

CS 7800: Advanced Algorithms

Class 14: Reductions and Intractability

- Finish Image Segmentation
- NP-Completeness

Jonathan Ullman

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Image Segmentation



- Separate image into foreground and background
- We have some idea of:
 - whether pixel i is in the foreground or background
 - whether pair (i,j) are likely to go together

Image Segmentation

- Input:

- a directed graph $G = (V, E)$
 - V = “pixels”, E = “pairs”
- likelihoods $a_i, b_i \geq 0$ for every $i \in V$
- separation penalty $p_{ij} \geq 0$ for every $(i, j) \in E$

- Output:

- a partition of V into (A, B) that maximizes

$$q(A, B) = \sum_{i \in A} a_i + \sum_{j \in B} b_j - \sum_{\substack{(i,j) \in E \\ \text{cut by } A, B}} p_{ij}$$

Reduction to MinCut

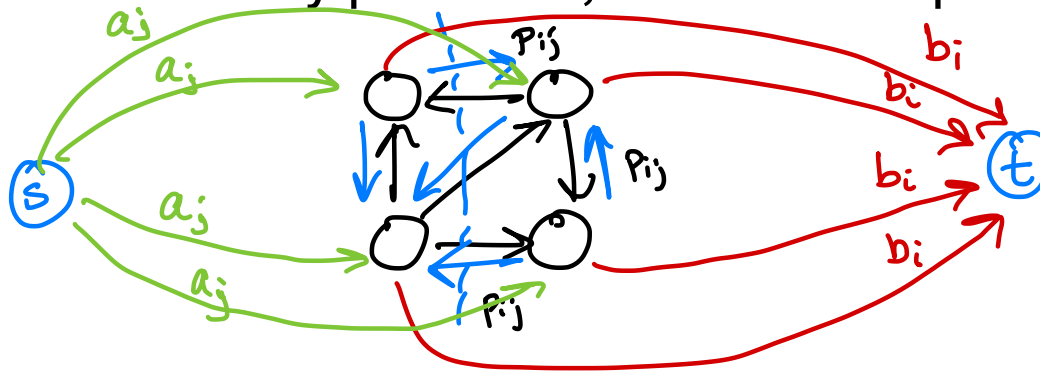
- Differences between **SEG** and **MINCUT**:

- SEG asks us to maximize, MINCUT asks us to minimize

$$\max_{A,B} \sum_{i \in A} a_i + \sum_{j \in B} b_j - \sum_{(i,j) \in E \text{ btw } A \text{ and } B} p_{ij} \quad \longleftrightarrow \quad \min_{A,B} \sum_{i \in A} b_i + \sum_{j \in B} a_j + \sum_{(i,j) \in E \text{ btw } A \text{ and } B} p_{ij}$$

How to include these?

- SEG allows any partition, MINCUT requires $s \in A, t \in B$



- SEG counts any cut edge, MINCUT counts $A \rightarrow B$ edges

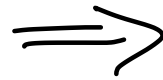
Reduction to MinCut

- How can we set up a flow network where the cost of the segmentation is the capacity of a cut

$$\min_{A,B} \sum_{i \in A} b_i + \sum_{j \in B} a_j + \sum_{\substack{(i,j) \in E \\ \text{btw } A \text{ and } B}} p_{ij}$$

