

#### **DATA SHEET**

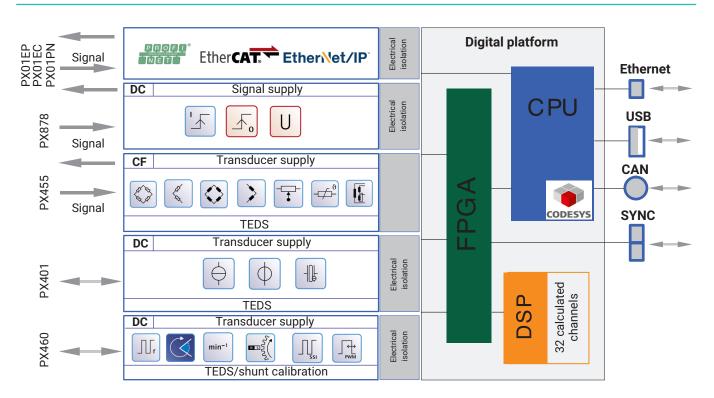
# PMX Modular measuring amplifier system

#### **SPECIAL FEATURES**

- Up to 16 measurement inputs with TEDS sensor detection
- 24-bit A/D converter and 19200 Hz or 38400 Hz sample rate per channel
- Automatic synchronization of several devices
- 32 calculated channels with peak values, limit values and mathematical functions
- · Digital inputs/outputs, analog outputs
- Fast PROFINET<sup>®</sup>, EtherCAT<sup>®</sup>, EtherNet/IP<sup>™</sup>
- Optional: CODESYS SoftPLC and CANopen interface
- · Rugged DIN rail or wall mounting
- Operation via integrated web server with user navigation on three levels (Operator, Maintenance, Administrator)



#### **BLOCK DIAGRAM**



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#### SPECIFICATIONS FOR THE BASIC DEVICE

Basic device		WGX001/002
Modules	Number	1 communication card, 4 measurement cards
Supply voltage range	V <sub>DC</sub>	10 30 (nominal (rated) voltage 24 V)
Supply voltage interruption		
(based on PLC standard DIN EN 61131-2)		
24 V (- 10 %)	ms	10
12 V (- 10 %)	ms	1
Power consumption at 24 V supply voltage		
Basic device	W	3
Per PX455	W	1.6
Per PX401	W	0.75
Per PX460	W	2
Per PX878	W	2
EtherCAT®1) communication card PX01EC	W	1.9
PROFINET® communication card PX01PN	W	2.3
EtherNet/IP™ <sup>2)</sup> communication card PX01EP	W	2.2
Ethernet (data link)		IEEE802.3.: 10 Base-T/100 Base-TX
Protocol/addressing		TCP/IP (direct IP address or DHCP)
Plug connection		RJ45, 8-pin
Cable type		Standard LAN, CAT 5, SFTP
Max. cable length to module	m	100
Synchronization		
NTP protocol		Time over Ethernet
HBM protocol		Measured values in measurement grid and carrier frequency (module
TIBWI PIOLOCOI		to module)
Plug connection		RJ45, 8-pin
Cable type		Standard LAN, CAT 5, SFTP
Number of devices		20
Line lengths between neighboring devices, max.	m	30
USB connection		USB 2.0 Host
Function		Resets all device parameters to the factory settings, sets the device
Tunction		name and network settings, resets user passwords, backs up
		measurement data (using the free CODESYS application)
CAN connection		CANopen interface only with WGX001 (CAN ISO11898)
Real-time calculation in the device		CAN 2.0b
Total sample rate	MW/s	400,000
Calculated channels	Number	32 in real time (max. 48 for internal calculations)
Update rate	Hz	19,200
Function		Peak values, Limit values, Mean values, Root mean square (RMS)
Tunoton		values, Tolerance bands, Mathematical calculated channels, Logical
		functions, Signal characteristic, Signal generators, 2-point scaling,
		2-state controller, PID controller, CASMA filter, Bessel and Butter-
		worth filters (IIR, high-pass and low-pass), Moving average (FIR), Mul-
		tiplexer, Sample and Hold, Time calculation, Counter, Trigger, 6x6 ma-
		trix calculation, Strain gauge rosette calculation, Coordinate calcula-
		tion (polar <-> Cartesian), Pulse-width measurement, Edge detector, Checkweigher, Connection to CODESYS
Peak-value memory		Great Great Great Control of Cont
Number		32
Reference level		All measurement signals, all calculated channels
Function		Min./Max., peak-to-peak
Update time	110	52
Clear	μs	JŁ
Via digital inputs	me	1
Via fieldbus	ms me	20
VIA HEIUDUS	ms	

<sup>1)</sup> EtherCAT® is a registered brand and patented technology, licensed by Beckhoff Automation GmbH, Germany.

 $<sup>^{2)} \ \ \</sup>text{EtherNet/IP}^{\tiny{\text{M}}} \ \text{is a trademark of ODVA Inc. For more information regarding ODVA, visit $www.odva.org.}$ 

# **SPECIFICATIONS (BASIC DEVICE CONTINUED)**

Limit switches			
Number		32. via fieldbus and Ethernet data link	
Number		8 via digital outputs per PX878 (max. 2 PX878 can be inserted)	
Reference level		All measurement signals, all calculated channels	
Function		Exceeding or falling below a level	
		Inside/outside a tolerance band	
Typical response time	μs	300	
Digital inputs			
Number		32 max. 17 32 via fieldbus and Ethernet data link	
Eunation		1 8 via digital signals per PX878 (max. 2 PX878 can be inserted) Zero balance, tare, reset limit value, digital output, parameter set	
Function		selection (bit-coded), calculated channel flags, CODESYS flags	
Typical response time	ms	1	
Digital outputs			
Number		16, via fieldbus and Ethernet data link	
		8 signals per PX878 (max. 2 PX878 can be inserted). Designed as	
		high-side switches.	
Function		Measured value/system status, digital input, fieldbus flag, limit value switch, current parameter set number (bit-coded), flags, calculated	
		channels, CODESYS flags)	
Typical response time	ms	1	
Parameter Sets			
Number		100, each parameter set comprises 4 parameter subsets	
Parameter subsets		Sensor settings, measurement acquisition, limit values, digital out-	
		puts	
Switching time	ms	Sensor data Measurement acquisitionLimit values Digital outputs st*)	
		1,200	
		1,200 950 2,150	
		- 100 - 100	
		1,200 950 100 - 2,250	
		80 80 1,200 950 100 80 2,330	
		*) Typical average switching time (in ms)	
Log file		For logging all parameter changes and (error) messages of all users	
Storage location		In the device	
File size, max.	MB	20	
Optional		Parallel transfer via network profile (RCF5424) to a network	
•		PC/server	
Nominal (rated) temperature range	°C	0 50	
Operating temperature range (no condensation allowed/module not immune to water condensation)	°C	-10 <b>+</b> 60	
Storage temperature range	°C	-20 +70	
Relative humidity	%	5 95 (non-condensing)	
Protection class (height up to 2,000 m, degree of contamination 2)		III	
Equipment protection level		IP 20 per EN60529	
Mechanical tests		·	
(test similar to IEC/EN 60068, Part 2-6)			
Oscillation (30 min in each direction)	m/s <sup>2</sup>	25 (5 65 Hz)	
Impact (3 times in each direction; impact duration 11 ms)	m/s <sup>2</sup>	200	
(test similar to IEC/EN 60068, Part 2-27)			

