

Generative Modeling with Succinct Representation Learning via Wyner's Common Information

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Problem setting

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Alice was beginning to get very tired of sitting ...when suddenly a White Rabbit with pink eyes ran close by her ...see it pop down a large rabbit-hole under the hedge.



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the bird has a white body,
black wings, and webbed
orange feet



a blue bird with gray
primaries and secondaries
and white breast and throat

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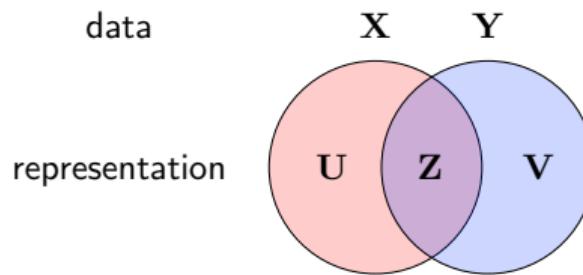
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 - **Cross-domain retrieval:** Given a query \mathbf{x} , retrieve **relevant** \mathbf{y} 's from a pool $\{\mathbf{y}_i\}_{i=1}^n$

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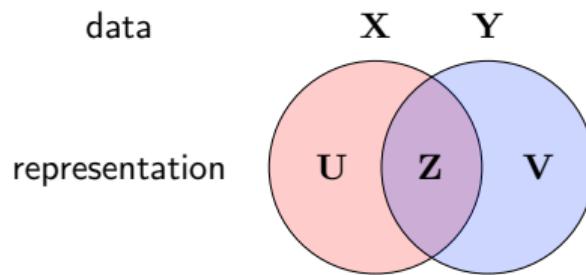
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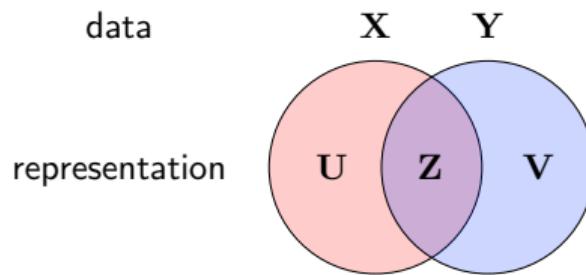
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 - a.k.a. cross-domain disentanglement problem



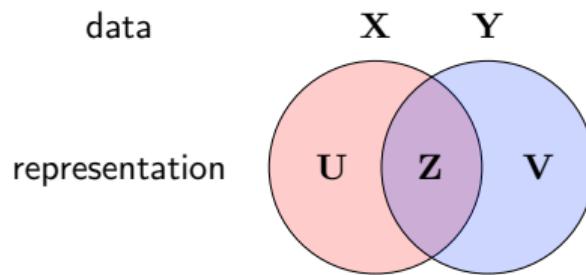
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- **Proposal:** use Wyner's common information to learn succinct common representation



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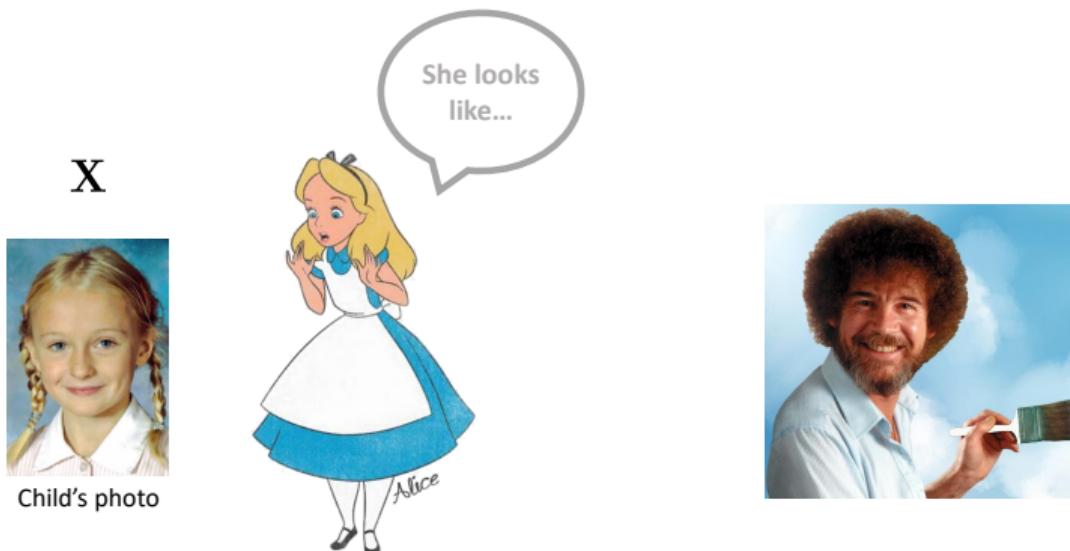


