

# Real-Time Operating System (Day 1 Lab)

**Jong-Chan Kim** 

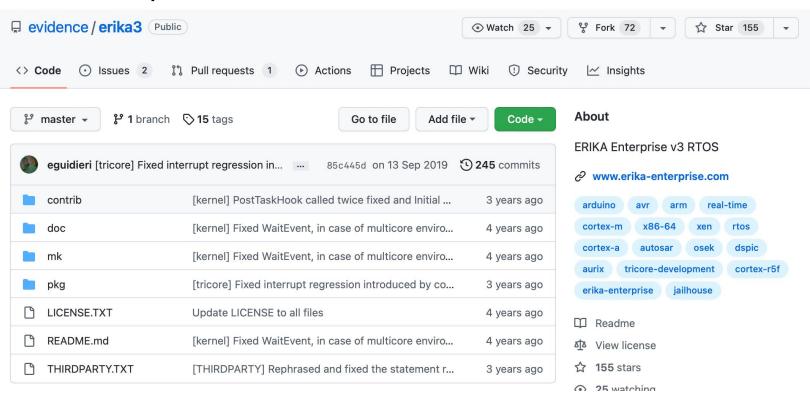
**Graduate School of Automotive Engineering** 



## **Erika Enterprise**



- 이탈리아 EVIDENCE에서 개발된 오픈소스 OSEK/VDX RTOS 구현체
- 듀얼 라이센스 정책 (오픈소스 라이센스 + 상용 라이센스)
- RTOS 연구 및 교육에 널리 사용
- GitHub 리포





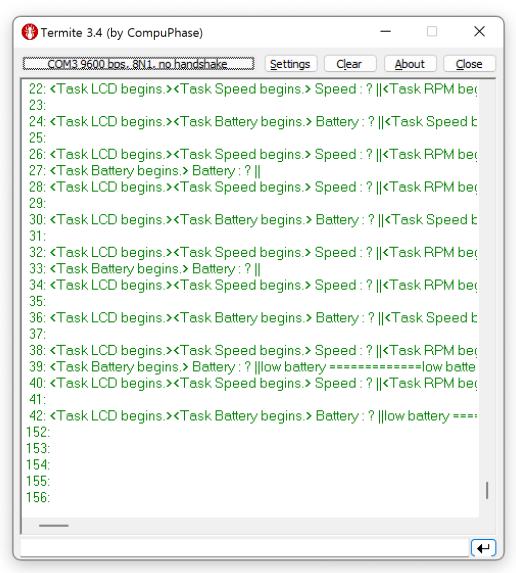
# Eclipse 기반 IDE

- 프로젝트 생성
- OIL 파일, C/C++ 파일 편집
- 프로젝트 빌드
- 실행파일 다운로드

```
eclipse-workspace - E1. Task/asw.c - Eclipse IDE
File Edit Source Refactor Navigate Search Project Run Window Help
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Pr... × $ Co... □ □
                     asw.c 🖂 🎳 conf.oil 🚨 asw.c 🚨 asw.c 🚨 ee oo api o...
                       1 #include "ee.h"
 > 🚝 E1. Task
                       2 #include "Arduino.h"
 > 55 E10, PCP
                       3 #include "serial.h"
 > 1 E11. Complex
 > 📂 E2. Task 2
                       5 void mdelay(unsigned long delay ms);
 > 👺 E3. ISR
 > F4. Alarm
                       7 /* Timer1 ISR2 */
 > E5. Event
                       8 ISR2(TimerISR)
 > 5 E6. Hook
                       9 {
                             static long c = 0;
 > 📂 E7. Integrity
                      10
                             static uint8 t state = 0;
 > E8. Deadlock
                      11
 > 👺 E9. PriorityInversion
                      12
                      13
                             printfSerial("\n%4ld: ", c++);
                      149
                      15
                             if(state == 0) {
                      16
                                 ActivateTask(Task1);
                     Problems 🔊 Tasks 💂 Console 🖾 🔲 Properties 🦏 Progress
                                                      <terminated> New configuration [Program] C:\Program Files (x86)\Arduino\hardware\tools\avr\
                     avrdude.exe: 5882 bytes of flash written
                     avrdude.exe: verifying flash memory against C:\Users\jongchank\ec
                     avrdude.exe: load data flash data from input file C:\Users\jongch
                     avrdude.exe: input file C:\Users\jongchank\eclipse-workspace\E1.
                     avrdude.exe: reading on-chip flash data:
                     avrdude.exe: verifying ...
                     avrdude.exe: 5882 bytes of flash verified
                     avrdude.exe done. Thank you.
F1. Task
```

