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EDUCATION

NYU, Courant Institute of Mathematical Sciences		2011-2015
Ph.D. CS	Advisor: Prof. Chris Bregler (secondary: Yann LeCun)	GPA: 4.0/4.0
Columbia University, SEAS		2006-2007
M.S. EE	Advisor: Prof. Peter Kinget	GPA: 3.6/4.0
Harvard University, DEAS		2002-2006
S.B. EE and CS	Advisor: Prof. Gu-Yeon Wei	with honors

PUBLICATIONS, INVITED TALKS AND AWARDS

- B. Mazoure, O. Nachum, I. Kostrikov, J. Tompson, *Improving Zero-shot Generalization in Offline Reinforcement Learning using Generalized Similarity Functions*, Submitted Paper
- P. Florence, C. Lynch, A. Zeng, O. Ramirez, A. Wahid, L. Downs, A. Wong, J. Lee, I. Mordatch, J. Tompson, *Implicit Behavioral Cloning*, CoRL 2021
- K. Zakka, A. Zeng, P. Florence, J. Tompson, J. Bohg, D. Dwibedi, XIRL: Cross-embodiment Inverse Reinforcement Learning, CoRL 2021
- I. Kostrikov, J. Tompson, R. Fergus, O. Nachum, Offline reinforcement learning with fisher divergence critic regularization, ICML 2021
- D. Seita, P. Florence, J. Tompson, E. Coumans, V. Sindhwani, K. Goldberg, A. Zeng, *Learning to rearrange deformable cables, fabrics, and bags with goal-conditioned transporter networks*, ICRA 2021
- D. Dwibedi, Y. Aytar, J. Tompson, P. Sermanet, A. Zisserman, With a little help from my friends: Nearest-neighbor contrastive learning of visual representations, ICCV 2021
- A. Zeng, P. Florence, J. Tompson, S. Welker, J. Chien, M. Attarian, T. Armstrong, I. Krasin, D. Duong, V. Sindhwani, J. Lee, Transporter networks: Rearranging the visual world for robotic manipulation, CoRL 2020
- D. Dwibedi, Y. Aytar, J. Tompson, P. Sermanet, A. Zisserman, Counting Out Time: Class Agnostic Video Repetition Counting in the Wild, CVPR 2020
- I. Kostrikov, O. Nachum, J. Tompson, Imitation Learning via Off-Policy Distribution Matching, ICLR 2020
- Y. Lu, J. Tompson, ADAIL: Adaptive Adversarial Imitation Learning, NeurIPS 2019 workshop
- D. Dwibedi, Y. Aytar, J. Tompson, P. Sermanet, A. Zisserman, Temporal Cycle-Consistency Learning, CVPR 2019
- C. Lynch, M. Khansari, T. Xiao, V. Kumar, J. Tompson, S. Levine, P. Sermanet, *Learning Latent Plans from Play*, submitted work.
- I. Kostrikov, K. Agrawal, D. Dwibedi, S. Levine, J. Tompson, *Discriminator-Actor-Critic: Addressing Sample Inefficiency and Reward Bias in Adversarial Imitation Learning*, ICLR 2019
- Invited talk: Fluid Simulation and PDE simulation using deep-learning, Stanford's ERE seminar 2018.
- S. Suwajanakorn, N. Snavely, J. Tompson, M. Norouzi, *Discovery of Semantic 3D Keypoints via End-to-end Geometric Reasoning*, ORAL presentation at NIPS 2018.
- D. Dwibedi, J. Tompson, C. Lynch, P. Sermanet, *Learning Actionable Representations from Visual Observations*, International Conference on Intelligent Robots (IROS) 2018.
- G. Papandreou, T. Zhu, L. Chen, S. Gidaris, J. Tompson, and K. Murphy, *PersonLab: Person Pose Estimation and Instance Segmentation with a Part-Based Geometric Embedding Model*, ECCV 2018
- D. Dwibedi, J. Tompson, C. Lynch, P. Sermanet, Self-Supervised Representation Learning for Continuous Control, Workshop in Machine Learning in the Planning and Control of Robot Motion at ICRA 2018
- K. Schlachter, C. DeFant, S. Herscher, J. Tompson, *Beyond Photo Realism for Domain Adaptation from Synthetic Data*, Submitted work 2018.
- D. Dwibedi, P. Sermanet, J. Tompson, Temporal Reasoning in Videos using Convolutional Gated Recurrent Units, Brave New Ideas in Video Understanding Workshop at CVPR 2018
- Invited Talk: RSS 2017 Workshop on Articulated Tracking, Human Person Detection and Pose Estimation.
- C. Schenck, J. Tompson, D. Fox, S. Levine, Learning Robotic Manipulation of Granular Media, CoRL 2017.
- J. Tompson, K. Schlachter, P. Sprechmann, K. Perlin, Accelerating Eulerian Fluid Simulation With Convolutional Networks, ICML 2017 & ICLR 2017 workshop.
- G. Papandreou, T. Zhu, N. Kanazawa, A. Toshev, J. Tompson, C. Bregler, K. Murphy, *Towards Accurate Multi-person Pose Estimation in the Wild*, CVPR 2017.
- A. Elhayek, E. De Aguiar, A. Jain, J. Tompson, L. Pishchulin, M. Andriluka, C. Bregler, B. Schiele, C. Theobalt, *MARCONI: ConvNet-based MARkerless Motion Capture in Outdoor and Indoor Scenes*, PAMI '16
- Awarded the '16 NYU Janet Fabri award for outstanding doctoral dissertation.
- R. Goroshin, J. Bruna, J. Tompson, D. Eigen, Y. LeCun, Unsupervised Learning of Spatiotemporally Coherent Metrics,