Child's photo



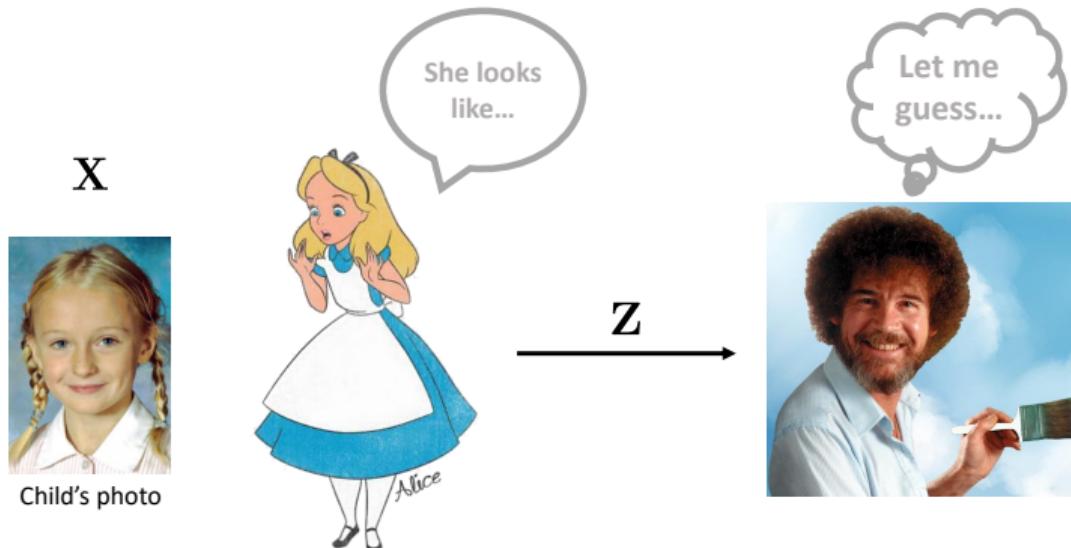
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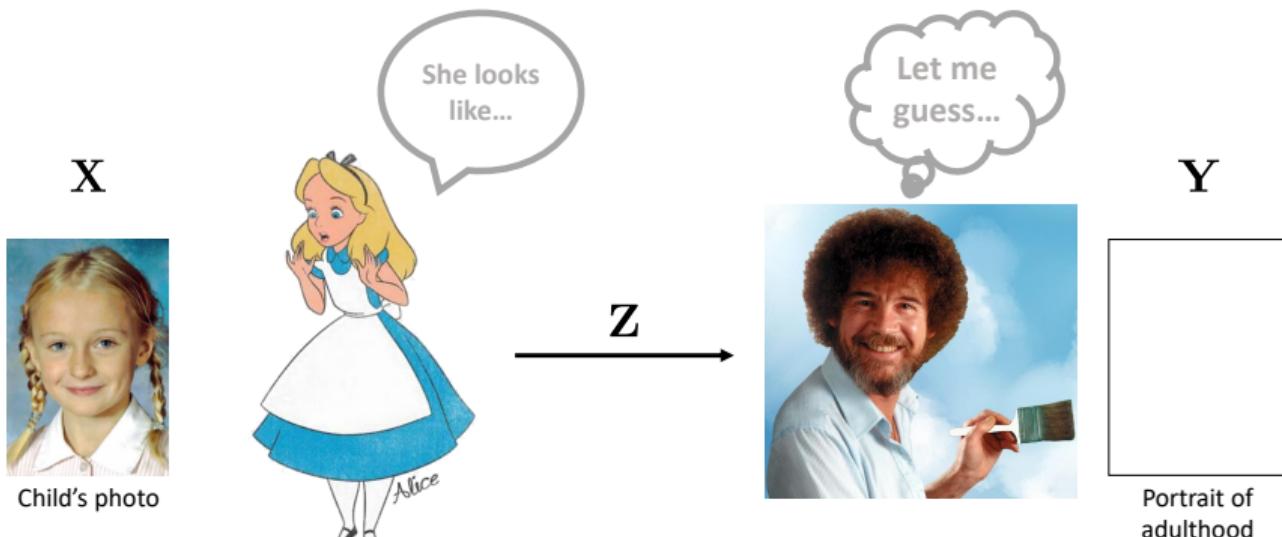
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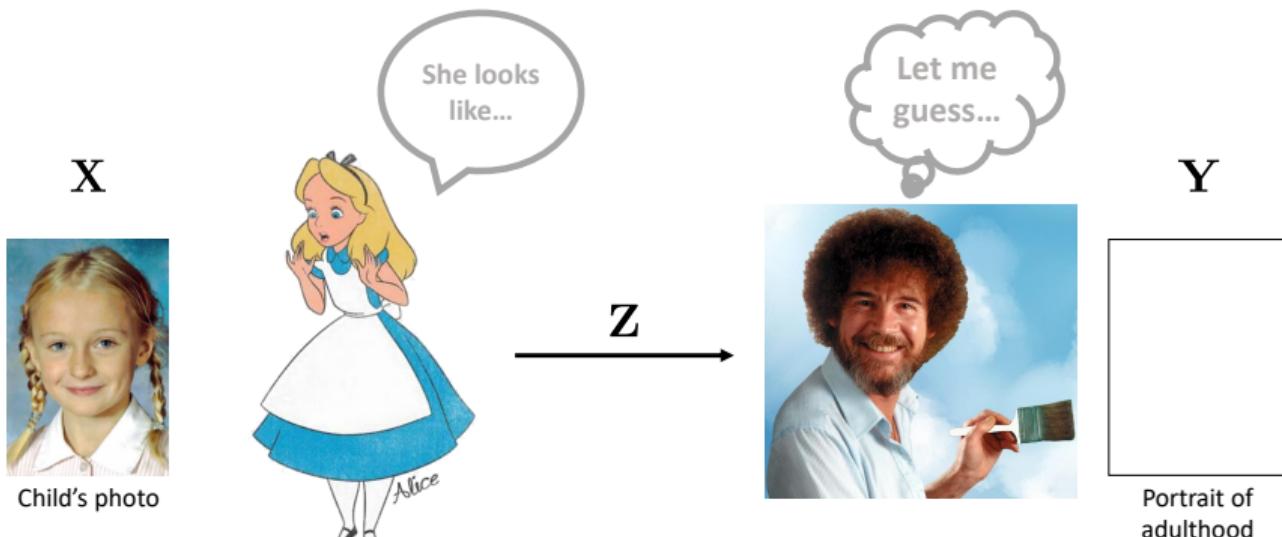
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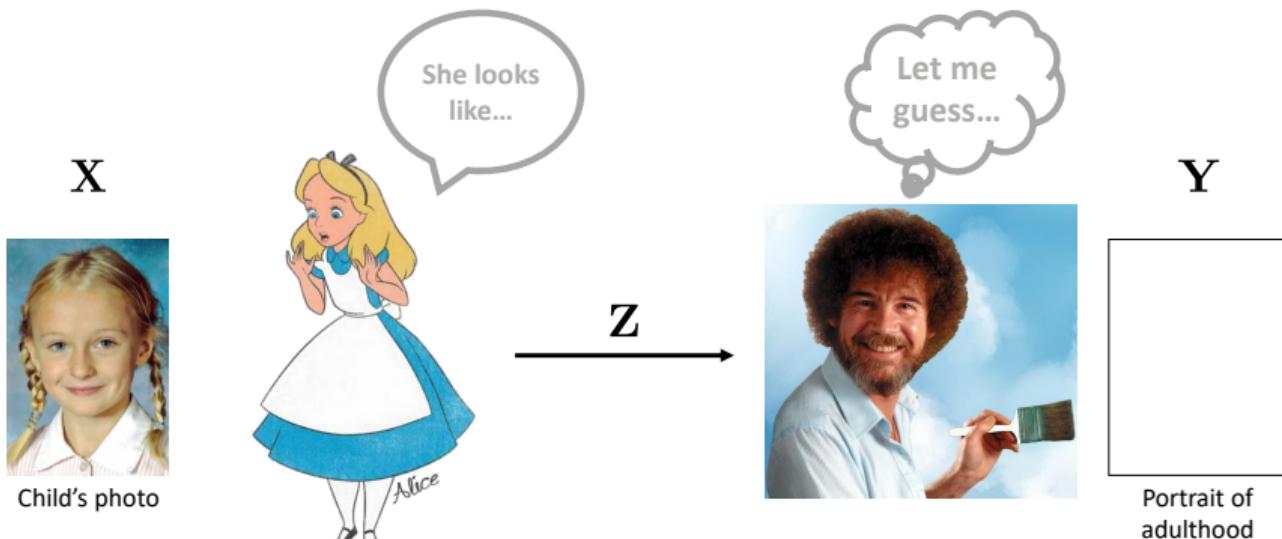
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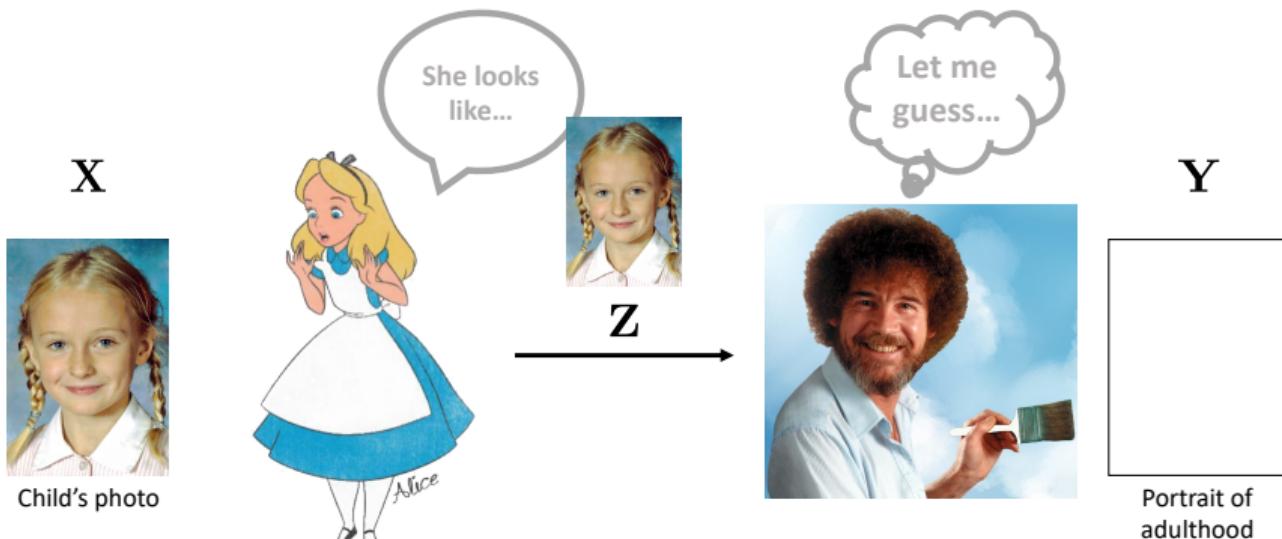
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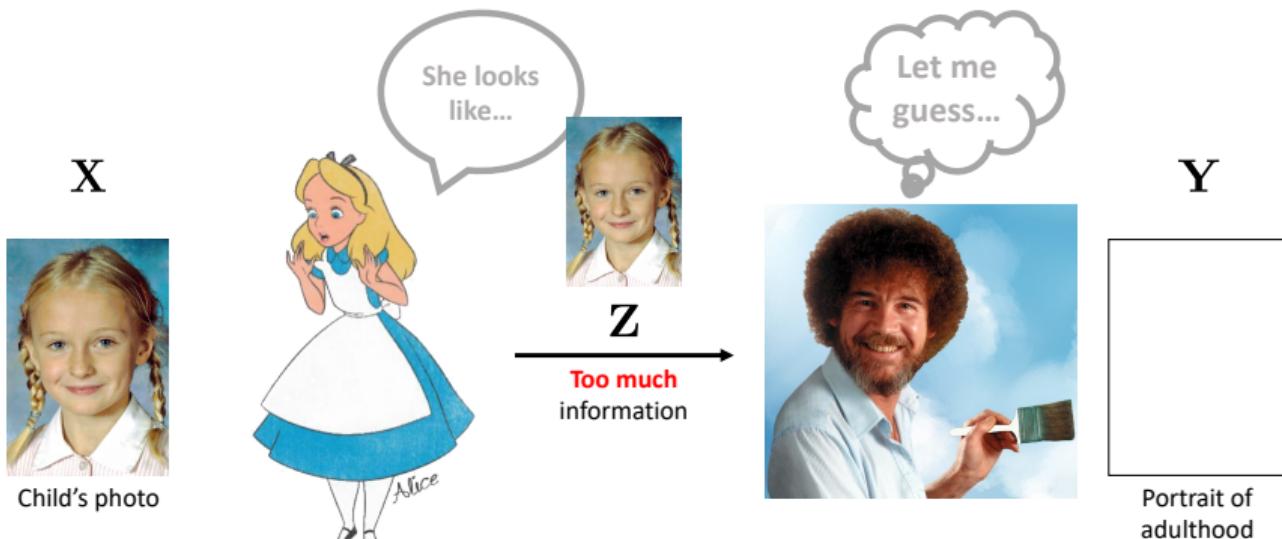
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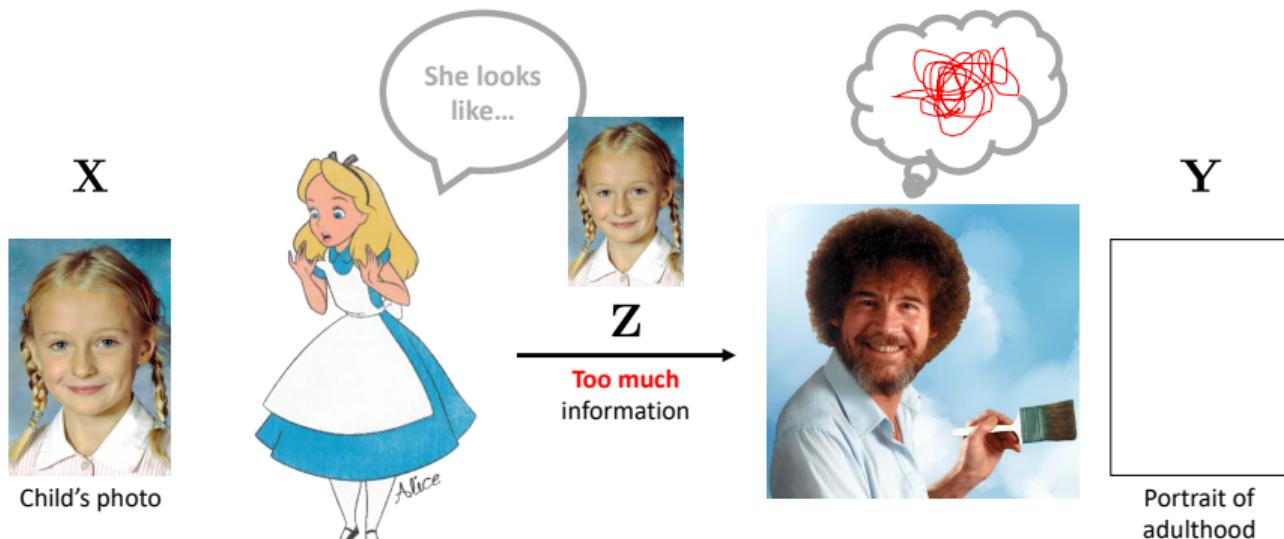
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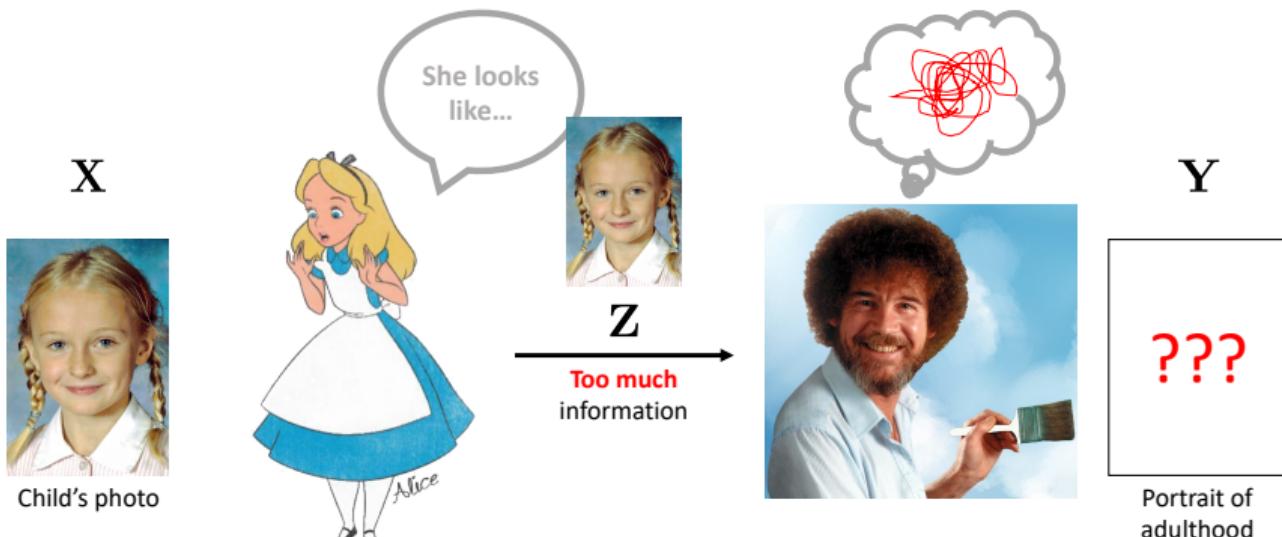