# **SPECIFICATIONS (BASIC DEVICE CONTINUED)**

EMC requirements		Ac nor EN 61226 and EN EE011 (Class P)
EMC requirements		As per EN 61326 and EN 55011 (Class B)  Relevant directives:
		2004/108/EC
		Relevant standards:
		Immunity to interference: DIN EN61326-1, Issue 2006-10 Table 2 (industrial environments)
		Emissions & Immunity (EME): DIN EN61326-1, Issue 2006-10, Class B
Proof of quality		
Declaration of compliance with the order		A PDF document of the manufacturer's certificate as per EN10204
·		2.1 is stored in the PMX device memory and can be downloaded via the PMX browser.
EMC update		The scope of inspection was updated with the requirements of the "EMC integration guideline for achieving electromagnetic compatibility in electrical systems in the automotive industry" version 1-03:
		EN61000-4-4: Burst test 2 kV
		EN55022: Interference current, interference voltage: expansion of frequency range 9 kHz 30 MHz
Quality requirements		
EMC requirements		Evaluation criteria A are met in all EMC tests. This means that operating behavior, i.e. accuracy and functions, remains in line with the specifications of the data sheet, even when subject to electromagnetic interference.
Long-term stability		All PMX components are pre-aged for 7 hours in an oven run to improve long-term stability.
Fuses		
Automatic current limiter Short-circuit resistance		Per device and per device card  Synchronization/fieldbus/input and output signals are secured
Dimensions (H x W x D)	mm	against mix-ups and short circuits 200 x 200 x 122
Weight (fully equipped), approx.		2,750
SoftPLC control (with WGX001)	g	CODESYS
,		IEC61131-3
Programming language	MD	
RAM	MB	10
Flash memory	MB	100
Timer resolution	Hz	300, for timer-controlled tasks (3.33 ms)
Number of tasks		100
Usable CODESYS channels in PMX		30 to 14 depending on the hardware configuration, (available number = 30 minus number of installed measurement channels)
Available channels in CODESYS	16	Measurement channels and status
	32	Calculated channels and status
	1	64bit timestamp
	1	System status
	32	Limit value status
	4	Slot status
CODESYS web visualization		Creates the web visualization with CODESYS software as an application suitable for running in PMX. The visualization can be used on all browser-based devices via the PMX Ethernet TCP/IP interface.

# **SPECIFICATIONS (BASIC DEVICE CONTINUED)**

CAN interface (with WGX001)								
Number of CAN interfaces				1				
Bus link			Two-wire as per ISO11898-2					
<b>Electrical isolation</b>		6	0 V DC vol	tage to supp	oly and mea	asuremen	t ground	
Protocol with CODESYS			CANo	pen 2.0, CiA	301, 302, 4	05, 401, 3	306	
CANopen		I	Node guard	ding, sync p	roducing/c	onsumino	]	
Usable CAN channels in PMX Internal in CODESYS, max. Can be used in calculated channels or mapped on analog output, fieldbus or Ethernet		;	128, freely programmable 30 to 14, depending on the hardware configuration					
CAN signal types			USINT, INT UINT, DINT UDINT, LINT ULINT, REAL SINT, LREAL					
Baud rate	bit/s	20k	50k	100k	125k	250k	500k	1M
Line length	m	1,000	1,000	1,000	500	250	100	25
CAN master (CODESYS), signal input		Several SDO channels, EDS and DCF file import; no DBC format, PDO mapping CIA401 (module-dependent), low-level CAN library						
CAN slave (CODESYS), signal output		Static PDO mapping, SDO parameter ranges, EDS file generation with the CODESYS programming system						
Number of PDOs, send or receive		Max. 16 PDO streams with max. total data size 128 bytes				es		
PDO transfer		Timer-controlled up to max. 300 Hz, measure value-controlled up to max. 1.2 kHz or via SYNC message (type: external, event:  MeasVal/Event)						
Number of SDOs		Max. 199 x 255 subIDs						
PDO, SDO generation			In the C	ODESYS pr	ogramming	environn	nent	
Connection technique				1 x N	112			
Transmit/receive CAN data								
Number of signals to be received/transmitted				128	maximum			
Number of signals for 1 Mbit/s, REAL format, 32-bit								
Signals		Readi transmiss (Hz	sion rate		asured atrolled (Hz	1 -	imer-conti (ms)	rolled
2		1,20	00	1,	200			
4		160	0		-		6	
8		160	0		-		6	
16		160	0		-		6	
24		100	0		-		10	
32		80	)		-		12	

