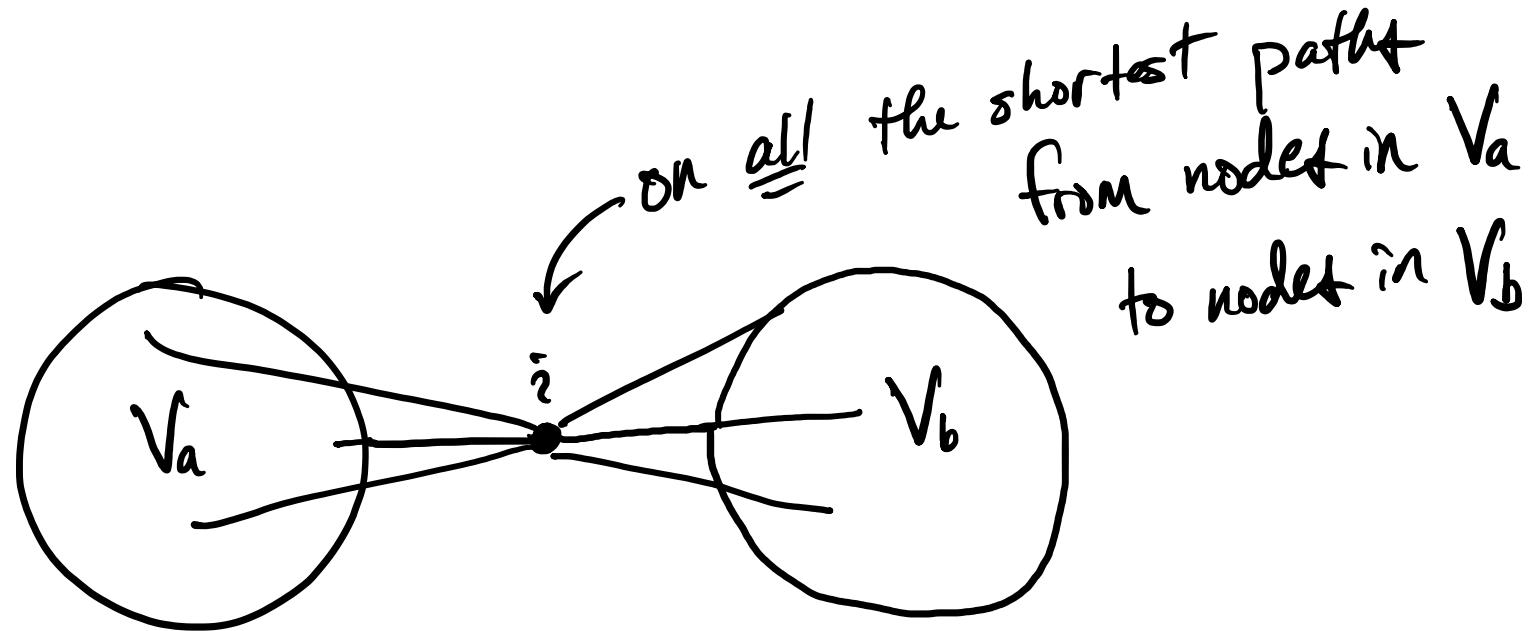
A less standard method: $\tilde{C}_i = \frac{1}{n-1} \sum_{j \neq i} \frac{1}{d_{ij}}$ (called a harmonic mean)

This allows for elegant inclusion of nodes in other components

Contribution to centrality is inversely proportional to distance,
so local connectivity dominates.

Betweenness Centrality

$$x_i = \sum_s \sum_t \frac{\text{\# of shortest paths from } s \text{ to } t \text{ that include } i}{\text{\# of shortest paths from } s \text{ to } t}$$



Degree Centrality

Nodes with higher number of connections are ranked as more important

⇒ "popularity"

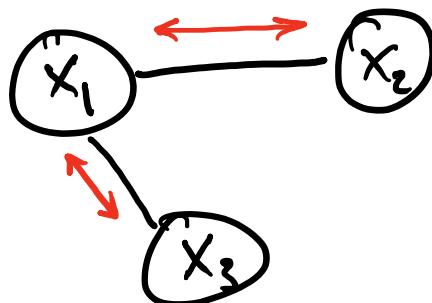
This is a local property of the node

Eigenvector Centrality



- ⇒ Degree assigns importance equally in terms of the # of neighbors.
- ⇒ Eigenvector Centrality assigns importance proportional to the importance of the node's neighbors

