CSC373

Week 4

5 steps of Dynamic Programming

- 1. Optimal substructure definition
- 2. Memorization
 - Define an appropriate array to store intermediate values
- 3. Rewrite the recurrence relation in terms of the array(s) defined in step 2
- 4. Bottom-up approach
- 5. Compute a path to an actual solution(not just value)

Example 1

Given: n requests $\{1, 2, ..., n\}$ with s_i (start time) and f_i (finish time)

Goal: Schedule jobs in such a way that you obtain maximum possible value/weight

Solution: Sort the jobs by their finish time and define $P(i) = \max i$ such that i < j and request i does not overlap with j

Let O_n denote an optimal solution and OPT(n) be its value

```
Step I: (sub-problems)

Case 1: n \in O_n

OPT(n) = w_n + OPT(P(n))

Case 2: n \notin O_n

OPT(n) = OPT(n-1)
```

Step II: Define array for cache Define M[j] =the optimum value obtained with jobs $\{1, ..., j\}$

Step III: (most difficult part)

$$M_{j} = \begin{cases} w_{j} + M[P[i]] & \text{if } j \in O_{j} \\ M[j-1] & \text{if } j \notin O_{j} \end{cases}$$

```
Step IV:

M_Compute_Opt(j):

If j = 0 then

return 0

If M[j] is defined, then

return M[j]

Else

M[j] = max(M_compute_Opt(j-1), w<sub>j</sub>+ M_compute_Opt(P[j])

return M[j]

EndIf
```

M[n] is the final optimal value complexity: O(n)

```
Bottom-up Approach
      M_Bottom_up_Opt():
            Define M[0 ... n] = (undefined)
            M[0] = 0
            for j = 1 to n
                  M[j] = max(M[j-1], w_i + M[P[j]])
            Endfor
      Return M[n]
```

Complexity $\Theta(n)$

Step V: Finding an optimal solution with the optimal value

```
M_compute_Path(j, M):
    If j = 0:
        return " "
    Else
        if w<sub>j</sub>+M[P[j]] > M[j-1] then
             output M_compute_math(P[j], M) + j
        Else
             output M_compute_path(j-1, M)
        Endif
    Endif
```

```
M_compute_Path_Iterative(n, M):
      for j = n to 1;
             if M[P[j]] + w_j > M[j-1]
                    output j + " "
                    j = P[j]
             Else
                    j = j - 1
             EndIf
      Endfor
```

Example 2: Rod Cutting Problem

P[i] = Price for rod of length i

Goal: Cut up the rod into pieces so that the sum of the price of the pieces is maximum

Step I: Defining optimal substructure

if you cut the rod at location
$$i$$
 then
$$OPT(n) = \max_{1 \le i \le n} (P[i] + OPT(n-i))$$

$$OPT(j) = \max_{1 \le i \le j} (P[i] + OPT(j - i))$$

Step II: Array definition M[j] = optimal value on a rod of length j

Step III:
$$M[j] = \max_{1 \le i \le j} (P[i] + M[j-1])$$

```
Step IV: Bottom-up Approach
Bottom_up_cut_Rod(P, n):
         Define M[0, ..., n], S[0, ..., n]
         M[0] = 0, S[0] = 0
         for j=1 to n:
                   d = -\infty
                   for i=1 to j:
                             if q < P[i] + M[j-i] then
                                       q = p[j] + M[j-i]
s[j] = i
                   Endfor
         Endfor
         Return M and S
Complexity: 1+2+3+4+...+n = \Theta(n^2)
```

Proof that algorithm works

Step V: Find a way of cutting up the rod optimally

```
Print_Path(P, n):
    (M, S) = Bottom_up_cut_Rod(P, n)
    while n > 0:
        print S[n]
        n = n - S[n]
```

Example 3

Subset Sum & Knapsack Problem

Given: n jobs $\{1, ..., n\}$ each with a value v_i and a weight w_i and a bound W (Each jobs runs for 1 unit of time)