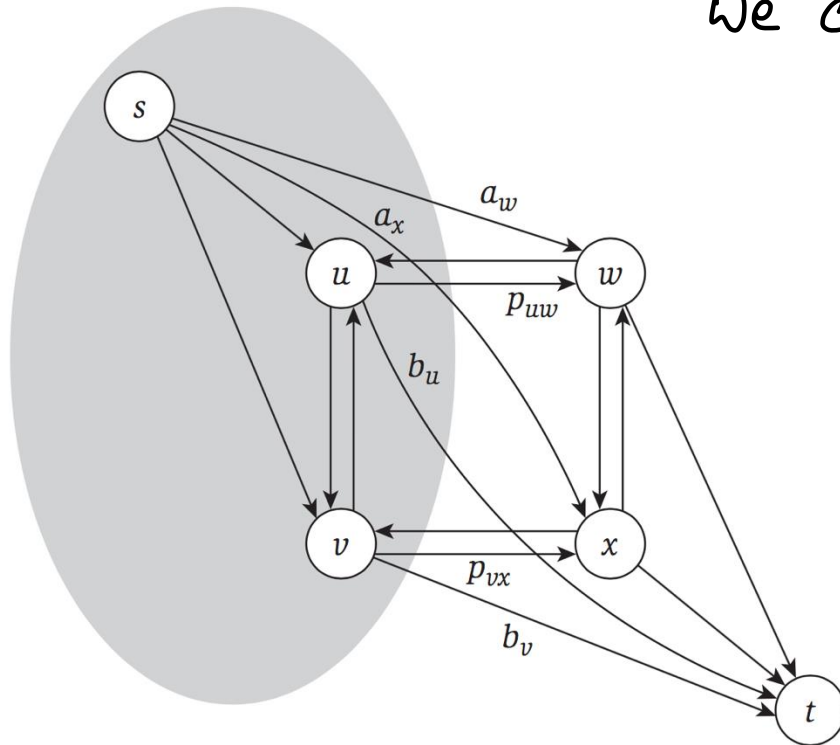
Step 1: Transform the Input

Given $G = (V, E, \{a_i\}, \{b_i\}, \{p_{ij}\})$
for SEG



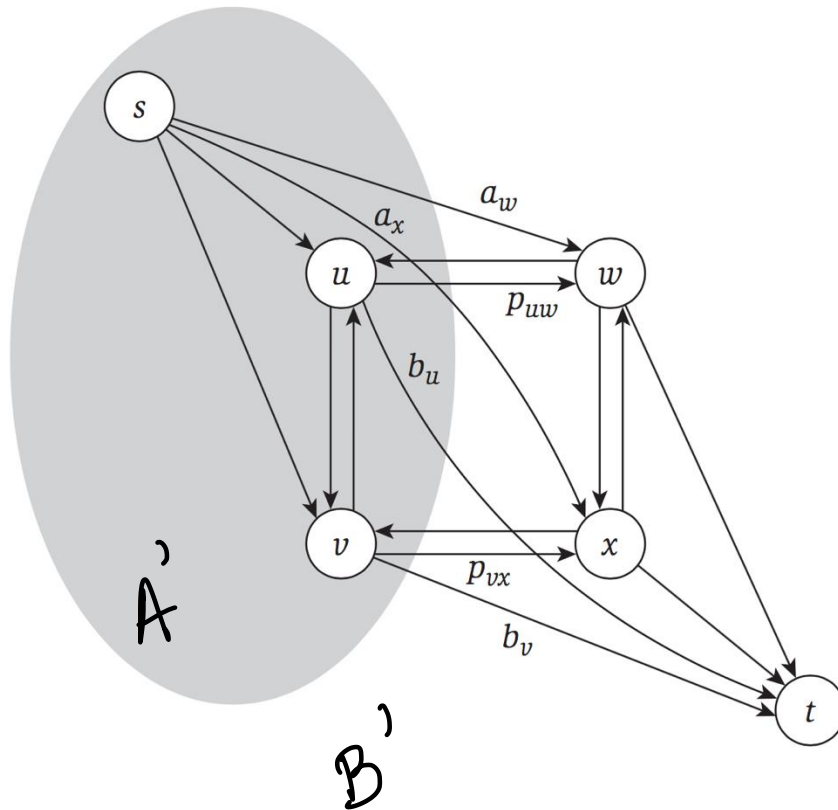
$G' = (V, E, s, t, \{c_e\})$
for MINCUT

We can run this step in $O(n)$ time



Step 2: Receive the Output

Receive A', B'
for MINWT



Step 3: Transform the Output

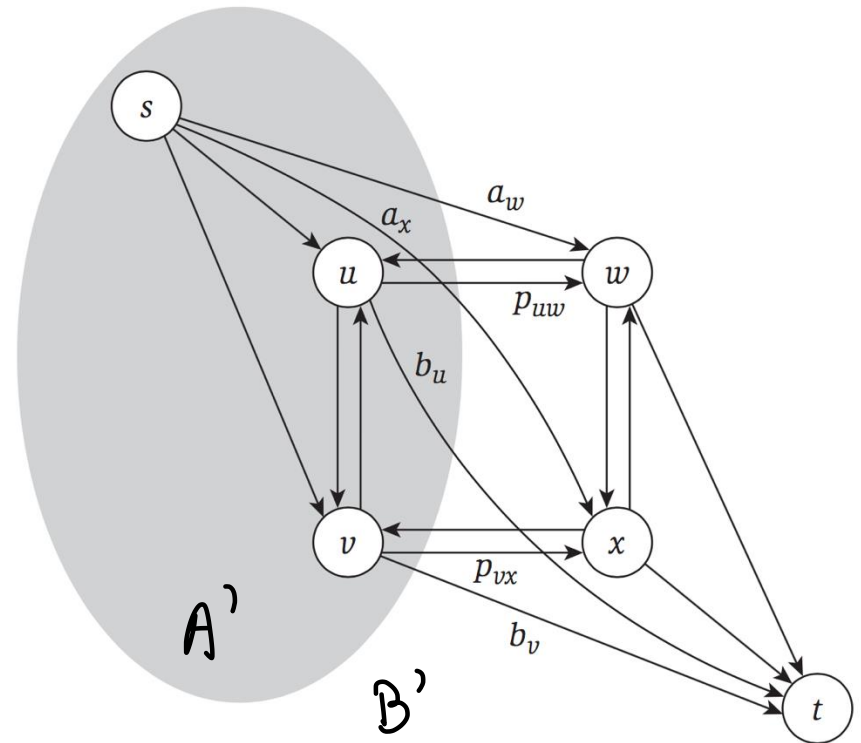
A', B' for MINCUT \Rightarrow

A, B for SEG

$$A = A' \setminus \{s\}$$

$$B = B' \setminus \{t\}$$

Can be done in $O(n)$ time



Summary

Solving minimum s-t cut in a graph with.
 $n + 2$ nodes and $2m + 2n$ edges in time T



Solving image segmentation in a graph with n
