

FOOD PERISH PREVENTION SYSTEM USING IOT

ARDUINO CODE:

```
#include <DHT.h>

#include <OneWire.h>

#include <DallasTemperature.h>

#include <Wire.h>

#include <LiquidCrystal_I2C.h>


#define DHTPIN 2

#define ONE_WIRE_BUS 3

#define LM35PIN A0

#define RELAY_HEAT 5

#define RELAY_COOL 4


#define BTN_HOT_MODE 6

#define BTN_COLD_MODE 7

#define BTN_SANDWICH 8

#define BTN_PUFFS 9

#define BTN_MILK 12

#define BTN_DRINKS 13


#define DHTTYPE DHT11


DHT dht(DHTPIN, DHTTYPE);

OneWire oneWire(ONE_WIRE_BUS);

DallasTemperature sensors(&oneWire);

LiquidCrystal_I2C lcd(0x27, 16, 2);


bool modeSelected = false;

bool foodSelected = false;
```

```
bool isColdMode = false;
```

```
String foodType = "";
```

```
float tempMin = 0.0;
```

```
float tempMax = 0.0;
```

```
void printLCDAndSerial(int row, const char* msg) {
```

```
    lcd.setCursor(0, row);
```

```
    lcd.print("      ");
```

```
    lcd.setCursor(0, row);
```

```
    lcd.print(msg);
```

```
    Serial.println(msg);
```

```
}
```

```
void blinkAlert() {
```

```
    while (true) {
```

```
        lcd.clear();
```

```
        lcd.setCursor(3, 0);
```

```
        lcd.print("!!! ALERT !!!");
```

```
        lcd.setCursor(3, 1);
```

```
        lcd.print("Sensor Error");
```

```
        Serial.println("!!! ALERT: Sensor error detected !!!");
```

```
        digitalWrite(RELAY_COOL, HIGH);
```

```
        digitalWrite(RELAY_HEAT, HIGH);
```

```
        delay(700);
```

```
        lcd.clear();
```

```
        delay(300);
```

```
    }
```

```
}
```

```
void setup() {
```

```
Serial.begin(115200);
```

```
dht.begin();
```

```
sensors.begin();
```

```
lcd.init();
```

```
lcd.backlight();
```

```
pinMode(RELAY_COOL, OUTPUT);
```

```
pinMode(RELAY_HEAT, OUTPUT);
```

```
digitalWrite(RELAY_COOL, HIGH);
```

```
digitalWrite(RELAY_HEAT, HIGH);
```

```
pinMode(BTN_HOT_MODE, INPUT_PULLUP);
```

```
pinMode(BTN_COLD_MODE, INPUT_PULLUP);
```

```
pinMode(BTN_SANDWICH, INPUT_PULLUP);
```

```
pinMode(BTN_PUFFS, INPUT_PULLUP);
```

```
pinMode(BTN_MILK, INPUT_PULLUP);
```

```
pinMode(BTN_DRINKS, INPUT_PULLUP);
```

```
lcd.clear();
```

```
printLCDAndSerial(0, "Select Mode:");
```

```
printLCDAndSerial(1, "HOT / COLD");
```

```
}
```

```
void loop() {
```

```
  if (!modeSelected) {
```

```
    if (digitalRead(BTN_HOT_MODE) == LOW) {
```

```
      modeSelected = true;
```

```
      isColdMode = false;
```

```
      lcd.clear();
```

```
      printLCDAndSerial(0, "HOT Mode Selected");
```

```
      delay(1000);
```

```
      lcd.clear();
```

```

    printLCDAndSerial(0, "Select Food:");
    printLCDAndSerial(1, "Puffs / Sand.");
    Serial.println("Mode: HOT selected");
}
else if (digitalRead(BTN_COLD_MODE) == LOW) {
    modeSelected = true;
    isColdMode = true;
    lcd.clear();
    printLCDAndSerial(0, "COLD Mode Selected");
    delay(1000);
    lcd.clear();
    printLCDAndSerial(0, "Select Food:");
    printLCDAndSerial(1, "Milk / Drinks");
    Serial.println("Mode: COLD selected");
}
return;
}

```

```

if (!foodSelected) {
    if (isColdMode) {
        if (digitalRead(BTN_MILK) == LOW) {
            foodType = "Milk";
            tempMin = 1.0;
            tempMax = 4.0;
            foodSelected = true;
        }
        else if (digitalRead(BTN_DRINKS) == LOW) {
            foodType = "Drinks";
            tempMin = 5.0;
            tempMax = 8.0;
            foodSelected = true;
        }
    }
}

