

Chapter 1

The spatially-adaptive solution of the azimuthally Fourier-decomposed equations of 3D time-harmonic linear elasticity on unstructured meshes

In this tutorial we re-visit the solution of the time-harmonic equations of 3D linear elasticity in cylindrical polar coordinates, using a Fourier decomposition of the solution in the azimuthal direction. The driver code is very similar to the one discussed in [another tutorial](#) – the main purpose of the current tutorial is to demonstrate the use of spatial adaptivity on unstructured meshes. Compared to the test case considered in the [other tutorial](#) we study a slightly less contrived test problem: the forced time-harmonic oscillations of a finite-length, hollow cylinder, loaded by a time-periodic pressure load on its inner surface.

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1.1 The test problem

The figure below shows the problem considered in this tutorial: an annular elastic body that occupies the region $r_{\min} \leq r \leq r_{\max}$, $z_{\min} \leq z \leq z_{\max}$ is loaded by a time-harmonic pressure load acting on its inner surface (at $r = r_{\min}$). The upper and lower ends of the hollow cylinder (at $z = z_{\min}$ and $z = z_{\max}$) are held at a fixed position. Here is an animation of the resulting displacement field for $r_{\min} = 0.1$ and $r_{\max} = 1.1$.



Figure 1.1 Forced oscillations of a thick-walled, hollow cylinder, subject to a pressure load on its inner surface. The pink shape in the background shows the cylinder's undeformed shape (in a radial plane); the mesh plotted in the region $r < 0$ illustrates how spatial adaptivity refines the mesh in regions of sharp displacement gradients (near the loaded surface and the supports).

1.2 The numerical solution

The driver code for this problem is very similar to the one discussed in [another tutorial](#). Running `sdiff` on the two driver codes

```
demo_drivers/time_harmonic_fourier_decomposed_linear_↵
elasticity/cylinder/cylinder.cc
```

and

```
demo_drivers/time_harmonic_fourier_decomposed_linear_↵
elasticity/cylinder/pressure_loaded_cylinder.cc
```

shows you the differences, the most important of which are:

- The change of the forcing to a spatially constant pressure load on the inside boundary.
- The provision of the `actions_before/after_adapt()` functions and a helper function `complete_↵ problem_setup()` which rebuilds the elements (by passing the problem parameters to the elements) following the unstructured mesh adaptation. (The need/rationale for such a function is discussed in [another tutorial](#).)
- The mesh generation and the application of boundary conditions at the upper and lower boundaries of the hollow cylinder.

All of this is reasonably straightforward and provides a powerful code that automatically adapts the mesh in regions of large displacement gradients. Have a look through the driver code and play with it.

1.3 Code listing

Here's a listing of the complete driver code:

```

//LIC// =====
//LIC// This file forms part of oomph-lib, the object-oriented,
//LIC// multi-physics finite-element library, available
//LIC// at http://www.oomph-lib.org.
//LIC//
//LIC//      Version 1.0; svn revision $LastChangedRevision$
//LIC//
//LIC// $LastChangedDate$
//LIC//
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//LIC// Foundation, Inc., 51 Franklin Street, Fifth Floor, Boston, MA
//LIC// 02110-1301 USA.
//LIC//
//LIC// The authors may be contacted at oomph-lib@maths.man.ac.uk.
//LIC//
//LIC//=====
// Driver
// The oomplib headers
#include "generic.h"
#include "time_harmonic_fourier_decomposed_linear_elasticity.h"
// The mesh
#include "meshes/rectangular_quadmesh.h"
#include "meshes/triangle_mesh.h"
using namespace std;
using namespace oomph;
//===start_of_namespace=====
/// Namespace for global parameters
//=====
namespace Global_Parameters
{
    /// Define Poisson's ratio  $\nu$ 
    std::complex<double> Nu(0.3,0.0);

    /// Define the non-dimensional Young's modulus
    std::complex<double> E(1.0,0.0);

    /// Define Fourier wavenumber
    int Fourier_wavenumber = 0;

    /// \short Define the non-dimensional square angular frequency of
    /// time-harmonic motion
    std::complex<double> Omega_sq (10.0,0.0);

    /// Length of domain in r direction
    double Lr = 1.0;

    /// Length of domain in z-direction
    double Lz = 2.0;
    /// Set up min & max (r,z) coordinates
    double rmin = 0.1;
    double zmin = 0.3;
    double rmax = rmin+Lr;
    double zmax = zmin+Lz;

    /// Define the imaginary unit
    const std::complex<double> I(0.0,1.0);
    /// Pressure load
    double P=1.0;

    /// The traction function at  $r=rmin$ : (t_r, t_z, t_theta)
    void boundary_traction(const Vector<double> &x,
                          const Vector<double> &n,
                          Vector<std::complex<double> > &result)
    {
        /// Radial traction
        result[0] = P;
        /// Axial traction
        result[1] = 0.0;
        /// Azimuthal traction
        result[2] = 0.0;
    }
}

} // end_of_namespace

