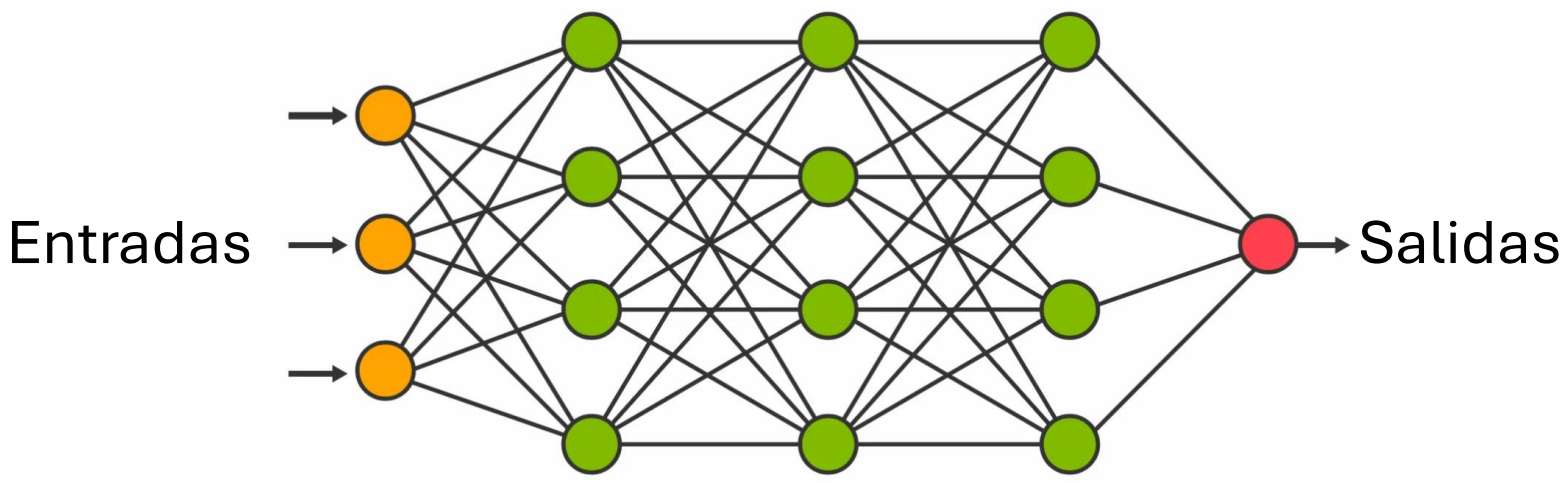
Avance de tesis

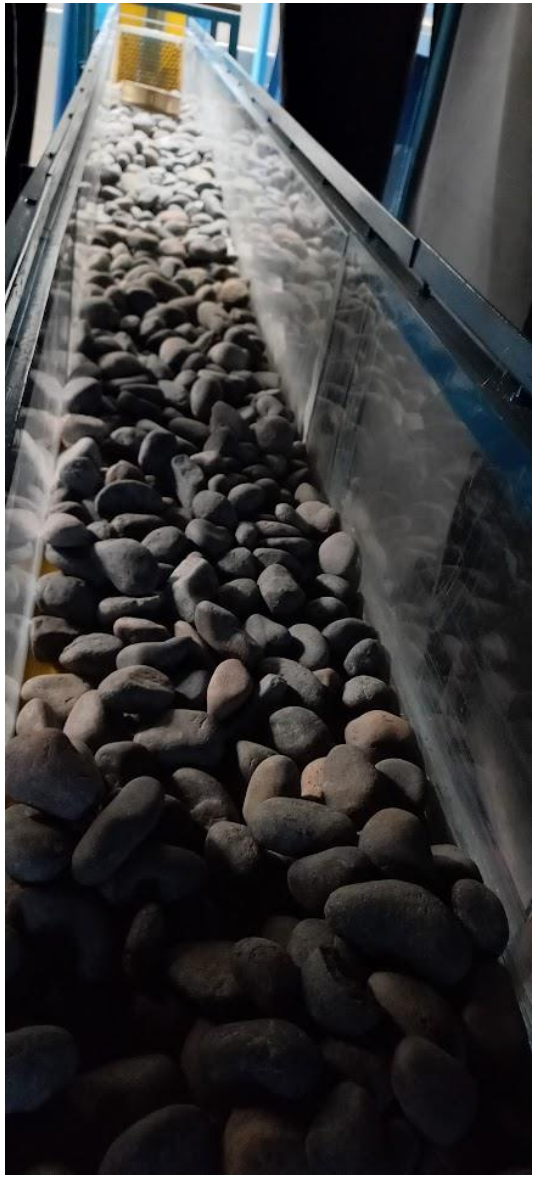
Utilización de aprendizaje de máquinas en simulaciones hidrodinámicas de canales abiertos y comparación con modelo numérico

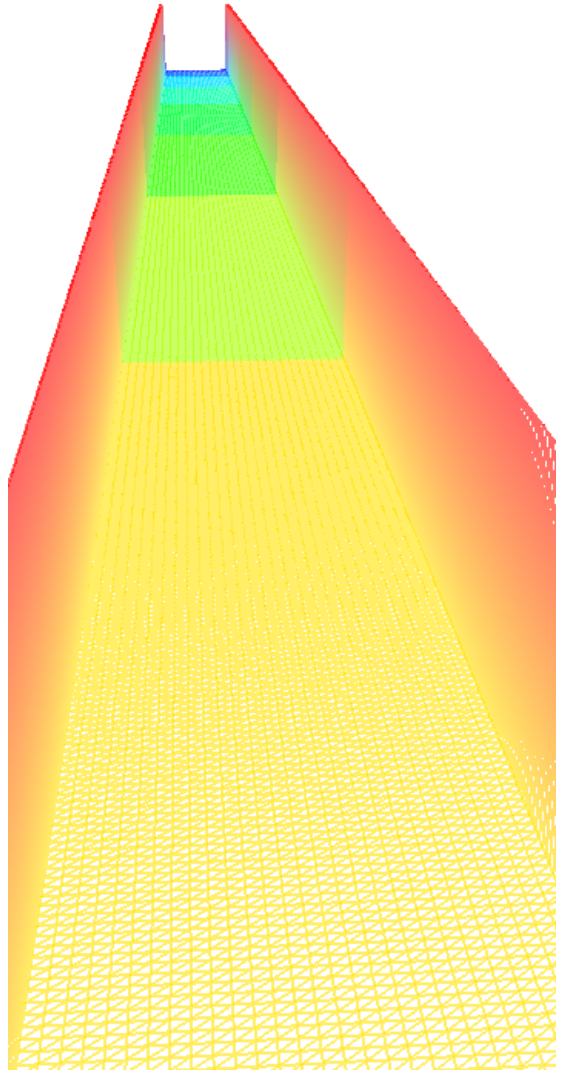
Entradas → openTELEMAC → Salidas

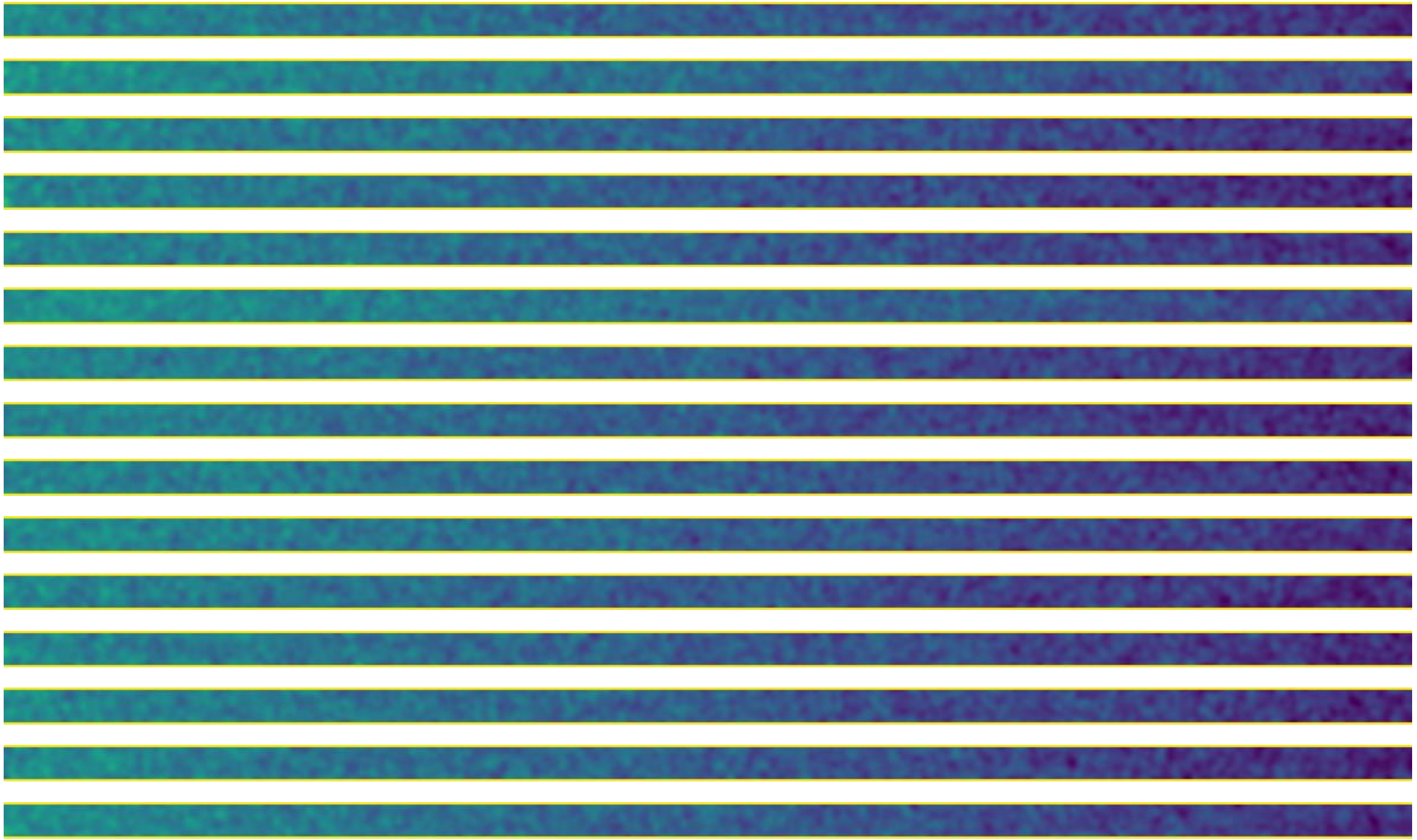
Modelo numérico

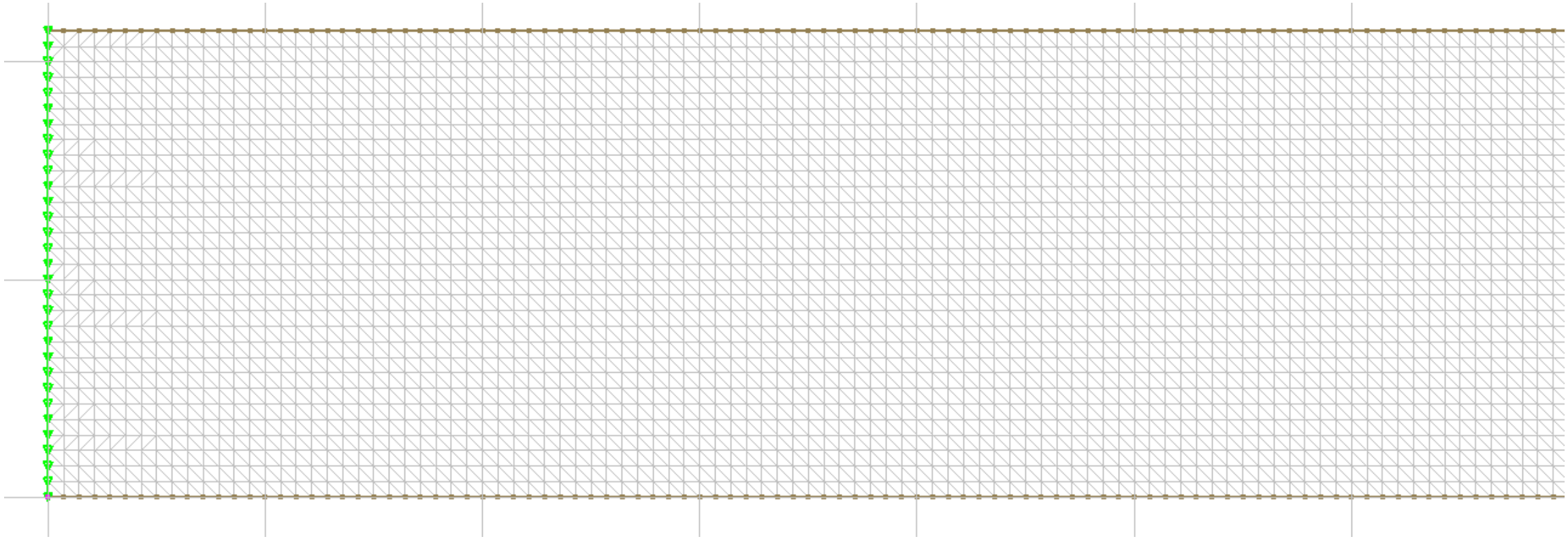


Red neuronal









```
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/ TELEMAC2D Version v8p4 Apr 1, 2024