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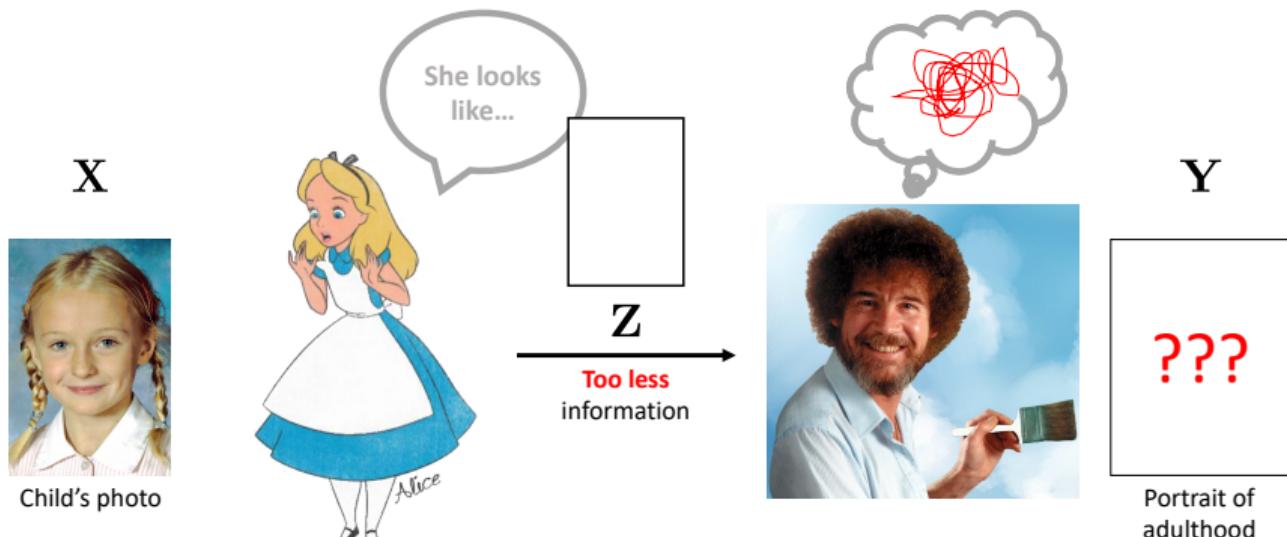
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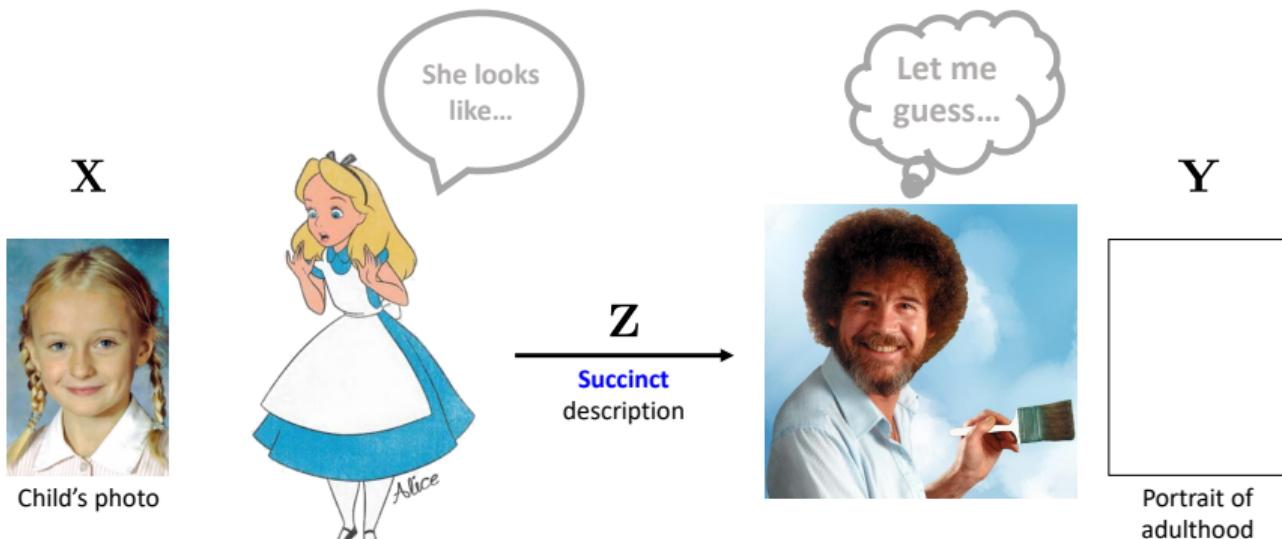
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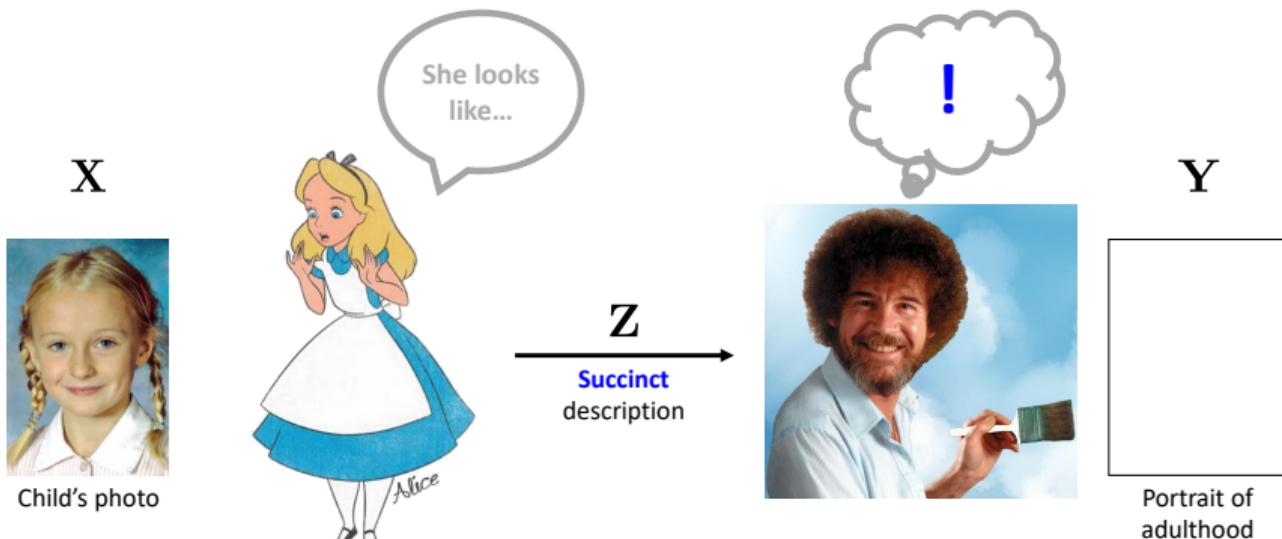
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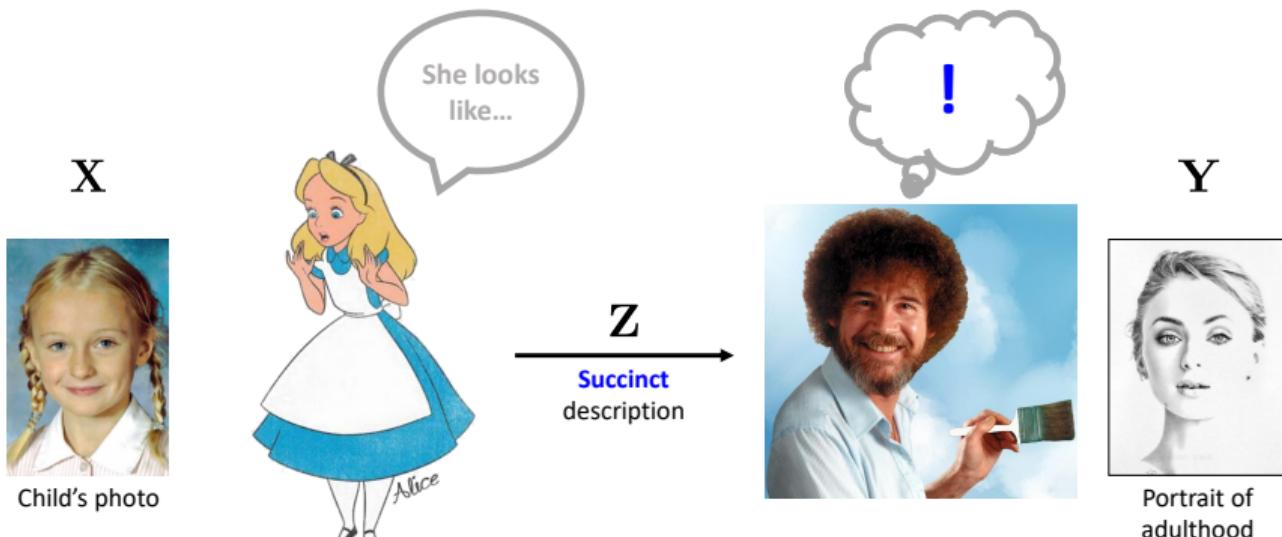
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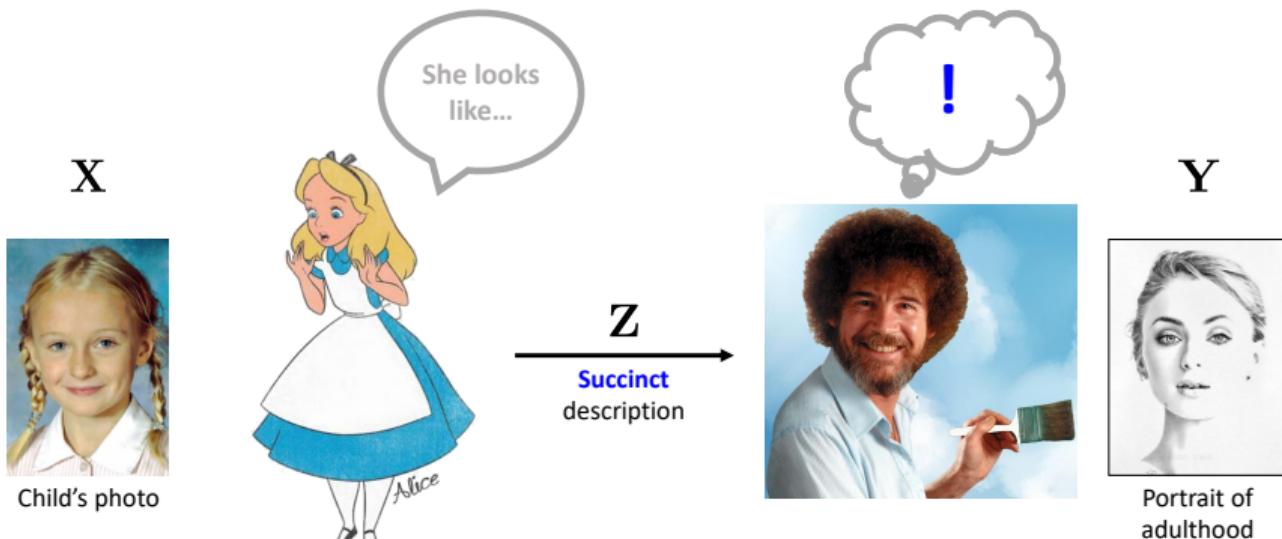
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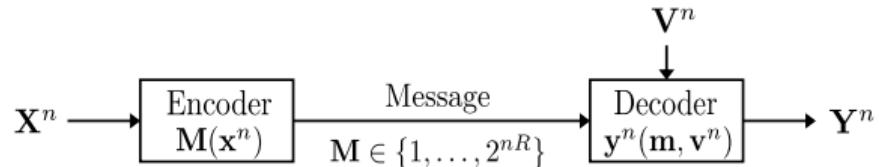
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- Alice can maximally help Bob by providing the most "succinct" description!



