

# Jongwon Lee

✉ jongwonjlee@gmail.com     jongwonjlee.github.io    in jongwonjlee     jongwonjlee

## Interests

Spatial AI, Robotic Perception and Navigation, Sensor Fusion and Calibration.

## Education

### University of Illinois Urbana-Champaign (UIUC)

Aug 2020 - Aug 2025

*Ph.D. in Aerospace Engineering*

(Expected)

- Dissertation: “Robust and Reliable Sensor Fusion and Localization for Autonomous Robotic Systems”
- Advisor: Dr. Timothy W. Bretl

### Korea Advanced Institute of Science and Technology (KAIST)

Mar 2014 - Aug 2020

*B.S. in Mechanical Engineering*

- GPA: 4.11/4.3, *Summa Cum Laude*

## Experience

### Student Researcher

Mountain View, CA

*Google*

Sep 2024 - Dec 2024

- Prototyped a visual navigation pipeline leveraging 3D Gaussian splatting (3DGS) and scene understanding for advanced scene representation.
- Initiated a patent filing for novel indoor image retrieval under scene changes, leveraging 3DGS and semantic segmentation.

### Graduate Research Assistant

Urbana, IL

*Bretl Research Group, UIUC*

Aug 2020 - Current

- Designed, developed, and validated navigation algorithms for flying vehicle takeoff and landing with visual and infrared fiducial markers, resulting in publications ([C5], [C3], [C2], [W1]).
- Designed, developed, and validated extrinsic self-calibration algorithms for multiple inertial sensor systems, resulting in publications ([C4], [J1]).
- Contributed to the design and implementation of a distributed inertial sensor system for CubeSat applications as part of NASA STTR-funded research.

### Research Intern

Seongnam, Korea

*NAVER LABS*

Feb 2020 - Aug 2020

- Examined the impact of learning-based image retrieval methods within a large-scale outdoor visual navigation pipeline.

### Research Intern

Daejeon, Korea

*Intelligent Robotic Autonomy and Perception Laboratory, KAIST*

Mar 2018 - Dec 2019

- Developed and validated depth estimation methods under low-light conditions using stereo infrared cameras, comparing conventional and learning-based approaches.
- Developed and validated a learning-based image retrieval for urban environments under scene changes, leveraging fisheye images and resulting in a publication ([C1]).

## Publications


[J2] David Hanley, **Jongwon Lee**, Su Yeon Choi, Timothy Bretl. “The MagPIE2 Dataset: Magnetic Field-Based Mapping, Localization, and SLAM”. *IEEE Transactions on Instrumentation and Measurement*, 2025. (submitted)


[C5] Su Yeon Choi, **Jongwon Lee**, Timothy Bretl. “Design and Detection of an Infrared Fiducial Marker”. *IEEE International Conference on Robotics and Automation (ICRA)*, 2025. (submitted)

[C4] **Jongwon Lee**, David Hanley, Timothy Bretl. “Efficient Extrinsic Self-Calibration of Multiple IMUs Using Measurement Subset Selection” . *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 2024.

[C3] **Jongwon Lee**, Su Yeon Choi, Timothy Bretl. “The Use of Multi-Scale Fiducial Markers to Aid Rotorcraft Navigation” . *AIAA SciTech Forum*, 2024.

[C2] Su Yeon Choi, **Jongwon Lee**, Timothy Bretl. “The Impact of Adverse Environmental Conditions on Fiducial Marker Detection from Rotorcraft” . *AIAA SciTech Forum*, 2024.

[W1] **Jongwon Lee**, Su Yeon Choi, David Hanley, and Timothy Bretl. “Comparative Study of Visual SLAM-Based Mobile Robot Localization Using Fiducial Markers” . IROS Workshop on Closing the Loop on Localization, 2023.

[J1] **Jongwon Lee**, David Hanley, Timothy Bretl. “Extrinsic Calibration of Multiple Inertial Sensors from Arbitrary Trajectories” . *IEEE Robotics and Automation Letters (RA-L)*, 2022. (Presented at ICRA 2022)

[C1] Jongwon Lee, Ayoung Kim. “Neural Network-Based Long-Term Place Recognition from Omni-Images” [🔗](#). *IEEE International Conference on Ubiquitous Robots (UR)*, 2019.

## Skills

---

**Programming:** Python, C++

**Libraries and Frameworks:** PyTorch, OpenCV, ROS, Optimization Libraries (Ceres, g2o, SymForce)

**Tools:** Docker, Git, 3D CAD (SolidWorks), LaTeX

## Awards and Honors

---

Mavis Future Faculty Fellows Program. *College of Engineering (CoE), UIUC*. 2024 - 2025.

Academic Excellence Award for Class of 2021. *Mechanical Engineering (ME), KAIST*. 2021.

Seong-Bu Kim Creative Activity Initiative Award. *ME, KAIST*. 2021.

The Korean Government Scholarship Program for Study Overseas. *Korean Ministry of Education*. 2020 - 2022.

Engineering Innovation Award. *CoE, KAIST*. 2020.

Travel Grants (ACCV 2018, UR 2019, IROS 2019, CES 2020). *KAIST*.

National Science and Engineering Scholarship. *Korea Student Aid Foundation*. 2014 - 2019.

Dean’s List. *CoE, KAIST*. 2014 - 2016, 2019.

Scholarship for Honors Students. *ME, KAIST*. Spring 2019.

Outstanding Achievement Award. *ME, KAIST*. 2014 - 2015, 2018.

Best Instructor Award. *KAIST Science Outreach Program*. 2018.

Bronze Prize, CEE-URP. *Civil and Environmental Engineering, KAIST*. 2018.

## Professional Services

---

### Reviewer

- IEEE Transactions on Robotics (*T-RO*). 2024 - Current.
- IEEE Robotics and Automation Letters (*RA-L*). 2024 - Current.
- IEEE Transactions on Instrumentation and Measurement (*TIM*). 2022 - Current.
- IEEE International Conference on Robotics and Automation (*ICRA*). 2022 - Current.

### Membership

- American Institute of Aeronautics and Astronautics (*AIAA*)
- Academy of Model Aeronautics (*AMA*)
- Institute of Electrical and Electronics Engineers (*IEEE*)

### Teaching Assistant

- Aerospace Control Systems (AE 353). *UIUC*. Spring 2025.
- Autonomous Systems Lab (AE 483). *UIUC*. Fall 2022.

### Mentorship

- Geonwoo Kim, ME 497, *UIUC*. Jan 2024 - May 2024.
- Chris Schreiber, Jiho Sim, and Katherine Ruiz, AE 298, *UIUC*. Jan 2024 - May 2024.
- Parth Shrotri and Shivani Atre, AE 298, *UIUC*. Jan 2023 - Dec 2023.
- Pradyun Narkadamilli, ECE 297, *UIUC*. Sep 2022 - Dec 2022.
- Arjun Shah and Varun Sarabudla, PURE, *UIUC*. Sep 2021 - Dec 2021.
- Chaemin Na, CEE-URP, *KAIST*. Jun 2018 - Dec 2018.