Lab 5: Pitch Detection in Audio

In this lab, we will use numerical optimization to find the pitch and harmonics in a simple audio signal. In addition to the concepts in the <u>gradient descent demo (./grad_descent.ipvnb)</u>, you will learn to:

- · Load, visualize and play audio recordings
- · Divide audio data into frames
- Perform nested minimization

The ML method presented here for pitch detection is actually not a very good one. As we will see, it is highly susceptible to local minima and quite slow. There are several better <u>pitch detection algorithms</u> (https://en.wikipedia.org/wiki/Pitch_detection_algorithm), mostly using frequency-domain techniques. But, the method here will illustrate non-linear estimation well.

Reading the Audio File

Python provides a very simple method to read a wav file in the scipy.io.wavefile package. We first load that along with the other packages.

In [1]:

```
from scipy.io.wavfile import read
import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
# Can Xu cx461@nyu.edu
```

In the github repository, you should find a file, <u>viola.wav(./viola.wav)</u>. Download this file to your local directory. Although the file is included in the github repository, you can find it along with many other audio samples in <u>CCRMA audio website (https://ccrma.stanford.edu/~jos/pasp/Sound_Examples.html)</u>. After you have downloaded the file, you can then read the file with the read command. Print the sample rate in Hz, the number of samples in the file and the file length in seconds.

In [2]:

```
# Read the file
sr, y = read('viola.wav')

# Convert to floating point values so that computations below do not overflow
y = y.astype(float)

# TODO: Print sample rate, number of samples and file length in seconds.
samplesn = len(y)
totalTime = len(y)/sr
print(sr, samplesn, totalTime)
```

44100 299350 6.787981859410431

You can then play the file with the following command. You should hear the viola play a sequence of simple notes.

In [3]:

```
import IPython.display as ipd
ipd.Audio(y, rate=sr) # Load a NumPy array
```

Out[3]:



For the analysis below, it will be easier to re-scale the samples so that they have an average squared value of 1. Find the scale value in the code below to do this.

In [4]:

```
# TODO
print(np.mean( y**2 ) )
scale = np.sqrt( np.mean( y**2 ) )
y = y / scale
print(scale, np.sqrt( np.mean( y**2 ) ) )
```

45668243.5215 6757.828314 1.0

Dividing the Audio File into Frames

In audio processing, it is common to divide audio streams into short frames (typically between 10 to 40 ms long). Since frames are often processed with an FFT, the frames are typically a power of two. Analysis is then performed in the frames separately. Given the vector y, create a nfft x nframe matrix yframe where

```
yframe[:,0] = samples y[k], k=0,...,nfft-1
yframe[:,1] = samples y[k], k=nfft,...,2*nfft-1,
yframe[:,2] = samples y[k], k=2*nfft,...,3*nfft-1,
...
```

You can do this with the reshape command with order=F. Zero pad y if the number of samples of y is not divisible by nfft. Print the total number of frames as well as the length (in milliseconds) of each frame.

Note that in actual audio processing, the frames are typically overlapping and use careful windowing. But, we will ignore that here for simplicity.

In [5]:

```
# Frame size
nfft = 1024

# TODO:
zeroNum = len(y) % nfft
zeroNum = (nfft - zeroNum) % nfft
y1 = np.append(y,[0 for i in range(zeroNum)])

nframe = len(y1) // nfft
yframe = y1.reshape(nfft,nframe,order='F')
print(zeroNum,nframe,yframe.shape)
```

682 293 (1024, 293)

Let i0=10 and set yi=yframe[:,i0] be the samples of frame i0. We will use this frame for most of the rest of the lab. Plot the samples of yi. Label the time axis in milliseconds (ms).

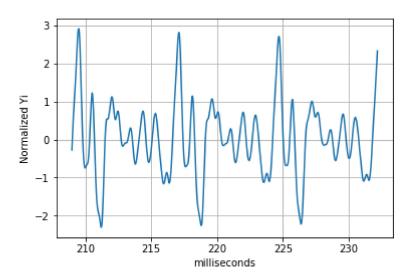
In [6]:

```
# Get samples from frame 10
i0 = 10
yi = yframe[:,i0]

tmi = np.arange(nfft)
print(tmi)
tmi += nfft*(i0-1)
tmi = tmi/float(sr)
print(tmi)

# TODO: Plot yi vs. time (in ms)
plt.plot(tmi*1000,yi)
plt.xlabel('milliseconds')
plt.ylabel('Normalized Yi')
plt.grid()
```

```
[ 0 1 2 ..., 1021 1022 1023]
[ 0.20897959 0.20900227 0.20902494 ..., 0.23213152 0.2321542 0.23217687]
```