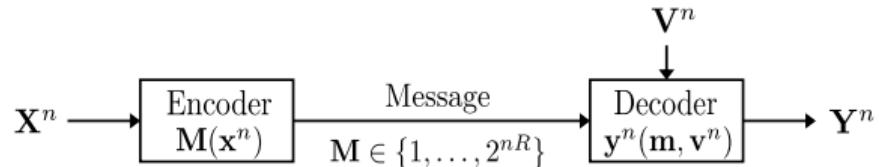
Channel synthesis (Cuff 2013)

- **Problem:** simulate a channel $q(y|x)$ by communicating nR bits



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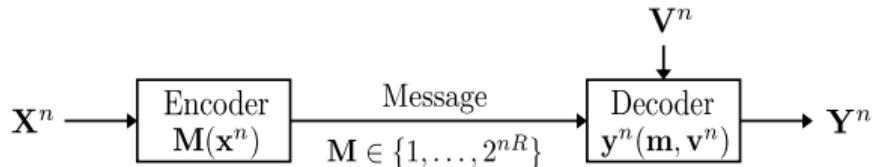
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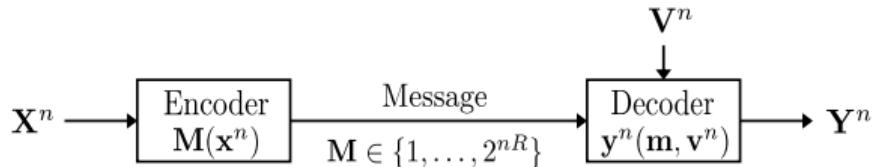


- **Question:** What is the minimum rate R^* ?
- **Answer:** Wyner's common information $R^* = J(\mathbf{X}; \mathbf{Y})$

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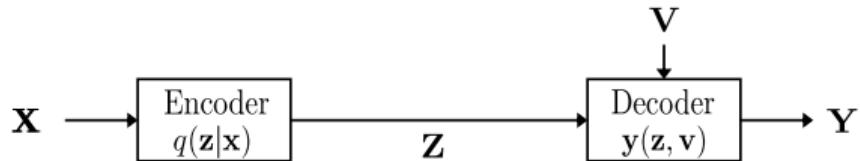
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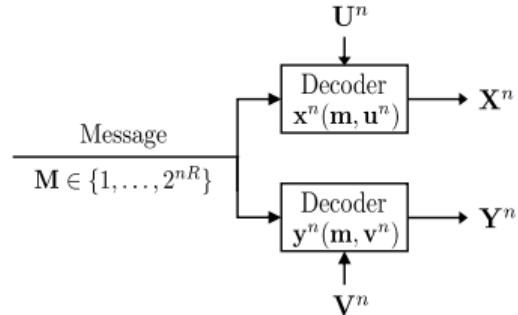
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- Single-letter characterization



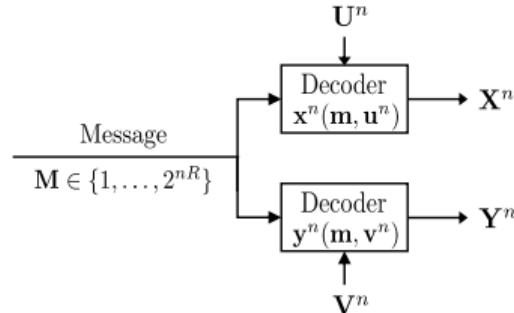
Distributed simulation (Wyner 1975)

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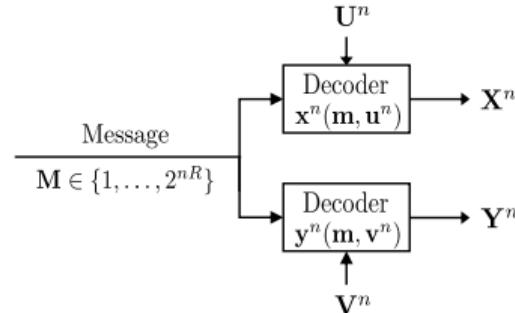
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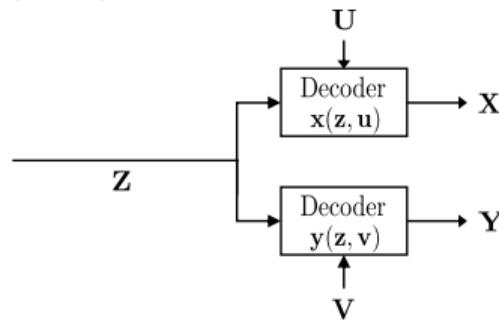
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Learning distributions based on Wyner's common information

- Channel synthesis → conditional generation
- Distributed simulation → joint generation
- Joint and conditional distributions share the same common information structure

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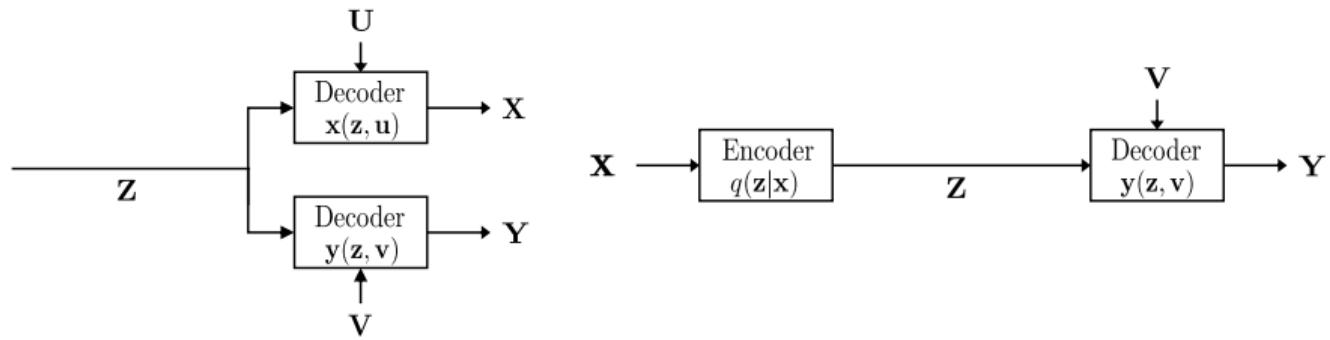
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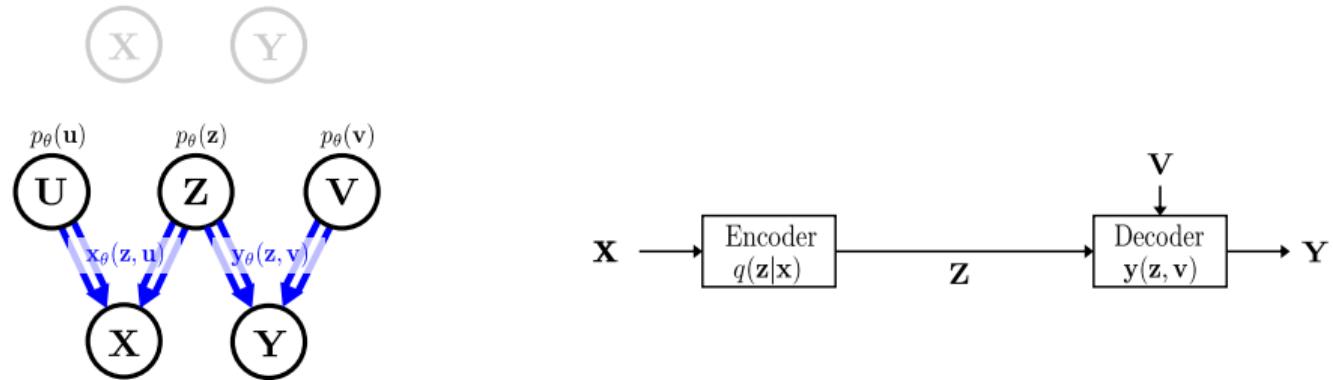
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- We will fit the generative models to data based on Wyner's optimization problem

