Linear models for classification . We szw that we can divide the in put space in regions, and assign a label to each of them decision X, boundary when linear for classification $\hat{f}_{o}(x) = \hat{f}_{o}(x) - \hat{f}_{o}(x)$ 5 fo(m) > fo(m) ~ fo(m) > fo(m) until now: classification based on linear regression Yx f(x) = B + Bx decision boundary between two classes & end & member of $X: \hat{f}_{k}(x) = \hat{f}_{k}(x)$ methods, namely methods based on discriminant functions discliminant functions & (v) posterier lities f_(x) = Pr[G=A | X=x] PotG=Blx=x) f. 4 - Pr[6=C1X=x) linear decision If Sk(x) or Pr[G=K|X=x) are linear in x -s ponuls vies

Adusty, we only need monotone transformation of Si(x) a PilG=KIX=X) to be linear (i) $\hat{S}_{k}(x) = \hat{f}_{k}(y) = \hat{f}_{k_{0}} + \hat{f}_{k_{1}} \times_{1} + \hat{f}_{k_{2}} \times_{2} + \hat{f}_{k_{3}} \times_{1} + \hat{f}_{k_{4}} \times_{2}$ the relationship is linear in the augmented space, but the decision beunclaries are quadratic in the original space lii) when there are two classes $\frac{PrTG=1 \mid X=X}{1+ exp(\beta_0 + \beta^T X)} = \frac{exp(\beta_0 + \beta^T X)}{1+ exp(\beta_0 + \beta^T X)} = \frac{\log i}{1+ exp(\beta_0 + \beta^T X)}$ $\frac{PrTG=1 \mid X=X}{1+ exp(\beta_0 + \beta^T X)} = \frac{1}{1-p}$ Pog Pr[G=11x=x) = Po + BX Linear regression of an Indicator Metrix -codify each of the classes 1, ..., is with an indicator $V_{e}^{(1)} = S_{e}^{(2)}$ $V_{e}^{(1)} = S_{e}^{(2)}$ $V_{e}^{(1)} = S_{e}^{(2)}$ $V_{e}^{(1)} = S_{e}^{(2)}$ $V_{e}^{(2)} =$ -b linear regression: $Y = X(X^TX)^TX^TY$ $N \times K$ $N \times K$ New observation xnew $\hat{y} = \hat{f}(x_{new}) = x_0 \hat{B}$ (f, (Knew) for (Knew)) G(Know) = ergmax Pru)

Yes and no - if intercept is included $\sum_{\kappa=1}^{K} \hat{f}_{\kappa}(x) = 1$ -) fix(x) can be <0 or >1 - problems happen when the new observation is many times it werks outside the traning hull, despite this issue due to the vigidity of likear regression A bigger problem is the so called masking effect -anly if K≥3 As we saw if Fig 4.3, when K=3, it is sufficient to have a quadratic rule. More generally, if we have K classes, we need a curve of degree K-1

Are fx(x) reasonable estimates of Pr[G=x/x=x]?

Why does it work

E[YK | X=x) = Pr[G=K | X=x]

LINEAR DISCRIMINANT ANALYSIS

· from the decision theory (Section ?4) we know that for optimal classification we need to know the class posterior $Pr(G=K \mid X=x)$

Suppose :

suppose:

• fr(x) is the density of x conditional to alres G=K Pr[X=x | G=K]

· IIk(x) is the prior probability to be inclass k, Pr[G=K]

We can choose Ko(x) and TIK(x) as we prefor ...

- When fr(x) is from a multivariate Gaussian distribution, then Linear Discriminant Analysis (LDA) Quadratic Discriminant Analysis (QDA)

fx(x)=\frac{1}{26)\frac{1}{2}\fra

In particular, for LDA we suppose $\Sigma_{\kappa} = \Sigma$

We con then compere two classes by 14 log-ratio log Pr[G=K|X=x] = log () | [| enp { - \frac{1}{2} | k - \rho] \frac{1}{2} | k - \rho] \frac{1}{12} | k - \rho] \frac{1} = Ry Tik - 1 (xTXx-2xTInx+ mZ) / x-xXx+2xTIng = log Th - 1 (Ma+Me) [(Ma-Me) + x [2" (Ma-Me)) the decision boundaries are NoT the perpendicular bisectors of the segments joining the confroids (hyppers only if $\Sigma = \sigma^2 I$) - the linear discriminant function Sk(x) is SK(x) = XT I'Mx - EMX I'Mx + log iik -0G(x) = 2 rgmex &x(x) Since we do not know the values of the parameters lik, Me, Z, we need to estimate them

** Total # of observations in class K

** Total # of observations

· MK = = X: /NK

. Î = E I (x; - Mx) (x; -Mx) (N-K)

With two dasses, there is a simple correspondence between LDA and dassification by linear regression (-> Ex. 4.2) With IS 28, there are substantial differences LDA does NOT suffer from the mesking effect.