```

```

//===start_of_problem_class=====
// Class to validate time harmonic linear elasticity (Fourier
// decomposed)
//========
template<class ELEMENT>
class FourierDecomposedTimeHarmonicLinearElasticityProblem : public Problem
{
public:

    /// \short Constructor: Pass number of elements in r and z directions
    /// and boundary locations
    FourierDecomposedTimeHarmonicLinearElasticityProblem(
        const unsigned &nr, const unsigned &nz,
        const double &rmin, const double &rmax,
        const double &zmin, const double &zmax);

    /// Update before solve is empty
    void actions_before_newton_solve() {}

    /// Update after solve is empty
    void actions_after_newton_solve() {}

    /// Delete traction elements
    void delete_traction_elements();

    /// Helper function to complete problem setup
    void complete_problem_setup();

    /// Actions before adapt: Wipe the mesh of traction elements
    void actions_before_adapt()
    {
        // Kill the traction elements and wipe surface mesh
        delete_traction_elements();

        // Rebuild the Problem's global mesh from its various sub-meshes
        rebuild_global_mesh();
    }

    /// Actions after adapt: Rebuild the mesh of traction elements
    void actions_after_adapt()
    {
        // Create traction elements from all elements that are
        // adjacent to FSI boundaries and add them to surface meshes
        assign_traction_elements();

        // Rebuild the Problem's global mesh from its various sub-meshes
        rebuild_global_mesh();

        // Complete problem setup
        complete_problem_setup();
    }

    /// Doc the solution
    void doc_solution(DocInfo& doc_info);

private:

    /// Allocate traction elements on the bottom surface
    void assign_traction_elements();

#ifdef ADAPTIVE

    /// Pointer to the bulk mesh
    RefineableTriangleMesh<ELEMENT>* Bulk_mesh_pt;
#else

    /// Pointer to the bulk mesh
    Mesh* Bulk_mesh_pt;
#endif

    /// Pointer to the mesh of traction elements
    Mesh* Surface_mesh_pt;
}; // end_of_problem_class
//===start_of_constructor=====
// Problem constructor: Pass number of elements in coordinate
// directions and size of domain.
//========
template<class ELEMENT>
FourierDecomposedTimeHarmonicLinearElasticityProblem<ELEMENT>::
FourierDecomposedTimeHarmonicLinearElasticityProblem
(const unsigned &nr, const unsigned &nz,
 const double &rmin, const double &rmax,
 const double &zmin, const double &zmax)
{
#ifdef ADAPTIVE
    // The boundary is bounded by four distinct boundaries, each
    // represented by its own polyline