#### **SPECIFICATIONS FOR PX455**

Strain gauge and inductive full/half bridge, 4.8 kHz CF		PX455
Accuracy class		
Full bridge		0.05
Half bridge		0.1
Carrier frequency (sine)	Hz	4800 ± 0.1 %
Bridge excitation voltage (effective)	V	2.5 ±5 %
Connectable transducers <sup>1), 2)</sup> in six or five-wire configuration		
Strain gauge half and full bridges	Ω	120 1000
Inductive half and full bridges, LVDTs	mH	4 33
Potentiometer		Deviations in accuracy class
Cable length	m	1
Resistance value 1 kΩ	%	< 0.1
Resistance value $5 \text{ k}\Omega$	%	< 0.1
PT100 resistance thermometer (in conjunction with a 100 $\Omega$ completion resistor as a half bridge circuit)	°C	-100 <b>+</b> 500
Measurement frequency range (-3 dB)	kHz	2
Data rate, max.	Hz	19200 per channel
Resolution of D/A converter	bit	24
Active low-pass filter (Bessel/Butterworth) 6th order, IIR	Hz	0.1 2000
Transducer connection		Plug terminals 4 x 7-pin
TEDS, IEEE1451.4		Zero-wire <sup>3), 4)</sup>
Permissible cable length between PX455 and transducer	m	1004)
Measurement ranges		
Strain gauge	mV/V	±4
Inductive	mV/V	±100, ±1000
LVDT	mV/V	±500
Nominal (rated) temperature range	°C	0 50
Operating temperature range (no condensation allowed/module not immune to water condensation)	°C	-10 <b>+</b> 60
Storage temperature range	°C	-20 +70
Relative humidity	%	5 95 (non-condensing)
Protection class (height up to 2,000 m, degree of contamination 2)		III
Equipment protection level		IP 20 per EN60529
EMC requirements		As per EN 61326 and EN 55011 (Class B)
Non-linearity	%	0.03
Zero drift (excitation, 2.5 V) at 4 mV/V rel. to full-scale value	%/10 K	Full bridge: 0.05; half bridge: 0.1
Full-scale drift (excitation, 2.5 V) at 4 mV/V rel. to measured value	%/10 K	Full bridge: 0.05; half bridge: 0.05
Half bridge offset <sup>5)</sup> (at 350 $\Omega$ and a cable length of $<$ 5 m)	μV/V	< ± 50
Accuracy class of full bridge strain gauge with Zener barrier SD01A, $350~\Omega$ , cable length of up to $100m$	%	0.5

 $<sup>^{1)}</sup>$  For bridge resistance from RB > 500  $\Omega$  or cable lengths >30 m: insert transducer-side resistors RB/2 in the feedback lines.

 <sup>2)</sup> With transducers >350 Ω, the zero point must be calibrated with cables >50 m (tare/zero balance).
 3) When using transducers with integrated zero-wire TEDS, RB/2 must be reduced by 100 Ω in each sense lead.
 4) Transducer-side TEDS cannot be read after RB/2 > 300 Ω.

<sup>5)</sup> The zero point for half bridges is heavily dependent on the test setup, the line length and the line type and should be tared or set to zero by the user.

# **SPECIFICATIONS (PX455 CONTINUED)**

Proof of quality		
Calibration certificate		A PDF document of the card calibration certificate as per ISO 10012 is stored in the PMX device memory as a PDF document and can be downloaded via the device browser.
Strain gauge full bridge 4 mV/V		
Noise at 25 °C and 2.5 V bridge excitation (peak-to-peak)		
With 0.1 Hz Bessel filter	μV/V	0.1
With 1 Hz Bessel filter	μV/V	0.2
With 10 Hz Bessel filter	μV/V	0.3
With 100 Hz Bessel filter	μV/V	0.5
With 1 kHz Bessel filter	μV/V	1.5
With 2 kHz Bessel filter	μV/V	3
Inductive full bridge 100 mV/V		
Noise at 25 °C and 2.5 V bridge excitation (peak-to-peak)		
With 0.1 Hz Bessel filter	μV/V	2
With 1 Hz Bessel filter	μV/V	3
With 10 Hz Bessel filter	μV/V	4
With 100 Hz Bessel filter	μV/V	5
With 1 kHz Bessel filter	μV/V	10
With 2 kHz Bessel filter	μV/V	15
Inductive full bridge 1,000 mV/V		
Noise at 25 °C and 2.5 V bridge excitation (peak-to-peak)		
With 0.1 Hz Bessel filter	μV/V	20
With 1 Hz Bessel filter	μV/V	30
With 10 Hz Bessel filter	μV/V	40
With 100 Hz Bessel filter	μV/V	50
With 1 kHz Bessel filter	μV/V	100
With 2 kHz Bessel filter	μV/V	200
Strain gauge half bridge 4 m/V		
Noise at 25 °C and 2.5 V bridge excitation (peak-to-peak)		
With 0.1 Hz Bessel filter	μV/V	1
With 1 Hz Bessel filter	μV/V	2
With 10 Hz Bessel filter	μV/V	3
With 100 Hz Bessel filter	μV/V	4
With 1 kHz Bessel filter	μV/V	5
With 2 kHz Bessel filter	μV/V	10
Inductive half bridge 100 m/V		
Noise at 25 °C and 2.5 V bridge excitation (peak-to-peak)		
With 0.1 Hz Bessel filter	μV/V	2
With 1 Hz Bessel filter	μV/V	3
With 10 Hz Bessel filter	μV/V	4
With 100 Hz Bessel filter	μV/V	5
With 1 kHz Bessel filter	μV/V	15
With 2 kHz Bessel filter	μV/V	30
Inductive half bridge 500 m/V, LVDT, potentiometer		
Noise at 25 °C and 2.5 V bridge excitation (peak-to-peak)		
With 0.1 Hz Bessel filter	μV/V	20
With 1 Hz Bessel filter	μV/V	30
With 10 Hz Bessel filter	μV/V	40
With 100 Hz Bessel filter	μV/V	50
With 1 kHz Bessel filter	μV/V	100
With 2 kHz Bessel filter	μV/V	200

# **SPECIFICATIONS (PX455 CONTINUED)**

0.4 -# (	Runtii	Runtime (ms)			
Cut-off frequency (Hz, -3dB)	Bessel	Butterworth			
2000	0.16	0.23			
1000	0.42	0.60			
500	0.85	1.24			
200	2.00	3.10			
100	4.15	6.17			
50	8.45	12.5			
20	21.4	30.7			
10	39	47			
5	74	91			
2	174	216			
1	340	430			
0.5	680	840			
0.2	1,680	2,090			
0.1	3,360	4,200			

# **SPECIFICATIONS FOR PX401**

Current and voltage module	PX401		
Accuracy class		0.1	
Data rate	Hz	19200 per channel	
Measurement frequency range (-3 dB)	kHz	3	
Resolution of D/A converter	bit	24	
Active low-pass filter (Bessel/Butterworth) 6th order, IIR	Hz	0.1 3000	
TEDS, IEEE1451.4		1-wire	
Transducer connection		Plug terminals 4 x 7-pin	
Transducer excitation (active transducers) Voltage (DC) Current limiter Electrical isolation	V A	Equivalent to device excitation 400 mA/card 60 V DC voltage between plug-in card and supply	
	Number	4	
Channels, individually switchable current/voltage		·	
Max. common-mode voltage (to housing and supply ground)	V	50	
Nominal (rated) temperature range	°C	0 50	
Operating temperature range (no condensation allowed/module not immune to water condensation)	°C	-10 <b>+</b> 60	
Storage temperature range	°C	-20 <b>+</b> 70	
Relative humidity	%	5 95 (non-condensing)	
Protection class (height up to 2,000 m, degree of contamination 2)		III	
Equipment protection level		IP 20 per EN60529	
EMC requirements		As per EN 61326 and EN 55011 (Class B)	
Voltage (DC) ±10 V			
Measurement range	V	-10.5 <b>+</b> 10.5	
Input impedance	ΜΩ	>1	
Noise at 25 °C (peak-to-peak)			
With 1 Hz Bessel filter	mV/V	0.25	
With 10 Hz Bessel filter	mV/V	0.3	
With 100 Hz Bessel filter	mV/V	0.5	
With 1 kHz Bessel filter	mV/V	1	