Goal: Find $S \subseteq \{1, ..., n\}$ such that $\Sigma_{i \in S} V_i$ is maximum possible subject to $\Sigma_{i \in S} w_i \leq W$ Subset sum is a special case of knapsack where $v_i = w_i$

```
Let O_n be an optimal solution and OPT(n) be its value OPT(n) = w_n + OPT(n-1) wrong!
```

To take care of the constraint

```
OPT(n, W)

If \ n \notin O_n : OPT(n, W) = OPT(n - 1, W)

If \ n \in O_n : OPT(n, W) = w_n + OPT(n - 1, W - w_n)
```

```
Step I: OPT(j,W) = \max(OPT(j-1,W), OPT(j-1,W-w_j) + w_j)

Step II: Define array M[ 1 .....n 1 .....w]

M[j, w] = the optimum value on {1, .....,j} jobs with upperbound w
```

Step III:

 $M[j, W] = max(M[j-1][w], m[j-1, w-w_i] + w_i)$

```
Step IV:
Subset_sum(n, W):
       Define M[0.....n 0.....W]
       M[0,w] = 0 for w = 0, ....,W
       for j = 1 to n:
              for w=1 to W:
                      if w < w<sub>i</sub> then
                             M[i,w] = M[i-1, w]
                      else
                             M[j, w] = max(M[j-1, w], M[j-1, w-w_i]+w_i)
       End
       Return M[n,w]
```

Complexity $\Theta(nw)$

Polynomial

Expression involving an actual input value is called pseudopolynomial

Knapsack – NP-complete (will talk about it later)
"Approximation Algorithm"
Functional knapsack: Polynomial

Step V: Actual Solution

Run through M[j, w] and figure out if j was in the schedule or not

Time complexity: $\Theta(n)$

Example 4: Largest Common Subsequence Problem

Given: Two sequences

$$X = \langle x_1, x_2,, x_n \rangle$$

 $Y = \langle y_1, y_2,, y_n \rangle$

Goal: Find out a subsequence that is common to both x and y, and that has the maximum possible length

<10, 13> is a common subsequence of X and Y <10, 13, 11> is a longest common subsequence of X and Y

```
Solution:

Step I:

Case I: X_m = Y_n

OPT(X, Y) = OPT(<x_1, ..., x_{m-1}>, <y_1, ..., y_{n-1}) + x_m

Case II: X_m \neq Yn

OPT(X_{1...m}, Y_{1...n}) = max(OPT(X_{1...m-1}, Y_{1...n}), OPT(X_{1...m}, Y_{1...n-1}))
```

Step II: Array definition

M[0.....n]

M[i,j]=length of a LCS(longest common subsequence of $X_{1,...,i}$

Step III:

$$M[i,j] = \begin{cases} 0 & if \ i = 0 \ or \ j = 0 \\ M[i-1,j-1] + 1 & if \ x_i = y_j \\ \max(M[i-1,j], M[i,j-1]) \ if \ x_i \neq y_j \end{cases}$$

```
Step IV: Bottom-up
         LCS(X[1, ...,m] Y[1, ...,m])
                  Define M[0 .....m 0.....n]
                  for i=0.....m
                           M[i,0]=0
                  for j=0.....m
                           M[0,j]=0
                  for i=1.....m:
                           for j=1.....n:
                                     if X[i]=Y[i] then
                                              M[i,j]=M[i,j-1]+1
                                     else
                                              M[i,j]=max(M[i, j-1], M[i-1, j])
                  Endfor
                  Return M[m,n]
Complexity Θ(mn) - Polynomial
```

```
LCSPath(M, X, Y, i, j)
       if i=0 or j=0 then
               return " "
       else if X[i] = Y[i] then
               return LCSPath(M, X, Y, i-1, j-1)+X[i]
       else
               if M[i, j-1] > M[i-1, j] then
                      return LCSPath(M, X, Y, I, j-1)
               else
                      return LCSPath(M, X, Y, i-1, j)
       Endif
Complexity \Theta(m + n)
```