nodes and m edges in time $T + O(m)$

- Can solve image segmentation in $O(mn)$ time

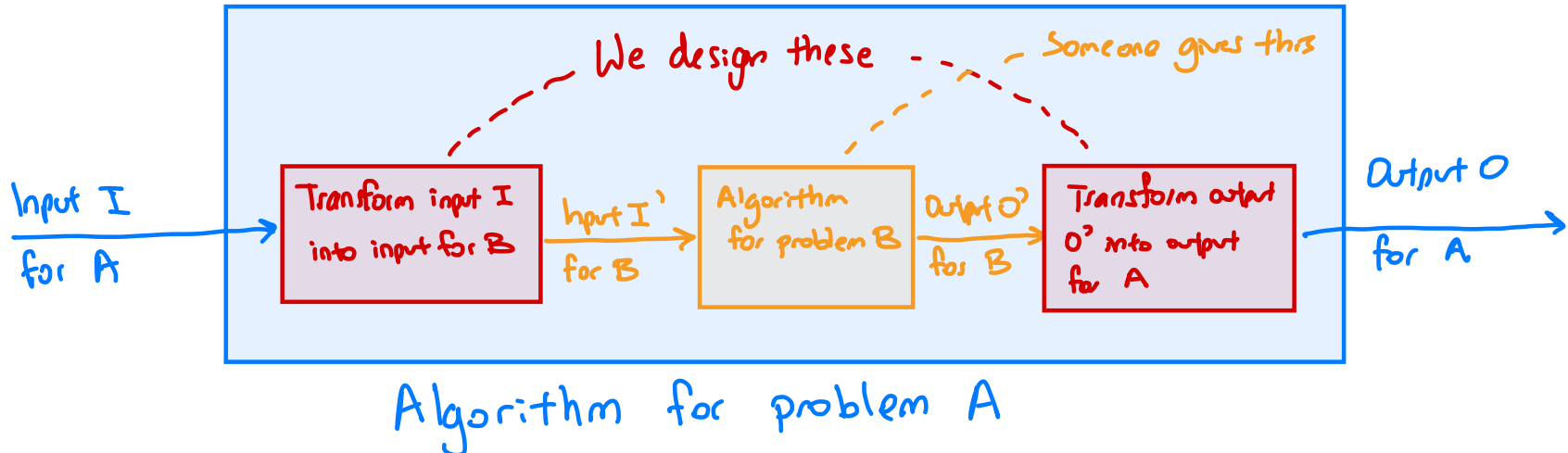
Flow Applications Summary

- Network flow algorithms are powerful
 - Can use them to solve many optimization problems
 - Improvements for maxflow implies lots of new algorithms
- Many natural applications
 - Bipartite matching
 - Image segmentation
 - Airline scheduling
 - Fair division
 - Auction design
 - ...
- Maxflow-Mincut duality (often) implies interesting duality theorems for these problems

Reductions

Reduction: Problem A reduces to Problem B if there is a polynomial-time algorithm that solves A using any efficient algorithm that solves B .

