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hasCondition(g_i, cg_n) \land \neg isPresent(c_k) \land (c_k \in cg_n) \land tryReach(ag_m, g_i) \rightarrow
                                                            violationCondition(ag_m, g_i, c_k)
                                                                                                       (3)
  hasRelation(g_i, rg_n) \land \neg isPresent(r_k) \land (r_k \in rg_n) \land tryReach(ag_m, g_i) \rightarrow
                                                             violationRelation(ag_m, g_i, r_k)
                                                                                                       (4)
    hasEntity(g_i, eg_n) \land \neg isPresent(e_k) \land (e_k \in eg_n) \land tryReach(ag_m, g_i) \rightarrow
                                                               violationEntity(ag_m, g_i, e_k)
                                                                                                       (5)
             violationCondition(ag_m, g_i, c_k) \land hasRisk(c_k, risk_j, f_m) \rightarrow
                                consequenceOfBadEvent(g_i, ag_m, risk_j, f_m)
                                                                                                       (6)
             violationRelation(ag_m, g_i, r_k) \land hasRisk(r_k, risk_i, f_m) \rightarrow
                               consequenceOfBadEvent(g_i, ag_m, risk_i, f_m)
                                                                                                       (7)
violationRelation(ag_m, g_i, r_k) \land affects(r_k, r_n) \land hasPossibility(r_n, false) \rightarrow
                                                                      hasPossibility(r_n, true) (8)
                        violationEntity(ag_m, g_i, e_k) \rightarrow stopIn(g_i)
                                                                                                       (9)
hasPossibility(r_k, true) \land happensBadEvent(r_k) \land hasRelation(g_i, rg_n) \land (r_k \subset rg_n)
                                                    \land hasRisk(r_k, risk_i, f_m) \land tryReach(ag_m, g_i)
                                                \rightarrow consequenceOfBadEvent(g_i, ag_m, risk_j, f_m)
                                                                                                       (10)
             consequenceOfBadEvent(g_k, ag_m, risk_i, f_m) \rightarrow stopIn(g_k)
                                                                                                      (11)
                 \neg stopIn(g_k, agg_n) \land (ago_n \subset agg_n) \rightarrow isReached(g_k)
                                                                                                      (12)
 hasRole(ag_n, \rho_m) \land hasPermission(\rho_m, g_j) \land nextGoal(g_i, g_j) \land isReached(g_i)
                                                                           \rightarrow tryReach(ag_n, g_j)
                                                                                                      (13)
 hasRole(ag_n, \rho_m) \land hasPermission(\rho_m, g_i) \land lastGoal(g_i, \rho_m) \land isReached(g_i)
                                                                                    \rightarrow stopIn(g_i)
                                                                                                      (14)
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 $hasObligation(\rho_m, g_j) \rightarrow hasPermission(\rho_m, g_j)$

(2)