

Geometry

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Lecture 1: Introduction

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1 Surfaces

1.1 Topological Surfaces

We start with some definitions.

Definition 1.1. A *topological surface* is a topological space Σ such that

1. **T1:** $\forall p \in \Sigma$ there is an open neighborhood $p \in U \subseteq \Sigma$ such that U is homeomorphic to \mathbb{R}^2 , or a disc $D^2 \subseteq \mathbb{R}^2$ with its usual Euclidean topology.
2. **T2:** Σ is Hausdorff and second countable.

Remark. We have the following remarks.

1. $\mathbb{R} \cong D(0, 1)$.
2. A space X is *Hausdorff* if for $p \neq q \in X$, there exists disjoint open sets $p \in U$ and $q \in V$ in X .
3. A space X is *second countable* if it has a countable base i.e. $\exists \{u_i\}_{i \in \mathbb{N}}$ open sets s.t. every open set is a union of some u .
4. **T1** is the point and **T2** is for technical honesty.
5. If X is Hausdorff/ second countable, so are subspaces of X . In particular, Euclidean space has these properties. (For second countable, consider open balls with rational center and rational radius).

Example. Here we present some examples of topological surfaces.

1. \mathbb{R}^2 the plane
2. Any open subset of \mathbb{R}^2 , i.e. $\mathbb{R}^2 \setminus Z$ where Z is closed:

- $Z = \{0\}$,
- $Z = \{(0, 0)\} \cup \{(0, \frac{1}{n} \mid n = 1, 2, 3, \dots)\}$.

3. Graphs:

Let $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ be a continuous function. The graph $\Gamma_f = \{(x, y, f(x, y)) \mid (x, y) \in \mathbb{R}^2\} \subseteq \mathbb{R}^3$ (subspace topology).

Recall that if X, Y are spaces, the product topology on $X \times Y$ has basic open sets $U \times V$ with U open and V open.

It has the feature that $f : Z \rightarrow X \times Y$ is continuous if and open if the two projective maps are continuous.

Application: $\Gamma_f \subseteq X \times Y$, if $f : X \rightarrow Y$ is continuous, if homeomorphic to X .

So $\Gamma_f \cong \mathbb{R}^2$ for any $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ that is continuous, so Γ_f is a topological surface.

Note. As a topological surface, Γ_f is independent of f , but later on as a geometric object, it will reflect features of f .

4. The sphere (subspace topology):

$$S^2 = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 + z^2 = 1\}.$$

Stereographic projection

$$\begin{aligned} \pi_+ : S^2 \setminus \{(0, 0, 1)\} &\rightarrow \mathbb{R}^2 \\ (x, y, z) &\mapsto \left(\frac{x}{1-z}, \frac{y}{1-z} \right) \end{aligned}$$

Note. The map is continuous and has an inverse, π_+ is a continuous bijection with continuous inverse, and hence a homeomorphism.

Stereographic projection from the South Pole is also a homeomorphism from $S^2 \setminus \{(0, 0, -1)\} \rightarrow \mathbb{R}^2$.

So S^2 is a topological surface:

$\forall p \in S^2$, either p lies in the domain of π_+ or of π_- (or both) and so it lies in an open set homeomorphic to \mathbb{R}^2 . (And Hausdorff and second countable from \mathbb{R}^2).

Remark. S^2 has a global property as it is compact as a topological space, since it is a closed bounded set in \mathbb{R}^3 .

5. The real projective plane:

The group $\mathbb{Z}/2$ acts on S^2 by homeomorphism via the *antipodal map* $a : S^2 \rightarrow S^2$.

$$a(x, y, z) = (-x, -y, -z).$$

i.e. There exists a homomorphism $\mathbb{Z}/2\mathbb{Z} \rightarrow \text{Homeo}(S^2)$, such that it maps the non-identity element to the antipodal map.

Commutative diagram

Stereographic projection graph

Explicit formula for inverse

Definition 1.2. The *real projective plane* is the quotient space of S^2 given by identifying every point with its antipodal image:

$$\mathbb{RP}^2 = S^2/\mathbb{Z}/2\mathbb{Z}.$$

Lemma 1.1. As a set, \mathbb{RP}^2 is naturally in bijection with the set of straight lines in \mathbb{R}^3 through the origin.

Proof. Any straight line that goes through the origin meets the sphere exactly twice, and any such pair determines a straight line. ■

Graph of
the sphere

Lemma 1.2. \mathbb{RP}^2 is a topological surface.

Proof. We check that it is Hausdorff:

Recall if X is a space and $q : X \rightarrow Y$ is a quotient map, $V \subseteq Y$ is open $\iff q^{-1}V \subseteq X$ open.

More balls

If $[p], [q] \in \mathbb{RP}^2$, then $\pm p, \pm q \in S^2$ are distinct antipodal pairs. Take small open discs around p, q and their antipodal images, as in the picture. ■