- Denoted $A \leq_p B$ (i.e. “ A is at most as hard as B ”)
- **View 1:** If B can be solved efficiently then so can A
- **View 2:** If A can't be solved efficiently then neither can B

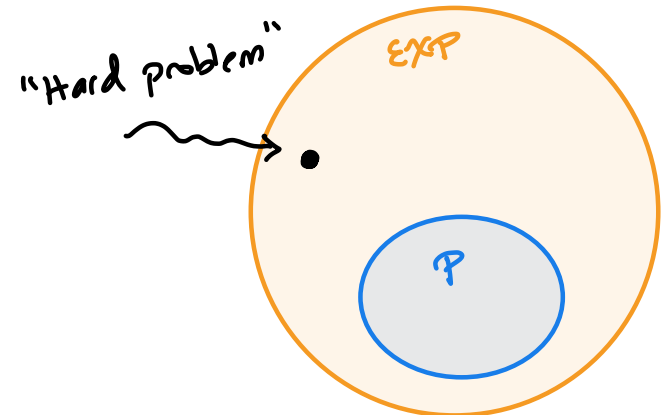


Tractable and Intractable Problems

- **Definition:** \mathcal{P} is the set of **decision problems** that can be solved in polynomial time

problems with a yes/no answer

- **Definition:** \mathcal{EXP} is the set of decision problems that can be solved in exponential time
- **Theorem:** $\mathcal{P} \neq \mathcal{EXP}$



Allegedly Intractable Problems

INDSET \equiv_P CLIQUE \equiv_P VERTEX COVER

Reduction in both directions ("Equally hard")

Assume: INDSET $\notin P$

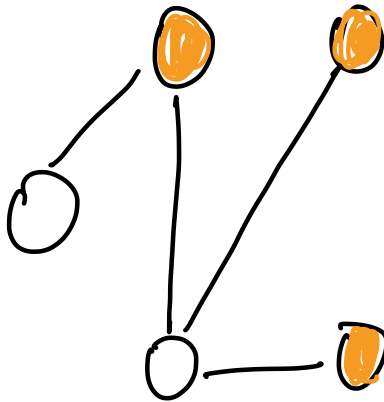
INDSET

Given an undirected graph G and number k , decide if G has an independent set of size $\geq k$.

INDSET

$S \subseteq V$

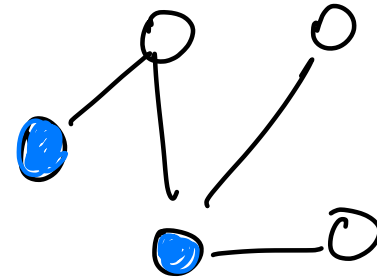
s.t. $\forall (u,v) \in E \quad u \notin S \text{ or } v \notin S$



VERTEX COVER

$S \subseteq V$ s.t. $\forall (u,v) \in E$

either $u \in S$ or $v \in S$



VERTEX COVER

Given an undirected G and k , decide if G has a vertex cover of size $\leq k$.

Allegedly Intractable Problems

INDSET \equiv_P CLIQUE \equiv_P VERTEX COVER

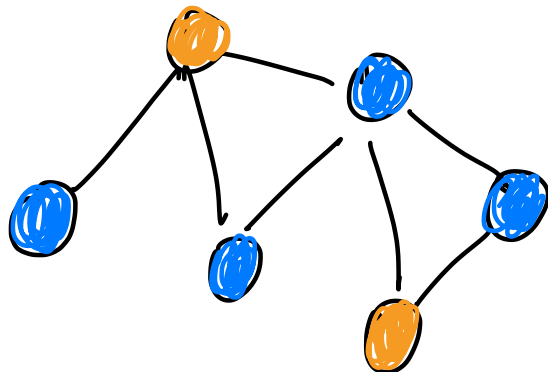
Reduction in both directions ("Equally hard")

Show $\text{INDSET} \leq_P \text{VERTEX COVER}$

Key Claim: If S is an independent set in G then $V \setminus S$ is a vertex cover and vice versa. (Immediately gives a reduction.)