## Termite 시리얼 콘솔

• 경량 시리얼 터미널



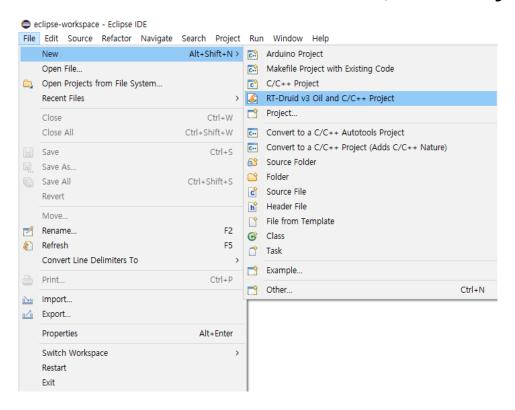
다운로드: https://www.compuphase.com/software\_termite.htm

## 프로젝트 생성

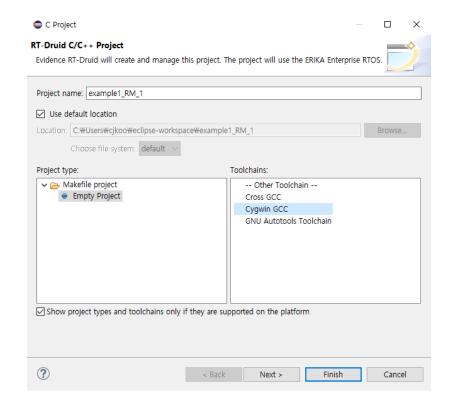
#### 1. 새 프로젝트

File -> New

-> RT-Druid v3 Oil and C/C++ Project

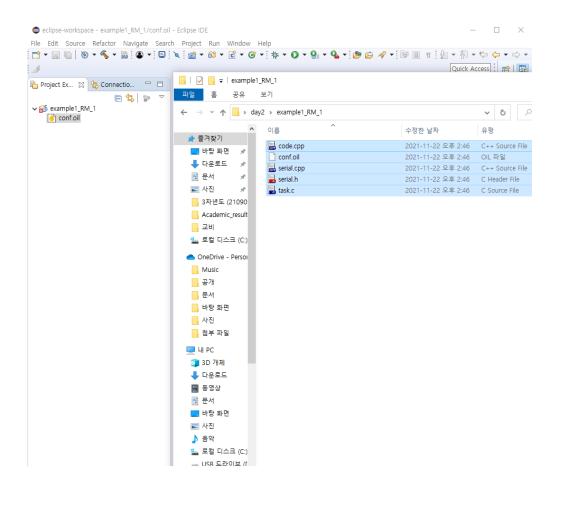


#### 2. 프로젝트 이름 입력 및 Cygwin GCC 선택



## 프로젝트 생성

#### 3. 파일 카피



#### 4. 디렉토리 생성 확인

```
- □ ×
   eclipse-workspace - example1_RM_1/conf.oil - Eclipse IDE
 File Edit Source Refactor Navigate Search Project Run Window Help
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Solution  

Conf.oil 

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✓ 

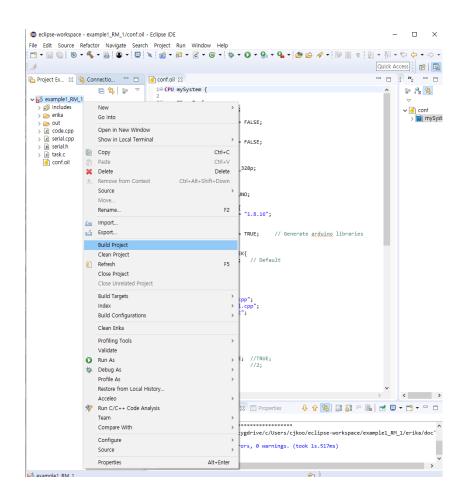
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conf

              > 📂 erika
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                 > 📂 out
            > 🕝 code.cpp
                                                                                                                                                                                                                                                                                                                             CPU DATA = AVR8{
              > 🕝 serial.cpp
                                                                                                                                                                                                                                                                                                                                                    MULTI_STACK = FALSE;
               > In serial.h
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               > 🖟 task.c
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                                                                                                                                                                                                                                                                                                                             LIB = ARDUINO{
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                                                                                                                                                                                                                                                                                                                                                      VARIANT = CC{
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                                                                                                                                                                                                                                                                                                                                                      STAND_ALONE = TRUE; // Generate arduino libraries
                                                                                                                                                                                                                                                   24
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                                                                                                                                                                                                                                                                                                                             KERNEL_TYPE = OSEK{
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                                                                                                                                                                                                                                                                                                  };
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                                                                                                                                                                                                                                                                                                     APPDATA myApp {
                                                                                                                                                                                                                                                                                                                           APP_SRC = "code.cpp";
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                                                                                                                                                                                                                                                                                                                           APP_SRC = "task.c";
