NeuralSVD:

Operator SVD with Neural Networks via Nested Low-Rank Approximation

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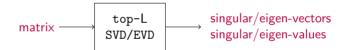
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Joint work with



Xiangxiang Xu, Mellihcan Erol, Yuheng Bu, Lizhong Zheng, and Gregory Wornell







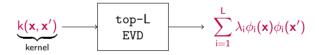
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The standard approach: decompose LARGE matrix (3)???

Example: With N electrons, $\mathbf{r} \in \mathbb{R}^{3N} \to O(\epsilon^{-3N})$ samples

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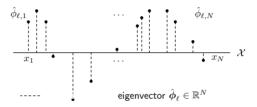
- **Example**: With N electrons, $\mathbf{r} \in \mathbb{R}^{3N} \to O(\epsilon^{-3N})$ samples
- Is there an alternative to this matrix approach?

Nonparametric Approach

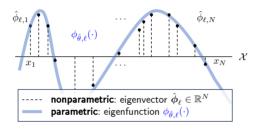


eigenvector $\hat{oldsymbol{\phi}}_\ell \in \mathbb{R}^N$

Nonparametric Approach



Negparametric Approach



$$\phi(\cdot) \approx [\phi(\mathsf{x}_1), \ldots, \phi(\mathsf{x}_\mathsf{N})]^\mathsf{T}$$

Matrix SVD

$$\mathsf{T} = \sum_{\mathsf{i}=1}^\mathsf{r} \sigma_\mathsf{i} \mathbf{u}_\mathsf{i} \mathbf{v}_\mathsf{i}^\mathsf{T}$$

where $\mathbf{u}_i^\mathsf{T} \mathbf{u}_i = \mathbf{v}_i^\mathsf{T} \mathbf{v}_i = \delta_{ii}, \ \sigma_1 \geq \sigma_2 \geq \ldots \geq 0$

Operator SVD

$$\mathcal{T} = \sum_{i=1}^{\infty} \sigma_i |\phi_i\rangle \langle \psi_i|$$

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Hilbert space $\mathcal{F} := \mathscr{L}^2_{\mu}(\mathcal{X}) := \{f \colon \mathcal{X} \to \mathbb{R} \mid ||f||^2 < \infty\}$ with inner product

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- When \mathcal{T} is symmetric PD. SVD = EVD
- Integral kernel operator: $(\mathcal{K}\phi)(y):=\int \mathsf{k}(\mathsf{x},\mathsf{y})\phi(\mathsf{x})\mu(\mathsf{d}\mathsf{x})$

Operator SVD

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 To train parametric eigen- (singular-) functions (parameterized by neural networks), solve an optimization problem that characterizes the top-L EVD/SVD

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- To train parametric eigen- (singular-) functions (parameterized by neural networks). solve an optimization problem that characterizes the top-L EVD/SVD
- Most (if not all) existing methods are based on Rayleigh quotient maximization
- We propose an optimization framework based on nested low-rank approximation!

Theorem (Eckart-Young, 1936)

$$\begin{split} (\boldsymbol{f}_{1:L}^{\star}, \boldsymbol{g}_{1:L}^{\star}) \in \underset{\boldsymbol{g}_{1}, \dots, \boldsymbol{f}_{L} \in \mathbb{R}^{M}}{\text{arg min}} \left\| \boldsymbol{T} - \sum_{i=1}^{L} \boldsymbol{f}_{i} \boldsymbol{g}_{i}^{\intercal} \right\|_{F}^{2} \\ & \boldsymbol{g}_{1}, \dots, \boldsymbol{g}_{L} \in \mathbb{R}^{N}^{N} \end{split}$$

$$If \, \boldsymbol{T} = \sum_{i=1}^{r} \sigma_{i} \boldsymbol{u}_{i} \boldsymbol{v}_{i}^{\intercal}, \ \, then \ \, \sum_{i=1}^{L} \boldsymbol{f}_{i}^{\star} (\boldsymbol{g}_{i}^{\star})^{\intercal} = \sum_{i=1}^{L} \sigma_{i} \boldsymbol{u}_{i} \boldsymbol{v}_{i}^{\intercal}$$

Theorem (Schmidt, 1907)

$$\begin{split} (\textbf{f}_{1:L}^{\star},\textbf{g}_{1:L}^{\star}) \in \underset{g_{1},\ldots,f_{L} \in \mathcal{F}, \\ g_{1},\ldots,g_{L} \in \mathcal{G}}{\text{arg min}} \left\| \mathcal{T} - \sum_{i=1}^{L} |f_{i}\rangle\langle g_{i}| \right\|_{\mathsf{HS}}^{2} \\ \textit{If } \mathcal{T} = \sum_{i=1}^{\infty} \sigma_{i} |\phi_{i}\rangle\langle\psi_{i}|, \; \textit{then} \; \sum_{i=1}^{L} |f_{i}^{\star}\rangle\langle g_{i}^{\star}| = \sum_{i=1}^{L} \sigma_{i} |\phi_{i}\rangle\langle\psi_{i}| \end{split}$$