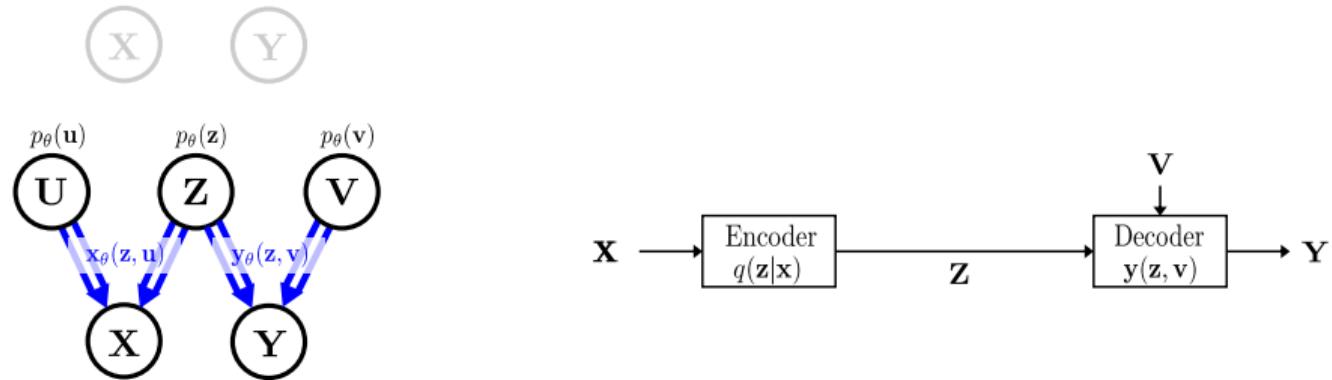
Probabilistic model for joint and conditional sampling



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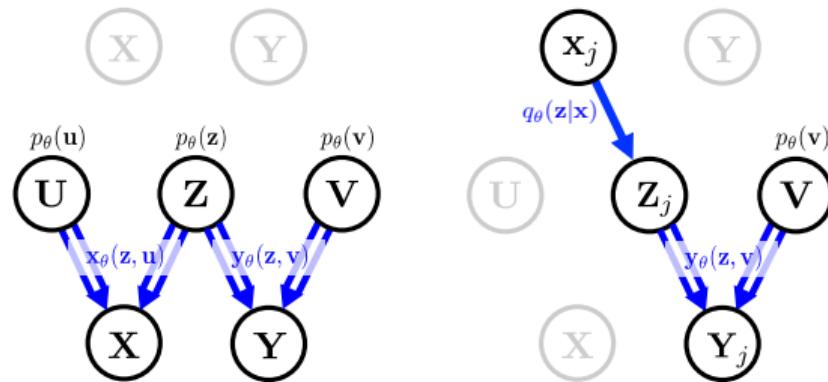


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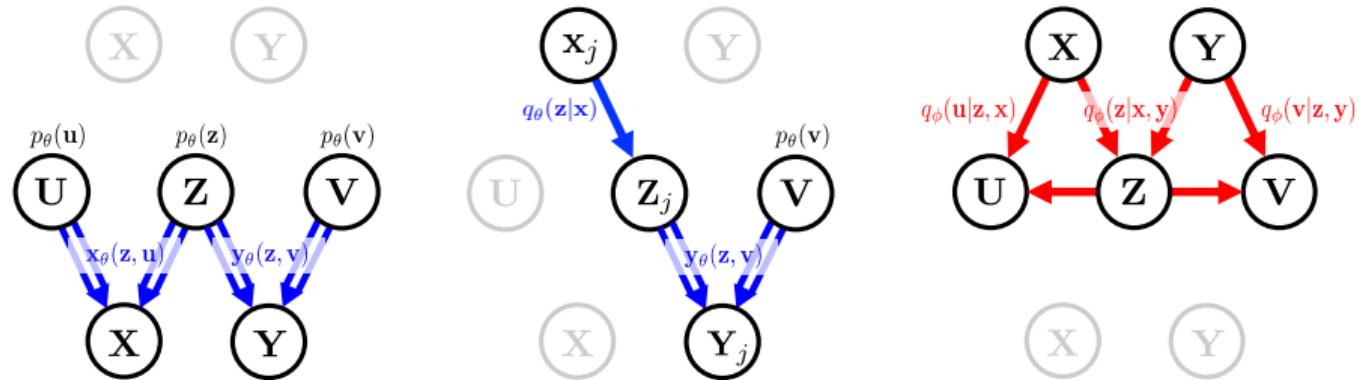
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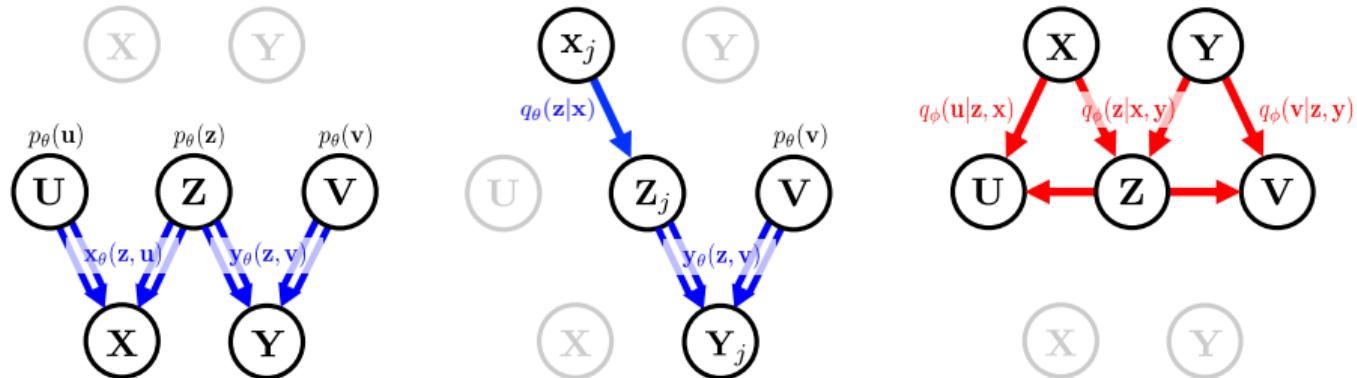
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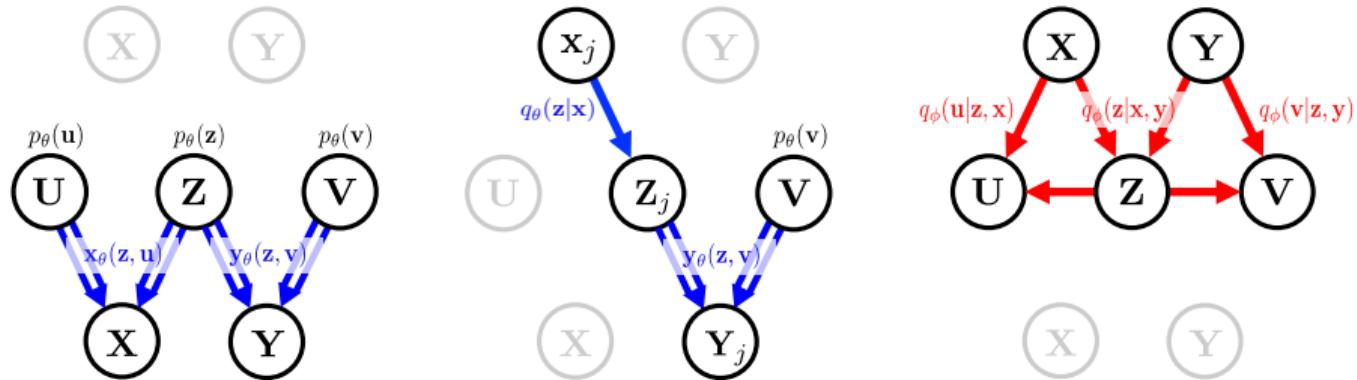
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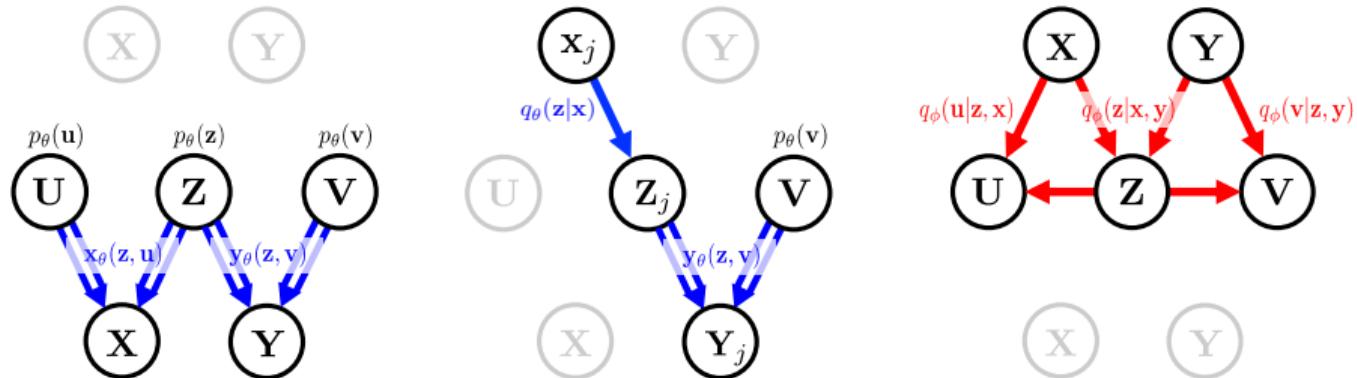
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- Call these components in entirety the **variational Wyner model**

Probabilistic model for joint and conditional sampling



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 - Call these components in entirety the variational Wyner model
- $\left. \begin{array}{l} \text{model } \theta \\ \text{variational } \phi \end{array} \right\}$

