

graph partitioning
community detection

SYSM 6302

CLASS 15

Divide network into groups/clusters

Heuristic Algorithms

- **Graph Partitioning** - fixed number/size of groups
 - goal is to divide the graph into more manageable pieces, i.e., the graph will be divided
 - reduce the number of edges between groups.
- **Community detection** - goal is to analyze a network to determine groups that may exist
 - reduce the number of edges compared to number expected
 - size & number of groups not fixed

Partitioning

in fact the division of groups
is called a cut set

- Fundamentally similar to finding a cut set
 - ↳ But would need to consider not only all-pairs of cut sets, but somehow aggregate the vertex pair cutsets into a "network cut set"
- Specify the number and approximate relative sizes of groups
 - ↳ Evenly distribute a network calculation to minimize inter-group communication

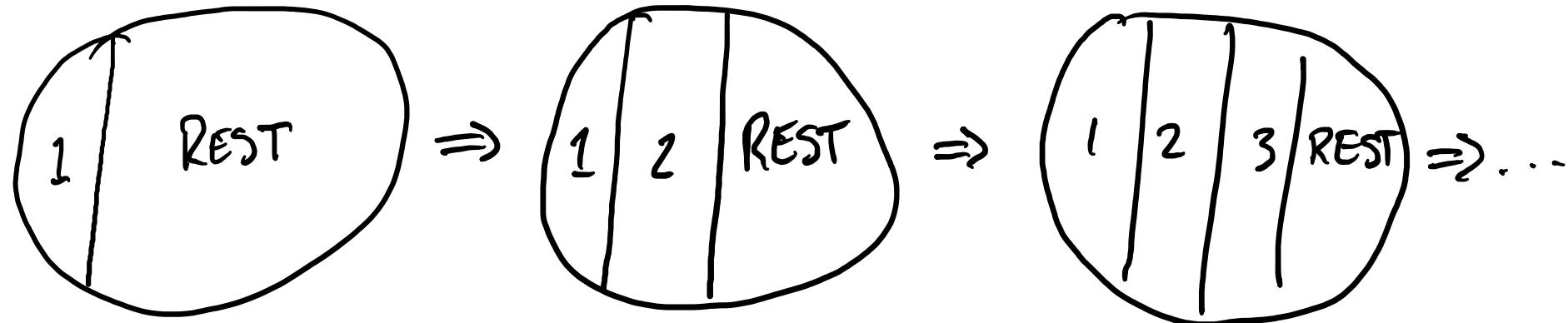
Community Detection

- Goal is not to minimize absolute number of edges (cut set)
 - ↳ Relative to the number expected (modularity)
- Many popular methods focus on Modularity maximization:
$$\max Q = \max \frac{1}{2m} \sum_{i=1}^n \sum_{j=1}^n \left(A_{ij} - \frac{k_i k_j}{2m} \right) \delta(c_i, c_j)$$
- Aim to find the groups in the network - if there is only one group, then don't need to divide the network ↳ more subjective than partitioning
 - Any black box optimization method can be used to max Q
 - Genetic algorithm, simulated annealing, particle swarm, or greedy

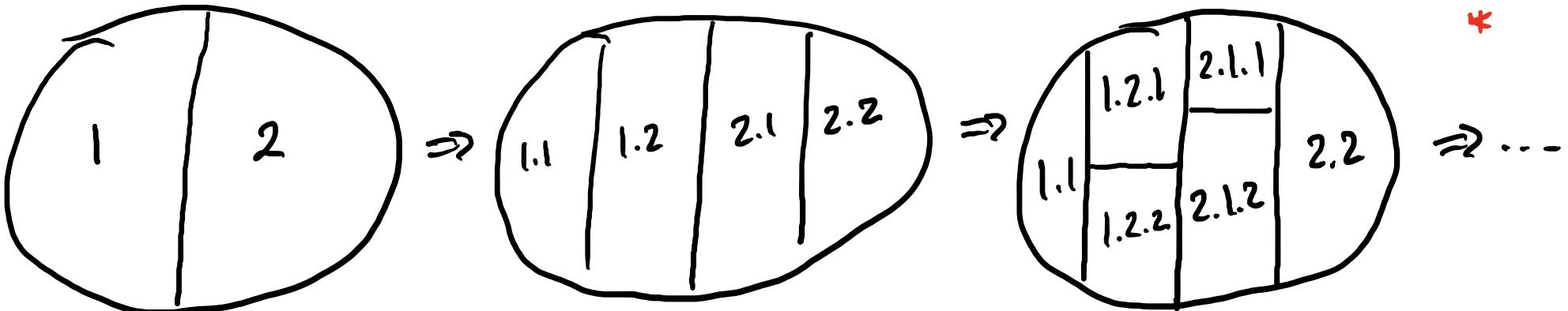
Bisection methods ← split something into 2 pieces (samurai style)