                                                                                                                                                                                                                                                                                                 };
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                                                                                                                                                                                                                                                     39
                                                                                                                                                                                                                                                                                                                             PRIORITY = 1;
                                                                                                                                                                                                                                                     40
                                                                                                                                                                                                                                                                                                                           STACK = SHARED;
                                                                                                                                                                                                                                                     41
                                                                                                                                                                                                                                                                                                                           SCHEDULE = FULL;
                                                                                                                                                                                                                                                     42
                                                                                                                                                                                                                                                                                                                             AUTOSTART = FALSE; //TRUE;
                                                                                                                                                                                                                                                     43
                                                                                                                                                                                                                                                                                                                             ACTIVATION = 1; //2;
                                                                                                                                                                                                                                                     44
                                                                                                                                                                                                                                                     45
                                                                                                                                                                                                                                                     46⊖
                                                                                                                                                                                                                                                                                                     TASK Task2 {
```

# 프로젝트 생성

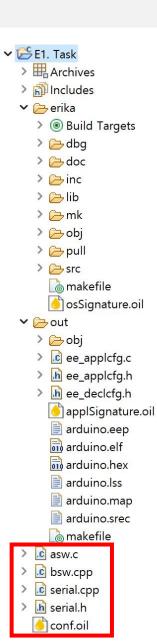
#### 5. 우클릭 & Build Project



## 프로젝트 구조

- 사용자 코드
  - -OIL 파일
  - C/C++ 파일 (TASK와 ISR)

- > c asw.c
- > c bsw.cpp
- > 🖻 serial.cpp
- > h serial.h
  - onf.oil

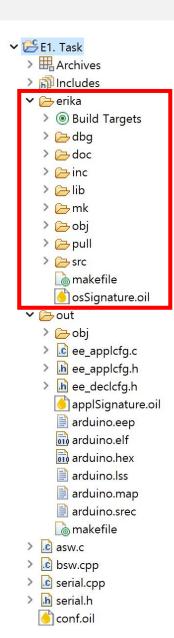


## 프로젝트 구조

- Erika Enterprise 파일
  - 커널 소스
  - -커널 헤더파일

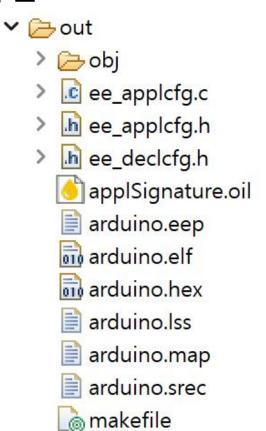


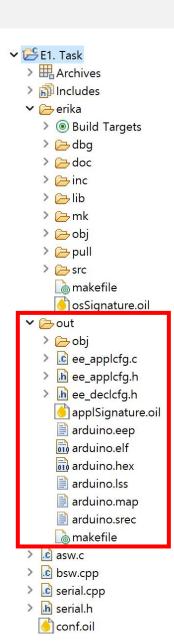
- > <a>® Build Targets</a>
- > 🗁 dbg
- > 🗁 doc
- > inc
- > (=) lib
- > > mk
- > 🗁 obj
- > 🗁 pull
- > 🗁 src
  - 🚵 makefile
  - \delta osSignature.oil