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- Decoders: $x_\theta(z, u), y_\theta(z, v)$
 - Priors (source of randomness): common $p_\theta(z)$, local $p_\theta(u), p_\theta(v)$
 - Model (marginal) encoders: $q_\theta(z|x), q_\theta(z|y)$
 - Variational encoders: joint $q_\phi(z|x, y)$, local $q_\phi(u|z, x), q_\phi(v|z, y)$
 - Call these components in entirety the **variational Wyner model**
- decoders p
encoders q

Training objectives

- The variational Wyner model induces four distributions:

joint

cond. ($x \rightarrow y$)

cond. ($y \rightarrow x$)

variational

Training objectives

- The variational Wyner model induces four distributions:

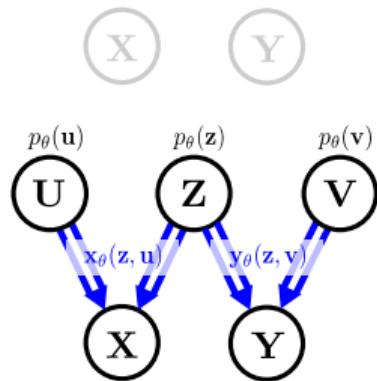
joint

$$p_{\rightarrow xy}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq p_\theta(\mathbf{z})p_\theta(\mathbf{u})p_\theta(\mathbf{v})\delta(\mathbf{x} - \mathbf{x}_\theta(\mathbf{z}, \mathbf{u}))\delta(\mathbf{y} - \mathbf{y}_\theta(\mathbf{z}, \mathbf{v}))$$

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cond. ($y \rightarrow x$)

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Training objectives

- The variational Wyner model induces four distributions:

joint

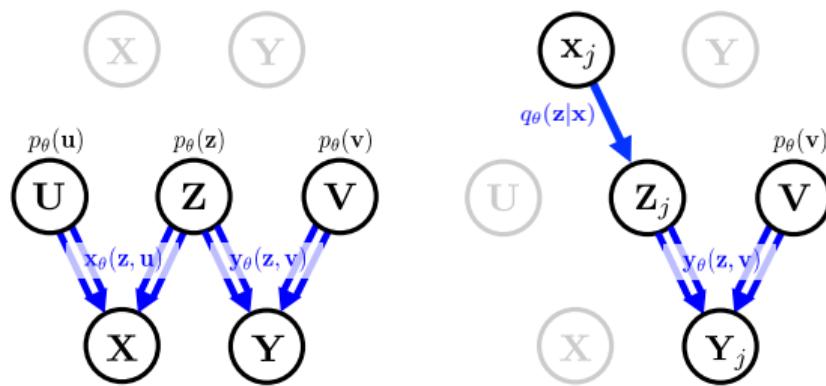
$$p_{\rightarrow xy}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq p_\theta(\mathbf{z})p_\theta(\mathbf{u})p_\theta(\mathbf{v})\delta(\mathbf{x} - \mathbf{x}_\theta(\mathbf{z}, \mathbf{u}))\delta(\mathbf{y} - \mathbf{y}_\theta(\mathbf{z}, \mathbf{v}))$$

cond. ($\mathbf{x} \rightarrow \mathbf{y}$)

$$p_{x \rightarrow y}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{v}) \triangleq q(\mathbf{x})q_\theta(\mathbf{z}|\mathbf{x})p_\theta(\mathbf{v})\delta(\mathbf{y} - \mathbf{y}_\theta(\mathbf{z}, \mathbf{v}))$$

cond. ($\mathbf{y} \rightarrow \mathbf{x}$)

variational



Training objectives

- The variational Wyner model induces four distributions:

joint

$$p_{\rightarrow xy}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq p_\theta(\mathbf{z})p_\theta(\mathbf{u})p_\theta(\mathbf{v})\delta(\mathbf{x} - \mathbf{x}_\theta(\mathbf{z}, \mathbf{u}))\delta(\mathbf{y} - \mathbf{y}_\theta(\mathbf{z}, \mathbf{v}))$$

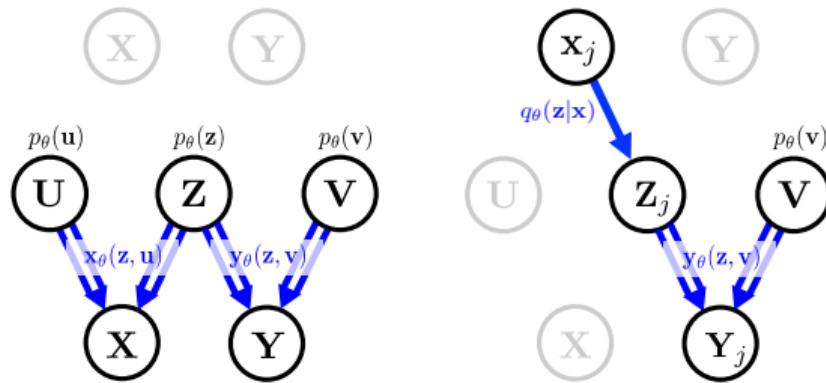
cond. ($x \rightarrow y$)

$$p_{x \rightarrow y}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{v}) \triangleq q(\mathbf{x})q_\theta(\mathbf{z}|\mathbf{x})p_\theta(\mathbf{v})\delta(\mathbf{y} - \mathbf{y}_\theta(\mathbf{z}, \mathbf{v}))$$

cond. ($y \rightarrow x$)

$$p_{y \rightarrow x}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}) \triangleq q(\mathbf{y})q_\theta(\mathbf{z}|\mathbf{y})p_\theta(\mathbf{u})\delta(\mathbf{x} - \mathbf{x}_\theta(\mathbf{z}, \mathbf{u}))$$

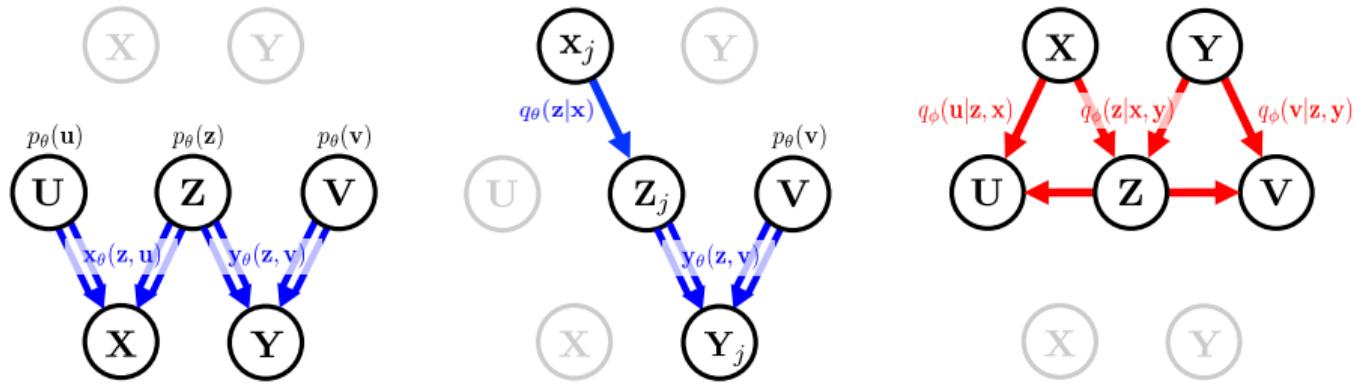
variational



Training objectives

- The variational Wyner model induces four distributions:

joint	$p_{\rightarrow xy}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq p_\theta(\mathbf{z})p_\theta(\mathbf{u})p_\theta(\mathbf{v})\delta(\mathbf{x} - \mathbf{x}_\theta(\mathbf{z}, \mathbf{u}))\delta(\mathbf{y} - \mathbf{y}_\theta(\mathbf{z}, \mathbf{v}))$
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cond. ($\mathbf{y} \rightarrow \mathbf{x}$)	$p_{y \rightarrow x}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}) \triangleq q(\mathbf{y})q_\theta(\mathbf{z} \mathbf{y})p_\theta(\mathbf{u})\delta(\mathbf{x} - \mathbf{x}_\theta(\mathbf{z}, \mathbf{u}))$
variational	$q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq q(\mathbf{x}, \mathbf{y})q_\phi(\mathbf{z} \mathbf{x}, \mathbf{y})q_\phi(\mathbf{u} \mathbf{z}, \mathbf{x})q_\phi(\mathbf{v} \mathbf{z}, \mathbf{y})$



Training objectives

- The variational Wyner model induces four distributions:

joint	$p_{\rightarrow xy}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq p_\theta(\mathbf{z})p_\theta(\mathbf{u})p_\theta(\mathbf{v})\delta(\mathbf{x} - \mathbf{x}_\theta(\mathbf{z}, \mathbf{u}))\delta(\mathbf{y} - \mathbf{y}_\theta(\mathbf{z}, \mathbf{v}))$
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variational	$q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq q(\mathbf{x}, \mathbf{y})q_\phi(\mathbf{z} \mathbf{x}, \mathbf{y})q_\phi(\mathbf{u} \mathbf{z}, \mathbf{x})q_\phi(\mathbf{v} \mathbf{z}, \mathbf{y})$

- Recall Wyner's optimization problem:

$$\begin{array}{ll}\text{minimize} & I(\mathbf{X}, \mathbf{Y}; \mathbf{Z}) \\ \text{subject to} & \mathbf{X} - \mathbf{Z} - \mathbf{Y} \\ \text{variables} & q_\phi(\mathbf{z}|\mathbf{x}, \mathbf{y})\end{array}$$

Training objectives

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variational	$q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq q(\mathbf{x}, \mathbf{y})q_\phi(\mathbf{z} \mathbf{x}, \mathbf{y})q_\phi(\mathbf{u} \mathbf{z}, \mathbf{x})q_\phi(\mathbf{v} \mathbf{z}, \mathbf{y})$

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- For each model $p_{\text{model}} \in \{p_{\rightarrow xy}, p_{x \rightarrow y}, p_{y \rightarrow x}\}$, we can relax the problem as

$$\text{minimize } D(p_{\text{model}}, q_{xy \rightarrow}) + \lambda_{\text{model}}^{\text{CI}} I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$$

Training objectives

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joint	$p_{\rightarrow xy}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \triangleq p_\theta(\mathbf{z})p_\theta(\mathbf{u})p_\theta(\mathbf{v})\delta(\mathbf{x} - \mathbf{x}_\theta(\mathbf{z}, \mathbf{u}))\delta(\mathbf{y} - \mathbf{y}_\theta(\mathbf{z}, \mathbf{v}))$
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$$\text{minimize } D(p_{\text{model}}, q_{xy \rightarrow}) + \lambda_{\text{model}}^{\text{CI}} I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$$