We can view this measure at the "steady-state" of each node
"passing" its importance to all of its neighbors



$$x(t+1) = Ax(t) \rightarrow \begin{matrix} \text{Steady state} \\ \text{when} \end{matrix} \rightarrow v = Av$$
$$x(t+1) = x(t) = v$$



Do this more carefully:

$$x(t+1) = Ax(t) \Rightarrow x(t) = A^t x(0)$$

IF $A \in \mathbb{R}^{n \times n}$ is symmetric \Rightarrow its eigenvectors span \mathbb{R}^n & are linearly independent

\Rightarrow Any $u \in \mathbb{R}^n$ can be written as a linear combination of these eigenvectors:

$$u = c_1 v_1 + c_2 v_2 + \dots + c_n v_n$$

Constants

Since $x(0) \in \mathbb{R}^n$: $x(0) = \sum_{i=1}^n c_i v_i \Rightarrow x(t) = A^t \sum_{i=1}^n c_i v_i$

$$x(t) = \sum_{i=1}^n c_i A^t v_i = \sum_{i=1}^n c_i \lambda_i^t v_i = c_1 \lambda_1^t v_1 + \lambda_1^t \sum_{i=2}^n c_i \left(\frac{\lambda_i}{\lambda_1}\right)^t v_i$$

largest eigenvalue

*Vector
a number*

$\xrightarrow[t \rightarrow \infty]{} c_1 \lambda_1^t v_1$

$$x(t) \rightarrow c_1 \lambda_1^t v_1 \quad \text{as } t \rightarrow \infty$$



But since absolute values of centrality are not important,

$x \sim v_1$ ← eigenvector corresponding to the largest eigenvalue of A

$$Av_1 = \lambda_1 v_1 \Rightarrow x = \frac{1}{\lambda_1} Ax$$

$$\Rightarrow x_i = \frac{1}{\lambda_1} \sum_{j=1}^n A_{ij} x_j$$

j points to i

↑
centrality of
node i

↑
centrality of
node j

x_i can be large because it is connected to many nodes OR because it is connected to nodes with large x_j (large centrality)

Perron-Frobenius Theorem

For a positive matrix A (i.e. $A_{ij} > 0 \quad \forall i, j = 1, \dots, n$):

- ① There exists a real, positive eigenvalue λ_1 such that the magnitude of all other eigenvalues is less than λ_1^+ : $|\lambda_i| < |\lambda_1| \quad \forall i = 2, 3, \dots, n$.
- ② The eigenspace of λ_1 is dimension 1 (it has only 1 corresponding eigenvector)
- ③ The corresponding eigenvector, v_1 , of λ_1 has entries that are the same sign (+/-)*. All other eigenvectors have at least 1 element that is positive and 1 that is negative.

For non-negative A ($A_{ij} \geq 0$)

* or zero + or the same $|\lambda_i| \leq |\lambda_1|$

Eigenvector Centrality for Directed Graphs

① A is not symmetric

eigenvectors do not always span \mathbb{R}^n

left \neq right eigenvectors

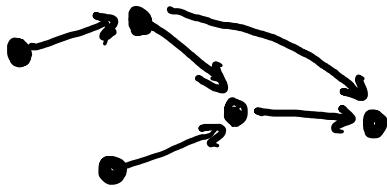
$$U^T A = \Lambda U^T$$

$$A V = \Lambda V$$

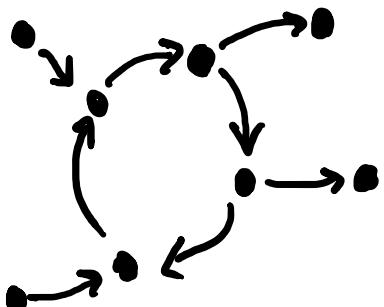
$$\begin{bmatrix} x_i \\ \vdots \\ x_j \end{bmatrix} = \begin{bmatrix} & & j \\ & \downarrow & \\ & A_{ij} & \\ & & \end{bmatrix} \begin{bmatrix} \\ \\ x_j \end{bmatrix}$$

Centrality is received

② Acyclic Graphs:



$$\text{What is: } A^{10} x = ?$$



The graph requires strongly connected components
to have nonzero centralities

Computation of Eigenvector Centrality

As n gets large computing eigenvectors can become costly.

A cheaper alternative is to use our iterative approach:

$$x(t+1) = Ax(t) \Rightarrow x(t) = A^t x(0)$$

for some large enough t , the direction of $x(t)$ will stabilize,
but the amplitude will grow.