/ Caso 1
/-----------------------------------------------------------------------
/-----------------------------------------------------------------------
/ EQUATIONS
/-----------------------------------------------------------------------
MASS-LUMPING ON TRACERS              =1.
IMPLICITATION COEFFICIENT OF TRACERS =0.6
LAW OF BOTTOM FRICTION               =4
FRICTION COEFFICIENT                 =[redacted]
TURBULENCE MODEL                     =3
/-----------------------------------------------------------------------
/ EQUATIONS, ADVECTION
/-----------------------------------------------------------------------
SCHEME FOR ADVECTION OF TRACERS    =5
SCHEME FOR ADVECTION OF VELOCITIES =14
SCHEME FOR ADVECTION OF K-EPSILON  =14
/-----------------------------------------------------------------------
/ EQUATIONS, BOUNDARY CONDITIONS
/-----------------------------------------------------------------------
PRESCRIBED ELEVATIONS =0.0;-0.03
PRESCRIBED FLOWRATES  =[redacted];0.0
VELOCITY PROFILES     =4;1
/-----------------------------------------------------------------------
/ EQUATIONS, INITIAL CONDITIONS
/-----------------------------------------------------------------------
INITIAL CONDITIONS ='ZERO DEPTH'
/-----------------------------------------------------------------------
/ INPUT-OUTPUT, FILES
/-----------------------------------------------------------------------
STEERING FILE            ='steering_1.cas'