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$$\mathcal{L}_{\mathsf{LoRA}}(\boldsymbol{f}_{1:L},\boldsymbol{g}_{1:L}) := \left\| \mathcal{T} - \sum_{i=1}^{L} |f_i\rangle \langle g_i| \right\|_{\mathsf{HS}}^2 - \|\mathcal{T}\|_{\mathsf{HS}}^2$$

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- 😌 Unconstrained optimization with computable objective!
- 🤨 But, the optimal solution only captures the top-L subspaces (i.e., not ordered)

Nesting for Symmetry Breaking

High-level idea: minimize $\mathcal{L}_{LoRA}(\mathbf{f}_{1:i}, \mathbf{g}_{1:i})$ for i = 1, ..., L

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- **High-level idea**: minimize $\mathcal{L}_{\mathsf{LoRA}}(\mathbf{f}_{1:i}, \mathbf{g}_{1:i})$ for $i = 1, \dots, \mathsf{L}$
- Why does this work?

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• How can we implement this idea?

• Idea: for each $i \in [L]$,

update $(f_i,\,g_i)$ as if $(\boldsymbol{f}_{1:i-1},\,\boldsymbol{g}_{1:i-1})$ were perfectly matched

Implementation: for each i ∈ [L],

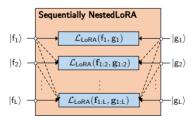
 $\text{update } (f_i^{(t)}, g_i^{(t)}) \text{ using gradient } \partial_{(f_i, g_i)} \mathcal{L}_{\mathsf{LoRA}}(f_{1:i}^{(t)}, \mathbf{g}_{1:i}^{(t)})$

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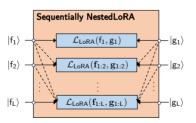


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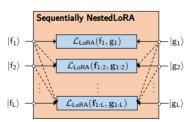
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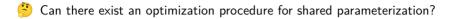
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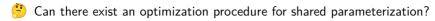
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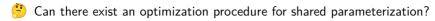


- Works as expected if (f_i, g_i) and (f_i, g_i) do not share parameters for any $i \neq j$
- When L \gg 1, disjoint parameterization might be not feasible





 $\textbf{Idea} : \ \mathsf{minimize} \ \mathsf{a} \ \mathsf{single} \ \mathsf{objective} \ \mathcal{L}_{\mathsf{jnt}}(\mathbf{f}_{1:L},\mathbf{g}_{1:L};\mathbf{w}) := \sum^{-} \mathsf{w}_{\mathsf{i}} \mathcal{L}_{\mathsf{LoRA}}(\mathbf{f}_{1:\mathsf{i}},\mathbf{g}_{1:\mathsf{i}})$



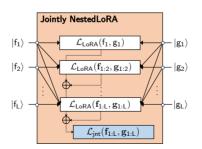
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- 🤔 Can there exist an optimization procedure for shared parameterization?
 - Idea: minimize a single objective $\mathcal{L}_{jnt}(\mathbf{f}_{1:L},\mathbf{g}_{1:L};\mathbf{w}) := \sum_{i=1}^{L} w_i \mathcal{L}_{LoRA}(\mathbf{f}_{1:i},\mathbf{g}_{1:i})$
 - Implementation:

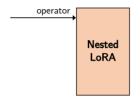
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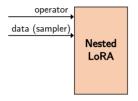
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 - $\bullet \ \, \textbf{Idea} \text{: minimize a single objective } \mathcal{L}_{jnt}(\textbf{f}_{1:L},\textbf{g}_{1:L};\textbf{w}) := \sum_{i=1}^{L} w_{i} \mathcal{L}_{LoRA}(\textbf{f}_{1:i},\textbf{g}_{1:i})$
 - Implementation:

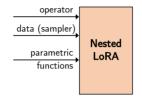
$$\text{update } (\boldsymbol{f}_{1:L}^{(t)}, \boldsymbol{g}_{1:L}^{(t)}) \text{ using gradient } \partial_{(\boldsymbol{f}_{1:L}, \boldsymbol{g}_{1:L})} \mathcal{L}_{jnt}(\boldsymbol{f}_{1:L}^{(t)}, \boldsymbol{g}_{1:L}^{(t)}; \boldsymbol{w}))$$

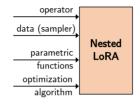


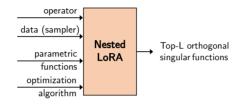




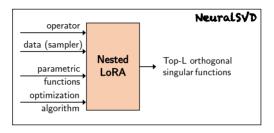


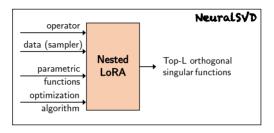




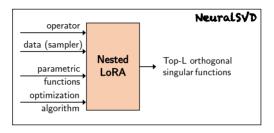


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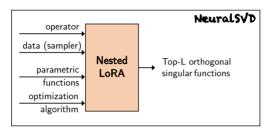