Proof:

$M = \text{independent set } S$ $M = \text{complement of } S$



- no edges btw nodes in S
- \Rightarrow every edge has at least endpoint in $V \setminus S$
- $\Rightarrow V \setminus S$ is vertex cover

Allegedly Intractable Problems

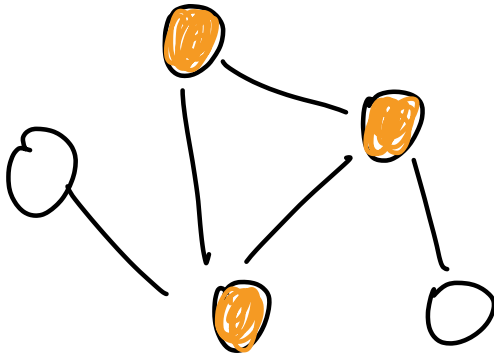
INDSET \equiv_P CLIQUE \equiv_P VERTEX COVER

Reduction in
both directions ("Equally hard")

CLIQUE

CLIQUE: $S \subseteq V$
s.t. $\forall u, v \in S, (u, v) \in E$

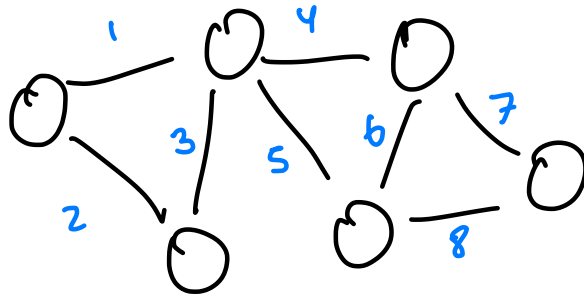
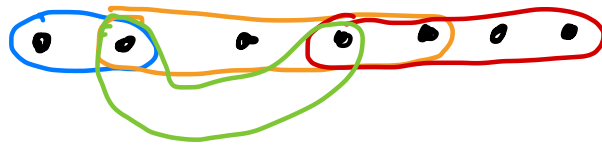
Given G and k , is there
a clique of size $\geq k$?



Allegedly Intractable Problems

VERTEX COVER \leq_P SETCOVER

SETCOVER: Given a family \mathcal{F} of sets $S \subseteq \{1, \dots, n\}$
decide: $\exists \mathcal{C} \subseteq \mathcal{F}$ such that ① $\bigcup_{S \in \mathcal{C}} S = \{1, \dots, n\}$ ② $|\mathcal{C}| \leq k$



- Given $G=(V,E)$ and k for VC
- Number edges $1, \dots, n$
- For every node $v \in V$ let $S_v = \{u \text{ s.t. } (u,v) \in E\}$
- Let $\mathcal{F} = \{S_v\}_{v \in V}$

Allegedly Intractable Problems

VERTEX COVER \leq_P ILP (0/1 Integer Linear Programming)

ILP:
$$\begin{array}{ll} \max & c^T x \\ \text{s.t.} & Ax \leq b \\ & x \geq 0 \end{array}$$

$$\forall i \quad x_i \in \{0, 1\}$$

Given an ILP (A, b, c) and V
decide if there exists a
feasible x s.t. $c^T x \geq V$

Given G, k for VC

Write the ILP

$$\min_x \sum_{u \in V} x_u$$

$$\forall (u, v) \in E \quad x_u + x_v \geq 1$$

$$x_u \in \{0, 1\}$$

Allegedly Intractable Problems

$$3\text{-SAT} \leq_P \text{INDSET}$$

A 3-SAT formula is a Boolean formula of the form

$$\begin{array}{ll} \text{vars } x_1, \dots, x_n & \text{formula } (x_3 \vee x_7 \vee x_{11}) \wedge (x_5 \vee \overline{x_7} \vee \overline{x_{11}}) \\ & \wedge \underbrace{(x_2 \vee x_8 \vee \overline{x_9})}_{\text{clause}} \wedge \dots \end{array}$$