## 프로젝트 구조

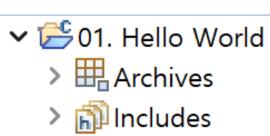
- Output 파일
  - OIL에서 자동 생성된 ...cfg.c와 ...cfg.h 파일
  - ELF 파일
  - 다운로드를 위한 HEX 파일





## 기본 소스코드 구성

- asw.c
  - 사용자 작성 C 코드 (C++도 가능)
- bsw.cpp & bsw.h
  - OS가 시작되는 main() 함수
  - mdelay() ms 단위 delay 함수
  - printfSerial() 콘솔 출력 함수
- conf.oil
  - OSEK 설정 파일

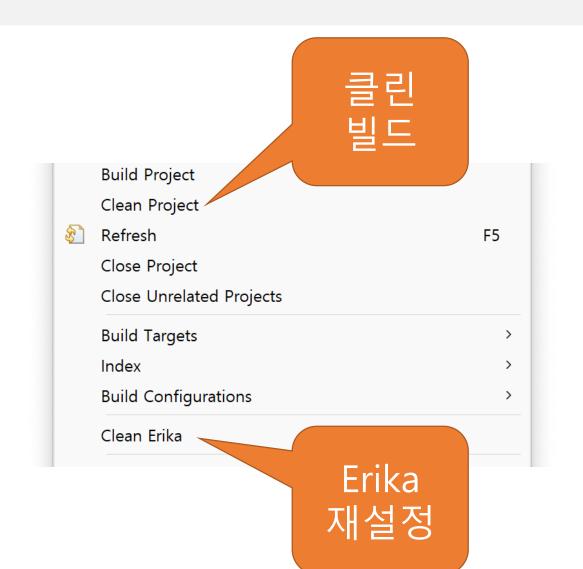


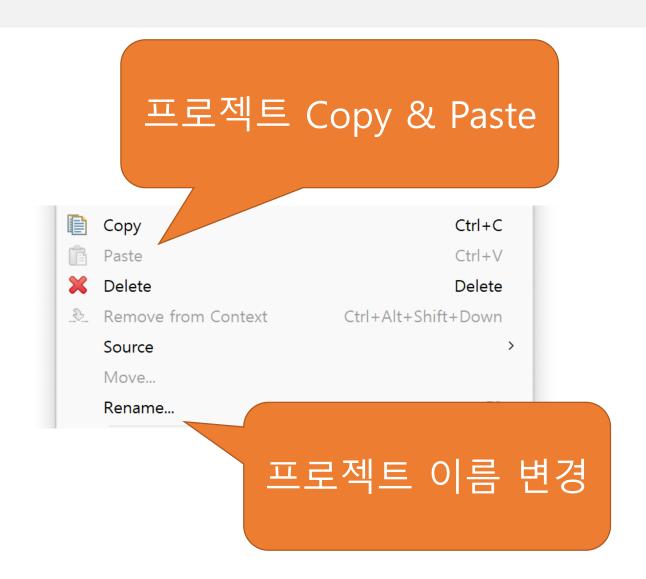
- > 🗁 erika
- > out
  > asw.c
  > bsw.cpp
- > h bsw.h
  conf.oil

# 버튼



# 프로젝트 우클릭





#### 01. Hello World

- 다운로드
  - bsw.cpp
  - bsw.h
  - conf.oil
- asw.c 작성
- OIL 파일에 TASK 추가

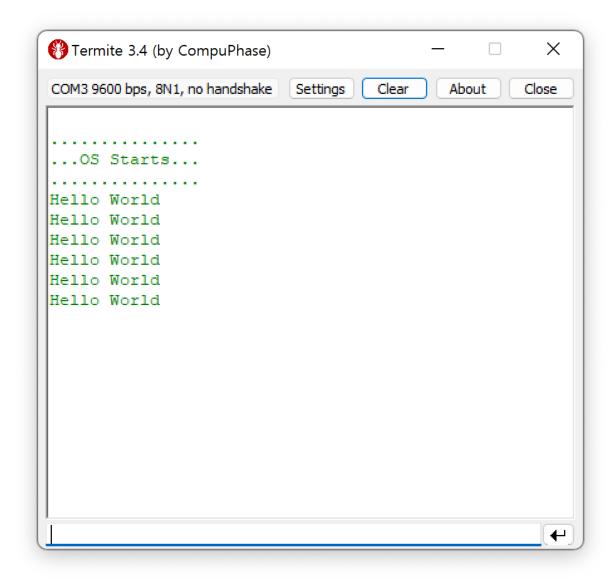
```
#include "bsw.h"

TASK(Task1)
{
    printfSerial("Hello World\n");
    TerminateTask();
}
```

```
TASK Task1 {
    PRIORITY = 1;
    STACK = SHARED;
    SCHEDULE = FULL; // preemptive
    AUTOSTART = TRUE;
    ACTIVATION = 1;
};
```