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- **Practical considerations**: NN architecture / optimization algorithm

Experiment 1. Schrödinger Equation (2D Hydrogen atom)

• Time-independent Schrödinger equation: for Hamiltonian $\mathcal{H} := -\nabla^2 + \mathcal{V}$,

$$\mathcal{H}|\psi\rangle = \mathsf{E}|\psi\rangle$$

• Single-electron potential $V(\mathbf{x}) = -\frac{1}{\|\mathbf{x}\|_2}$

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We decompose the **negative Hamiltonian** (ground-state first)

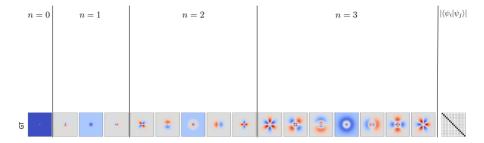


Figure: Learned eigenfunctions from SpIN, NeuralEF, and NeuralSVD.

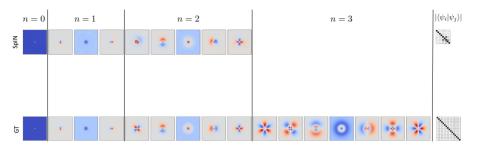


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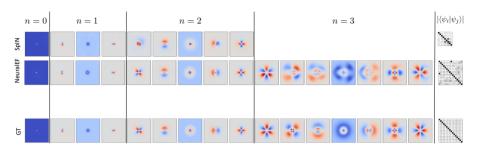


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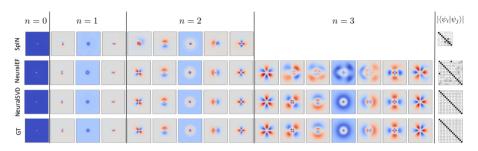


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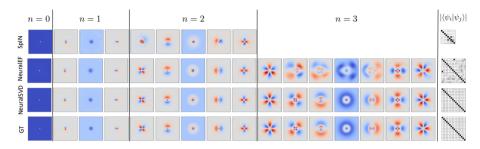


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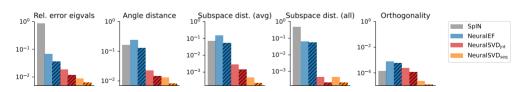
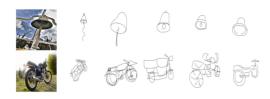


Figure: Summary of quantitative evaluations for solving TISE of 2D hydrogen atom. Non-hatched, light-colored bars represent batch size of 128, while hatched bars indicate batch size of 512.



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- Structured representation: coordinates are ordered in the order of importance

Table: Evaluation of the ZS-SBIR task with the Sketchy Extended dataset [4].

Model	Gen. model	Ext. knowledge	P@100	mAP	Split
LCALE [3]	*	Word embed.	0.583	0.476	1
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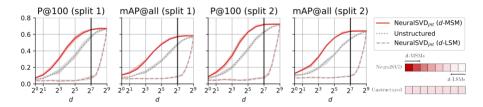
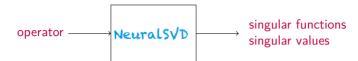


Figure: The mAP performance of NeuralSVD on ZS-SBIR task, when varying dimensions.





NeuralS√D → principled & scalable solutions for innumerous applications

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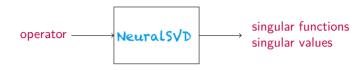
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- **Nested low-rank approximation** (Nested LoRA)
 - ✓ Unconstrained optimization
 - ✓ Unbiased gradient estimates
 - No additional regularization required



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- Check out our preprint and implementation: jongharyu.github.io

Unified Implementation: Gradient Masking

A unified gradient expression:

$$|\,\partial_{f_i}\mathcal{L}\rangle = 2\Big\{-m_i|\mathcal{T}^*g_i\rangle + \sum_{i'=1}^L M_{ii'}|f_{i'}\rangle\langle g_{i'}|g_i\rangle\Big\}$$

For sequential nesting:

$$\mathbf{m} \leftarrow \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}, \quad \mathsf{M} \leftarrow \begin{bmatrix} \frac{1}{0} & 1 & \dots & 1 \\ 0 & 1 & \dots & 1 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}$$

For joint nesting:

$$\boldsymbol{m} \leftarrow \begin{bmatrix} w_1 + w_2 + \ldots + w_L \\ w_2 + \ldots + w_L \\ \vdots \\ w_L \end{bmatrix}, \quad \boldsymbol{M} \leftarrow \begin{bmatrix} \underline{w_1} & w_2 & \ldots & w_L \\ \underline{w_2} & w_2 & \ldots & w_L \\ \vdots & \vdots & \ddots & \vdots \\ \underline{w_L} & w_L & \ldots & w_L \end{bmatrix}$$

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