Assumption: $3\text{-SAT} \notin P$

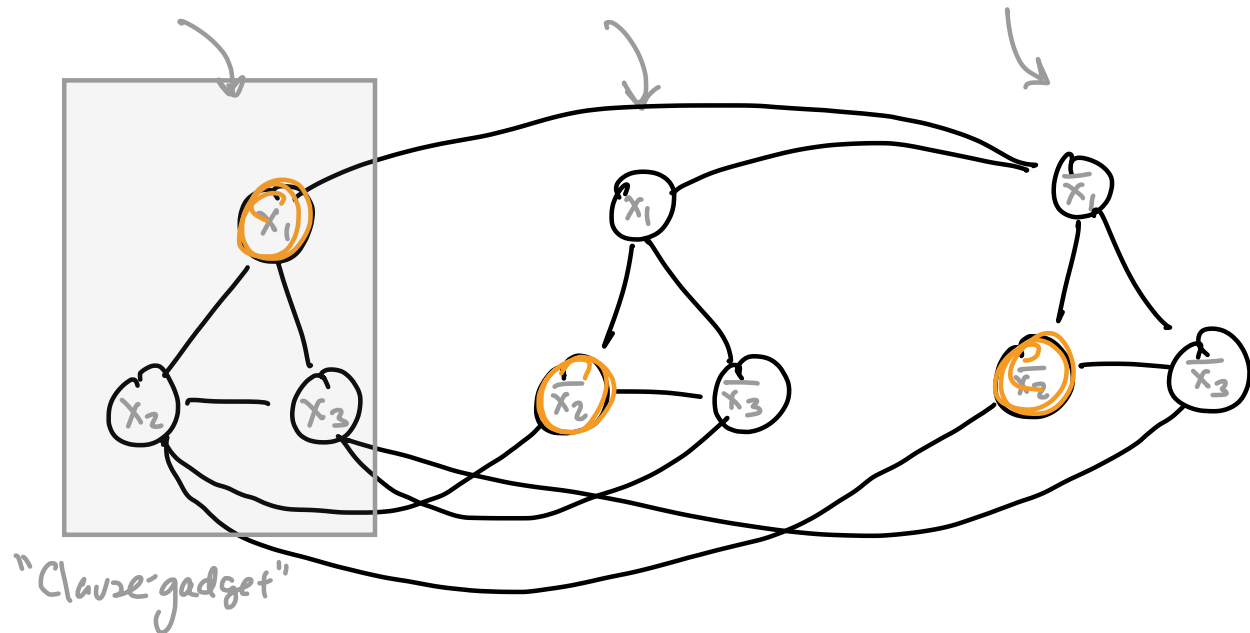
Allegedly Intractable Problems

$$3\text{-SAT} \leq_P \text{INDSET}$$

$$F(x) = (x_1 \vee x_2 \vee x_3) \wedge (x_1 \vee \bar{x}_2 \vee \bar{x}_3) \wedge (\bar{x}_1 \vee \bar{x}_2 \vee \bar{x}_3)$$