→ Most algorithms will perform bisection, but can be used to do further division

PARTITIONING:



COMMUNITY
DETECTION :



*important to evaluate Q based on the entire graph not only the subgraph being split

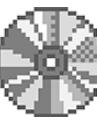
Kernighan-Lin Algorithm for Partitioning

- ① Randomly split network (nodes) into the groups (respecting number & size)
- ② Find the pair $i \in \text{Group 1}, j \in \text{Group 2}$ that, if swapped, reduces the cut set size the most. Must test all pairs i, j . If no pair reduces the cut set size, pick the pair that increases it the least. $\leftarrow O(n^2)$
- ③ Make this swap. $\leftarrow O(\frac{n}{2})$
- ④ Continue this (without picking the same nodes again) until you run out of nodes that haven't been picked before.
- ⑤ Look back over all these swaps & pick the partitioning that has the ^{smallest} _{cut}
- ⑥ Start with this partition and begin again at ②. Do this "several" times.

Simple Modularity Maximization for Community Detection

- ① Split the network into two groups
- ② Determine the modularity improvement for moving each node to the other group.
- ③ Make the move for the node that most increases (or least decreases) modularity
- ④ After each node has been moved once, pick the grouping with max modularity
- ⑤ Use these groups and start again at ②. Do this "several" times.

Spectral Modularity Maximization



$$Q = \frac{1}{2m} \sum_{i=1}^n \sum_{j=1}^n \left(A_{ij} - \frac{k_i k_j}{2m} \right) \delta(c_i c_j) = \frac{1}{2m} \sum_{i,j} B_{ij} \delta(c_i c_j)$$

Let $s \in \mathbb{R}^n$ such that $s_i = \begin{cases} +1 & \text{if node } i \text{ belongs to group 1} \\ -1 & \text{if node } i \text{ belongs to group 2} \end{cases}$

$$\delta(c_i, c_j) = \frac{1}{2}(s_i s_j + 1)$$

in lab show: $\sum_j B_{ij} = 0$

$$Q = \frac{1}{4m} \sum_{i,j} B_{ij} (s_i s_j + 1) = \frac{1}{4m} \sum_{i,j} B_{ij} s_i s_j = \frac{1}{4m} \sum_{i=1}^n s_i \sum_{j=1}^n B_{ij} s_j$$

$$= \frac{1}{4m} \vec{s}^\top B \vec{s}$$

$$\max_{S_i \in \{-1, 1\}} \frac{1}{4m} S^T B S \approx \max_{S_i \in \mathbb{R}} \frac{1}{4m} S^T B S$$

Called a relaxation of the integer optimization problem, leading to a new constraint

$$S^T S = n$$

using the convexity of the quadratic form

$$S^2_1 + S^2_2 + \dots + S^2_n = n$$


$$\frac{\partial}{\partial S} (S^T B S) = 0 \Rightarrow \frac{\partial}{\partial S} [S^T B S + \beta(n - S^T S)] = 0$$

Lagrange multiplier method for adding constraints.

see next slide

$$\Rightarrow 2B_S - 2\beta S = 0 \rightarrow BS = \beta S \leftarrow \text{Eigenvector !!}$$

To maximize $\frac{1}{4m} S^T B S = \frac{1}{4m} S^T (\beta S) = \frac{\beta}{4m} S^T S \stackrel{=n}{\sim}$ *pick largest β , ie, largest eigenvalue*

Select $S = v_i$ *eigenvector corresponding to largest eigenvalue*

EXCEPT $S_i \in \{\pm 1\}$ $\Rightarrow S_i = \begin{cases} +1 & [v_i]_i > 0 \\ -1 & [v_i]_i < 0 \end{cases} \Rightarrow S = \text{sign}(v_i)$

Consider $a = x^T A x = \sum_{i=1}^n x_i \sum_{j=1}^n A_{ij} x_j = \sum_{i,j} x_i A_{ij} x_j$ notice $a \in \mathbb{R}$ (scalar)

$$\frac{\partial a}{\partial x_k} = \sum_{i=1}^n \sum_{j=1}^n \underbrace{\frac{\partial}{\partial x_k} (x_i A_{ij} x_j)}_{\begin{cases} A_{ij} x_j & \text{if } i=k \\ x_i A_{ij} & \text{if } j=k \\ 0 & \text{otherwise} \end{cases}} = \sum_{j=1}^n 1 A_{kj} x_j + \sum_{i=1}^n x_i A_{ik} 1 = [Ax]_k + [A^T x]_k$$

$$\Rightarrow \frac{\partial a}{\partial x} = \begin{bmatrix} [Ax]_1 + [A^T x]_1 \\ [Ax]_2 + [A^T x]_2 \\ \vdots \\ [Ax]_n + [A^T x]_n \end{bmatrix} = Ax + A^T x = (A + A^T)x$$