- Distribution matching with CI regularization

Derivation

- For each model $p_{\text{model}} \in \{p_{\rightarrow xy}, p_{x \rightarrow y}, p_{y \rightarrow x}\}$:

$$\begin{array}{ll}\text{minimize} & I_{xy \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z}) \\ \text{subject to} & \mathbf{X} - \mathbf{Z} - \mathbf{Y} \\ \text{variables} & q_\phi(\mathbf{z} | \mathbf{x}, \mathbf{y})\end{array}$$

Derivation

- For each model $p_{\text{model}} \in \{p_{\rightarrow xy}, p_{x \rightarrow y}, p_{y \rightarrow x}\}$:

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- Replace $\mathbf{X} - \mathbf{Z} - \mathbf{Y}$ with the model consistency

Derivation

- For each model $p_{\text{model}} \in \{p_{\rightarrow xy}, p_{x \rightarrow y}, p_{y \rightarrow x}\}$:

minimize $I_{xy \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$

subject to $p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \equiv q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})$

variables $q_\phi(\mathbf{z}|\mathbf{x}, \mathbf{y}), q_\phi(\mathbf{u}|\mathbf{z}, \mathbf{x}), q_\phi(\mathbf{v}|\mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})$

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Derivation

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minimize	$I_{xy \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
subject to	$D(p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}), q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})) = 0$
variables	$q_\phi(\mathbf{z} \mathbf{x}, \mathbf{y}), q_\phi(\mathbf{u} \mathbf{z}, \mathbf{x}), q_\phi(\mathbf{v} \mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})$

- Replace $\mathbf{X} - \mathbf{Z} - \mathbf{Y}$ with the model consistency

Derivation

- For each model $p_{\text{model}} \in \{p_{\rightarrow xy}, p_{x \rightarrow y}, p_{y \rightarrow x}\}$:

$$\begin{aligned} & \text{minimize} && I_{xy \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z}) \\ & \text{subject to} && D(p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}), q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})) = 0 \\ & \text{variables} && q_\phi(\mathbf{z}|\mathbf{x}, \mathbf{y}), q_\phi(\mathbf{u}|\mathbf{z}, \mathbf{x}), q_\phi(\mathbf{v}|\mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \end{aligned}$$

- Replace $\mathbf{X} - \mathbf{Z} - \mathbf{Y}$ with the model consistency
- Replace $I_{xy \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$ with $I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$

Derivation

- For each model $p_{\text{model}} \in \{p_{\rightarrow xy}, p_{x \rightarrow y}, p_{y \rightarrow x}\}$:

$$\begin{aligned} & \text{minimize} && I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z}) \\ & \text{subject to} && D(p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}), q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})) = 0 \\ & \text{variables} && q_\phi(\mathbf{z}|\mathbf{x}, \mathbf{y}), q_\phi(\mathbf{u}|\mathbf{z}, \mathbf{x}), q_\phi(\mathbf{v}|\mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \end{aligned}$$

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- Replace $I_{xy \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$ with $I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
- Relax the equality constraint

Derivation

- For each model $p_{\text{model}} \in \{p_{\rightarrow xy}, p_{x \rightarrow y}, p_{y \rightarrow x}\}$:

$$\begin{aligned} & \text{minimize} && I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z}) \\ & \text{subject to} && D(p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}), q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})) \leq \epsilon \\ & \text{variables} && q_\phi(\mathbf{z}|\mathbf{x}, \mathbf{y}), q_\phi(\mathbf{u}|\mathbf{z}, \mathbf{x}), q_\phi(\mathbf{v}|\mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \end{aligned}$$

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Derivation

- For each model $p_{\text{model}} \in \{p_{\rightarrow xy}, p_{x \rightarrow y}, p_{y \rightarrow x}\}$:

minimize	$I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
subject to	$D(p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}), q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})) \leq \epsilon$
variables	$q_\phi(\mathbf{z} \mathbf{x}, \mathbf{y}), q_\phi(\mathbf{u} \mathbf{z}, \mathbf{x}), q_\phi(\mathbf{v} \mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})$

- Replace $\mathbf{X} - \mathbf{Z} - \mathbf{Y}$ with the model consistency
- Replace $I_{xy \rightarrow}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$ with $I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$
- Relax the equality constraint
- Convert to an unconstrained Lagrangian minimization

Derivation

- For each model $p_{\text{model}} \in \{p_{\rightarrow xy}, p_{x \rightarrow y}, p_{y \rightarrow x}\}$:

$$\begin{array}{ll} \text{minimize} & D(p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}), q_{xy \rightarrow}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v})) + \lambda_{\text{model}}^{\text{CI}} I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z}) \\ \text{subject to} & \\ \text{variables} & q_{\phi}(\mathbf{z} | \mathbf{x}, \mathbf{y}), q_{\phi}(\mathbf{u} | \mathbf{z}, \mathbf{x}), q_{\phi}(\mathbf{v} | \mathbf{z}, \mathbf{y}), p_{\text{model}}(\mathbf{x}, \mathbf{y}, \mathbf{z}, \mathbf{u}, \mathbf{v}) \end{array}$$

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Training method

- For each model $p_{\text{model}} \in \{p_{\rightarrow xy}, p_{x \rightarrow y}, p_{y \rightarrow x}\}$,

$$\text{minimize} \quad D(p_{\text{model}}, q_{xy \rightarrow}) + \lambda_{\text{model}}^{\text{CI}} I_{\text{model}}(\mathbf{X}, \mathbf{Y}; \mathbf{Z})$$

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Training method

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- Simultaneous training: minimize a weighted sum of the objectives

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- Variational density-ratio estimation technique [Pu+17]: a variant of the discriminator trick of generative adversarial networks (GANs)

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- Variational density-ratio estimation technique [Pu+17]: a variant of the discriminator trick of generative adversarial networks (GANs)
- In practice, $\lambda_{\text{model}}^{\text{CI}}$ can be chosen by trial-and-errors

Training with variational density-ratio estimation technique

- A variant of the **discriminator trick** of **generative adversarial networks** [Pu+17]

Training with variational density-ratio estimation technique

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- Suppose we wish to solve

$$\min_{\theta} D_{\text{KL}}(p_{\theta}(s) \parallel q_{\theta}(s)) = \mathbb{E}_{p_{\theta}(s)} \left[\log \frac{p_{\theta}(s)}{q_{\theta}(s)} \right]$$

with no explicit density models on $p_{\theta}(s)$ and $q_{\theta}(s)$

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- We can approximate the objective if we knew how to compute the ratio $p_{\theta}(s)/q_{\theta}(s)$

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- **Variational density-ratio estimation:** We learn $r_{\psi}(s) \approx p_{\theta}(s)/q_{\theta}(s)$ by solving

$$D_{\text{JS}}(p_{\theta}(s), q_{\theta}(s)) = \max_{\psi} \mathbb{E}_{p_{\theta}(s)} [\log \sigma(\log r_{\psi}(s))] + \mathbb{E}_{q_{\theta}(s)} [\log \sigma(-\log r_{\psi}(s))]$$

Training with variational density-ratio estimation technique

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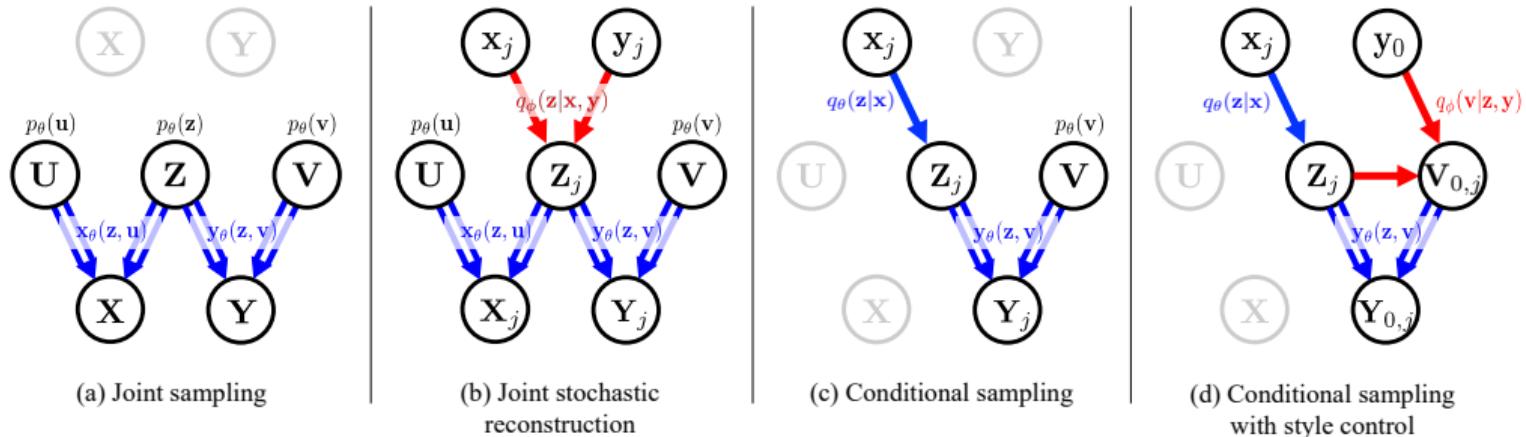
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- **Plug in and optimize:**

$$\min_{\theta} D_{\text{KL}}(p_{\theta}(s) \parallel q_{\theta}(s)) \approx \min_{\theta} \mathbb{E}_{p_{\theta}(s)} [\log r_{\psi}(s)]$$

How to use the variational Wyner model



- Variational encoders are introduced for training, but can be also used in sampling
- Local variational encoders $q_\phi(u|z, x)$, $q_\phi(v|z, y)$ can be viewed as style extractors

Experiment. MNIST–SVHN add-1 dataset

- $(X, Y) = (\text{MNIST}, \text{SVHN})$ with $\text{label}(\text{SVHN}) = \text{label}(\text{MNIST}) + 1$

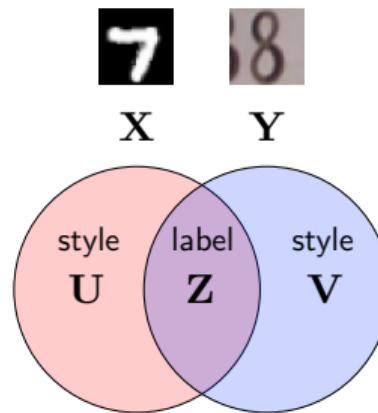


Experiment. MNIST–SVHN add-1 dataset

- $(\mathbf{X}, \mathbf{Y}) = (\text{MNIST}, \text{SVHN})$ with $\text{label}(\text{SVHN}) = \text{label}(\text{MNIST}) + 1$