### 01. Hello World

- OS 시작 후
- Hello World 반복 출력
  - 타이머 초기화 안됨



## 02. Timer

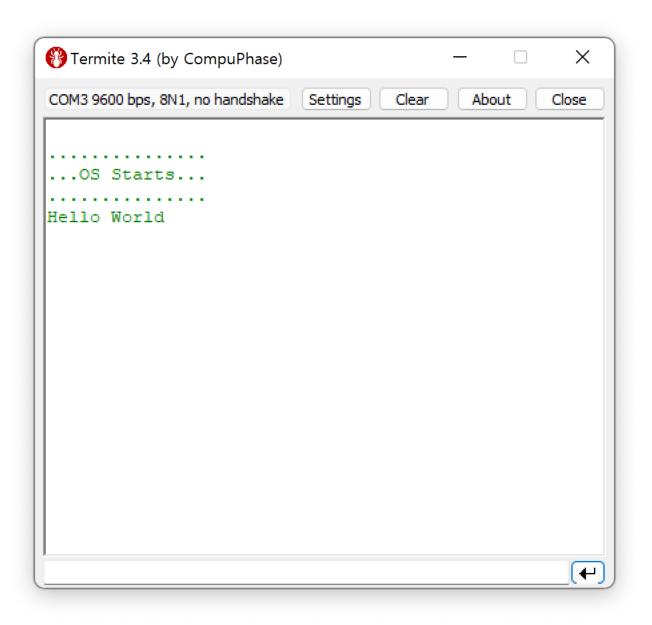
- C 파일에 ISR2로 빈 TimerISR 추가
- OIL 파일에 TimerISR 추가
  - Category 2
  - Timer 1 Compare Match A

```
ISR2(TimerISR)
{
   ;
}
```

```
ISR TimerISR {
    CATEGORY = 2;
    SOURCE = "TIMER1_COMPA";
};
```