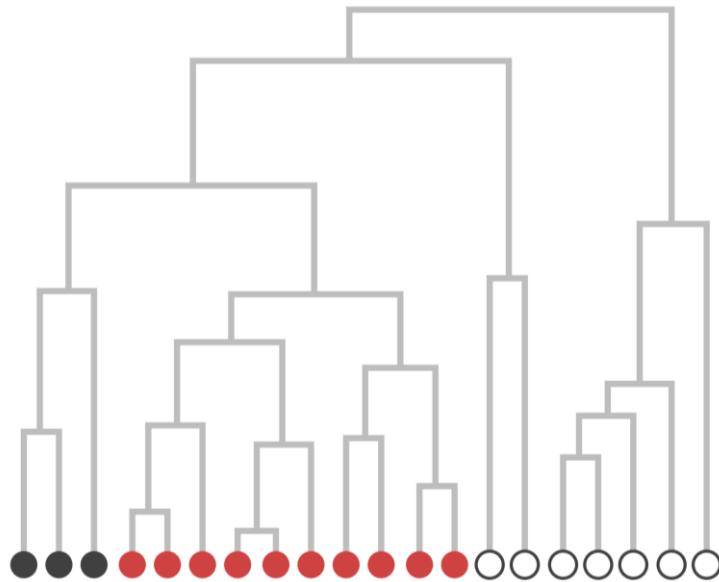
if $A = A^T$ (symmetric)

$$\frac{\partial a}{\partial x} = \frac{\partial}{\partial x} (x^T A x) = 2Ax$$

Betweenness-based Community Detection

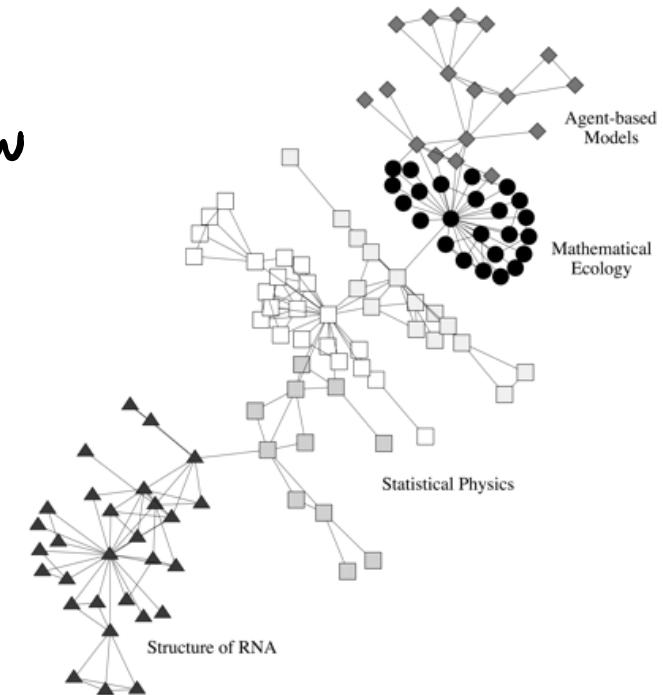
→ Edges that lie between communities have high betw

- ① Remove the edge with highest betweenness
- ② Continue ① until there are no edges



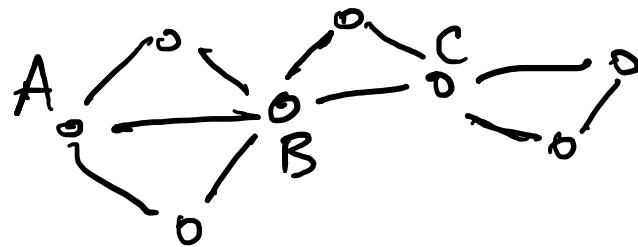
yields a **dendrogram** which captures the process of decomposing nodes down to n individual components.

↳ Identify a meaningful cutoff



Louvain Community Detection

- Modularity maximization requires testing all possible groupings
- ↳ Beyond ~100 nodes this combinatorial explosion is ungainly



if A and C belong to the same community,
how likely is it that B does too?

⇒ Adjacent nodes are more likely to belong
to the same community

Louvain Community Detection

- ① Assign every node to its own community
- ② Compute modularity of the network
- ③ For each node: assign it the same community as each of its neighbors
if modularity increases keep the assignment
- ④ If modularity has increased since ③, go back to ②
- ⑤ Otherwise contract all nodes of the same type into a single meta node
with self loops representing edges between the community
weighted edge aggregating edges between communities
- ⑥ If no contraction occurs: stop. Otherwise go back to ②