↳ Solution! Normalize at each iteration step

Katz Centrality

"Everyone should be at least a little important"

$$x(t+1) = Ax(t)$$



$$x(t+1) = \alpha A x(t) + \beta \vec{1}$$

Eigenvector

Why α ?



$$\text{if } \alpha \rightarrow 0 \Rightarrow x = \beta \cdot \vec{1}$$

all nodes have equal centrality

Katz



$$x(t+1) = x(t)$$

"steady state"

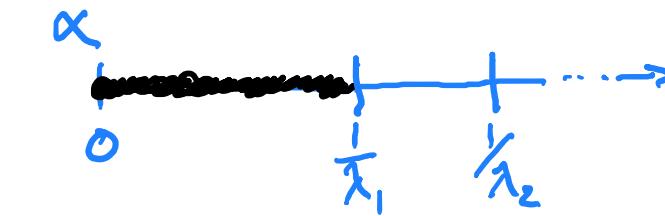
$$x = (\underbrace{I - \alpha A}^{-1}) \cdot \beta \vec{1}$$

blows up when $(I - \alpha A)$ is singular!

$$\det(I - \alpha A) = 0 \Rightarrow \det(A - \alpha^{-1} I) = 0$$

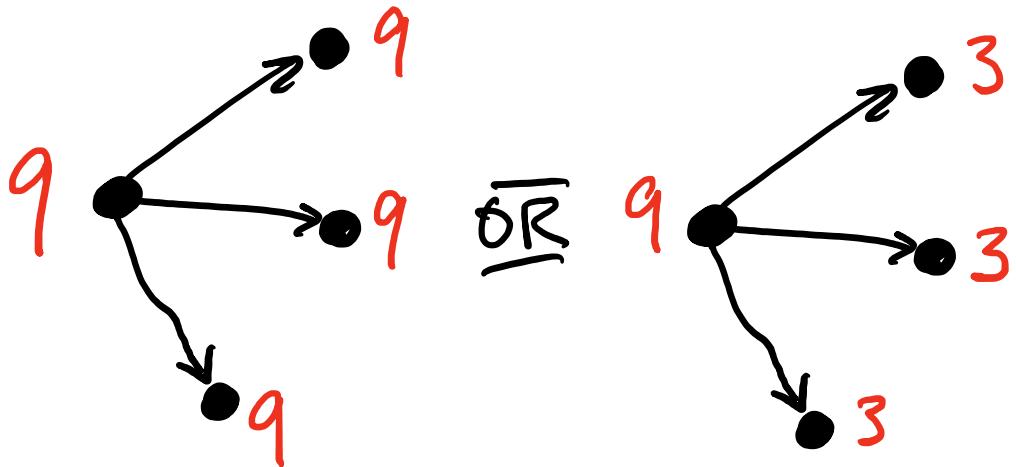
$$\uparrow \frac{1}{\alpha} = \lambda$$

$$0 \leq \alpha < \frac{1}{\lambda_1}$$



PageRank Centrality

"Exploring conservation of centrality"



$$x_i = \alpha \sum_{j=1}^n A_{ij} x_j + \beta \quad \text{Katz}$$

$$x_i = \alpha \sum_{j=1}^n A_{ij} \frac{x_j}{k_j^{\text{out}}} + \beta \quad \text{Page Rank}$$

out degree of
node j

$$x = \alpha A D^{-1} x + \beta \vec{1}$$

$D_{ii} = \max(k_i^{\text{out}}, 1)$

$$= (I - \alpha A D^{-1})^{-1} \cdot \beta \vec{1}$$

for undirected: $0 \leq \alpha < 1$

↑ in lab!

Google uses
 $\alpha = 0.85$

Hubs & Authorities

$$\begin{array}{c} \downarrow \\ y_i \\ \downarrow \\ x_i \end{array}$$

Two Centralities:

$$x_i = \alpha \sum_j A_{ij} y_j$$

\Rightarrow

$$x = \alpha A y$$



$$A A^T x = \frac{1}{\alpha \beta} x$$

$$y_i = \beta \sum_j A_{ij} x_j$$

$$y = \beta A x$$



$$A^T A y = \frac{1}{\alpha \beta} y$$

Cocitation!
bibliographic coupling!

Authorities = eigenvector centrality of the cocitation graph

Hubs = eigenvector centrality of the bibliographic coupling graph