#### **SPECIFICATIONS (PX401 CONTINUED)**

Common-mode rejection		
with DC common mode	dB	100
For 50/60 Hz common mode, typically	dB	80
Non-linearity at 25 °C	%	0.05
Zero drift rel. to full-scale value	%/10 K	0.1
Full-scale drift rel. to measured value	%/10 K	0.05
Current (DC) ± 20 mA		
Measurement range	mA	± 20
Load resistance	Ω	50 ±1 %
Noise at 25 °C (peak-to-peak)		
With 1 Hz Bessel filter	μΑ	0.5
With 10 Hz Bessel filter	μΑ	0.6
With 100 Hz Bessel filter	μΑ	1
With 1 kHz Bessel filter	μA	2
Non-linearity	%	0.05
Zero drift rel. to full-scale value	%/10 K	0.1
Full-scale drift rel. to measured value	%/10 K	0.1
Proof of quality		
Calibration certificate		A PDF document of the card calibration certificate as per ISO 10012 is stored in the PMX device memory as a PDF document and can be downloaded via the device browser.

Cut off framework (III) ( 24D)	Runt	Runtime (ms)			
Cut-off frequency (Hz) (-3dB)	Bessel	Butterworth			
3000	0.10	0.14			
2000	0.20	0.28			
1000	0.42	0.61			
500	0.86	1.23			
200	2.00	3.10			
100	4.15	6.17			
50	8.45	12.5			
20	21.4	30.7			
10	39	47			
5	74	91			
2	174	216			
1	340	430			
0.5	680	840			
0.2	1680	2090			
0.1	3360	4200			

The following applies to the **PX401** measurement card: If the digital filter is switched off, only the hardware filter will function with a cut-off frequency of 3900 Hz (-3 dB).

# **SPECIFICATIONS FOR PX460**

Frequency measurement card		PX460
Accuracy class (frequency measurement and counting)		0.01
Inputs	Number	Channel 1/3: frequency
		Channel 2/4: frequency (digital, inductive), counter/encoder, SSI, PWM
Transducers that can be connected		Up to four measurement channels for frequency measurement up to 2 MHz or two angle/incremental encoders, SSI sensors, PWM sensors, magnetic transducers or pulse counters incl. two shunt calibrations and two 1-wire TEDS (sensor detection)
		HBM torque flanges (T10, T12, T40): max. four torque flanges for measuring torque (without rotational speed and without direction of rotation/angle of rotation measurement)
		Max. two torque flanges for simultaneous torque and rotational speed measurement (without direction of rotation/angle of rotation measurement)
		One torque flange for simultaneous torque, rotational speed, angle of rotation and direction of rotation measurement and reference signal detection
Transducer technologies		
RS485 inputs		Torque transducers, incremental encoders, frequency signal sources (square-wave)
AC input		Passive inductive rotational speed sensors, frequency signal sources (any signal shape)
Transducer identification (TEDS chip, IEEE 1451.4)		
Max. TEDS module distance	m	100
Transducer connection		Two plug terminals, 13 + 2-pin
Power consumption	W	2
Transducer excitation (active transducers) The transducer excitation must be directed to the supply input from outside.		5 V and 10 30 V are available
Transducer supply input	V	10 30, 3 A safety fuse, continuous current max. 2 A
Maximum output power	W	2 x 48 W continuous output (at U <sub>B</sub> = 24 V)
Transducer excitation voltage	V	5, max. continuous current 200 mA, max. continuous output 1 W
Electrical isolation		60 V DC voltage between plug-in card and supply
Nominal (rated) temperature range	°C	0 50
Operating temperature range (no condensation allowed/module not immune to water condensation)	°C	-10 +60
Storage temperature range	°C	-20 +70
Relative humidity	%	5 95 (non-condensing)
Protection class (height up to 2,000 m, degree of contamination 2)		III
Equipment protection level		IP 20 per EN60529
Mechanical stress capability (test similar to IEC/EN 60068, Part 2-6)		
Oscillation (30 min in each direction) Impact (3 times in each direction, impact duration 11 ms) (test similar to IEC/EN 60068, Part 2-27)	m/s <sup>2</sup> m/s <sup>2</sup>	25 (5 65 Hz) 200

# **SPECIFICATIONS (PX460 CONTINUED)**

Transducer technology		
Frequency signals (digital)		
Input frequency range		
RS485 inputs	Hz	0.1 2000000
AC inputs	Hz	10 50,000
Frequency measurement resolution, min.	mHz	1
Square-wave signal measurement (RS485 inputs)		Quadrature signals with index
F1 (+/-)		Frequency or pulse signal
F2 (+/-)		Directional signal offset by 90° to F1
Zero index (+/-)		Zero position signal
Input level (RS485 inputs) for single-pole mode (unbalanced)		
Source at signal (+) and ground		
Low level	V	< 1.5
High level	V	>2.3
Input signal range (RS485 inputs) for differential signal mode (balanced)		
Differential-mode signal at signal (+) and signal (-)		
Low level	mV	Signal (+) < signal (-) - 200
High level	mV	Signal (+) < signal (-) - 50
Input voltage range (RS485 inputs)		
Common-mode voltage range (to ground)	V	-7 <b>+</b> 12
Max. permissible voltages (to ground)	V	±15 (max. 1 mA continuous current)
Frequency signals (inductive) AC input (F1) passive only		
Input level for AC input (F1)		
Minimum level (sinusoidal, peak-to-peak)	V	0.1 (to 1 kHz)
	V	1 (at 10 kHz)
Maximum level (peak-to-peak)	V	5.5 (at 50 kHz) 40
Counter signals (encoder)		10
<u> </u>		
Counter (RS485 inputs) Frequency	Hz	0 2000000
Increments	Pulses	± 8000000
SSI signals (only synchronous serial interface active)	1 dioco	
Number of data bits	1	6 31
	IsDite /e	
Bit rate	kBits/s	10, 100, 200, 500, 1,000
Minimum time interval between data words (bit rate)	μs	1000 (at 10 kBit/s) 100 (at 100 kBit/s)
		75 (at 200 kBit/s)
		45 (at 500 kBit/s)
		30 (at 1000 kBit/s)
Coding		Gray code or binary code
Passive operating mode (no clock display, listen only)		Not supported
Parity check		Not supported
Shunt signal		Depending on SSI encoder, e.g. change direction of rotation, set to zero
Termination		Connection of an internal termination resistor to prevent reflectivity with long sense leads (>10 m) or high baud rates