Fitting a Multi-Sinusoid

A common model for audio samples, yi[k], containing an instrument playing a single note is the multisinusoid model:

where sr is the sample rate. The parameter freq0 is called the fundamental frequency and the audio signal is modeled as being composed of sinusoids and cosinusoids with frequencies equal to integer multiples of the fundamental. In audio processing, these terms are called *harmonics*. In analyzing audio signals, a common goal is to determine both the fundamental frequency freq0 (the pitch of the audio) as well as the coefficients of the harmonics,

```
beta = (c, a[0], ..., a[nterms-1], b[0], ..., b[nterms-1]).
```

To find the parameters, we will fit the mean squared error loss function:

```
mse(freq0,beta) := 1/N * \sum_{k \in \mathbb{N}} - yhati[k])**2, N = len(yi).
```

In practice, a separate model would be fit for each audio frame. But, in this lab, we will mostly look at a single frame.

Nested Minimization

We will perform the minimization of mse in a nested manner: First, given a fundamental frequency freq0, we minimize over the coefficients beta. Call this minimum mse1:

```
mse1(freq0) := min beta mse(freq0,beta)
```

Importantly, this minimizaiton can be performed by least-squares. Then, we find the fundamental frequency freq0 by minimizing mse1:

```
min_{freq0} mse1(freq0)
```

We will use gradient-descent minimization with mse1(freq0) as the objective function. This form of *nested* minimization is commonly used whenever we can minimize over one set of parameters easily given the other.

Setting Up the Objective Function

We will use the class AudioFitFn below to perform the two-part minimization. Complete the feval method in the class. The method should take the argument freq0 and perform the minimization of the MSE over beta. Specifically, fill the code in feval to perform the following:

- Construct a matrix, A such that yhati = A*beta.
- Find betahat with the np.linalg.lstsq() method using the matrix A and the samples self.yi. This is simpler than constructing a linear regression object.
- Compute and store the estimate self.yhati = A.dot(betahat).
- Compute the mse1, the minimum MSE, by comparing self.yhati and self.yi.
- For now, set the gradient to mse1_grad=0. We will fill this part in later.
- Return mse1 and mse1 grad.

In [7]:		

```
class AudioFitFn(object):
    def __init__(self,yi,sr=44100,nterms=8):
       A class for fitting
       yi: One frame of audio
        sr: Sample rate (in Hz)
        nterms: Number of harmonics used in the model (default=8)
        self.yi = yi
        self.leny = len(yi)
        self.sr = sr
        self.nterms = nterms
    def feval(self,freq0):
        Optimization function for audio fitting. Given a fundamental frequency, freq0,
the
       method performs a least squares fit for the audio sample using the model:
       yhati[k] = c + \sum_{j=0}^{n} \{nterms-1\} \ a[j] * cos(2*np.pi*k*freq0*(j+1)/sr)
                                           + b[j]*sin(2*np.pi*k*freq0*(j+1)/sr)
        The coefficients beta = [c,a[0],...,a[nterms-1],b[0],...,b[nterms-1]]
        are found by least squares.
        Returns:
        mse1:
                The MSE of the best least square fit.
        mse1_grad: The gradient of mse1 wrt to the parameter freq0
        # TODO
        Mat a = np.zeros( (self.leny, int(2*self.nterms +1) ))
        for k in range(self.leny):
            Ma_1 = np.array([1])
            Ma_a = np.arange(self.nterms) + 1;
            Ma_a = np.cos(2*np.pi*k*freq0/sr*Ma_a)
            Ma b = np.arange(self.nterms) + 1;
            Ma_b = np.sin(2*np.pi*k*freq0/sr*Ma_b)
            Ma_1 = np.append(Ma_1, [Ma_a, Ma_b])
            Mat_a[k] = Ma_1
        #print(Mat a)
        # print(Mat_a.shape) (1024, 17)
        betahat1 , rs1 = np.linalg.lstsq(Mat_a,self.yi)[0:2]
        #print(betahat1,rs1)
        self.yhati = Mat a.dot(betahat1)
        mse1 = np.mean( (self.yhati-yi )**2 )
        # Compute the gradient wrt to freq0
        Mat_ag = np.zeros( (self.leny, int(2*self.nterms +1) ))
        for k in range(self.leny):
            Ma 1g = np.array([0])
            Ma ag = np.arange(self.nterms) + 1;
            Ma_ag = -np.cos(2*np.pi*k*freq0/sr*Ma_ag) * (2*np.pi*k/sr*Ma_ag)
            Ma_bg = np.arange(self.nterms) + 1;
```

```
Ma_bg = np.cos(2*np.pi*k*freq0/sr*Ma_bg) * ( 2*np.pi*k/sr*Ma_bg )
           Ma_1g = np.append(Ma_1g,[Ma_ag,Ma_bg])
           Mat_ag[k] = Ma_1g
       #print(Mat_ag)
       mse1_grad = np.array ( [np.mean (2*(yi-self.yhati)*( - Mat_ag.dot(betahat1) ))]
)
       mse1 grad.reshape(1)
       # print(mse1_grad.shape)
                                  # (1,)
       return mse1, mse1_grad
```