ICCV 2015

- Awarded the 2015 NYU Henning Biermann award for exceptional contributions to education and service.
- J. Tompson, R. Goroshin, A. Jain, Y. LeCun, C. Bregler, Efficient Object Localization Using Convolutional Networks, CVPR 2015
- A. Elhayek, E. De Aguiar, A. Jain, J. Tompson, L. Pishchulin, M. Andriluka, C. Bregler, B. Schiele, C. Theobalt, *Efficient ConvNet-based Markerless Motion Capture in General Scenes with a Low Number of Cameras*, CVPR 2015
- J. Tompson, A. Jain, Y. LeCun, C. Bregler, *Joint Training of a Convolutional Network and a Graphical Model for Human Pose Estimation*, NIPS 2014
- A. Jain, J. Tompson, Y. LeCun, C. Bregler, MoDeep: A Deep Learning Framework Using Motion Features for Human Pose Estimation, ACCV 2014
- R. Goroshin, J. Bruna, A. Szlan, J. Tompson, D. Eigen, Y. LeCun, Unsupervised Feature Learning from Temporal Data, NIPS 2014 workshop & ICML.
- A. Jain, J. Tompson, M. Andriluka, G. Taylor, C. Bregler, *Learning Human Pose Estimation Features with Convolutional Networks*, ICLR 2014
- J. Tompson, M. Stein, Y. LeCun, K. Perlin, *Real-Time Continuous Pose Recovery of Human Hands Using Convolutional Networks*, ACM TOG/SIGGRAPH 2014
- Awarded the 2013 Jacob T. Schwartz Ph.D. Fellow for outstanding performance in the NYU Ph.D. program.
- Invited Talk: K. Perlin, M. Stein, J. Tompson. ARCADE: A System for Augmenting Gesture-Based Presentations, SIGGRAPH Real-Time Live demo (2012).
- J. Tompson, A. Dolin and P. Kinget, 2.6GHz RF Inductive Power Delivery for Contactless On-Wafer Characterization, IEEE ICMTS, 2008 (Patent: WO/2009/065040)

WORK EXPERIENCE

Google Brain Google Inc.: 2022-present

Google Brain Google Inc.: 2015-2022

Google Daydream (VR)

Google Inc.: 2013-2015 Perceptive Code LLC

PhD CS

NYU: 2011-2014

startup: 2015-2015

Distributed Systems MongoDB Inc: 2013

Integrated Circuits Epoch Micro: 2007-2011

Masters EE Columbia: 2006-2008

- Staff Research Scientist: Team lead within Robotics At Google focusing on imitation learning for robotic manipulation.
- Senior Research Scientist: Worked within the Brain robotics group on a number of projects (RL, fluids, tracking, etc).
- Research Scientist: Worked on Google Cardboard team on an unreleased project.
- Developed in-house hand-tracking system for google cardboard.
- Cofounder: Started small consulting company (with Arjun Jain) to provide state-of-the-art vision-based tracking solutions. IP assets were sold.
- **Student:** Multiple ML publications on pose inference of human bodies and hands in cluttered RGB scenes. Also worked on unsupervised feature learning.
- **Summer intern:** working with the MongoDB kernel server team (under Alberto Lerner). Redesigned the distributed lock protocol for the configuration server.
- Hardware Engineer: Researched state-of-the-art mixed-signal IC solutions for telecom and data-conversion systems.
- **Student:** Fabricated contactless IC testing using inductive coupling. Investigated onchip ring-oscillator matching and compared statistics to theory.

OTHER EXPERIENCE AND QUALIFICATIONS

Teaching Assistant

Columbia & NYU: 2006-2007, 2011-2015

• NYU: Computer Vision: D. Geiger. Introductory CS, Computer Graphics, Computer games: K. Perlin. Columbia: Circuits: C. Zukowski, Wireless Com: P. Diament, VLSI Circuits: A. Bhavnagarwala.

Programming Languages

• C/C++/C#, Java, Lua, LISP, OpenGL/CL, CUDA, GLSL, Matlab, HTML, Python

REFERENCES

• Chris Bregler – bregler@courant.nyu.edu

• Yann LeCun - yann@cs.nyu.edu