```

```

Vector<TriangleMeshCurveSection*> boundary_polyline_pt(4);

// Vertex coordinates on boundary
Vector<Vector<double> > bound_coords(2);
bound_coords[0].resize(2);
bound_coords[1].resize(2);

// Horizontal bottom boundary
bound_coords[0][0]=rmin;
bound_coords[0][1]=zmin;
bound_coords[1][0]=rmax;
bound_coords[1][1]=zmin;

// Build the boundary polyline
unsigned boundary_id=0;
boundary_polyline_pt[0]=new TriangleMeshPolyLine(bound_coords,boundary_id);

// Vertical outer boundary
bound_coords[0][0]=rmax;
bound_coords[0][1]=zmin;
bound_coords[1][0]=rmax;
bound_coords[1][1]=zmax;

// Build the boundary polyline
boundary_id=1;
boundary_polyline_pt[1]=new TriangleMeshPolyLine(bound_coords,boundary_id);

// Horizontal top boundary
bound_coords[0][0]=rmax;
bound_coords[0][1]=zmax;
bound_coords[1][0]=rmin;
bound_coords[1][1]=zmax;

// Build the boundary polyline
boundary_id=2;
boundary_polyline_pt[2]=new TriangleMeshPolyLine(bound_coords,boundary_id);

// Vertical inner boundary
bound_coords[0][0]=rmin;
bound_coords[0][1]=zmax;
bound_coords[1][0]=rmin;
bound_coords[1][1]=zmin;

// Build the boundary polyline
boundary_id=3;
boundary_polyline_pt[3]=new TriangleMeshPolyLine(bound_coords,boundary_id);

// Pointer to the closed curve that defines the outer boundary
TriangleMeshClosedCurve* closed_curve_pt=
    new TriangleMeshPolygon(boundary_polyline_pt);

// Use the TriangleMeshParameters object for helping on the manage of the
// TriangleMesh parameters
TriangleMeshParameters triangle_mesh_parameters(closed_curve_pt);
// Specify the maximum area element
double uniform_element_area=0.2;
triangle_mesh_parameters.element_area() = uniform_element_area;
// Create the mesh
Bulk_mesh_pt=new RefineableTriangleMesh<ELEMENT>(triangle_mesh_parameters);
// Set error estimator
Bulk_mesh_pt->spatial_error_estimator_pt()=new Z2ErrorEstimator;
#else
//Now create the mesh
Bulk_mesh_pt = new RectangularQuadMesh<ELEMENT>(nr,nz,rmin,rmax,zmin,zmax);
#endif
//Create the surface mesh of traction elements
Surface_mesh_pt=new Mesh;
assign_traction_elements();

// Complete problem setup
complete_problem_setup();
// Add the submeshes to the problem
add_sub_mesh(Bulk_mesh_pt);
add_sub_mesh(Surface_mesh_pt);
// Now build the global mesh
build_global_mesh();
// Assign equation numbers
cout << assign_eqn_numbers() << " equations assigned" << std::endl;
} // end of constructor
//===start_of_complete_problem_setup=====
// Complete problem setup
//=====
template<class ELEMENT>
void FourierDecomposedTimeHarmonicLinearElasticityProblem<ELEMENT>::
complete_problem_setup()
{
    // Set the boundary conditions for this problem: All nodes are

```

```

// free by default -- just pin & set the ones that have Dirichlet
// conditions here
// Pin displacements everywhere apart from boundaries 1 and 3
//-----
for (unsigned ibound=0;ibound<3;ibound=ibound+2)
{
    unsigned num_nod=Bulk_mesh_pt->nboundary_node(ibound);
    for (unsigned inod=0;inod<num_nod;inod++)
    {
        // Get pointer to node
        Node* nod_pt=Bulk_mesh_pt->boundary_node_pt(ibound,inod);

        // Pinned in r, z and theta
        nod_pt->pin(0);nod_pt->pin(1);nod_pt->pin(2);
        nod_pt->pin(3);nod_pt->pin(4);nod_pt->pin(5);

        // Set the displacements
        nod_pt->set_value(0,0.0);
        nod_pt->set_value(1,0.0);
        nod_pt->set_value(2,0.0);
        nod_pt->set_value(3,0.0);
        nod_pt->set_value(4,0.0);
        nod_pt->set_value(5,0.0);
    }
}
// Complete the problem setup to make the elements fully functional
// Loop over the elements
unsigned n_el = Bulk_mesh_pt->nelement();
for(unsigned e=0;e<n_el;e++)
{
    // Cast to a bulk element
    ELEMENT *el_pt = dynamic_cast<ELEMENT*>(Bulk_mesh_pt->element_pt(e));
    // Set the pointer to Poisson's ratio
    el_pt->nu_pt() = &Global_Parameters::Nu;
    // Set the pointer to Fourier wavenumber
    el_pt->fourier_wavenumber_pt() = &Global_Parameters::Fourier_wavenumber;
    // Set the pointer to non-dim Young's modulus
    el_pt->youngs_modulus_pt() = &Global_Parameters::E;
    // Set the pointer to square of the angular frequency
    el_pt->omega_sq_pt() = &Global_Parameters::Omega_sq;
} // end loop over elements
// Loop over the traction elements
unsigned n_traction = Surface_mesh_pt->nelement();
for(unsigned e=0;e<n_traction;e++)
{
    // Cast to a surface element
    TimeHarmonicFourierDecomposedLinearElasticityTractionElement<ELEMENT*>*
    el_pt =
    dynamic_cast<TimeHarmonicFourierDecomposedLinearElasticityTractionElement
    <ELEMENT*>* >(Surface_mesh_pt->element_pt(e));

    // Set the applied traction
    el_pt->traction_fct_pt() = &Global_Parameters::boundary_traction;

} // end loop over traction elements
}
//====start_of_traction=====
// Make traction elements along the boundary r=rmin
//=====
template<class ELEMENT>
void FourierDecomposedTimeHarmonicLinearElasticityProblem<ELEMENT>::
assign_traction_elements()
{
    unsigned bound, n_neigh;
    // How many bulk elements are next to boundary 3
    bound=3;
    n_neigh = Bulk_mesh_pt->nboundary_element(bound);
    // Now loop over bulk elements and create the face elements
    for(unsigned n=0;n<n_neigh;n++)
    {
        // Create the face element
        FiniteElement *traction_element_pt
        = new TimeHarmonicFourierDecomposedLinearElasticityTractionElement<ELEMENT>
        (Bulk_mesh_pt->boundary_element_pt(bound,n),
        Bulk_mesh_pt->face_index_at_boundary(bound,n));

        // Add to mesh
        Surface_mesh_pt->add_element_pt(traction_element_pt);
    }
} // end of assign_traction_elements
//====start_of_delete_traction=====
// Delete traction elements
//=====
template<class ELEMENT>
void FourierDecomposedTimeHarmonicLinearElasticityProblem<ELEMENT>::
delete_traction_elements()