## 02. Timer

• Hello World 한번 출력

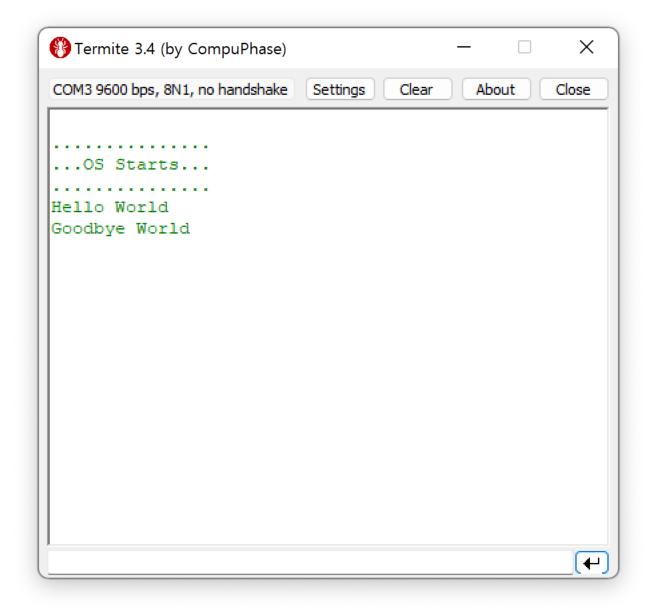


## 03. mdelay

• mdelay 함수 이용 3초 실행시간

```
TASK(Task1)
{
    printfSerial("Hello World\n");
    mdelay(3000);

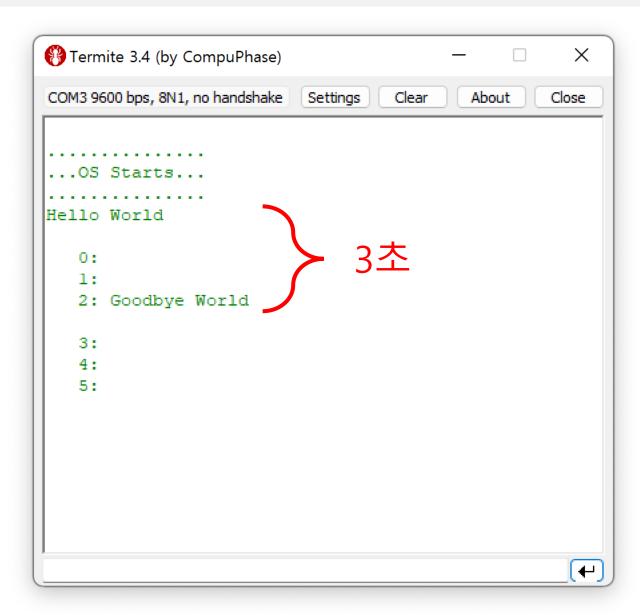
    printfSerial("Goodbye World\n");
    TerminateTask();
}
```



### 04. Timeline

• TimerISR 이용 초단위 시간 출력

```
ISR2(TimerISR)
{
    static long c = 0;
    printfSerial("\n%41d: ", c++);
}
```



## 05. Tasks

```
TASK(Task1)
    printfSerial("Task1 Begins...");
    mdelay(3000);
    printfSerial("Task1 Finishes...");
    TerminateTask();
TASK(Task2)
    printfSerial("Task2 Begins...");
    mdelay(3000);
    printfSerial("Task2 Finishes...");
    TerminateTask();
```

• 우선순위 2의 Task2 추가

```
TASK Task2 {
    PRIORITY = 2;
    STACK = SHARED;
    SCHEDULE = FULL; // preemptive
    AUTOSTART = TRUE;
    ACTIVATION = 1;
};
```

### 05. Tasks

- Task2가 먼저 시작
- Task2 종료 후 Task1 시작
- 우선순위를 바꾼다면?

```
Termite 3.4 (by CompuPhase)
                                                          X
COM3 9600 bps, 8N1, no handshake Settings
                                                       Close
                                      Clear
                                               About
...OS Starts...
Task2 Begins...
   0:
   2: Task2 Finishes...Taskl Begins...
   3:
   5: Taskl Finishes...
   6:
   7:
   8:
```

#### 06. Task Activation

```
ISR2(TimerISR)
                                           TASK(Task2)
                                               printfSerial("Task2 Begins...");
    static long c = -4;
    if (c == 0)
                                               mdelay(3000);
        ActivateTask(Task1);
                                               printfSerial("Task2 Finishes...");
    printfSerial("\n%4ld: ", c++);
                                               TerminateTask();
                                           TASK Task1 {
TASK(Task1)
                                               AUTOSTART = FALSE;
    printfSerial("Task1 Begins...");
    mdelay(3000);
                                           };
    ActivateTask(Task2);
    mdelay(3000);
                                           TASK Task2 {
    printfSerial("Task1 Finishes...");
    TerminateTask();
                                               AUTOSTART = FALSE;
                                           };
```

## 06. Task Activation

- Timeline -4부터 카운트다운
- Task2의 Task1 선점 확인
- ActivateTask 위치 바꾸면?
- 우선순위가 바뀌면?
- ChainTask 활용
- Task3까지 만들어서 연쇄 실행

```
Termite 3.4 (by CompuPhase)
                                                          X
COM3 9600 bps, 8N1, no handshake
                            Settings
                                                        Close
                                               About
...OS Starts...
  -4:
  -2:
   0: Taskl Begins...
   1:
   2:
   3: Task2 Begins...
   4:
       Task2 Finishes...
   9: Taskl Finishes...
  10:
  11:
  12:
                                                           ₽
```

#### 07. GetTaskID

```
TASK(Task1)
                                               TASK(Task2)
   TaskType id;
                                                   TaskType id;
    printfSerial("Task1 Begins...");
                                                   printfSerial("Task2 Begins...");
   mdelay(3000);
                                                   mdelay(3000);
   ActivateTask(Task2);
                                                   GetTaskID(&id);
   mdelay(3000);
                                                   printfSerial("Task ID = %d...", id);
   GetTaskID(&id);
                                                   printfSerial("Task2 Finishes...");
    printfSerial("Task ID = %d...", id);
                                                   TerminateTask();
    printfSerial("Task1 Finishes...");
    TerminateTask();
```