# **SPECIFICATIONS (PX460 CONTINUED)**

Pulse-width modulated (PWM) signals				
Frequency	Hz	Hz 0.1 100,000		
Pulse width/duty ratio	%	5 95		
General specifications (PX460)				
Internal sample rate	MHz	98.3		
Glitch filter time constant (adjustable)		0.82 ns, 1 μs, 10 μs, 100 μs		
Permissible cable length between PMX460 and transducer	m	100		
Measurement frequency range (-1 dB)				
At 38,400 samples/s	kHz	0 10		
At 19,200 samples/s	kHz	0 5		
Measurement frequency range (-3 dB)				
At 38,400 samples/s	kHz	0 17		
At 19,200 samples/s	kHz	0 8.5		
<b>Active low-pass filter</b> (Bessel/Butterworth, can be disabled) 6th order, IIR	Hz	0.1 6000, filter off		
Frequency measurement deviation	%	<0.01 from measured value		
PWM deviation	%/kHz	0.3		
Zero drift	%/10 K	0		
Full-scale drift	%/10 K	<0.01 from measured value		
Input impedance				
RS485 inputs, connectable termination resistor (terminator)	kΩ	>45		
RS485 inputs	Ω	125		
AC input	kΩ	>100		
SHUNT calibration signal output				
SHUNT level active	V	Transducer excitation - 1 V at 50 mA		
Proof of quality				
Calibration certificate		A PDF document of the card calibration certificate as per ISO 10012 is stored in the PMX device memory as a PDF document and can be downloaded via the device browser.		

Cut-off frequency (Hz) (-3dB)	Runt	Runtime (ms)	
Cut-off frequency (HZ) (-3aB)	Bessel	Butterworth	
6000	0.07	0.94	
5000	0.08	0.12	
3000	0.10	0.14	
2000	0.20	0.28	
1000	0.42	0.61	
500	0.86	1.23	
200	2.00	3.10	
100	4.15	6.17	
50	8.45	12.5	
20	21.4	30.7	
10	39	47	
5	74	91	
2	174	216	
1	340	430	
0.5	680	840	
0.2	1680	2090	
0.1	3360	4200	

# Input/output

Analog output and digital input/output card		PX878	
Transducer connection		4 plug terminals, 7-pin	
Update rate of all output signals	kHz	19.2	
Nominal (rated) temperature range	°C	0 50	
Operating temperature range (no condensation allowed/ module not immune to water condensation)	°C	-10 +60	
Storage temperature range	°C	-20 <b>+</b> 70	
Relative humidity at 31 °C	%	5 95 (non-condensing)	
Protection class (height up to 2000 m, degree of contamination 2)		III	
Equipment protection level		IP 20 as per DIN EN 60529	
EMC requirements		As per EN 61326 and EN 55011 (Class B)	
Electrical isolation		60 V DC voltage between plug-in card and supply	
Analog outputs			
Accuracy class		0.1	
Number		5	
Signal sources		Real measurement signals and calculated signals	
Nominal (rated) voltage (output)	V	±10	
D/A converter resolution	bit	16	
Output rate, max.	kHz	19.2	
Cut-off frequency (-3 dB)	kHz	3	
Output resistance	Ω	< 10	
Permissible input impedance		10 kΩ    20 nF	
Noise (peak-to-peak)	mV	< 10	
Reference signal (common)		For all 5 outputs	
Integral Non-Linearity (INL)	LSB	±16	
Crosstalk attenuation	dB	>90	
Zero drift rel. to full scale	mV/10 K	10	
Full-scale drift rel. to output value	mV/10 K	10	
Cable length, max.	m	100	
Digital inputs			
Number		8 signals per PX878 (max. two PX878 can be inserted)	
Functions		Zero balance, tare, reset limit value, digital output, parameter set selection (bit-coded), calculated channel flags, CODESYS flags	
Switching time	ms	1	
Input signal range	V	0 30	
Maximum permitted input signal range	V	30	
Low state input High state input	V	0 5 (or open) 10 30	
Input resistance (nominal)	kΩ	7.5	
Cable length, max.	m m	100	
Cable type (required in the event of interference)	111	Shielded	
Cable type (required in the event of interference)		Sillelueu	

# **SPECIFICATIONS (PX878 CONTINUED)**

Digital outputs			
Number		8 signals per PX878 (max. two PX878 can be inserted)	
Functions		Measured value/system status, digital input, fieldbus flag, limit value switch, current parameter set number (bit-coded), flags, calculated channels, CODESYS flags	
Switching time	ms	1	
Input voltage (24 V nominal) U <sub>IN</sub>	V	10 30	
Output current per output, max.	mA	200	
Output current (outputs total), max.	Α	1.6	
Minimum voltage level when subject to 200 mA		Typical: U <sub>IN</sub> - 0.7 V	
Cable length, max.	m	100	
Proof of quality			
Calibration certificate		A PDF document of the card calibration certificate as per ISO 10012 is stored in the PMX device memory as a PDF document and can be downloaded via the device browser.	

#### **Communication cards**

EtherCAT®-communication card <sup>1)</sup>		PX01EC	
Туре		EtherCAT® complex slave	
Data transport layer		Ethernet II, IEEE802.3	
Power consumption, max.	W	2	
Electrical isolation		60 V DC voltage between plug-in card and supply	
Cable type		Standard Cat 5, shielded	
Cable length, max.	m	100	
Connector socket		RJ45 (IN/OUT)	
PMX to PLC communication			
Baud rate	Mbit/s	100	
Update rate	kHz	1.2; 2.4; 4.8; 9.6	
Slave synchronization (Distributed Clocks (DC))	-	No	
Cyclic process input data, max. (master -> slave)	Bytes	400	
Cyclic process output data, max. (slave -> master)	Bytes	200	
CAN		COE (CAN over Ethernet)	
PLC to PMX communication	Signals	Max. 8 signals (REAL type), can be used as CPU channels in calculated channels	
Data rate, max.	Hz	250 (adjustable)	
Device description file		Supplied with the device, or can be created in line with the device configuration using the PMX web server	

<sup>1)</sup> EtherCAT® is a registered brand and patented technology, licensed by Beckhoff Automation GmbH, Germany.