```

```

} else {
    if (digitalRead(BTN_PUFFS) == LOW) {
        foodType = "Puffs";
        tempMin = 60.0;
        tempMax = 70.0;
        foodSelected = true;
    }
    else if (digitalRead(BTN_SANDWICH) == LOW) {
        foodType = "Sandwich";
        tempMin = 50.0;
        tempMax = 60.0;
        foodSelected = true;
    }
}

if (foodSelected) {
    lcd.clear();
    printLCDAndSerial(0, "Food Selected:");
    printLCDAndSerial(1, foodType.c_str());
    delay(1500);
    lcd.clear();
}

return;
}

float lm35Temp = analogRead(LM35PIN) * (5.0 / 1023.0) * 100.0;
float dhtTemp = dht.readTemperature();
float dhtHum = dht.readHumidity();
sensors.requestTemperatures();
float ds18Temp = sensors.getTempCByIndex(0);

// Alert on sensor error

```

```

100) {
    if (isnan(dhtHum) || isnan(dhtTemp) || ds18Temp == -127.0 || lm35Temp < -20 || lm35Temp >
        blinkAlert();
    }

    bool coolOn = false, heatOn = false;
    if (ds18Temp > tempMax && isColdMode) {
        digitalWrite(RELAY_COOL, LOW);
        digitalWrite(RELAY_HEAT, HIGH);
        coolOn = true;
    }
    else if (ds18Temp < tempMin && !isColdMode) {
        digitalWrite(RELAY_COOL, HIGH);
        digitalWrite(RELAY_HEAT, LOW);
        heatOn = true;
    }
    else {
        digitalWrite(RELAY_COOL, HIGH);
        digitalWrite(RELAY_HEAT, HIGH);
    }

    // Serial debug output
    Serial.println("=== Sensor Readings ===");
    Serial.print("LM35 Temp: "); Serial.println(lm35Temp);
    Serial.print("DHT11 Temp: "); Serial.println(dhtTemp);
    Serial.print("Humidity: "); Serial.println(dhtHum);
    Serial.print("DS18B20 Temp: "); Serial.println(ds18Temp);
    Serial.print("Cooling Relay: "); Serial.println(coolOn ? "ON" : "OFF");
    Serial.print("Heating Relay: "); Serial.println(heatOn ? "ON" : "OFF");
    Serial.print("Selected Food: "); Serial.println(foodType);
    Serial.println("=====");

    // LCD Output

```

```

lcd.setCursor(0, 0);

lcd.print("T:");

lcd.print(ds18Temp, 1);

lcd.print((char)223);

lcd.print("C ");

if (coolOn) lcd.print("C:ON ");
else if (heatOn) lcd.print("H:ON ");
else lcd.print("STBY ");

char line2[17];

snprintf(line2, sizeof(line2), "H:%d%% %s", (int)dhtHum, foodType.c_str());

lcd.setCursor(0, 1);

lcd.print("      ");

lcd.setCursor(0, 1);

lcd.print(line2);

delay(5000);
}

```

ESP01 Wifi Module Code

```

#include <ESP8266WiFi.h>

#include <WiFiClient.h>

const char* ssid = "<Wifi_Name>";

const char* password = "<Wifi_Password>";

const char* host = "api.thingspeak.com";

const char* apiKey = "5WD8MGBI66TQXEHT";

WiFiClient client;

```

```

void setup() {
  Serial.begin(9600); // Connect to Arduino
  delay(1000);

  WiFi.begin(ssid, password);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.println("Connecting to WiFi...");
  }

  Serial.println("Connected to WiFi!");
  Serial.print("IP Address: ");
  Serial.println(WiFi.localIP());
}

void loop() {
  if (Serial.available()) {
    String data = Serial.readStringUntil('\n');
    data.trim(); // remove whitespace or \r
    Serial.println("Received from Arduino: " + data);

    // Split the data
    int idx1 = data.indexOf(',');
    int idx2 = data.indexOf(',', idx1 + 1);
    int idx3 = data.indexOf(',', idx2 + 1);

    if (idx1 > 0 && idx2 > idx1 && idx3 > idx2) {
      String val1 = data.substring(0, idx1);          // ds18Temp
      String val2 = data.substring(idx1 + 1, idx2);    // dhtTemp
      String val3 = data.substring(idx2 + 1, idx3);    // lm35Temp
      String val4 = data.substring(idx3 + 1);          // dhtHum
    }
  }
}

```



```

if (client.connect(host, 80)) {
    String url = "/update?api_key=" + String(apiKey) +
        "&field1=" + val1 +
        "&field2=" + val2 +
        "&field3=" + val3 +
        "&field4=" + val4;

    client.print(String("GET ") + url + " HTTP/1.1\r\n" +
        "Host: " + host + "\r\n" +
        "Connection: close\r\n\r\n");

    Serial.println("Data sent to ThingSpeak!");
    Serial.println("URL: " + url);
} else {
    Serial.println("Connection to ThingSpeak failed.");
}
} else {
    Serial.println("Invalid data format received.");
}

delay(2000); // optional delay between uploads
}
}

```