Terminal 1 untuk command roscore

```
Conscient http://ENOVO-11311/
--bash: /opt/ros/kinetic/sstup.bash: No such file or directory
-bash: /opt/ros/kinetic/sstup.bash: No such file of disk as directory
-bash: /opt/ros/kinetic/sstup.bash: No such file of disk as directory
-bash: /opt/ros/kinetic/sstup.bash: No such file of disk as directory
-bash: /opt/ros/kinetic/sstup.bash: No such file of disk as directory
-bash: /opt/ros/kinetic/sstup.bash: No such file of disk as directory
-bash: /opt/ros/kinetic/sstup.bash: No such file of disk as directory
-bash: /opt/ros/kinetic/sstup.bash: No such file of disk as directory
-bash: /opt/ros/kinetic/sstup.bash: No such file of disk as directory
-bash: /opt/ros/kinetic/sstup.bash: /opt/ros/kinetic/sstup.bash: /opt/ros/kinetic/sstup.bas
```

Terminal 2 untuk catkin_make

```
| dentguernovo: "/caron_ws
entgle:NDMO:-5 cd catkin_ws
entgle:NDMO:-5 cd catkin_ws
catkin_ms
ase path: /home/dent/catkin_ws
ource space: /home/dent/catkin_ws/build
evel space: /home/dent/catkin_ws/build
evel space: /home/dent/catkin_ws/devel
nstall space: /home/dent/catkin_ws/install
dent@LENOVO: ~/catkin_ws
Install space: /home/dent/catkin_ws/install
```

Terminal 3 untuk rosrun publisher_subscriber publisher_node(untuk node publisher)

```
Odent@LENOVC: "/catkin_ws"

-bash: /opt/ros/kinetic/setup.bash: No such file or directory
-bash: /opt/ros/kinetic/setup.bash: No such file or directory
dentalENOVC: -$ source devel/setup.bash
-bash: devel/setup.bash: No such file or directory
dentalENOVC: -$ cd catkin_ws
dentalENOVC: -$ cd catkin_ws
source devel/setup.bash
dentalENOVC: -⟨catkin_ws$ source devel/setup.bash
dentalENOVC: -⟨catkin_ws$ rosrun publisher_subscriber publisher_node
```

Terminal 4 untuk rosrun publisher_subscriber subscriber_node(untuk node subscriber)