PROFINET® IO communication card		PX01PN	
Data transport layer		Ethernet II, IEEE802.3	
Power consumption, max.	W	2.4	
<b>Electrical isolation</b>		60 V DC voltage between plug-in card and supply	
Cable type		Standard Cat 5, shielded	
Cable length, max.	m	100	
Connector socket		RJ45 (port 1/port 2)	
PMX to PLC communication			
Baud rate	Mbit/s	100	
Update rate	kHz	1	
Slave synchronization		No	
Cyclic process input data, max. (device -> controller)	bytes	400	
Cyclic process output data, max. (controller -> device)	Bytes	200	

# SPECIFICATIONS (COMMUNICATION CARDS CONTINUED)

PROFINET® IO communication card		PX01PN	
Minimum cycle time (with max. 28 signals)	ms	1	
PLC to PMX communication	Signals	Max. 8 signals (REAL type), can be used as CPU channels in calculated channels	
Data rate, max.	Hz	250 (adjustable)	
Supported protocols		RTC – Real-Time Cyclic Class 1 unsynchronized Class 3 synchronized (IRT)	
		RTA – Real Time Acyclic	
		DCP – Discovery and Configuration Protocol	
		CL-RPC – Connectionless Remote Procedure Call	
		LLDP – Link Layer Discovery Protocol	
		SNMP - Simple Network Management Protocol	
		MRP client – Media Redundancy Protocol	
Topology recognition		LLDP, SNMP, MIB2, physical device	
VLAN and priority tagging (setting priorities)		Yes	
Identification and maintenance		I&M0 I&M4 read and write	
Unsupported protocols		RT via UDP	
		Multicast communication	
		DHCP	
		Fast startup	
		Media redundancy (except MRP client)	
		Supervisor AR (Supervisor-DA AR <b>is</b> supported)	
		Maximum one input CR and one output CR	
Device description file		Supplied with the device, or can be created in line with the device configuration using the PMX web server	

EtherNet/IP <sup>™1)</sup> communication card		PX01EP	
Туре		Communication adapter	
Power consumption, max.	W	2.3	
Cable type		Standard Cat 5, shielded	
Cable length, max.	m	100	
Connector socket		RJ45 (port 1/port 2)	
Maximum number for input data	Bytes	504 per assembly instance	
Maximum number for output data	Bytes	504 per assembly instance	
IO connection types		Exclusive owner, Listen only, Input only	
IO connection trigger types	ms	Cyclic, min. 1 <sup>2)</sup>	
		Application triggered, min. 1 <sup>2)</sup>	
		Change of state, min 1 <sup>2)</sup>	
Explicit messages		Connected and unconnected	
Maximum number of connections		8 (total of connected explicit and implicit connections)	
Unconnected Message Manager (UCMM)		Supported	
Objects		Identity (0x01)	
		Message router (0x02)	
		Assembly (0x04)	
		Connection manager (0x06)	
		DLR (0x47)	
		QoS (0x48)	
		TCP/IP interface (0xF5)	
		Ethernet link (0xF6)	
PLC to PMX communication	Signals	Max. 8 signals (REAL type), can be used as CPU channels in calculated channels	
Data rate, max.	Hz	250 (adjustable)	

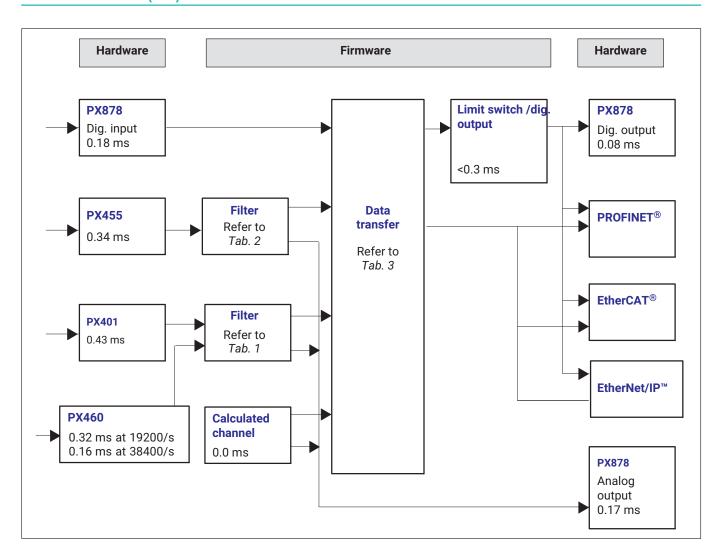
EtherNet/IP™ is a trademark of ODVA Inc. For more information regarding ODVA, visit www.odva.org.
 Depends on the number of connections and the number of I/O data.

#### SPECIFICATIONS (COMMUNICATION CARDS CONTINUED)

EtherNet/IP <sup>™1)</sup> communication card		PX01EP	
DHCP		Supported	
ВООТР		Supported	
Baud rates	Mbit/s	10,100	
Duplex modes		Half-duplex, full-duplex, auto-negotiation	
Data transport layer		Ethernet II, IEEE802.3	
ACD		Supported	
DLR V2 (ring topology)		Supported	
Integrated switch		Supported	
Reset services		Type 0 supported	
CIP Sync services		Not supported	
TAGs		Not supported	
Device description file		Supplied with the device, or can be created in line with the device configuration using the PMX web server	

 $<sup>^{1)}</sup>$  EtherNet/IP $^{\text{m}}$  is a trademark of ODVA Inc. For more information regarding ODVA, visit www.odva.org.