```

```

{
    // How many surface elements are in the surface mesh
    unsigned n_element = Surface_mesh_pt->nelement();

    // Loop over the surface elements
    for(unsigned e=0;e<n_element;e++)
    {
        // Kill surface element
        delete Surface_mesh_pt->element_pt(e);
    }

    // Wipe the mesh
    Surface_mesh_pt->flush_element_and_node_storage();
} // end of delete_traction_elements
//===start_of_doc_solution=====
// Doc the solution
//=====
template<class ELEMENT>
void FourierDecomposedTimeHarmonicLinearElasticityProblem<ELEMENT>::
doc_solution(DocInfo& doc_info)
{
    ofstream some_file;
    char filename[100];

    // Number of plot points
    unsigned npts=5;

    // Output solution
    sprintf(filename,"%s/soln.dat",doc_info.directory().c_str());
    some_file.open(filename);
    Bulk_mesh_pt->output(some_file,npts);
    some_file.close();
    // Output norm of solution (to allow validation of solution even
    // if triangle generates a slightly different mesh)
    sprintf(filename,"%s/norm.dat",doc_info.directory().c_str());
    some_file.open(filename);
    double norm=0.0;
    unsigned nel=Bulk_mesh_pt->nelement();
    for (unsigned e=0;e<nel;e++)
    {
        double el_norm=0.0;
        Bulk_mesh_pt->compute_norm(el_norm);
        norm+=el_norm;
    }
    some_file << norm << std::endl;
} // end_of_doc_solution
//===start_of_main=====
// Driver code
//=====
int main(int argc, char* argv[])
{
    // Number of elements in r-direction
    unsigned nr=10;

    // Number of elements in z-direction (for (approximately) square elements)
    unsigned nz=unsigned(double(nr)*Global_Parameters::Lz/Global_Parameters::Lr);
    // Set up doc info
    DocInfo doc_info;

    // Set output directory
    doc_info.set_directory("RESLT");
#ifdef ADAPTIVE
    // Set up problem
    FourierDecomposedTimeHarmonicLinearElasticityProblem
    <ProjectableTimeHarmonicFourierDecomposedLinearElasticityElement
    <TTimeHarmonicFourierDecomposedLinearElasticityElement<3> > >
    problem(nr,nz,Global_Parameters::rmin,Global_Parameters::rmax,
            Global_Parameters::zmin,Global_Parameters::zmax);
    // Solve
    unsigned max_adapt=3;
    problem.newton_solve(max_adapt);
#else
    // Set up problem
    FourierDecomposedTimeHarmonicLinearElasticityProblem
    <QTimeHarmonicFourierDecomposedLinearElasticityElement<3> >
    problem(nr,nz,Global_Parameters::rmin,Global_Parameters::rmax,
            Global_Parameters::zmin,Global_Parameters::zmax);

    // Solve
    problem.newton_solve();
#endif

    // Output the solution
    problem.doc_solution(doc_info);
} // end_of_main

```

1.4 Source files for this tutorial

- The source files for this tutorial are located in the directory:

```
demo_drivers/time_harmonic_fourier_decomposed_linear_↵  
elasticity/cylinder/
```

- The driver code is:

```
demo_drivers/time_harmonic_fourier_decomposed_linear_↵  
elasticity/cylinder/pressure_loaded_cylinder.cc
```

1.5 PDF file

A [pdf version](#) of this document is available.