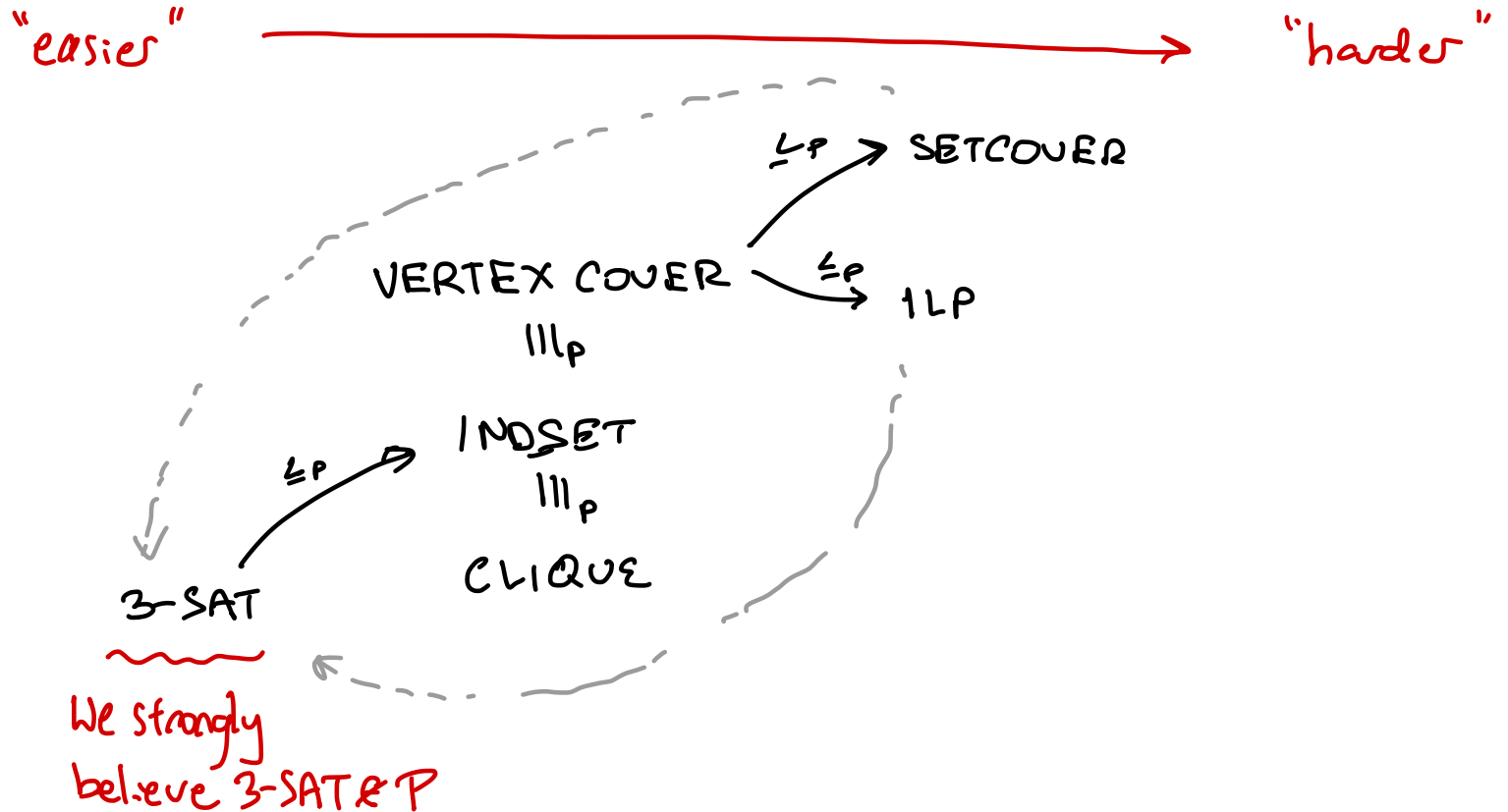
Given

Want a graph G
and number k st.
 G has an ind. set of
size $\geq k$ iff F is
satisfiable

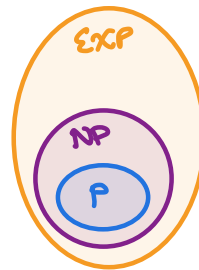


Claim: F is satisfiable if and only if G
has an independent set of size $\geq m$

Allegedly Intractable Problems



Note: Reductions are transitive

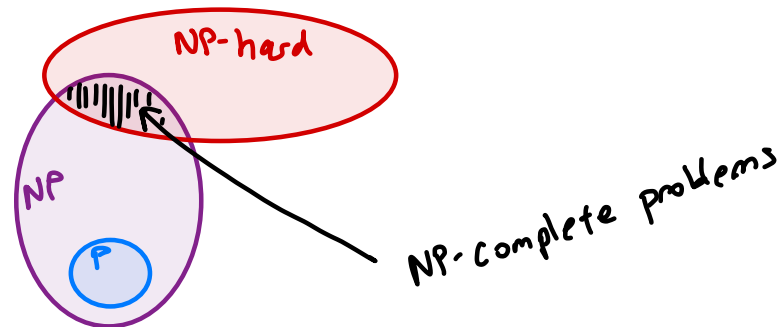


The Class NP

- **Definition:** \mathcal{NP} is the class of problems for which there is an efficient verifier for solutions
 - An algorithm V is an efficient verifier for problem A if
 - (1) V takes as input I and a solution S
 - (2) V is a polynomial-time algorithm
 - (3) $I \in A$ if and only if there exists a polynomial-size solution S such that $V(I, S) = \text{YES}$
- \mathcal{P} = easy to solve, \mathcal{NP} = easy to check solution
- Natural hard optimization problems are in \mathcal{NP}
 - 3-SAT, Vertex-Cover, Independent-Set...