#### **SIGNAL DELAYS (MS)**



# SPECIFICATIONS (SIGNAL DELAYS CONTINUED)

Cut off fragrance to (II= 24D)	Runtime (in ms)			
Cut-off frequency fc (Hz, -3dB)	Bessel	Butterworth		
6000 (with PX460 only)	0.07	0.94		
5000 (with PX460 only)	0.08	0.12		
3000	0.10	0.14		
2000	0.20	0.28		
1000	0.42	0.61		
500	0.86	1.23		
200	2.00	3.10		
100	4.15	6.17		
50	8.45	12.5		
20	21.4	30.7		
10	39	47		
5	74	91		
2	174	216		
1	340	430		
0.5	680	840		
0.2	1680	2090		
0.1	3360	4200		

Tab. 1 Phase shifts for PX401, PX460

Cut-off frequency fc (Hz, -3dB)	Runtime (in ms)			
	Bessel	Butterworth		
2000	0.16	0.23		
1000	0.42	0.60		
500	0.85	1.24		
200	2.00	3.10		
100	4.15	6.17		
50	8.45	12.5		
20	21.4	30.7		
10	39	47		
5	74	91		
2	174	216		
1	340	430		
0.5	680	840		
0.2	1680	2090		
0.1	3360	4200		

Tab. 2 Phase shifts for PX455

Data transfer rate (in Hz)	Minimum (in ms)	Typical (in ms)	Maximum (in ms)
1200	0.1	0.52	0.93
2400 (factory setting)	0.1	0.31	0.52
4800	0.1	0.21	0.31
9600	0.1	0.16	0.21

Tab. 3 Data phase shifts

#### SPECIFICATIONS (SIGNAL DELAYS CONTINUED)

#### **Example**

Signal delay of a sensor signal via the analog output with filter:

Signal path  $PX455 \rightarrow 2 \text{ kHz Bessel} \rightarrow PX878$  $0.34^* + 0.16 (Tab. 2) + 0.17^* \text{ ms} = 0.67 \text{ ms}$ 

Delay time until signal appears in cyclic data frame.

Protocol	Data copy rate [Hz]	Typical [ms]	Maximum [ms]
PROFINET®	1200 (standard and max.)	1.8 + frame_cycle /2	2.4 + frame_cycle
EtherCAT®	2400 (standard) 4800 9600 (max)**	1.0 + frame_cycle /2	1.5 + frame_cycle
EtherNet/IP™	1200 (standard and max.)	1.8 + frame_cycle /2	2.4 + frame_cycle

Tab. 4 Fieldbus phase shifts

"Data copy rate" is the time in which the data are copied to the communication card in slot 0; frame\_cycle is the rate of the cyclic data frame that is set by the bus configuration tool.

#### **Example**

Signal delay of a sensor signal via the EtherCAT® fieldbus:

Signal path PX455  $\rightarrow$  2 kHz Bessel  $\rightarrow$  Data transfer @ 2,4 Hz  $\rightarrow$  EtherCAT@2,4 kHz PX01EC 0.34\*\*\* + 0.16 (*Tab. 2*) + 0.31 ms + 1.2 ms = 2.00 ms (average signal delay from input terminal to EtherCAT® fieldbus)

#### **CONNECTIONS**

# 2x RJ45 sockets for synchronization of up to 20 modules CODESYS and CAN bus (WGX001 only) Voltage supply 10 ... 30V USB host LED system status RJ45 Ethernet socket to PC/network Measurement card status LED Fieldbus status LEDs DIN rail positioning Max. 4 measurement cards or input/output card, e.g. Communication card: PX455, PX460, PX878 or PX401 EtherCAT®, PROFINET® or EtherNet/IP™

<sup>\*</sup> See diagram on page 16.

<sup>\*\*</sup> The EtherCAT® data copy rate has only minor effects on the signal delay. This is 0.16 ms between copy rates of 2.4 and 9.6 kHz.

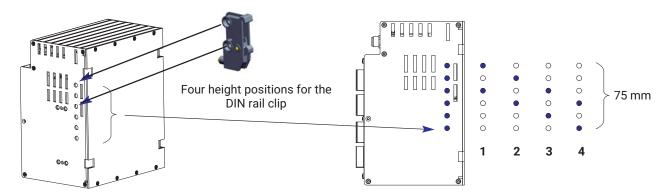
<sup>\*\*\*</sup> See diagram on page 16.

# COMBINATION OPTIONS (WGX001/WGX002)

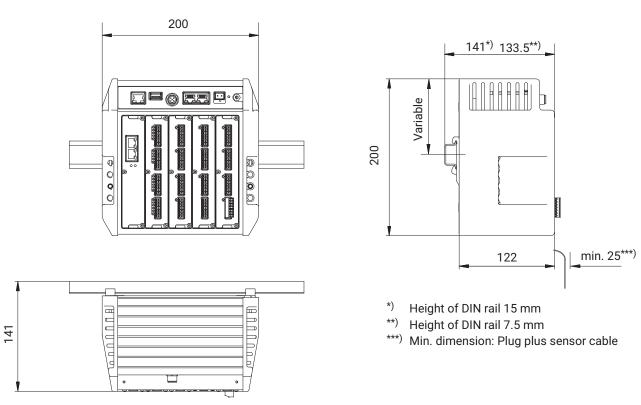
	Slot 0	Slot 1	Slot 2	Slot 3	Slot 4	Number of plug-ins
Fieldbus or real-time Ethernet	Х	-	-	-	-	0-1
PX401	-	х	х	х	х	0-4
PX455	-	х	х	х	х	0-4
PX460	-	х	х	х	х	0-4
PX878	-	х	х	-	-	0-2

Installation/tools	Required tools	Tightening torque
Fastening the rail clip to the DIN rail Hexagon socket screw M2.5	Hexagon socket screwdriver, 2.5 a.f.	1.0 - 1.2 Nm
Fastening the DIN rail clip to the housing Hexagon socket screw M5	Hexagon socket screwdriver, 3 a.f.	5 Nm
Fastening the plug-in card Torx screws M2.5	Torx screwdriver TX8	0.5 - 0.6 Nm
Fastening the wall mount kit Hexagon socket screw M4	Hexagon socket screwdriver, 3 a.f.	3 Nm
Fastening the side parts  Torx screw M3	Torx screwdriver TX10	0.8 - 1 Nm

#### DIN rail clip (included with delivery)



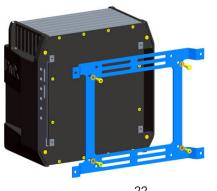
#### Basic device, WGX001/WGX002 for max. 5 plug-in cards

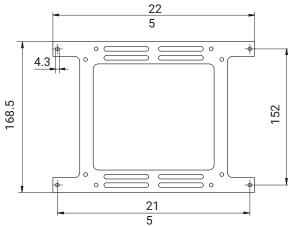


#### **IMPORTANT:**

To ensure sufficient ventilation/cooling, a 2 cm gap must be maintained above and below neighboring devices.