### 07. GetTaskID

• 자연수 Task ID 확인

```
Termite 3.4 (by CompuPhase)
                                                        X
COM3 9600 bps, 8N1, no handshake Settings
                                    Clear
                                             About
                                                     Close
  -4:
  -3:
  -2:
  -1:
   0: Taskl Begins...
   1:
   3: Task2 Begins...
   4:
   6: Task ID = 2...Task2 Finishes...
   9: Task ID = 1...Taskl Finishes...
  10:
  11:
  12:
  13:
  14:
                                                        ₩]
```

### 08. GetTaskState

```
TASK(TaskM)
   printState(Task1);
   printState(Task2);
   TerminateTask();
TASK TaskM {
    PRIORITY = 3;
    STACK = SHARED;
    SCHEDULE = FULL;
    AUTOSTART = FALSE;
    ACTIVATION = 1;
};
```

```
void printState(TaskType id) {
    TaskStateType state;
    if (GetTaskState(id, &state) == E_OK) {
        switch (state) {
            case SUSPENDED:
                printfSerial("%d: suspended...", id);
                break;
            case READY:
                printfSerial("%d: ready...", id);
                break:
            case WAITING:
                printfSerial("%d: waiting...", id);
                break;
            case RUNNING:
                printfSerial("%d: running...", id);
                break;
```

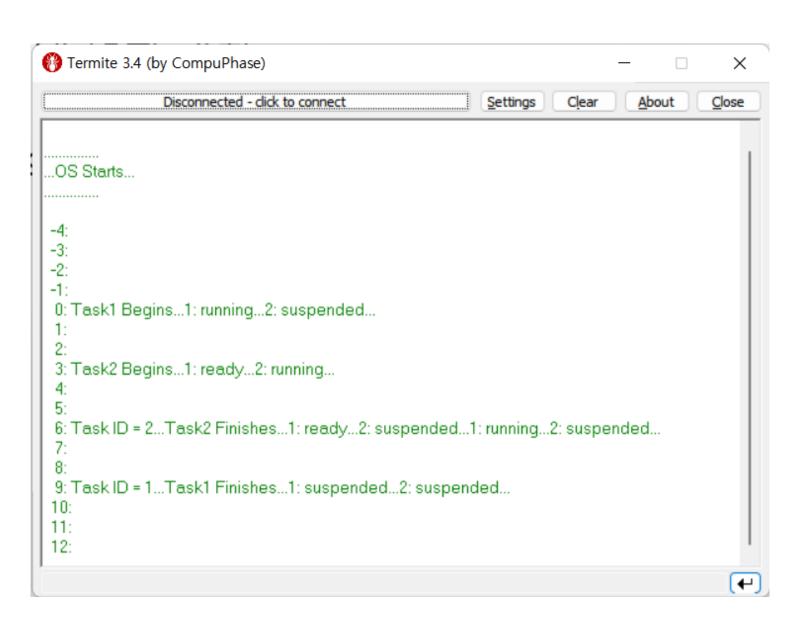
#### 08. GetTaskState

```
TASK(Task1)
                                               TASK(Task2)
    TaskType id;
                                                   TaskType id;
    printfSerial("Task1 Begins...");
                                                   printfSerial("Task2 Begins...");
    PrintState(Task1);
                                                   PrintState(Task1);
    PrintState(Task2);
                                                   PrintState(Task2);
   mdelay(3000);
                                                   mdelay(3000);
   ActivateTask(Task2);
                                                   GetTaskID(&id);
                                                   printfSerial("Task ID = %d...", id);
    PrintState(Task1);
                                                   printfSerial("Task2 Finishes...");
    PrintState(Task2);
   mdelay(3000);
                                                   ChainTask(TaskM);
   GetTaskID(&id);
    printfSerial("Task ID = %d...", id);
    printfSerial("Task1 Finishes...");
    ChainTask(TaskM);
```

### 08. GetTaskState

• Task 상태 변화 관찰

• 우선순위, Activation 패턴 변화의 영향은?



# **Questions**