Instatiate an object, audio_fn from the class AudioFitFn with the samples yi. Then, using the feval method, compute and plot mse1 for 100 values freq0 in the range of 40 to 500 Hz. You should see a minimum around freq0 = 130 Hz, but there are several other local minima.

In [8]:

```
# TODO
freqs = np.linspace(40,500,100)
print(freqs.shape)
audio_fn = AudioFitFn(yi)
mse1s = np.zeros(0)
for i in range(100):
    mse1, mse1_grad = audio_fn.feval(freqs[i])
    mse1s = np.append(mse1s,mse1)
#print(mse1s)
mini = np.argmin(mse1s)
minfreq = freqs[mini]
print(mini,minfreq)
(100,)
```

20 132.929292929

Print the value of freq0 that achieves the minimum mse1. Also, plot the estimated function audio_fn.yhati for that along with the original samples yi.

In [9]:

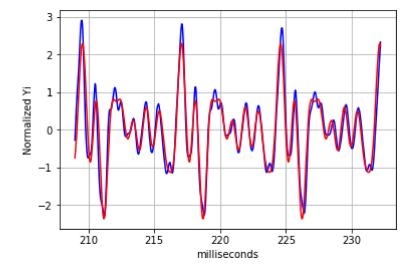
```
# TODO

print(mini,minfreq)
mse1, mse1_grad = audio_fn.feval(minfreq)

# TODO: Plot yi vs. time (in ms)
plt.plot(tmi*1000,yi,'b',tmi*1000,audio_fn.yhati,'r')
# red is yhat

plt.xlabel('milliseconds')
plt.ylabel('Normalized Yi')
plt.grid()
```

20 132.929292929



Computing the Gradient

The above method found the estimate for freq0 by performing a search over 100 different frequency values and selecting the frequency value with the lowest MSE. We now see if we can estimate the frequency with gradient descent minimization of the MSE. We first need to modify the feval method in the AudioFitFn class above to compute the gradient. Some elementary calculus (see the homework), shows that

```
dmse1(freq0)/dfreq0 = dmse(freq0,betahat)/dfreq0
```

So, we just need to evaluate the partial derivative of mse = np.mean((yi-yhati)**2) with respect to the parameter freq0 holding the parameters beta=betahat. Modify the feval method above to compute the gradient and return the gradient in mse1 grad.

Then, test the gradient by taking two close values of freq0, say freq0_0 and freq0_1 and verifying that first-order approximation holds.

In [10]:

```
# TODO

freq0_0 = 50.5
freq0_1 = 50.7
mse1_00, mse1_grad00 = audio_fn.feval(freq0_0)
mse1_01, mse1_grad01 = audio_fn.feval(freq0_1)
mse1_01est = mse1_00+mse1_grad00*(freq0_1-freq0_0)
print(mse1_00,mse1_grad00,mse1_grad01)
print(mse1_01,mse1_01est)
#est is close to the mse1_01 , correct

0.557669700267 [ 0.02541533] [ 0.01613275]
```

```
0.557669700267 [ 0.02541533] [ 0.01613275] 
0.567475089552 [ 0.56275277]
```

Run the Optimizer

We cut and paste the optimizer from the gradient descent demo (./grad_descent.ipynb).

