

# Notes on *Hands-On Machine Learning with Scikit-Learn, Keras, and TensorFlow*

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# 1 Machine Learning Landscape

## 1.1 What is ML?

- **ML**: science of programming computers so they can learn from data
- **training set**: examples the system uses to learn
  - each example = a sample / training instance
- **model**: system that learns and makes predictions
- **performance measures**: used to evaluate the model
- situations to use ML
  - if rules are too complicated to write completely
  - rules could be changing constantly
  - you want to use ML and learn from how they learned
- **data mining**: digging into large amounts of data and finding patterns

## 1.2 Types of ML

- training supervision
  - supervised
    - \* training set contains labels
    - \* divided into classification and regression tasks based on the type of labels
      - **classification**: categorical labels
      - **regression**: numerical labels
  - unsupervised
    - \* unlabeled data
    - \* **clustering** algorithms: cluster data into bins
    - \* **visualization** algorithms: outputs 2D or 3D representations of data that can be plotted
    - \* **dimensionality reduction**: simplify data without losing too much information
    - \* **feature extraction**: transforming raw data into meaningful features; often a good idea to do dimensionality reduction before feeding it to a supervised model
    - \* **anomaly detection**: check for rare samples
    - \* **novelty detection**: check for completely unseen data before
    - \* **association rule learning**: dig into large amounts of data and discover relationships between attributes

- semi-supervised
  - \* partially labeled data
  - \* most are combinations of unsupervised and supervised algorithms
  - \* example: use unsupervised for grouping, label those data based on grouping, then put into supervised model
- self-supervised
  - \* turn fully unlabeled data to fully labeled data
  - \* example: use masked images as inputs and full images as outputs
  - \* usually not the final goal, example: want to train network to repair images, then transfer learn and classify
- reinforcement learning
  - \* agent observes
  - \* agent selects action using policy
  - \* agent chooses action
  - \* agent gets rewarded / punished
  - \* agent updates policy as a result
  - \* iterates until optimal policy is found
- batch vs. online learning
  - batch learning
    - \* trained using all available data
    - \* offline and requires lots of time / computing resources
    - \* **offline learning**: train and then deploy after it is done learning – doesn't learn after deployment
    - \* **model rot**: performance decays over time as the world evolves, so should regularly retrain
    - \* impossible to use if:
      - amount of data is huge
      - need to be autonomous
      - limited resources
      - continuous stream of data
  - online learning
    - \* training a model incrementally with data fed one instance at a time in small **minibatches**
    - \* fast, on-the-fly learning that adapts to rapidly changing environments
    - \* good for limited resources
    - \* **learning rate**
      - high learning rate = fast adaptation but risks forgetting old data

- low learning rate = slower learning but more stable and less prone to noise or outliers
- \* bad data can quickly degrade performance so live systems must be monitored closely through anomaly detection, disabling learning, reverting to previous state of the model

## References

- [1] Aurélien Géron, *Hands-On Machine Learning with Scikit-Learn, Keras, and TensorFlow*, 3rd Edition, O'Reilly Media, 2022.