- $\mathbf{Z} = \text{label}$, $(\mathbf{U}, \mathbf{V}) \approx (\text{style of MNIST}, \text{style of SVHN})$



Experiment. MNIST–SVHN add-1 dataset

- Generated samples: same labels across the rows; same styles across the columns
- A red box highlights inputs; a yellow box highlight style references



(a) →(MNIST,SVHN)



(b) MNIST→SVHN



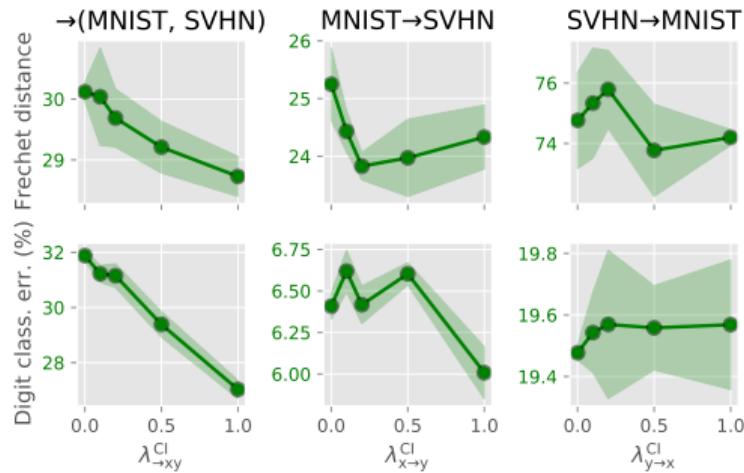
(c) SVHN→MNIST



(d) MNIST→SVHN
with style transfer

Experiment. MNIST–SVHN add-1 dataset

- Numerical evaluation: $\lambda_{\text{model}}^{\text{CI}}$ vs. quality of generated samples



Experiment. Sketchy dataset [San+16]

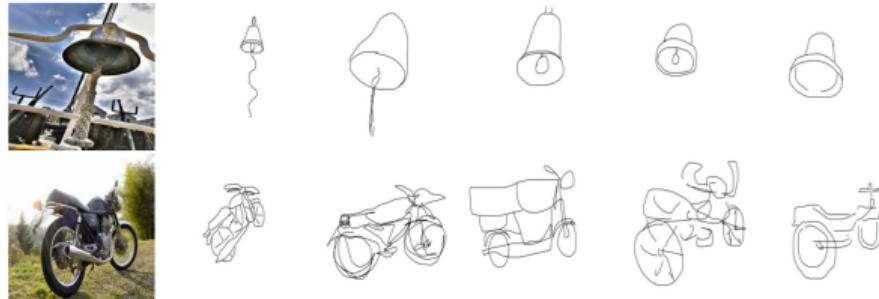
- $(\mathbf{X}, \mathbf{Y}) = (\text{photo, human sketch})$



- $\mathbf{Z} \approx \text{image class, } (\mathbf{U}, \mathbf{V}) \approx (\text{variation in photo, style of sketch})$

Experiment. Sketchy dataset [San+16]

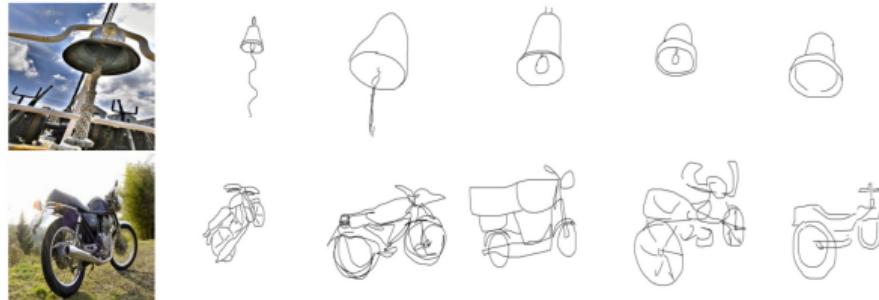
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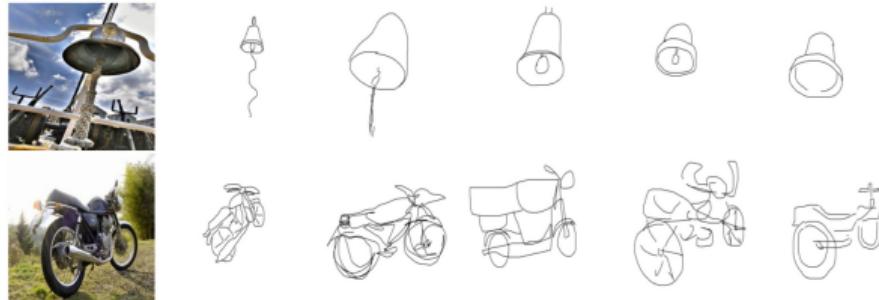
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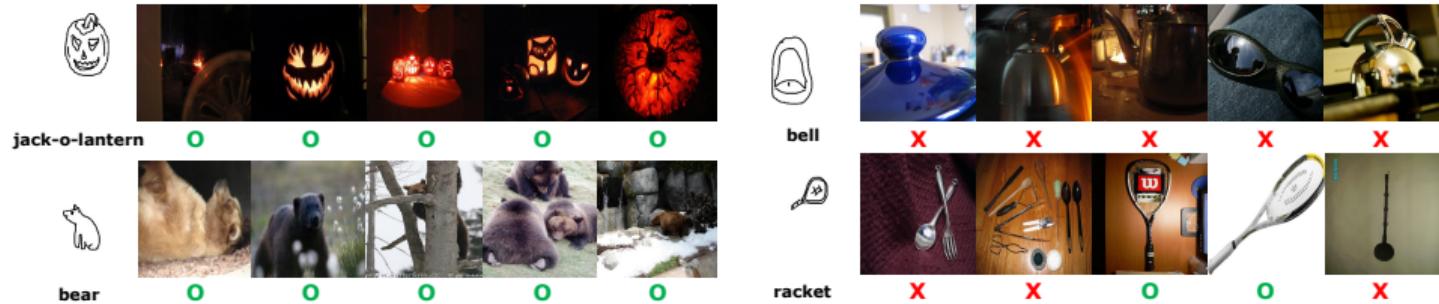
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- **Cross-domain retrieval**: given a sketch (y), retrieve photos (x)
- **Zero-shot**: training set has **no overlapping classes** with test set
- Our method: **retrieve via common representations**

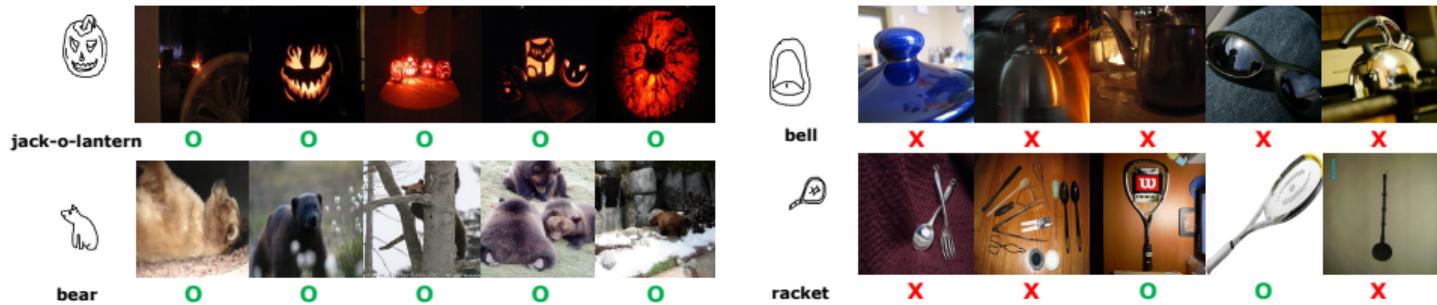
Experiment. Sketchy dataset [San+16]

- Examples: correct (left)/wrong (right) retrievals



Experiment. Sketchy dataset [San+16]

- Examples: correct (left)/wrong (right) retrievals



- Numerical evaluation: precision@K (P@K), mean average precision (mAP)

Models	P@100	mAP
LCALE [Lin+20]	0.583	0.476
IIAE [Hwa+20]	0.659	0.573
Variational Wyner	0.703	0.629

Experiment. CUB image-caption

- $(X, Y) = (\text{bird images}, \text{captions})$



the bird has a white body,
black wings, and webbed
orange feet



a blue bird with gray
primaries and secondaries
and white breast and throat

- Used ResNet-101 features for images

Experiment. CUB image-caption

→(image, caption)

			
this small bird is black white white with a small bill bill and black feet	this bird is grey with grey and a black beak , pointy short pointy beak .	this is a black and white black bird and a short black beak .	this bird has a black and and white and white feathers and
			
this white bird is mostly white white with a long bill , and black feet	this bird is grey with grey and has long long, pointy short pointy beak	this is a black and white black bird and a long long yellow ..	this bird has a white and and white and white with and feet .

image→caption

input image from test set	generated captions
	this bird has a black crown and breast , with a crown , and and black red its ..
	this bird has a black crown and breast , with yellow breast and and and its of its feathers .
	this bird has a red crown and breast , with red red red and red and on on red its ..
	this is a very , and white and and color with with a , and and a long blue patches ..
	this bird has yellow small , black beak and a breast and a black feathers . the bird it's the body ..
	the bird has red red red red , and red red and a red beak . the red 's feathers .

caption→image

input text from test set	ground truth	retrievals from generated features
This bird has yellow topped black and white striped wings and some red markings on its belly.		       
This bird has wings that are gray and has a white belly.		       

Experiment. CUB image-caption

- Numerical evaluation: correlation of generated samples

Model	joint	image→caption	caption→image
Test set		0.273	
MMVAE [Shi+19]	0.263	0.104	0.135
Variational Wyner	0.303	0.327	0.318

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- Learning distributions with Wyner's common information
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“Learning with Succinct Common Representation with Wyner’s Common Information”, **J. Jon Ryu**, Yoojin Choi, Young-Han Kim, Mostafa El-Khamy, and Jungwon Lee, arXiv:1905.10945, Under Review

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