In [11]:

```
def grad_opt_adapt(feval, winit, nit=1000, lr_init=1e-3):
    Gradient descent optimization with adaptive step size
    feval: A function that returns f, fgrad, the objective
           function and its gradient
   winit: Initial estimate
           Number of iterations
   nit:
    Lr:
            Initial learning rate
    Returns:
         Final estimate for the optimal
    f0: Function at the optimal
   # Set initial point
   w0 = winit
    f0, fgrad0 = feval(w0)
    lr = lr init
   # Create history dictionary for tracking progress per iteration.
    # This isn't necessary if you just want the final answer, but it
   # is useful for debugging
   hist = {'lr': [], 'w': [], 'f': []}
   for it in range(nit):
        # Take a gradient step
       w1 = w0 - lr*fgrad0
        # Evaluate the test point by computing the objective function, f1,
        # at the test point and the predicted decrease, df_est
        f1, fgrad1 = feval(w1)
        df est = fgrad0.dot(w1-w0)
       # Check if test point passes the Armijo rule
        alpha = 0.5
        if (f1-f0 < alpha*df_est) and (f1 < f0):</pre>
            # If descent is sufficient, accept the point and increase the
            # Learning rate
            lr = lr*2
            f0 = f1
            fgrad0 = fgrad1
            w0 = w1
        else:
            # Otherwise, decrease the Learning rate
            lr = lr/2
        # Save history
        hist['f'].append(f0)
        hist['lr'].append(lr)
        hist['w'].append(w0)
   # Convert to numpy arrays
    for elem in ('f', 'lr', 'w'):
        hist[elem] = np.array(hist[elem])
    return w0, f0, hist
```

Now, run the optimizer with the feval function with a starting estimate for freq0 = 130 Hz. Use lr_init=1e-3 and f0_init=130. Print the final frequency estimate. Also, print the <u>midi number</u> (https://newt.phys.unsw.edu.au/jw/notes.html) of the estimated frequency:

```
midi_num = 12*log2(freq/440 Hz) + 69
```

If the note was exactly a musical note, midi_num should be an integer. But you will see that the frequency does not exactly lie on a note since the pitch in a viola bends around the note.

In [12]:

```
# TODO
nit=40

w0, f0, hist = grad_opt_adapt(audio_fn.feval,130,nit=nit,lr_init=1e-3)
print(w0, f0)
# print(hist) # converge near nit = 16

midi_num = 12* np.log2(w0/440) + 69
print(midi_num)
```

```
[ 131.51418411] 0.0225735824255
[ 48.09257859]
```

Plot the MSE as a function of the iteration.

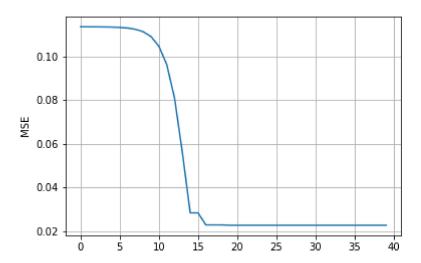
In [13]:

```
#TODO

plt.plot(hist['f'])
plt.grid()
plt.ylabel(" MSE ")
```

Out[13]:

<matplotlib.text.Text at 0x26e68ad40b8>



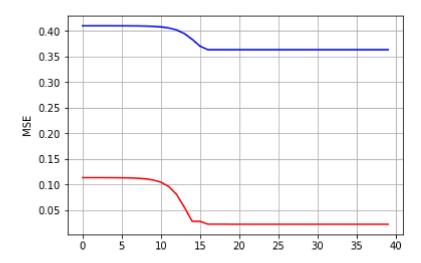
Now, repeat with an initial frequency of 200 Hz. Print the final estimated frequency. Also plot the MSE per iteration on the same graph as the MSE per iteration with the initial condition = 130 Hz. You will see that that the optimizer does not obtain the minimum MSE since it gets stuck at a local minima. This is the main reason this form of pitch detection is not used -- it requires a very good initial condition.

In [16]:

```
# TODO
# TODO
nit=40
w1, f1, hist1 = grad_opt_adapt(audio_fn.feval,200,nit=nit,lr_init=1e-3)
print(w1, f1)
# print(hist)
                 # converge near nit = 16
# Local minima
midi num = 12* np.log2(w1/440) + 69
print(midi_num)
#TODO
plt.plot(hist['f'],'r',label='from130')
plt.plot(hist1['f'],'b',label='from200')
plt.grid()
plt.ylabel(" MSE ")
#plt.legend()
```

```
[ 198.11699273] 0.363366094141
[ 55.18618924]
Out[16]:
```

<matplotlib.text.Text at 0x26e69b3b630>



More Fun

While the above method does not work very well, there are many good approaches. For one thing, we can obtain a good initial condition using an FFT of the frame. The FFT is used in many pitch detection methods. More difficult problems include multi-tone detection, chord detection and instrument separation. A useful python library that contains all sorts of interesting audio analysis tools in the librosa package (<a href="https://librosa.github.io/librosa/).

10/18/2017	lab_audio_partial

In []: