

force operator
in real space

$$\tilde{f}_\alpha = \frac{\partial}{\partial s} D_\alpha^{ss}(s) \frac{\partial}{\partial s} + D_\alpha^{\theta\theta}(s) \frac{\partial^2}{\partial \theta^2} + D_\alpha^{\phi\phi}(s) \frac{\partial^2}{\partial \phi^2}$$

force operator
in Fourier space

$$\tilde{F}_\alpha^{mn} = \frac{\partial}{\partial s} D_\alpha^{ss} \frac{\partial}{\partial s} - m^2 D_\alpha^{\theta\theta} - n^2 D_\alpha^{\phi\phi}$$

defining eqn for $Y_{R/Z}$ (precond'd forces)

$$\tilde{F}_\alpha^{mn} Y_\alpha^{mn} = \boxed{F}_\alpha^{mn}(\mathbf{X})$$

radial discretization leads to tri-diagonal equation:

$$\mathbf{M}_{ij}^{mn} \cdot Y_\alpha^{mn}(s_j) = F_\alpha^{mn}(s_i)$$

M_{ij} needs to include additional “-” sign!

=> M_{ij} is the discretized version of $-\tilde{F}_\alpha$

$$\tilde{F}_\alpha^{mn} = \frac{\partial}{\partial s} D_\alpha^{ss} \frac{\partial}{\partial s} - m^2 D_\alpha^{\theta\theta} - n^2 D_\alpha^{\phi\phi}$$

$$M_{ij}^{mn} = \begin{cases} \frac{D_\alpha^{ss}(s_{i-1/2})}{\Delta s^2}, & j = i-1, \\ -\frac{D_\alpha^{ss}(s_{i-1/2}) + D_\alpha^{ss}(s_{i+1/2})}{\Delta s^2} - m^2 D_\alpha^{\theta\theta}(s_i) - n^2 D_\alpha^{\phi\phi}(s_i), & j = i, \\ \frac{D_\alpha^{ss}(s_{i+1/2})}{\Delta s^2}, & j = i+1. \end{cases} \quad (6b)$$

=> tri-diagonal eqn: $b_i Y(s_{i-1}) + d_i Y(s_i) + a_i Y(s_{i+1}) \approx F(s_i)$

In order to understand M_{ij} , need to understand what is meant by $\frac{\partial}{\partial s} D_\alpha^{ss} \frac{\partial}{\partial s}$ applied to Y

$$a) \quad - \frac{\partial Y_i^{1,[s]}(s)}{\partial s} D_{ss}^{Y^1}(s) \frac{\partial Y_j^{1,[s]}(s)}{\partial s}$$

(GVEC)

$$b) \quad \frac{\partial}{\partial s} \left(D_\alpha^{ss}(s) \frac{\partial Y}{\partial s} \right) = \frac{\partial D_\alpha^{ss}}{\partial s} \frac{\partial Y}{\partial s} + D_\alpha^{ss} \frac{\partial^2 Y}{\partial s^2}$$

(J.S.)

These expressions identical, except boundary conditions!

$$\frac{\partial}{\partial s} \left(D_{\alpha}^{ss}(s) \frac{\partial Y}{\partial s} \right) = \underbrace{\frac{\partial D_{\alpha}^{ss}}{\partial s}}_1 \underbrace{\frac{\partial Y}{\partial s}}_2 + \underbrace{D_{\alpha}^{ss}}_3 \underbrace{\frac{\partial^2 Y}{\partial s^2}}_4$$

- D_{α}^{ss} is on half-grid
- Y is on full-grid
- result should approximate $F_{\alpha}(s_i)$ on full grid

$$1) \quad \frac{\partial D_{\alpha}^{ss}}{\partial s} \approx \frac{D_{\alpha}^{ss}(s_{i+1/2}) - D_{\alpha}^{ss}(s_{i-1/2})}{\Delta s}$$

$$2) \quad \frac{\partial Y}{\partial s} \approx \frac{Y(s_{i+1}) - Y(s_{i-1})}{2\Delta s}$$

$$3) \quad D_{\alpha}^{ss}(s_i) \approx \frac{D_{\alpha}^{ss}(s_{i+1/2}) + D_{\alpha}^{ss}(s_{i-1/2})}{2}$$

$$4) \quad \frac{\partial^2 Y}{\partial s^2} \approx \frac{Y(s_{i+1}) - 2Y(s_i) + Y(s_{i-1}))}{\Delta s^2}$$

$$1^{\text{st}} \text{ order central: } f_x(x, y) \approx \frac{f(x+h, y) - f(x-h, y)}{2h}$$

interpolate to full-grid from neighboring half-grid points

$$2^{\text{nd}} \text{ order central: } f''(x) \approx \frac{f(x+h) - 2f(x) + f(x-h)}{h^2}$$

... putting it all together:

$$\boxed{b_i} Y(s_{i-1}) + \boxed{d_i} Y(s_i) + \boxed{a_i} Y(s_{i+1}) \approx F(s_i)$$

$$\frac{\partial}{\partial s} \left(D_{\alpha}^{ss}(s) \frac{\partial Y}{\partial s} \right) \approx \underbrace{\frac{D_{\alpha}^{ss}(s_{i-1/2})}{\Delta s^2}}_{b_i} Y(s_{i-1}) - \underbrace{\frac{D_{\alpha}^{ss}(s_{i-1/2}) + D_{\alpha}^{ss}(s_{i+1/2})}{\Delta s^2}}_{d_i} Y(s_i) + \underbrace{\frac{D_{\alpha}^{ss}(s_{i+1/2})}{\Delta s^2}}_{a_i} Y(s_{i+1})$$

$$M_{ij}^{mn} = \begin{cases} \frac{D_{\alpha}^{ss}(s_{i-1/2})}{\Delta s^2}, & j = i - 1, \\ -\frac{D_{\alpha}^{ss}(s_{i-1/2}) + D_{\alpha}^{ss}(s_{i+1/2})}{\Delta s^2} - m^2 D_{\alpha}^{\theta\theta}(s_i) - n^2 D_{\alpha}^{\phi\phi}(s_i), & j = i, \quad (6b) \\ \frac{D_{\alpha}^{ss}(s_{i+1/2})}{\Delta s^2}, & j = i + 1. \end{cases}$$

... putting it all together:

$$\mathbf{b}_i Y(s_{i-1}) + \mathbf{d}_i Y(s_i) + \mathbf{a}_i Y(s_{i+1}) \approx F(s_i)$$

$$\frac{\partial}{\partial s} \left(D_{\alpha}^{ss}(s) \frac{\partial Y}{\partial s} \right) \approx \underbrace{\frac{D_{\alpha}^{ss}(s_{i-1/2})}{\Delta s^2}}_{\mathbf{b}_i} Y(s_{i-1}) - \underbrace{\frac{D_{\alpha}^{ss}(s_{i-1/2}) + D_{\alpha}^{ss}(s_{i+1/2})}{\Delta s^2}}_{\mathbf{d}_i} Y(s_i) + \underbrace{\frac{D_{\alpha}^{ss}(s_{i+1/2})}{\Delta s^2}}_{\mathbf{a}_i} Y(s_{i+1})$$

... plus additional diagonal terms for θ and Φ