Does $\mathcal{P} = \mathcal{NP}$?

- We do not know, but we believe it very strongly!
 - One of the Millenium Problems
- If we believe $\mathcal{P} \neq \mathcal{NP}$ what does that tell us about problems we care about?
 - **Def:** B is \mathcal{NP} -hard if for $A \in \mathcal{NP}$, $A \leq_p B$
 - **Def:** B is \mathcal{NP} -complete if $B \in \mathcal{NP}$ and B is \mathcal{NP} -hard
 - If B is \mathcal{NP} -hard and $B \in \mathcal{P}$ then $\mathcal{P} = \mathcal{NP}$



What problems are \mathcal{NP} -complete?

- The Circuit Satisfiability Problem (CKT-SAT)
 - **Input:** Circuit C with n wires and AND/OR/NOT gates
 - **Output:** Decide if there exists x such that $C(x) = 1$

Sort of Cook '71, Levin '73

-  **Thm:** CIRCUIT-SAT is \mathcal{NP} -complete

What problems are \mathcal{NP} -complete?

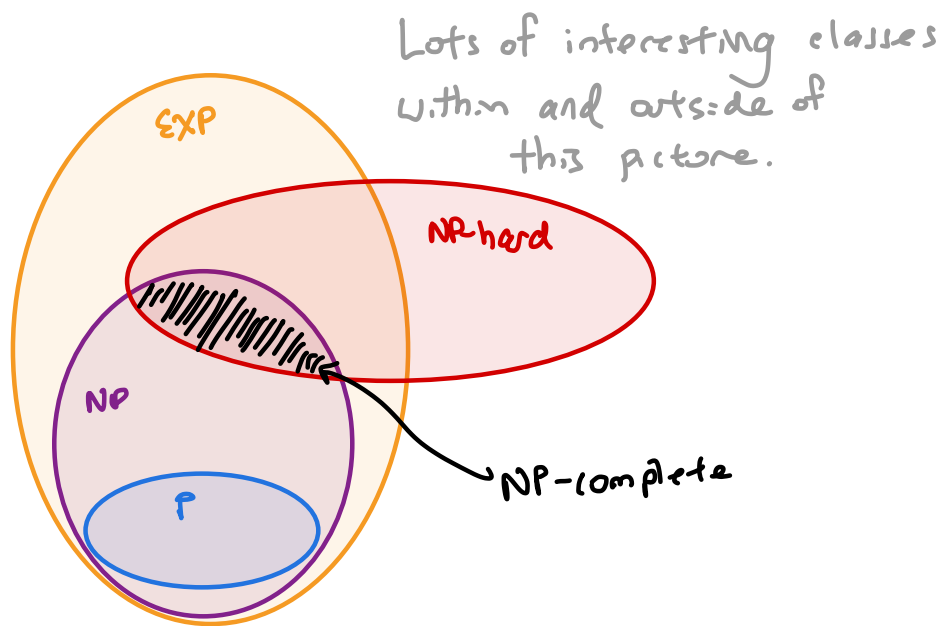
(\Rightarrow 3-SAT is NPC)

- **Thm (Cook '71, Levin '73):** $\text{CKT-SAT} \leq_P \text{3-SAT}$

What problems are \mathcal{NP} -complete?

(\Rightarrow 3-SAT is NPC)

- **Thm (Cook '71, Levin '73):** $\text{CKT-SAT} \leq_P \text{3-SAT}$
 - Now we know IND-SET, CLIQUE, VERTEX-COVER, SET-COVER, IP, and 3-SAT are all \mathcal{NP} -complete
 - There are thousands more known \mathcal{NP} -complete problems in essentially every area within CS



What problems are \mathcal{NP} -complete?

- **Thm (Cook '71, Levin '73):** $\text{CKT-SAT} \leq_p \text{3-SAT}$
 - Now we know IND-SET, CLIQUE, VERTEX-COVER, SET-COVER, IP, and 3-SAT are all \mathcal{NP} -complete
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