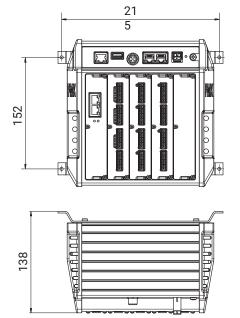
#### Wall mount kit (included with delivery)

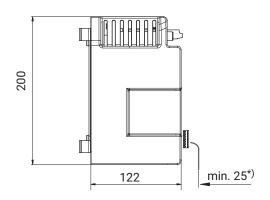






The wall mount kit can also be fitted rotated 90°.





\*) Min. dimension: Plug plus sensor cable

#### **IMPORTANT**:

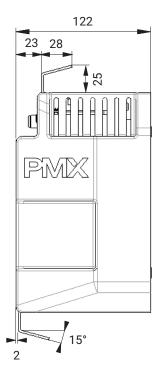
To ensure sufficient ventilation/cooling, a 2 cm gap must be maintained above and below neighboring devices.

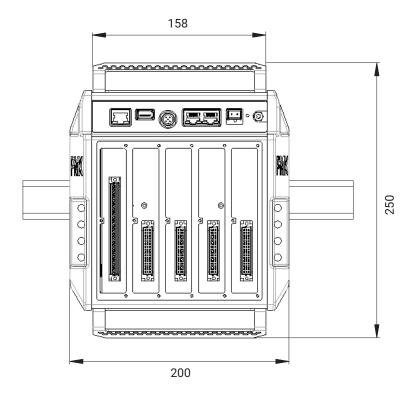
#### INSTALLING CABLE FASTENING PLATES (INCLUDED WITH DELIVERY)



To ensure cables running from and to the PMX are fastened securely and reliably, an optional plate can be mounted at the top and bottom of the PMX basic device to fasten the cables.

Holes in the plate can be used to fasten the cables using cable ties.





#### **ACCESSORIES AND REPLACEMENT PARTS**

Accessories	Ordering number
Ethernet crossover cable	
For direct operation of devices on a PC or notebook, length 2 m, type CAT5+	1-KAB239-2
AC/DC adapter Input: 90 V 264 V, 1.5 m cable Output 24 V <sub>DC</sub> , max. 1.25 A, 2 m cable with ODU plug	1-NTX001
Replacement parts	Ordering number
PX01, PMX blank plate for plug-in card Slot 0	1-PX01
PX02, PMX blank plate for plug-in card Slots 1-4	1-PX02
RAILCLIP, PMX DIN rail mount kit (2x), incl. screws	1-RAILCLIP
Phoenix plug terminals  Set of plug terminals (push-in) for PMX plug-in cards (4 x 7-pin, incl. coding plug and labeling sheets)  Set of screw terminals PMX voltage supply (1 x 2-pin, incl. coding plug and labeling sheets)  Set of plug terminals (push-in) for PMX plug-in cards (2, 13 and 2-pin, incl. coding plug and	1-CON-S1008 1-CON-S1010 1-CON-S1012
labeling sheets)  Mating connector M12x1 for CAN interface for WGX001	1-CON-S1002

In general, the mating connectors are always included for all plug-in cards (PX401, PX455, PX460 and PX878). When ordering a PMX basic device, DIN rail clip, wall mount kit and mating plug are always included with delivery.

#### SPECIFICATIONS FOR NTX001 POWER SUPPLY

NTX001		
Nominal (rated) input voltage (AC)	V	100 240 (±10 %)
No-load power consumption at 230 V	W	0.5
Nominal load		
U <sub>A</sub>	V	24
I <sub>A</sub>	Α	1.25
Static output data		
U <sub>A</sub>	V	24 ± 4 %
IA	Α	0 1.25
U <sub>Br</sub> (output ripple voltage; peak-to-peak)	mV	≤120
Current limiter, typically from	Α	1.6
Galvanic isolation primary – secondary		electrical, by optocoupler and transducer
SG creep and clearances	mm	≥8
High-voltage test	kV	≥4
Ambient temperature	°C	0 +40
Storage temperature	°C	-40 <b>+</b> 70

Web server	
Web server	Integrated web server for full parameterization and operation of the PMX with integrated password protection
User levels	3 levels (Operator, Service, Administrator), Level 2 (Service) can be configured
System requirements for the web browser	Internet Explorer (IE) 9.0 or higher, FireFox or Google Chrome

PC software	Ordering number
catman®Easy software	1-CATMAN-EASY
catman®AP software	1-CATMAN-AP

Software driver	
HBM common API	Function library for integrating PMX amplifiers in their own development environments in Microsoft .NET.
LabVIEW driver <sup>1)</sup>	Universal driver for integrating PMX amplifiers in LabVIEW (LabVIEW 2012 and higher)
DIAdem driver <sup>1)</sup>	Universal driver for integrating PMX amplifiers in DIAdem data acquisition software (for 32-bit DIAdem version 10.1 or higher)

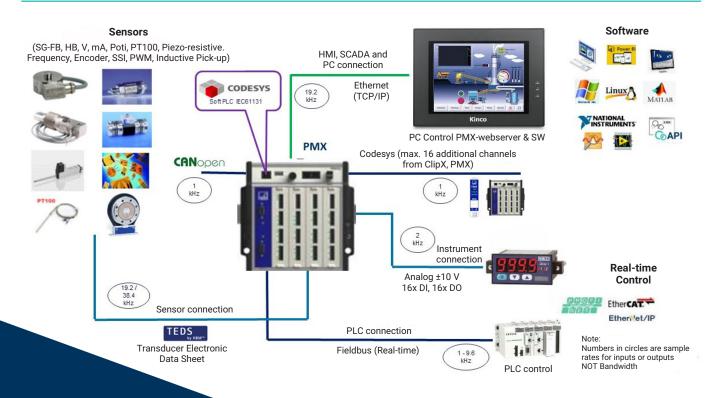
<sup>1)</sup> LabVIEW and DIAdem are registered trademarks of the National Instruments Corporation

#### **NOTE**

All software packages can be downloaded free of charge or as trial versions from the PMX website. They include detailed assistance and program examples for you to run:

https://www.hbm.com/de/2981/pmx-modular-measuring-amplifier-system-for-the-iot/

#### **PMX - CONNECTIVITY**



#### Hottinger Brüel & Kjaer GmbH

 $\label{lem:timefen} Im \ Tiefen \ See \ 45\cdot 64293 \ Darmstadt \cdot Germany \\ Tel. \ +49\ 6151\ 803-0 \cdot Fax \ \ +49\ 6151\ 803-9100 \\ www.hbkworld.com \cdot info@hbkworld.com \\$