

view\_frames Result

Recorded at time: 1894.300

map

odom

base\_link

base\_footprint

top\_plate\_link

front\_bumper\_link

imu\_link

inertial\_link

rear\_bumper\_link

top\_chassis\_link

user\_rail\_link

front\_left\_wheel\_link

front\_right\_wheel\_link

rear\_left\_wheel\_link

rear\_right\_wheel\_link

base\_laser\_mount

base\_laser

top\_plate\_front\_link

top\_plate\_rear\_link

Broadcaster: /amcl  
Average rate: 47.686 Hz  
Most recent transform: 1895.280 ( -0.980 sec old)  
Buffer length: 4.970 sec

Broadcaster: /ekf\_localization  
Average rate: 50.201 Hz  
Most recent transform: 1894.300 ( 0.000 sec old)  
Buffer length: 4.980 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1894.300 sec old)  
Buffer length: 0.000 sec

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