GEOMETRY FILE            ='geometry/geometry_0.slf'
RESULTS FILE             ='results/[redacted].slf'
BOUNDARY CONDITIONS FILE ='boundary/boundary.cli'
/-----------------------------------------------------------------------
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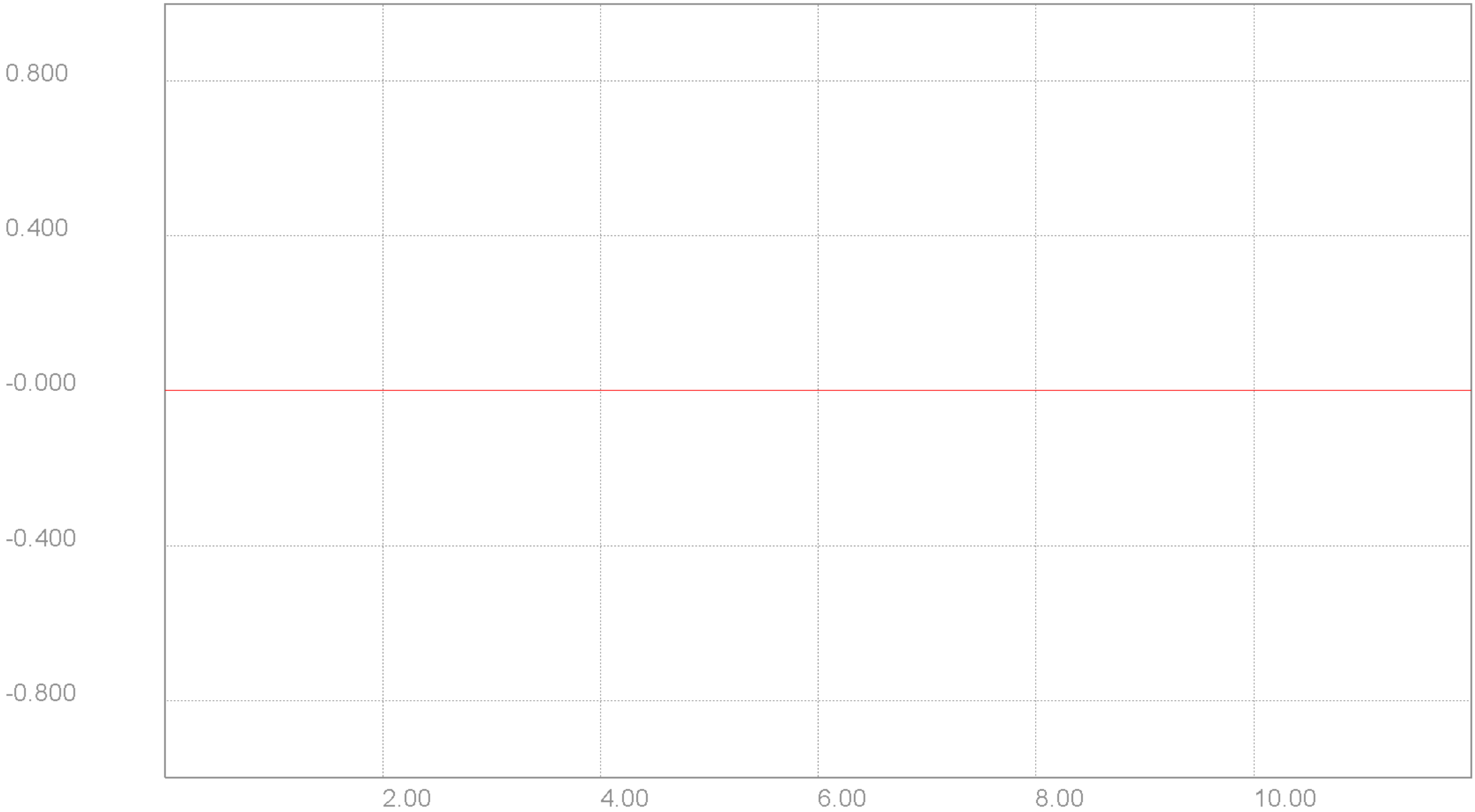
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0.400
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-0.400
-0.800
2.00
4.00
6.00
8.00
10.00